Preface

The aim of this book is to help towards the understanding of microeconomic theory, particularly where it concerns general economic equilibrium with its implications for prices and resource allocation. I shall deal with the structure of the theory and briefly discuss its motivation. But I shall make only passing remarks about its practical relevance or about the precepts that have been deduced from it for applied economics.

Like the first one, this revised and extended edition is addressed to students who possess a good background in mathematics and have been introduced to economic phenomena and concepts. But their power of abstraction is not considered high enough to allow them to take immediate full advantage of the most rigorous and condensed works in mathematical economics.† On the other hand, they need some introduction to the many extensions that the theory has received during the past thirty years.

The theoretical exposition does not attempt to achieve the greatest generality that is possible today. Most of the results could be strengthened. But a complete catalogue of the known theorems would be tedious and of only secondary interest to the student. Those who wish to specialise in microeconomic theory must refer to the original works for those questions which they want to investigate more deeply.

On the other hand, the various chapters do cover almost completely the different viewpoints that have contributed to our precise understanding of general equilibrium. The scope of these lectures is satisfactorily defined by the table of contents, without the need for further discussion here.

It follows from my purpose that the proofs of the principal results should be given or at least outlined, since they are essential for the understanding of the properties involved. It makes it equally desirable that the level of rigour currently achieved by microeconomic theory should be respected. Therefore the assumptions used in the main proofs have been stated explicitly even when they could have been eliminated by resort to a more powerful argument. In many cases, where simplicity seemed to be advisable, special models with very few agents and commodities have been used rather than general specifications. In short, the accent is placed on the logical structures of the theory rather than on the statement of its results.

As thus described, the text should be useful to those who are solidly equipped in mathematics, are ready to make the effort required to understand existing microeconomic theory and are not prepared to be content with less rigorous presentations, which are naturally easier but also are responsible for some confusion.

The historical development of microeconomic theory has been only occasionally touched on. To trace and describe the origin of each result would have been to overburden the exposition. The few references given in the various chapters do not pretend to do justice to the authors of the most important contributions, but rather to give the student some indications as to how he may follow up certain questions. When the book is to be used for a course, the teacher will be well advised to prepare a reading list appropriate to the specific needs of his students.

It is a pleasure to acknowledge that once again Mrs. Anne Silvey was good enough to prepare the English translation of my work and to make it both fluent and accurate.
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1. Object of the theory

L. Robbins put forward the following definition: 'economics is the science which studies human behaviour as a relationship between ends and scarce means which have alternative uses'.† Such a statement does not make it clear that economics is a social science which studies the activity of men living in organised communities. It also risks failure to make sufficient distinction between economics and political science, since the terms 'ends' and 'means' may be interpreted in a very general sense.

In a work which follows marxist thinking, O. Lange writes: 'Political economy, or social economy, is the study of the social laws governing the production and distribution of the material means of satisfying human needs.'‡ There is nothing to say about this very compact definition except that the terms 'social laws' and 'material means' are capable of misinterpretation. The social nature lies in the analysed phenomena, production and distribution, rather than in the permanent relations which we establish between them, and which we call laws. 'Material means', also called 'goods', must be interpreted sufficiently widely to include, for example, the provision of services.

Here we propose the alternative, more explicit definition: economics is the science which studies how scarce resources are employed for the satisfaction of the needs of men living in society: on the one hand, it is interested in the essential operations of production, distribution and consumption of goods, and on the other hand, in the institutions and activities whose object it is to facilitate these operations.

The most cursory observation of economic life under the differing regimes which exist today reveals a juxtaposition of large numbers of individuals,

Conceptual framework of microeconomic theory

each acting with some autonomy but within a complex institutional framework which organises their mutual interdependences.

So, in so far as it is a positive, that is, explanatory science, economics must analyse the behaviour of agents who enjoy some freedom but are subject to the constraints imposed on them by nature and institutions. It must investigate the consequences of such individual behaviour for the state of affairs which is realised in the community.

In so far as it is a normative science, economics must also investigate the best way of organising production, distribution and consumption. It must give the conceptual tools which enable us to assess the comparative advantages of different forms of organisation.

In its pursuit of this double activity, positive and normative, our science has come to attribute a central role to the prices which regulate the exchange of goods among agents. For the individual, these prices reflect more or less exactly the social scarcity of the products which he buys and sells. This is why the study of the price system is just as important as the study of production and consumption.

The main object of the theory in which we are interested is the analysis of the simultaneous determination of prices and the quantities produced, exchanged and consumed. It is called microeconomic because, in its abstract formulations, it respects the individuality of each good and each agent. This seems a necessary condition a priori for a logical investigation of the phenomena in question. By contrast, the rest of economic theory is in most cases macroeconomic, reasoning directly on the basis of aggregates of goods and agents.

The theory of prices and resources allocation, somewhat improperly called 'microeconomic theory', has now attained a fairly high level of rigour, in the sense that its main sections are constructed from a consistent set of abstract concepts, which provide a formal representation of the society under study. So the reasoning in these lectures will be based on a single general model to which more specific assumptions will be introduced as we proceed. The first task is to define the elements of this model.

2. Goods, agents, economy

'Goods' and 'agents' are the first two concepts. Bread, coal, electrical power, buses, etc., are considered as goods, the quantity of each being measured in appropriate units. Services such as transport, hairdressing, medical care, etc., are also goods since they satisfy human needs. Labour is a good of particular importance since it is an essential element in all production. In relation to it, we should, properly speaking, distinguish as many goods as there are types of labour. We shall speak of 'commodities' interchangeably with 'goods'. These two terms will be taken as equivalent, at least
up to Chapter 10 where it will be convenient to give them different meanings.

The economic activity of individuals is both professional and private; in most cases, professional activity takes place in the context of firms engaged in production; private activity generally occurs within households and involves the consumption of goods for the satisfaction of widely varying needs. It is convenient for the purposes of theory to distinguish the two types of organised cells in which each activity is carried on. So we shall speak of 'producer agents' and 'consumer agents'.

More generally, 'agents' are the individuals, groups of individuals or organisms which constitute the elementary units of activity. To each agent there corresponds an autonomous centre of decision.

Here we shall assume in most cases that the agents can be divided into two categories: 'producers', who transform certain goods into other goods, and 'consumers' who use certain goods for their own needs. The former are also sometimes called 'enterprises' or 'firms'. The latter may represent either individuals, or cells of united individuals who constitute households, or possibly larger social groups pursuing common aims for the direct satisfaction of their needs.

In the model with which we shall mainly be concerned, there exist $l$ commodities, $m$ consumers and $n$ producers. Certain resources, which are available a priori, can be used either for production or for consumption. Finally, we shall often add to the model the clause that every good has a price. Let us briefly examine these notions in turn.

(a) With each commodity, identified by an appropriate index $h$ ($h = 1, 2, \ldots, l$), there is associated a definite unit of quantity. The commodity is characterised by the property that two equal quantities of it are completely equivalent for each consumer and each producer. When taking the normative standpoint, we also assume that two equal quantities of the same good are socially equivalent.

We shall often have to consider 'complexes of goods', a complex being defined as a set of quantities of the $l$ commodities, for example, $z_1, z_2, \ldots, z_l$. It is therefore a vector of $R^l$, $z$ say.

(b) The social organisation of economic activity generally allows individuals to exchange goods among themselves. One of our main objects in these lectures is to understand how these exchanges are carried out. In most of the following chapters, these exchanges conform to prices given to the different goods.

With each commodity, therefore, we associate a price which is a positive or zero number. We say, for example, that the price of the $h$th good is $p_h$. For the set of goods, we can define a corresponding vector $p$, the price vector.

By definition, the value of a complex $z$ of goods is

$$\sum_{h=1}^{l} p_h z_h.$$
which can obviously be denoted by \( pz \). Two complexes with the same value are considered to be mutually exchangeable. Thus, \( z^1 \) and \( z^2 \) are exchangeable if \( pz^1 = pz^2 \).

Suppose that in particular we have the following two complexes:

\[
    z^1 = (0, 0, ..., 0, 1, 0, ..., 0), \\
    z^2 = (0, 0, ..., 0, x),
\]

where the component 1 has the \( h \)th position in \( z^1 \). The complexes are exchangeable if

\[
    p_h = p_t x.
\]

So the ratio between \( p_h \) and \( p_t \) defines the quantity of the good \( l \) which must be given in exchange for one unit of \( h \).

In what follows we shall be concerned only with the ratios of the values of different complexes. In fact, in our formulations, the vector \( p \) will be defined only up to a multiplicative constant, \( \lambda p \) representing the same price vector as \( p \), whatever the positive number \( \lambda \). We shall verify this in each of the following chapters.

It is sometimes convenient to eliminate this indeterminacy by demanding that \( p \) satisfy a conventionally chosen condition. Thus, the price of one commodity is often fixed at 1, and the commodity in question is then called the 'numéraire'. For the purposes of theory, there is no necessity to choose a numéraire; we shall not do this except where explicitly mentioned.

(c) With each consumer there is associated an index \( i(i = 1, 2, ..., m) \). The activity of the \( i \)th consumer is represented by the complex \( x_i \) whose components \( x_{ih} \) define the quantities consumed of the different goods. The \( x_{ih} \) are not necessarily positive; for example, we shall often assume that the \( i \)th consumer provides labour of a certain description. This will be represented by negative consumption which appears in \( x_i \) as a negative component for the good corresponding to labour of this kind.

(d) With each producer there is associated an index \( j(j = 1, 2, ..., n) \). The \( j \)th producer transforms certain goods, called his 'inputs', into other goods, his 'outputs'. Let \( a_j \) and \( b_j \) be the vectors which represent respectively the complex of inputs (the \( a_{jh} \)) and the complex of outputs (the \( b_{jh} \)). The \( j \)th producer's net production of the good \( h \) is, by definition, \( y_{jh} = b_{jh} - a_{jh} \). It is positive if \( h \) is one of his outputs, negative if it is an input. We shall later consider often the complex of net productions and the vector \( y_j \) without involving inputs and outputs explicitly.

(e) A priori, the community has at its disposal certain quantities \( \omega_h \) of the different goods. These are the initial resources, the vector \( \omega \) of which is one of the data of the situation under study.

Like the notions previously introduced, that of initial resources has some flexibility. Thus, we might conceivably represent the labour provided by the
Possible interpretations of the concept of a good

individuals of the community in two ways. As we have just said, this can be considered as negative consumption by consumers. It can also be considered as an initial resource available to the economy. According to the latter point of view, if \( h \) represents labour of a certain kind, \( x_{ih} \) is zero while \( \omega_h \) represents the total quantity of that labour provided by the individuals of the community.

We shall have to introduce many variants of the general model. For example, we shall sometimes assume that the initial resources are privately owned and are therefore in the possession of individual consumers. We shall often simplify our theoretical study by considering a model with no producers, where only the distribution or exchange of goods among consumers is analysed.

Having introduced these initial ideas, we can define formally what we mean by the 'economy'. In fact the definition will vary according to the particular model. Obviously we shall come to elaborate our representation of consumers and producers and to add new concepts. But at this very early stage, we can say that an economy is defined by a list of goods, a list of consumers, a list of producers, and a vector \( \omega \) of initial resources. A state of the economy is then defined when particular values are given for the \( m \) vectors \( x_i \) and the \( n \) vectors \( y_j \). In positive theory, where the aim is also to explain how prices are determined, we shall have to introduce a vector \( p \) (specified up to a multiplicative constant) when we define a state of the economy.

In this general conceptual context, there are two types of objective for microeconomic theory. In the first place, it must describe the activity of agents, that is, it must provide models which explain in abstract terms how each consumer \( i \) determines \( x_i \) and how each producer \( j \) determines \( y_j \), and it must also describe how all the \( x_{ih} \) and all the \( y_{jh} \), and possibly also prices \( p_{ih} \), are simultaneously determined. (It must therefore place itself at the level of the individual agent in a partial perspective as well as at the level of the whole economy). This is the objective of equilibrium theory, first partial, then general equilibrium.

In the second place, it must look for an optimal organisation of production, consumption and exchange, and then study the properties of a state of the economy in which this optimal organisation is realised. This is the objective of optimum theory, also called welfare theory.

These are the questions which we shall be discussing in the course of these lectures. Our immediate task is to examine the validity of the general conceptual framework on which all later analysis will be based.

3. Possible interpretations of the concept of a good

What kind of picture of economic reality can we derive from these general concepts?
They present us with a community composed of two types of individual, consumers and producers, and of these two types alone. At a given instant, the community finds itself in possession of certain initial resources involving a finite number of goods. It is about to engage in the operations of production, distribution and consumption.

We propose to discover \textit{a priori} how consumers and producers will act when they find themselves in an institutional framework to which we shall later give formal representation. We wish to know what prices will be established for the exchange of goods. We wish to find what might be the best system of production and consumption. In doing this, we appear to assume that the community will act once for all, as if it were taking part in a game with fixed rules.

It is up to the reader to consider, throughout the coming lectures, how far this picture approximates to reality. It is not my purpose to discuss it much further. However, it must be emphasised that these concepts have greater flexibility than may appear at first. In particular, let us examine the definition of goods.

(i) \textit{Quality of goods}

Each commodity must be perfectly homogeneous since two equal quantities of it must be equivalent. In actual fact, many products show a more or less immense range of qualities. Two foodstuffs of the same kind may differ in flavour or nutritive content. Two machines designed for the same tasks may differ in durability, power consumption or ease of operation.

However, the concept of a commodity can be adapted to this diversity among products of the same kind. Two different qualities of the same product or service may in fact be represented by two different commodities. Of course the number of goods then becomes much greater than that of products and services. But there is no reason why \( l \) should not be very large.

The model is therefore still appropriate unless the range of qualities of some products appears perfectly continuous, which is never properly speaking true, but may represent the real situation better than a very large number of distinct qualities. For example, if the specification of a crude oil is defined by its composition in terms of certain elements whose number is \( r \), then a distinct quality corresponds to each of the points of a bounded region of \( r \)-dimensional space. The qualities are no longer finite in number.

Our model does not cover such cases. However, the theories can be generalised, subject to certain conditions, so that the restriction is not too serious.†

(ii) Location

We assume goods to be directly exchangeable, and this is not the case if they are available in different places. Two equal quantities of the same good are not really equivalent if they are not available in the same place. This does not destroy the usefulness of the concept of a good since we may consider the same product available in two different places as two distinct goods. Transport of the product from the first place to the second is then a productive activity with the first good as input and the second as output.

As in the case of qualities, it is restrictive to assume the number of locations finite, but this is not a serious restriction both because, for the most part, economic activity is concentrated in relatively few geographical centres, and because the theories discussed later will be capable of generalisation subject to some fairly natural additional assumptions.

(iii) Date

Two equal quantities of the same product which are available at different times are not really equivalent, so that these quantities must be considered to correspond to different commodities.

Obviously the model does not require that we confine our discussion to operations relating to a single period. We can multiply the number of periods at will, provided that we simultaneously multiply the number of commodities. However, to keep within the terms of the model just defined, we must adopt a discrete representation of time and put a limiting terminal date to the future.

We have already said that it is permissible to represent the range of goods by continuous variables. So we can consider time \( t \) as a real variable belonging to a certain interval and let the function \( z_q(t) \) denote quantities of the product \( q \) at each instant \( t \).

Also, we may prefer unlimited future time to choosing a finite number of dates, which implies that the future period to be considered has a definite limiting horizon. Under certain additional assumptions, the theories with which we shall be concerned can be generalised to the case where time is represented by an unlimited sequence of periods

\[
t = 1, 2, \ldots, \text{etc.}
\]

However, the generalisation is not straightforward and often leads to weaker results.

Thus, subject only to the reservation that qualities, locations and periods are finite in number, the conceptual framework introduced above easily takes account of the actual diversity of products and services.

Suppose that the index \( q = 1, 2, \ldots, Q \) characterises both the nature and quality of products and services, that there are \( S \) locations represented by an index \( s = 1, 2, \ldots, S \) and \( T \) periods represented by \( t = 1, 2, \ldots, T \). The index
h now represents \((q, s, t)\) and \(l = QST\). The quantity \(x_{ih}\) denotes the \(i\)th consumer's consumption of the product whose nature and quality is \(q\), available at place \(s\) in period \(t\).

We shall not go on reminding ourselves that the positive or normative theories we are discussing can be interpreted so as to take account of the diversity of locations and times, since this would become tedious. But there is an accompanying risk of unwittingly disguising difficulties, since some of the assumptions to be adopted may become more restrictive when several places and several dates are distinguished. An example of this will be given shortly. But the student must ask himself throughout the lectures how far the various assumptions adopted are appropriate to a space-time economy. In Chapter 10 we shall have occasion to examine more closely the complications which arise from the progress of time.

To enlarge on the above remarks, we now ignore differences of quality and location. So the index \(h\) stands for the double index \((q, t)\). Our theories have an \textit{a priori} standpoint. Their aim is, for example, to explain how production, consumption and price will be determined. In a time perspective, this means (i) that the periods \(t = 1, 2, \ldots, T\) are future periods and (ii) that consumption, production and price are determined simultaneously for all periods.

To choose \(x_i\) is to choose all the components \(x_{iqt}\) which refer to multiple products and services, but also at multiple future dates. Thus, \(x_i\) is a \textit{consumption programme or plan} which relates to all the periods considered. Similarly, to explain the simultaneous determination of the \(x_i\), the \(y_j\) and \(p\) is to explain how, at the moment considered, the programmes of all agents and prices are determined for all future periods.

To suppose that a price vector \(p\) exists at a certain instant is to suppose that, at that instant, there exist well-defined prices for each index \((q, t)\), that is, for each product and each future date. So, corresponding to each product \(q\), there are as many prices as there are dates. The price \(p_{qt}\) is that price which must be paid now (at the moment considered) to obtain delivery at time \(t\) of a unit of the product \(q\). It is therefore a 'forward price'.

To assume the existence of forward prices for all dates and all products, as we do here for a time economy, is clearly more restrictive and perhaps much less realistic than to assume the existence of actual prices for all products in an economy without time. 'In fact', the sceptic might say, 'in what actual exchanges do forward prices apply? Are they as numerous as the theory would like them to be?' This demonstrates that doubts may be expressed as to the relevance of some possible temporal interpretations of our theories. But such doubts do not destroy its usefulness, though they may sometimes restrict its field of application. We shall of course come back to this question in Chapter 10, when we shall deal explicitly with time.
4. Descriptive relevance of the accounting economy

Enough has been said about the concept of a good. Now we must say a little about the most obvious omissions from our representation of the economy.

It is an economy with no public bodies and in particular, with no government agencies. Of course, there is no reason why the institutional rules which govern it should not be decided by some political power with its attendant administration. But our model ignores the fact that certain public bodies also participate directly in the production and consumption of goods. In order to ensure the satisfaction of collective needs, these organisations acquire some of the goods produced and themselves carry out some production operations. As we shall see later, this situation is easily explained: the market economy, which has a certain efficiency in the satisfaction of individual needs, does not as spontaneously ensure the satisfaction of collective needs, which must be taken over by agents representing all interested parties. However, at this stage we ignore the existence of collective needs. We shall return to this simplification later (cf. Chapter 9).

For the moment, we have taken account only of operations on goods and services within the economy. We can introduce income formation in a fairly natural way; the price of the work done by a consumer is the rate of remuneration for his labour; the value of the net production of a firm constitutes its profit, which is distributed to consumers if they hold the property of the firm.† Indeed, microeconomic theory is much concerned with this aspect of the distribution of incomes. However, its representation of income-formation ignores the many transfers which take place in modern societies: taxes raised to cover the cost of collective services, graduated taxation and subsidies to ensure a more equitable distribution of incomes, etc. Similarly, the model does not represent the multifarious financial operations which actually take place.‡

In our economy, prices are defined only up to a multiplicative constant and can be referred to any numéraire. In real life, prices are expressed as a function of money, which serves as a medium of exchange. Economic science must explain how their absolute level varies, that is, it must explain changes in the purchasing power of money, since such changes affect very many phenomena.

We shall abstract here from this aspect of reality. To visualise the world represented by our model, one might consider that commodities are directly exchanged, as in a 'barter economy'. Better justice is done to the conceptual power of the model if we assume an 'accounting economy', in which the value

† Similarly, a representation of 'rent' will be given in Chapter 5.
‡ Taxes and transfers have some part to play in Chapter 9. We shall also see in Chapter 10 that the time version of the model involves borrowing and lending operations: but it does so in a very summary way, without taking account of the liquidity of the various debts.
of each economic operation is properly recorded in accounts that are held for each agent and use the 'numéraire' as unit of value. In such an economy rules are imposed on the accounts of each agent, for instance consumer \( i \) may be required to balance his budget.

Finally, we are interested in a closed economy with no relationships with other economies. Our community cannot take advantage of the trade possibilities offered by the international market. Its price structure is completely independent of foreign price structures.

These various simplifications can be justified by the requirements of teaching; one cannot introduce everything all at once in a lecture course without running the risk of swamping the audience completely. Monetary theory, public finance and international trade are dealt with elsewhere in economic literature.

However, it must be pointed out that at present there exists no microeconomic theory which has the degree of rigour that we adopt and which recognises explicitly the existence of public bodies, monetary operations and external trade. Just as physics has not yet integrated the theories of electromagnetism and gravitation, so our science has not yet managed fully to integrate the microeconomic theory of the accounting economy with the macroeconomic theories of money, public finance and international trade.

But clearly, this does not destroy the usefulness of microeconomics as it exists today. Its relevance, although somewhat limited by the above simplifications, still persists since the theory as presently constructed does give a correct analysis of the principal phenomena and questions relating to the production and consumption of goods. It gives a conceptual frame of reference which often proves essential, and which no economist can afford to neglect, whatever his speciality.

5. The demands of rigour and simplicity

I have set myself two rules in these lectures. In the first place, I aim at rigour in order clearly to reveal the logical connection between certain formulations and assumptions and the properties deduced from them. In the second place, I aim at simplicity. When dealing with each of the important properties deduced by microeconomic theory, I try to select from all the presently available variants that which seems to be the best compromise between the greatest generality and the greatest simplicity. I therefore avoid those formulations which try to remain closer to reality but can do so only at the price of considerable complexity. I also refrain from listing the different variants, thus embarking on distinctions which are of interest only to specialists.

Such a course has the drawback that it does not lead to the greatest generality which is presently possible. The reader must see this clearly.
Thus, I shall be led to state precisely and to discuss assumptions that will be useful at one time or another in proofs. In order to reveal the nature of these assumptions more clearly, I shall give counter-examples, that is, situations in which they are not naturally satisfied. However, I must warn against an error of interpretation. These counter-examples will not necessarily reveal cases where the theory breaks down. There are several reasons for this.

In the first place, in most cases I shall use in each proof only some of the assumptions stated. They will be indicated in the statement of the properties. In the second place, the sole object of some of the assumptions adopted will be to facilitate the proofs. In the choice between generality and simplicity, I shall often tend to favour the latter. Those who wish to go further must consult the books and articles in which the theory has been more fully elaborated.

In the third place, the assumptions in question always take the role of sufficient conditions for the validity of the results. In most cases, it would be wrong to take them as necessary, since, among these assumptions, there are few which could not be replaced by others whose content would be less restrictive from some points of view although often more restrictive from others.

Having completed these lectures, but as yet lacking knowledge of the extensive underlying literature, the reader may be tempted to say 'microeconomic theory assumes that ...'. When he or she feels this temptation, I beg him or her to say instead 'in his presentation of microeconomic theory Målinvaud assumes that ...'. If the reader then thinks that the restriction is serious, he or she should look for generalisations which do not involve it.
The consumer

1. Outline of the theory

Our first task is to make a detailed study of a formulation which applies to consumer activity and constitutes the basic element for the development of positive and normative theories concerning the whole economy. We have a double objective.

In the first place, we must represent human needs and take account of the fact that they can be satisfied more or less well, more or less completely. This representation will serve for explanation of the choices made by consuming individuals or households. It will also contribute to normative theories, when we try to classify states of the economy according as they satisfy individual needs more or less well or badly.

In the second place, we must find out how consumers act when placed in the institutional context which we attribute to the economy as a whole when discussing general equilibrium. At this stage, we assume that well defined prices, which for the consumers are given, govern exchanges that are otherwise free.

To achieve the second objective, we must start with the representation of needs. So the study of the laws of consumer behaviour is the natural objective of the present chapter.

In short, the purpose of the model to be discussed here is to explain how the vector $x_i$ of the consumption $x_{ih}$ of a particular individual $i$ is determined. For simplicity, the index $i$ is suppressed in this chapter, and we write $x$ rather than $x_i$ for the consumptions vector.

The main elements of the theory will now be stated briefly before it is discussed in detail, to give an indication of the line of development. The idea of the model is very simple: the consumer chooses the best complex $x$ from a set of complexes that are feasible for him \textit{a priori}. Let us define what is meant by a feasible complex and how the preferences of a particular individual are represented.
The consumer is subject to physical constraints and to an economic constraint:

(i) The vector $x$ must belong to a set $X$ which is given \textit{a priori} and may depend on the particular consumer $i$ under consideration. The definition of the set $X$ takes account of the physical limitations on the consumer’s activity. For instance, if the particular individual does not contribute to production, then $X$ may simply be the subset of $\mathbb{R}^l$ consisting of the vectors with no negative component. But $X$ is often defined more strictly to exclude the vectors $x$ that do not ensure the satisfaction of certain elementary needs. Thus the model may involve the idea of a subsistence standard, which may be either biological or based on social conventions. However, it will often be evident that this idea of a subsistence standard is ignored for the sake of simplicity in these lectures.

(ii) In addition, the consumer has a limited ‘income’ $R$ and must act within a market where each commodity $h$ has a well-defined price $p_h$. So the value of $x$ must not exceed $R$:

$$px = \sum_{h=1}^{l} p_h x_h \leq R$$ (1)

For the model in this chapter, $R$ and the $p_h$ are exogenous data.

(iii) The consumer’s preferences among different vectors $x$, which satisfy his needs more or less well, are represented by a real function $S(x_1, x_2, \ldots, x_i)$ called the ‘utility function’ or ‘satisfaction function’, and defined in $X$. The values $S(x^1)$ and $S(x^2)$ of this function corresponding to two different complexes $x^1$ and $x^2$ measure as it were to what extent each of these complexes satisfies the consumer.† Therefore when we say that $S(x^1) > S(x^2)$, we are saying that the consumer prefers $x^1$ to $x^2$. It follows that, from all the feasible complexes, he chooses that one which maximises $S(x)$.

An \textit{equilibrium} for the consumer is therefore a vector $x^0$ which maximises $S$ subject to the double constraint expressed by (1) and the fact that $x$ belongs to $X$.

So the function $S$, the set $X$, the vector $p$ and the number $R$ are taken as exogenous in the theory. On the other hand, the $x_h$ are endogenous quantities, that is, quantities whose determination is explained by the theory.

Obviously the vector $x$ chosen by the consumer depends on $S$, $X$, $p$ and $R$. But generally we are content to make clear the dependence on prices $p_h$ and income $R$, since they are subject to variation with other variables of the general economic environment in which the consumer acts. (In fact, $p$ and $R$ will be treated as endogenous in general equilibrium theory.)

Assuming that the vector $x^0$ maximising $S$ is unique, we shall discuss the

---

† Here and throughout the lectures, superscripts are used for particular vectors such as $x^0$, $y^1$, $y^2$, ... etc.
vector function \( \xi(p, R) \) whose components are the real functions \( \xi_h(p_1, p_2, \ldots, p_h, R) \) that determine the \( x^*_h \) from the \( p_h \) and \( R \). The function \( \xi_h \) will be called the consumer's demand function for commodity \( h \).

In the course of this chapter, we must first make the initial concepts of the model more precise, that is, we must define more clearly and discuss briefly the nature of the two constraints and of the utility function. We must then show that, under certain conditions, the model allows us to determine the equilibrium \( x^0 \), and to determine it uniquely. Finally we must find certain general properties of demand functions, properties which remain true independently of the particular specification of the set \( X \) and the function \( S \).

In considering the initial concepts we shall have to spend more time on the definition of the function \( S \) than on that of the two constraints. So we start by discussing utility.

2. The utility function

A quick survey of the history of economic science will give us a better idea of the sense in which the economist understands the term utility or satisfaction.

The first theories of general equilibrium date from the end of the eighteenth and the beginning of the nineteenth century.† They concentrated almost solely on production; price, value and the distribution of income were explained by costs, and mainly by the amounts of labour involved. Of course, the goods produced had to have utility for the consumer. To their 'exchange value' determined by costs there must correspond a 'use value'. But the appropriate conclusions were not drawn from this observation.

The main contribution of the so-called 'marginalist' school was to show how the conditions under which production responds to consumers' needs could be integrated in an analysis of general equilibrium. The 'theory of marginal utility' was put forward independently and almost simultaneously by three economists: the Englishman Stanley Jevons (1871), the Austrian Carl Menger (1871) and the Frenchman Léon Walras (1874). But there had been a whole current of thought leading up to it.‡

It is fairly natural to say that an individual acquires a good only if its price is less than its use value. Similarly, from the collective point of view, there is no apparent advantage in providing a good for an individual if its cost of production is greater than its utility to him.

But the marginalists emphasised the fact that the utility of a given quantity

† The most typical date is certainly 1817, the year of publication of David Ricardo’s treatise, *The Principles of Political Economy and Taxation*, New edition, C.U.P., Cambridge, 1951.

of a good to be supplied to a consumer depends on the quantity of the same
good already in his possession. The third glass of water or the third overcoat
have less utility than the first. If the consumer acquires goods at fixed prices,
the exchange value must correspond to the marginal utility, that is, to the utility of the last quantity bought.

Jevons, Menger and Walras represented the utility of the commodity \( h \) by
a function \( u_h(x_h) \) of the quantity consumed of the good, this function having
a continuous derivative \( u'_h \), which must be decreasing in most cases and
measures marginal utility, by definition. The utility that the consumer derives
from the whole complex \( x \) is then

\[
S(x) = \sum_{h=1}^{I} u_h(x_h).
\]  

(2)

Let us consider this formulation. We can imagine small variations with
respect to the complex \( x \). Suppose, for example, that there is a positive
increase \( dx_r \) in the consumption of \( r \) and a decrease in the consumption of \( s \)
(a negative \( dx_s \)). The utility of the complex remains unchanged if

\[
dS = u'_r \, dx_r + u'_s \, dx_s = 0,
\]

that is, if

\[
- \frac{dx_r}{dx_s} = \frac{u'_s}{u'_r}.
\]  

(3)

The derivative \( u'_r \) is the marginal utility of the good \( r \). The ratio \( u'_s/u'_r \) is
called the marginal rate of substitution of the good \( s \) with respect to the good \( r \).
It is the additional quantity of \( r \) which will exactly compensate the consumer
for a decrease of one unit of \( s \), assuming this unit to be infinitely small. When
(3) is satisfied, the consumer attributes the same utility to the complex \( x \) and
the complex \( x + dx \), where the vector \( dx \) has all zero components other than
\( dx_r \) and \( dx_s \). We shall see later on in this chapter that, if \( x \) is an equilibrium,
the two equivalent complexes \( x \) and \( x + dx \) must also have the same value,
and so

\[
p_r \, dx_r + p_s \, dx_s = 0,
\]
hence

\[
\frac{p_s}{p_r} = \frac{u'_s}{u'_r};
\]  

(4)

the marginal utilities must be proportional to prices.

According to the definition given by (3), the marginal rate of substitution
of \( s \) with respect to \( r \) depends on the quantities consumed of \( r \) and \( s \); it does
not depend on the quantities \( x_h \) relating to other goods. This soon appears
unrealistic. For example, the quantity of water which compensates for a quantity of wine will generally depend on the quantity of beer which the consumer possesses.

In order to present marginal rates of substitution without this particular property, Edgeworth introduced in 1881 a formula which has been adopted ever since. Utility is some function of the \( l \) arguments \( x_h \), for example \( S(x_1, x_2, \ldots, x_l) \). If this function is differentiable, the marginal rate of substitution of \( s \) with respect to \( r \) can be defined as the ratio

\[
\frac{S'_s}{S'_r}
\]

where \( S'_s \) and \( S'_r \) denote the partial derivatives of \( S \) with respect to \( x_s \) and \( x_r \). Here we have a function of all the \( x_h \).

The theory of utility is essentially logical in nature. It can be applied whatever are the motivations of consumer choices since the economist takes the function \( S \) as given and does not attempt to explain how it is arrived at. But this fact, which will become quite clear after the following section, did not appear so initially. The theory has wrongly been associated with utilitarian or hedonist philosophy according to which every human action is motivated by the search for pleasure or the desire to avoid pain. There have also been attempts to see in it a debatable psychological theory.

In fact, the word 'utility' may lend itself to such an error of interpretation. The term 'satisfaction', or Pareto's term 'ophelimity', does not seem much better in this respect. But this is of little importance if the technical meaning of these expressions in economics is clearly understood.

3. Utility function and preference relation

The utility function \( S(x) \) represents the consumer's preferences. Its essential characteristic from our point of view is that the consumer chooses \( x^1 \) rather than \( x^2 \) if \( S(x^1) > S(x^2) \). We can therefore use the function \( S \) to classify complexes in their order of choice by the consumer.

In particular, we can define an 'indifference surface' corresponding to the complex \( x^0 \) as the subset \( \mathcal{S}_0 \) of \( R_l \) consisting of the vectors \( x \) such that

\[
S(x) = S(x^0).
\]

There are therefore as many indifference surfaces as there are values of the function \( S \). Two complexes \( x^1 \) and \( x^2 \) belong to the same indifference surface if and only if the consumer is indifferent between \( x^1 \) and \( x^2 \).

Obviously indifference surfaces can easily be represented geometrically if \( l = 2 \), the two goods being, for example, 'foodstuffs' and 'other goods'. On such a diagram we can, if necessary, indicate the direction of increase of the function \( S \).

\[\dagger\] A utility function that may be given form (2) is said to be 'strongly separable'.

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\[\dagger\] A utility function that may be given form (2) is said to be 'strongly separable'.
Clearly the ordered system of indifference surfaces can be represented by functions $S$ other than the particular function on which it was based. If $\phi$ is some increasing function

$$S^*(x) = \phi[S(x)]$$

has the same indifference surfaces as $S(x)$, classifies them in the same way, and so provides another analytic representation of the same system of preferences.

Conversely, if $S^*$ and $S$ are two utility functions giving the same indifference surfaces, there exists a function $\phi$ such that (6) is satisfied. (Let $I$ be the interval of the values of $S(x)$; for every $s$ in $I$, we define $\phi(s)$ as the value of $S^*$ on the indifference surface along which $S$ takes the value $s$.) If $S^*$ and $S$ classify the indifference surfaces in the same way, then $\phi$ is increasing.

When we are interested only in the ordered system of indifference surfaces, we say that $S$ is defined up to an increasing function. To recall this indeterminacy, we sometimes describe $S$ as 'relative utility' or 'ordinal utility'. It is then important to verify that the conclusions from our theories do not vary with any change in the definition of utility function.

For the purposes of these lectures, it will be sufficient that ordinal utility exists. The student should verify this himself whenever we use the function $S$. Our theories are based on a given system of preferences rather than on a given function defining use-value in the sense of the nineteenth-century writers.
It might therefore be asked if the introduction of the function $S$ is not superfluous. Since we are interested only in the order of preferences, can we not restrict ourselves to a formal representation of it?

Clearly we can. To see this in detail, let us consider the properties of a system of preferences represented by a utility function. Let $\succeq$ denote the relation defined among the $x$'s of $X$ by

$$x^1 \succeq x^2 \quad \text{if} \quad S(x^1) \geq S(x^2).$$

From this we can derive the following two relations:

$$x^1 > x^2 \quad \text{if} \quad x^1 \succeq x^2 \quad \text{but not} \quad x^2 \succeq x^1,$$

therefore if $S(x^1) > S(x^2)$;

$$x^1 \sim x^2 \quad \text{if} \quad x^1 \succeq x^2 \quad \text{and} \quad x^2 \succeq x^1,$$

therefore if $S(x^1) = S(x^2)$.

We immediately find the following properties of the relation $\succeq$:

A.1 For every pair $x^1, x^2$ of vectors of $X$

- either $x^1 \succeq x^2$ or $x^2 \succeq x^1$ (the ordering is total)

A.2 For every $x$ of $X$

- $x \succeq x$ (reflexivity)

A.3 If $x^1 \succeq x^2$ and $x^2 \succeq x^3$, then

- $x^1 \succeq x^3$ (transitivity).
Utility function and preference relation

Instead of starting with the function $S$, we could have given the relation $\succeq \text{ a priori.}$ It would seem reasonable to demand that this relation satisfy the three properties A.1, A.2 and A.3, which would then be taken as axioms, so that $\succeq$ would then appear as a relation of the category that mathematicians call 'preorderings'.

This is the approach adopted in the most modern presentations of consumer theory. Only the preordering relation is involved; the notion of utility is not necessarily mentioned.

Why then do we use the utility function as the initial formal concept in the representation of preferences? The reasons are the following.

In the first place, the theory based on the utility function leads to results, well known in economics, which cannot be obtained directly from the preordering relation. These results are not indispensable for the most essential part of microeconomics. However, economists should known them; they are helpful in the consideration of the structure and bearing of our theories.

In the second place, reasoning based on the utility function will seem more familiar to students than the most modern presentations. There should be less trouble with mathematical difficulties, so that the student is free to concentrate on the economic assumptions and the main logical developments.

In the third place, taking a utility function is not much more restrictive than starting with the set of axioms A.1, A.2 and A.3. In fact, when the set $X$ satisfies fairly unrestrictive general conditions, we can represent by a continuous utility function every preordering which satisfies the following additional axiom:†

A.4 For any $x^0 \in X$, the set $\{ x \in X / x^0 \succeq x \}$ of all the $x$'s which are not preferred to $x^0$ and the set $\{ x \in X / x \succeq x^0 \}$ of all the $x$'s to which $x^0$ is not preferred are closed in $X$.

The extent to which the generality of a preference relation must be restricted in order to justify the introduction of a continuous utility function will be made clear in an example of a preordering which does not satisfy A.4. Suppose then that $l = 2$, that $X$ is the set of vectors neither of whose two components is negative, and consider the relation defined as follows: given $x^1$ and $x^2$ in $X$, we say that $x^1 \succeq x^2$ if

either $x^1_1 > x^2_1$

$x^1_1 = x^2_1$, and $x^1_2 \geq x^2_2$.

This relation, called the 'lexicographic ordering' does not satisfy A.4. Thus on Figure 3, the set

$\{ x \in X / x \succeq x^0 \}$

† For the proof, see Debreu, Theory of Value, Section 4.6.
The consumer

Fig. 3

is shaded; it does not contain that part of its boundary which lies below \( x^0 \). In fact, it cannot be represented by a continuous real function \( S \).

Such a preference relation has sometimes been considered; it hardly seems likely to arise in economics, since it assumes that, for the consumer, the good 1 is immeasurably more important than the good 2. We lose little in the way of realism if we eliminate this and similar cases which do not satisfy A.4.

Having reached this point, we have a better understanding of the purely logical nature of the 'theory of utility' on which our reasoning will be based. The consumer's system of preferences is given; we do not have to concern ourselves with the motivation of these preferences and we do not exclude \textit{a priori} any individual ethical system. All that matters is that the axioms A.1 to A.4 should hold. They are philosophically and psychologically neutral, and express a certain internal consistency of choices.†

4. The feasible set

We have said enough about the meaning to be attributed to the representation of preferences in consumer theory. Now we must set certain more precise assumptions about the set \( X \) and the function \( S(x) \) so that we can

† The axioms A.1, A.2 and A.3 have sometimes given rise to discussion. Thus, it has been suggested that the choices of an individual are not always transitive. But the counterexamples given usually depend on an incomplete analysis of the situations among which lack of transitivity is supposed to occur. They seem to have no genuine effect on the force of the axioms, provided that we assume that an individual's system of preferences vary with age, education and other characteristics.
prove certain results about the existence of equilibrium or the properties of demand functions.

In accordance with the principles stated at the end of the first chapter, we shall here present and discuss assumptions which are not all really necessary for the validity of the following results, but which will be brought into the proofs as sufficient conditions.

To establish the required properties I shall most frequently use the following assumption about the set $X$ of the vectors $x$ representing the feasible consumption complexes.

**Assumption 1.** The set $X$ is convex, closed and bounded below. It contains the null vector. If it contains a vector $x^1$, it also contains every vector $x^2$ such that

$$x^2_h \geq x^1_h \quad \text{for} \quad h = 1, 2, \ldots, l.$$

On Figure 4, which relates to the case of two goods, the shaded part represents a set $X$ which satisfies assumption 1 (obviously the set can be prolonged indefinitely both upwards and to the right). The first commodity can only be consumed, but on the other hand, the consumer may supply certain quantities of the second commodity, which must therefore be considered to represent labour.

Let us examine the clauses of assumption 1 in turn.

A set is said to be convex if it contains every vector of the segment $(x^1, x^2)$ whenever it contains $x^1$ and $x^2$. This condition, which has often been assumed implicitly in economic theory, does not seem notably to restrict the significance of the results. However, in order that everything should be quite clear, we shall state two cases in which it is not satisfied.
Some goods can be consumed only in integral quantities. If, for example, this is the case for the good 1 when \( l = 2 \), the set \( X \) reduces to a certain number of vertical half-lines; it is not convex (see Figure 5, where the vector \( x^3 \) does not belong to \( X \) although it lies on the segment joining the two feasible vectors \( x^1 \) and \( x^2 \)). This particular situation is obviously not serious if we have to consider quantities \( x_1 \) of the first good which consist of an appreciable number of units; substitution of a convex set for \( X \) is then an approximation of the kind permissible in all fields of science. Significant indivisibilities will, however, be ruled out in this chapter and in most parts of our lectures; they are indeed ruled out in most of microeconomic theory.

It was pointed out earlier that goods might be distinguished by their location. Suppose that \( l = 2 \), and that the goods 1 and 2 represent consumption at Paris and at Lyon respectively. In some applications it will be natural to assume that an individual can consume either at Paris or at Lyon, but not at both simultaneously. The set \( X \) then consists of two parts: it is not convex (cf. Figure 6).

To assume that \( X \) is closed is to assume that, if each of the vectors \( x^t \) of a convergent sequence of vectors \( (t = 1, 2, \ldots) \) defines a feasible consumption complex, then the limit vector \( \bar{x} \) of \( x^t \) also defines a feasible complex. There is no difficulty in accepting this clause.

The fact that \( X \) is bounded below means that there exists a vector \( x \) such that \( x_h \geq \bar{x}_h \) for \( h = 1, 2, \ldots, l \) and for every \( x \) of \( X \). This condition is not restrictive since it is satisfied if the quantities of work supplied by the consumer are bounded above and if the consumption of other commodities cannot be negative.

It seems less satisfying to assume that an individual may have zero con-
sumption of all goods, since this ignores the existence of a biological or sociological subsistence minimum, which the economist should recognise. However, the assumption that the null vector belongs to $X$ simplifies the proofs, and this seems sufficient justification here. Note that, because of this clause, the $x_h$ are all negative or zero.

Finally, the last part of assumption 1 means that it is always open to the consumer to accept a supplement of goods even if he does not have to do anything with them. We say that there is free disposal of surplus, and shall meet this assumption again in considering the producer. By itself, it eliminates the above two cases of non-convexity, but only postpones the difficulty till later, when assumption 4 on the utility function is formulated.

![Fig. 6](image)

Apart from the physical constraint expressed by the condition that $x$ belongs to $X$, the consumer is bound by the economic constraint

$$px \leq R \tag{7}$$

where the $p_h$ and $R$ are exogenous data imposed on him.

To assume that price $p_h$ is exogenous is equivalent to assuming that it is not influenced by the more or less large extent of the consumer's demand for the good $h$ or for other goods. This assumption seems admissible in the circumstances. We shall return to it for fuller discussion in relation to the theory of the firm. It is in fact one of the basic elements in the definition of perfect competition.

In accordance with practice, we shall speak of $R$ as the consumer's 'income'. However, when the labour he supplies is considered as negative consumption, $R$ represents resources other than those earned by this labour. Moreover, if the model explicitly involves several periods, $R$ must be interpreted as the total wealth available to the consumer for his consumption during all the periods; the term 'income' is then particularly unsuitable. Throughout the lectures, you must therefore be ready at any time to substitute the term 'wealth' to designate $R$ for that of 'income'.
We shall assume that the consumer is subject to a single economic constraint. This assumption may seem unrealistic in certain contexts. For example, if we consider the choice of a consumption programme relating to several periods $t = 1, 2, \ldots, T$, to restrict ourselves to the constraint (7) means that we suppose that the consumer is free to borrow to cover a temporary deficit and is only required to balance out his operations over all $T$ periods. Substituting the double index $(q, t)$ for $h$, the restraint (7) becomes

$$
\sum_{t=1}^{T} \sum_{q=1}^{Q} p_{q} x_{qt} \leq R.
$$

On the other hand, a consumer who can lend, but who can never be a debtor must obey $T$ budget constraints

$$
\sum_{t=1}^{T} \sum_{q=1}^{Q} (p_{q} x_{qt} - R_{r}) \leq 0 \quad t = 1, 2, \ldots, T
$$

where $R_{r}$ represents that part of his total resources which is available to him in the $r$th period.

Let us note moreover that the economic constraint (7) imposes no upper bound on the quantity of commodity $h$ that the consumer can buy on the market, as long as he is ready to pay the price $p_{h}$. This excludes any kind of rationing of individual demands.

5. Assumptions about the utility function

We now state three assumptions relating to the function $S(x)$.

**Assumption 2.** The function $S$ defined on $X$ is continuous and increasing, in the sense that

$$
x_{h}^{1} > x_{h}^{2} \quad \text{for} \quad h = 1, 2, \ldots, l \quad \text{implies that} \quad S(x^{1}) > S(x^{2}).
$$

The continuity of $S$ follows from what was said in Section 4, and in particular from axiom A.4, which we have already discussed. Assumption 2 also supposes that no good is harmful to the consumer. (It must be remembered here that labour is counted negatively so that, for a good $h$ which corresponds to labour, $x_{h}^{1} > x_{h}^{2}$ means that the consumer's contribution is smaller in $x^{1}$ than in $x^{2}$.) The assumption also eliminates the possibility of a state of complete saturation beyond which satisfaction cannot be increased.

**Assumption 3.** The function $S$ is twice differentiable. Its first derivatives are never all simultaneously zero.

This assumption is introduced particularly for reasons of mathematical convenience. We use it when we wish to reveal certain marginal equalities and when we employ the analytic calculus in our reasoning. The most modern theoreticians are reluctant to make it and abstain from its use as much as
Assumptions about the utility function

possible when proving general results. But research on specific problems or on difficult developments of the theory often makes it.

In the present context, it does not seem very restrictive given that \( S(x) \) is assumed to be continuous. However, it is not satisfied in the following example relating to two goods:

\[
S(x) = \min \left\{ \frac{x_1}{a_1}, \frac{x_2}{a_2} \right\},
\]

where \( a_1 \) and \( a_2 \) are two given positive constants. This function, two of whose indifference curves are represented in Figure 7, is not first order differentiable at any point \( x^0 \) such that

\[
\frac{x_1^0}{a_1} = \frac{x_2^0}{a_2}.
\]

In fact, the variation in \( S \) around such a point is described by

\[
dS = \begin{cases} 
\frac{dx_1}{a_1} & \text{if } \frac{dx_1}{a_1} \leq \frac{dx_2}{a_2} \\
\frac{dx_2}{a_2} & \text{if } \frac{dx_1}{a_1} \geq \frac{dx_2}{a_2}
\end{cases}
\]

Therefore the variation \( dS \) is not linear in \( dx_1 \) and \( dx_2 \), as is required for differentiability.

Such a function may be appropriate to the case of strict complementarity between two goods (for example, oil and vinegar for a consumer who cannot tolerate cooking in oil, but enjoys a vinaigrette dressing of fixed composition). Cases of this kind will be eliminated when we proceed to differential calculus.

The assumption that the derivatives of the differentiable function \( S \) are not all simultaneously zero will be useful on occasion later. It does not seem to restrict the nature of the system of preferences. For example, it eliminates a
function $S^*$ defined by the transformation $S^* = \phi(S)$ applied to an $S$ satisfying assumption 3, the function $\phi$ being increasing but having a zero derivative for a particular value of $S$.

**Assumption 4.** The function $S$ is 'strictly quasi-concave'† in the sense that if $S(x^2) \geq S(x^1)$ for two different complexes $x^1$ and $x^2$, then

$$S(x) > S(x^1)$$

for every complex $x$ of the open interval $(x^1, x^2)$, that is, for every complex $x$ defined by

$$x_h = \alpha x^1_h + (1 - \alpha)x^2_h \quad h = 1, 2, \ldots, l$$  \(9\)

where $\alpha$ is a positive number less than 1.

Note that $S(x)$ is defined for the vector $x$ with coordinates (9) if $X$ is convex in accordance with assumption 1. A weaker version of assumption 4 is sometimes used. The function $S$ is said to be 'quasi-concave' if $S(x) \geq S(x^1)$ with the same conditions for the definition of $x^1$, $x^2$ and $x$. Note also that if $S$ is strictly quasi-concave (or simply quasi-concave) then so also is $S^* = \phi(S)$ whenever $\phi$ is increasing.

Assumption 4 means that the indifference surfaces are concave upwards (see Figure 8). It is often considered as admissible owing to the fact that a complex $x$ of the segment $(x^1, x^2)$ has a composition which is intermediary to those of $x^1$ and $x^2$, and therefore is better balanced than either. It may fall down for example in certain choices relating to the consumer's chosen way of life. An individual may be indifferent as between two complexes, one ensuring a comfortable life dedicated to the arts and the other an adventurous sporting life. But he may prefer one or other of these to an intermediary third complex which does not allow full enjoyment of either way of life. Also, one may verify that the previous examples relating to the non-convexity of $X$ become examples of the non-quasi-concavity of $S$ if there is free disposal of surplus (cf. Figures 5 and 6).

6. The existence of equilibrium and demand functions

We shall now prove that, under certain conditions, an equilibrium exists, so that our theory provides a consistent explanation of consumer behaviour. This will illustrate how to carry out a rigorous proof of a question of economic theory.

**Proposition 1.** If assumptions 1 and 2 are satisfied, if $p_h > 0$ for $h = 1, 2, \ldots, l$ and if $R \geq 0$, then there exists a vector $x^0$ which maximises $S$ in $X$

† The definition of quasi-concave functions introduced here may be compared with the definition of concave functions in Section 1 of the Appendix.
subject to the constraint (1). This vector $x^0$ is such that $px^0 = R$. If, moreover, assumption 4 is satisfied, then $x^0$ is unique and the demand function $\xi(p, R)$ defining $x^0$ is continuous for every vector $p$ all of whose components are positive, and for every positive number $R$.

Consider the set $P$ of physically and economically feasible vectors $x$. This set can be defined as the intersection of $X$ and the set $P^*$ of vectors satisfying

$$\begin{cases} x_h \geq x_n & \text{for } h = 1, 2, \ldots, l \\ px \leq R \end{cases}$$

(For example, in Figure 9, $P$ is the shaded set, $P^*$ the right-angled triangle containing $P$ and with apex $(0, x_2)$.) The set $X$ is closed in view of assumption 1. The set $P^*$ is closed and bounded; for,

$$x_h \leq x_n \leq \frac{R - px}{p_h}.$$  

(The second of these inequalities stems from the fact that, in view of (10) and the sign of the $p_k$, $p_h x_h \leq R - \sum_{k \neq h} p_k x_k$, $- p_k x_k \leq - p_h x_h$, and $0 \leq - p_h x_h$; therefore $p_h x_h \leq R - px$.)

Thus $P$ is closed and bounded, that is, it is compact. $P$ is not empty since it contains the null vector, which belongs to $X$ in view of assumption 1 and satisfies the budget constraint (1) whenever $R$ is not negative. $S$ is continuous, in view of assumption 2; now, we know that every continuous function in a non-empty compact set has a maximum.† This is the vector $x^0$ whose existence we were trying to prove.

We must now show that $px^0 = R$. Suppose $px^0 < R$. There then exists a vector $x^1$ all of whose components are greater than the components of $x^0$, and is such that $px^1 \leq R$. In view of assumption 1, $x^1$ is in $X$ and therefore in $P$; in view of assumption 2, it is preferable to $x^0$. Therefore $x^0$ is not the maximum of $S$ in $P$, which is impossible.

Consider now the case where assumption 4 is satisfied. Suppose that there exists a vector $x^1$ different from $x^0$ which also maximises $S$ in $P$. Obviously $S(x^0) = S(x^1)$, but every vector of the segment $(x^0, x^1)$ then belongs to the convex set $P$ and gives a value of $S$ greater than $S(x^0)$, which is impossible. Therefore the vector $x^0$ is determined uniquely.

Finally, we must show that $\xi(p, R) = x^0$ depends on $p$ and $R$ continuously.‡ Suppose that this is not the case. Then there exists a sequence of vectors $p^t$...
and a sequence of numbers \( R^t \) tending to \( p \) and \( R \) respectively (for \( t = 1, 2, \ldots \)) but such that

\[
x^t = \xi(p^t, R^t)
\]
does not tend to \( x^0 \). If necessary, after elimination of some of their elements, these sequences can be chosen in such a way that the distance between \( x^t \) and \( x^0 \) remains greater than a suitably chosen positive number \( \varepsilon \).

Consider the vector \( z^t \) which is nearest \( x^0 \) in Euclidean distance, in the set \( P^t \) of vectors \( z \) belonging to \( X^* \) and satisfying \( p^t z \leq R^t \) (see Figure 10). Since \( P^t \) is a compact, non-null set and the distance between \( x^0 \) and \( z \) is a continuous function of \( z \), such a vector \( z^t \) does in fact exist. From the definition of \( x^t \),

\[
S(x^t) \geq S(z^t)
\]
and, in view of the above result,

\[
p^t x^t = R^t. \tag{13}
\]

By similar reasoning to that used to establish the inequalities (11) it can be established that, for all sufficiently large \( t \), the fact that \( x \) belongs to \( P^t \) implies

\[
x_h \leq x_h \leq \frac{R^t - p^t x}{p^t_h} \leq \frac{R + 1 - 2p x}{\frac{1}{2} p_h}.
\]

The outside inequalities show that the double sequence consisting of the \( x^t \) and the \( z^t \) belongs to a compact set (independent of \( t \)). It has a limit point which we can denote \( x^* \), \( z^* \).

Because of the choice of the \( p^t \) and the \( R^t \), the vector \( x^* \) differs from \( x^0 \), since the distance between \( x^* \) and \( x^0 \) is at least \( \varepsilon \). The vector \( x^* \) belongs to \( X \) and satisfies the equality \( px^* = R \) because of (13). Therefore

\[
S(x^0) > S(x^*) \tag{14}
\]
since $x^0$ is the unique maximum of $S$ in $P$. The inequality (12) implies

$$S(x^*) \geq S(z^*).$$

But $z^*$ necessarily coincides with $x^0$, otherwise there exists a sphere around $x^0$ which does not intersect the sets $\{p'x \leq R\} \cap X$ for an infinite sequence of values of $t$. There then exists a number $\theta$ smaller than 1 such that $\theta x^0$ is in this sphere. Since it is in $X$, then $p'\theta x^0 > R$ for the same sequence of values of $t$, and therefore also $\theta px^0 \geq R = px^0$. Since this is impossible with $\theta < 1$ and $R > 0$, $z^*$ must coincide with $x^0$. Inequalities (14) and (15) are therefore contradictory: this completes the proof of proposition 1.

Proposition 1 shows that, if assumptions 1, 2 and 4 are satisfied, the demand functions $\xi_h(p_1, p_2, \ldots, p_i; R)$ defining the components of $x^0$ are themselves continuous and well-defined for all values of the $p_h$ and of $R$ such that

$$p_h > 0 \quad \text{for} \quad h = 1, 2, \ldots, l$$

$$R > 0.$$

It would have been preferable to be able to state that the $\xi_h$ are defined and also continuous when some of the $p_h$ are zero. But this requires more complex assumptions. If some of the $p_h$ are zero, the set $P^*$ and therefore also $P$ are not bounded above. In this case, some of the $\xi_h$ may tend to infinity as some of the $p_h$ tend to zero. We shall ignore this case in what follows and shall on occasion discuss situations where some prices are zero, while the demands remain finite.

7. Marginal properties of equilibrium

Assuming now that the utility function is differentiable (assumption 3) we shall establish certain classical relations between prices and marginal rates of substitution relating to a consumer equilibrium $x^0$. To do this, we shall consider the case where $x^0$ lies within $X$. We shall then discuss necessary modifications to the relations if the equilibrium point lies on the boundary of the set of feasible consumptions.

If assumptions 1 and 2 are satisfied and if $x^0$ lies within $X$, then this vector is a local maximum of $S(x)$ subject to the 'budget constraint' $px = R$. If, moreover, $S(x)$ is differentiable, the classical maximisation conditions must necessarily be realised (see theorems VI and VII in the appendix, relating to the extrema of functions of several variables).

In view of the first order conditions (theorem VI), there exists a number $\lambda$ (a Lagrange multiplier) such that the first derivatives of

$$S(x) - \lambda(px - R)$$

(16)
with respect to the $x_h$ are all zero at $x^0$, that is, such that
\[
S'_h - \lambda p_h = 0 \quad \text{for} \quad h = 1, 2, \ldots, l.
\] (17)

These equalities imply that the marginal rate of substitution of any good $s$ with respect to any good $r$ is equal to the ratio between the price of $r$ and the price of $s$:
\[
\frac{S'_s}{S'_r} = \frac{p_s}{p_r}
\] (here $S'_r$ and $p_r$ are assumed to differ from zero).

We note here that the marginal rates of substitution are invariant with respect to any change in the specification of the function $S$ representing a given system of preferences. If $S^* = \phi(S)$ is substituted for $S$, then $S'^* = \phi' \cdot S'_r$; ratios such as (18) are unaffected and the Lagrange multiplier $\lambda$ is multiplied by the value of $\phi'$ for $S(x^0)$.

We can interpret (17) as implying that, in the space $R^l$, the vector $p$, normal to the budget constraint, is collinear with the normal at $x^0$ of the indifference surface containing this point. It is equivalent to say that this indifference surface is tangential to the plane representing the budget constraint (see Figure 9 where this property is clearly shown for the case of two goods).

The second order conditions (theorem VII) relate to the matrix of the second-order derivatives of the 'Lagrangian' expression (16). The derivatives with respect to the $x_h$ are here equal to those of $S(x)$. Let $S''_{hk}$ be the value at $x^0$ of the second derivative of $S$ with respect to $x_h$ and $x_k$. The second order conditions imply that the quadratic form $\sum_{hk} \mu_h S''_{hk} u_k$ is negative or zero for every vector $u$ such that $\sum_{h} p_h u_h = 0$, that is, for every vector $u$ normal to $p$. (Obviously this property expresses the fact that, in the budget plane, the variations of $S$ in the neighbourhood of $x^0$ which are zero at the first order, are negative or zero at the second order.)

It is clearly restrictive to assume that $x^0$ lies within $X$ since this requires that the individual chooses to consume positive amounts of all those goods which he cannot himself supply. If $x^0$ lies on the boundary of $X$, some of the constraints to which he is subject must be expressed by inequalities rather than by equalities. The necessary conditions for maximisation must then be found in the Kuhn-Tucker theorem (theorem XI in the Appendix) rather than in the classical results used here.

To avoid too much complication, we shall now consider the case where the set $X$ is the positive orthant, that is, it imposes the condition that none of the components of $x$ is negative. Given assumption 1, this case assumes that the individual considered cannot supply any good. It is easy to think of less particular cases which can be treated in the same way as this one.
In this case $x^0$ is a maximum of $S(x)$ subject to the $l + 1$ constraints expressed by
\[
R - px \geq 0 \\
x_h \geq 0 \quad \text{for} \quad h = 1, 2, \ldots, l.
\]
For the application of theorem XI we then find ourselves in the particular case discussed in p. 312 of the Appendix. There necessarily exists a non-negative Lagrange multiplier $\lambda$ such that the derivatives with respect to the $x_h$ of
\[
S(x) + \lambda(R - px)
\]
are all non-positive at $x^0$, and also are zero for the $h$'s corresponding to positive components $x_h^0$ of $x^0$.

We can then divide the $l$ goods into two categories:
(i) the $h$ goods whose consumption is positive in the equilibrium ($x_h^0 > 0$),
(ii) the $k$ goods for which consumption is zero ($x_k^0 = 0$), the condition then becoming
\[
S'_h - \lambda p_h = 0, \quad (20)
\]
\[
S'_k - \lambda p_k \leq 0. \quad (21)
\]

Consider first a pair of goods $r$ and $s$ which are both consumed in the equilibrium. Since equalities (17) are satisfied for these two goods, the marginal rate of substitution of $s$ with respect to $r$ is the ratio of $p_s$ and $p_r$.

The relation previously obtained remains unchanged.

Consider now a pair $(h, k)$, where $h$ represents a good consumed and $k$ a good which is not consumed. Relations (20) and (21) imply
\[
\frac{S'_k}{S'_h} \leq \frac{p_k}{p_h}. \quad (22)
\]

The marginal rate of substitution of $k$ with respect to $h$ is less than or at most equal to the relative price of $k$ with respect to $h$ (the price of $k$ is too high for the consumer to wish to consume it). Figure 11 illustrates a case of this type, where the good 2 is not consumed at $x^0$. The modification to the marginal equality appears very natural.

8. The case where the marginal equalities are sufficient to determine equilibrium

The budget constraint and the marginal equalities (17) define the following system of $l + 1$ equations:
\[
\begin{cases}
\frac{\partial}{\partial x_h} S(x_1, x_2, \ldots, x_l) - \lambda p_h = 0, \quad h = 1, 2, \ldots, l \\
\sum_k p_k x_k = R
\end{cases}
\]

\[ (23) \]
We can consider this system as allowing us to find the \( l + 1 \) unknowns which are \textit{a priori} the \( l \) quantities \( x_h \) and the Lagrange multiplier \( \lambda \). The system has a solution if the equilibrium \( x^0 \) lies within \( X \).

Conversely, is every solution of this system an equilibrium point for the consumer? Is it sufficient that a vector \( x^0 \) satisfy the marginal equalities and the budget constraint for it to be an equilibrium point? When discussing the theory of the optimum we shall need to know in which cases the answer to this question is in the affirmative. This motivates the following proposition:

\textbf{PROPOSITION 2.} If assumptions 1 to 4 are satisfied, and if no price \( p_h \) is negative, then a vector \( x^0 \) which lies in the interior of \( X \) and satisfies system (23) for an appropriate value of \( \lambda \) is an equilibrium point for the consumer.

To prove this proposition,† we must establish that \( px^1 > R \) for every \( x^1 \) of \( X \) such that

\[
S(x^1) > S(x^0).
\]

Before considering such an \( x^1 \), we shall show that \( px \geq R \) for every \( x \) such that \( S(x) = S(x^0) \). If \( dt \) is a positive infinitesimal, the quasi-concavity of \( S \) (assumption 4) implies

\[
S[dx + (1 - dt)x^0] > S(x^0),
\]

or

\[
\frac{S[x^0 + (x - x^0) dt] - S(x^0)}{dt} > 0.
\]

In the limit, when \( dt \) tends to zero, the following inequality must apply:

\[
\sum_{h=1}^{l} S_h(x^0) \cdot (x_h - x_h^0) \geq 0.
\]

In system (23) \( \lambda \) is positive since the \( p_h \) are non-negative, the fact that \( S \) is

† The proof is rather long. The reader may go straight on to Section 9 if he so wishes.
increasing (assumption 2) implies that none of its first derivatives is negative and assumption 3 excludes the case where all these derivatives are zero. The marginal equalities (23) and inequality (25) then imply \( p(x - x^0) \geq 0 \), and so \( px \geq px^0 = R \).

Consider now a vector \( x^1 \) of \( X \) such that \( S(x^1) > S(x^0) \). Then the quasi-concavity of \( S \) implies that \( S(x) > S(x^0) \) for every vector \( x \) of the open interval \((x^0, x^1)\). Since \( x^0 \) lies within \( X \) there exists, centred on \( x^0 \), a cube with side \( 2\varepsilon \) entirely contained in \( X \). Consider then a vector \( x^* \) of the interval \((x^0, x^1)\) and such that

\[
|x_h^0 - x_h^*| < \frac{\varepsilon}{2} \quad h = 1, 2, \ldots, l.
\]

Let us also define the vector \( \hat{x} \) as

\[
\hat{x}_h = \frac{x_h^0 + x_h^*}{2} - \frac{\varepsilon}{2} \quad h = 1, 2, \ldots, l.
\]

We see immediately that \( \hat{x} \) is in the cube and therefore in \( X \), and moreover that \( \hat{x}_h < x_h^0 \) and \( \hat{x}_h < x_h^* \) for all \( h \).

![Fig. 12](image_url)

Let us now prove the inequality \( px^* > R \). We know that

\[
S(x^*) > S(x^0)
\]

and that \( S(\hat{x}) < S(x^0) \). So in the interval \((\hat{x}, x^*)\) there exists a vector \( \tilde{x} \) such that \( S(\tilde{x}) = S(x^0) \). In view of what we established at the beginning of this proof, \( p\tilde{x} \geq R \), which implies \( px^* > R \) since \( \hat{x}_h < x_h^* \) for all \( h \).

Since \( px^* > px^0 \) and since \( x^* \) is contained in the interval \((x^0, x^1)\), it necessarily follows that \( px^1 > px^0 = R \), which is the required result.†

† It is clear from this proof that, without bringing in the assumption that \( x^0 \) lies in the interior of \( X \), we found that \( x^0 \) minimises \( px \) in the set of \( x \)'s such that \( S(x) > S(x^0) \). But if we wish to establish that \( x^0 \) also maximises \( S(x) \) in the set of \( x \)'s such that \( px < px^0 \) we must introduce the condition that \( x^0 \) lie in the interior of \( X \), or other less restrictive conditions which need not be mentioned here.
9. The study of demand functions

Up till now we have been concerned with how to characterise and determine consumer equilibrium. But we have spent little time on the demand functions $\xi_h(p, R)$, that is, the functions which define how the equilibrium varies with the exogenous variables $p$ and $R$. We must now investigate this question.

We start with an initial property which is easily established.

**Property 1.** The demand functions are homogeneous of degree zero with respect to prices $p_h$ and income $R$.

For, suppose that all the $p_h$ and $R$ are simultaneously multiplied by the same positive number $a$. Neither the function to be maximised nor the domain defined by the constraints will be changed since $p$ and $R$ occur only in the homogeneous linear inequality $px \geq R$. The equilibrium is therefore unchanged.

Property 1 shows that the choice of the 'numéraire' does not affect demand functions. If it did not hold, we could not maintain the statement in the first lecture that prices are defined only up to a multiplicative positive constant.

It is sometimes said that property 1 establishes the absence of money illusion. In fact, it would not hold if a change in the monetary unit used as numéraire affected consumer behaviour in respect of the demand for goods.

In order to reveal two less immediate properties of demand functions, we shall now carry out a local study of the $\xi_h(p, R)$, assuming that $S$ is increasing and twice differentiable (assumptions 2 and 3). We shall moreover introduce an assumption that will make $\xi_h(p, R)$ not only continuous but also differentiable.

Suppose therefore that the $p_h$ and $R$ vary by infinitely small quantities $dp_h$ and $dR$; let us find conditions relating to the quantities $dx_h$ by which the components $x_h$ of $x^0$ then vary. We confine ourselves here to the case where $x^0$ is a point in the interior of $X$ and so necessarily satisfies (23). In short, we shall investigate how the solution of system (23) varies when $p$ and $R$ vary by $dp$ and $dR$.

Differentiating (23), we obtain

$$
\begin{align*}
\sum_k S''_{kh} \, dx_k - d\lambda p_h - \lambda \, dp_h &= 0 \quad h = 1, 2, \ldots, l \\
\sum_h p_h \, dx_h + \sum_h dp_h x_h &= dR,
\end{align*}
$$

where $S''_{kh}$ denotes the value at $x^0$ of the second derivative of $S$ with respect to $x_h$ and $x_k$. We can also use the matrix form

$$
\begin{bmatrix}
S'' & -\text{grad } S \\
-\text{grad } S' & 0
\end{bmatrix}
\begin{bmatrix}
dx \\
d\lambda
\end{bmatrix}
= 
\begin{bmatrix}
I & 0 \\
0 & \lambda
\end{bmatrix}
\begin{bmatrix}
dp \\
dR
\end{bmatrix}
$$

(26)
where $S''$ is the matrix of the second derivatives of $S$, $\text{grad } S$ the column vector of its first derivatives, while $(- \text{grad } S)'$ and $x'$ represent the transposes of the column vectors $p$ and $- \text{grad } S$. This system will determine $dx$ and $d\lambda$ if and only if the matrix on the extreme left is non singular, a property that we shall assume to hold. This is the condition for $\xi(p, R)$ to be differentiable. (The property is maintained if $S$ is replaced by another function $S^*$ deduced from $S$ by a transformation $\phi$ having a positive derivative.) It is equivalent to assuming that the contour hypersurfaces of $S(x)$ have non-zero curvature.†

Let

$$
\begin{bmatrix}
U & -v \\
-v' & w
\end{bmatrix} = \lambda
\begin{bmatrix}
S'' & -\text{grad } S' \\
(- \text{grad } S)' & 0
\end{bmatrix}^{-1}.
$$

(27)

System (26) then implies:

$$
dx = U \, dp + v(dR - x' \, dp).
$$

(28)

(As an exercise, the reader may verify that $U$ and $v$ are invariant when $S$ is replaced by another function $S^*$ deduced from $S$ by a transformation having a positive derivative.)

Formula (28) expresses $dx$ as the sum of two terms, the first involving $dp$, the second $dR - x' \, dp$. The latter quantity is the amount by which the increase in income exceeds the increase in the cost of acquiring $x^0$. For this reason it is called the compensated variation in income (the subtraction of $x' \, dp$ ‘compensates’ for the variation in the cost of $x$). We shall denote $dR - x' \, dp$ by $dp$ in what follows.

We note that $dp = 0$ is equivalent to $\sum_h p_h \, dx_h = 0$ since $R - px = 0$; it therefore follows from (23) that $dp = 0$ is equivalent to

$$
dS = \sum_h S'_h \, dx_h = 0.
$$

The variation in utility is zero at the same time as the compensated income change.

We can write

$$
dx = U \, dp + v \, dp.
$$

(29)

The first term is called the substitution effect, the second the income effect.

This equation will be more clearly understood if it is interpreted in the simple case where there exist only two goods and where only the price of the first varies

$$(dp_1 < 0, dp_2 = 0, dR = 0).$$

† On this property see G. Debreu, 'Smooth Preferences', *Econometrica*, July 1972.
Consider a graph of \((x_1, x_2)\) with the line \(AB\) representing the initial budget equation \(px = R\): let \(N\) be the point representing the initial equilibrium; let \(AC\) be the line representing the new budget equation, and \(T\) the new equilibrium. We can draw the line \(DE\) parallel to \(AC\) but tangent (at \(P\)) to the indifference curve passing through the initial equilibrium. The displacement of \(N\) to \(T\) can be split up as follows:

(i) the displacement of \(N\) to \(P\): the 'substitution effect' of good 1 for good 2 following the price variation which makes 2 relatively dearer than 1 (by definition, this effect is measured along the indifference curve passing through \(N\));

(ii) the displacement of \(P\) to \(T\): the 'income effect' which follows from the fact that the decrease in \(p_1\) increases the consumer's purchasing power \((d\rho > 0)\).

Since, from (28), \(v_1 = \frac{\partial x_1}{\partial R}\), we can in this case write formula (29) as follows:

\[
\frac{\partial x_1}{\partial p_1} = \left(\frac{\partial x_1}{\partial p_1}\right)_{s=ct} - x_1 \left(\frac{\partial x_1}{\partial R}\right)
\]

where \(\left(\frac{\partial x_1}{\partial p_1}\right)_{s=ct}\) conventionally denotes the value of the ratio \(\frac{dx_1}{dp_1}\) when \(dp_2 = 0\) and \(d\rho = 0\) (and therefore \(dR = x_1 dp_1\)); from (29), this value is equal to \(U_{11}\).

Since \(S''\) is a symmetric matrix, it follows that \(U\) also is symmetric. We can therefore write

\[
U_{hk} = U_{kh}
\]

or, using the conventional notation defined above,

\[
\left(\frac{\partial x_h}{\partial p_k}\right)_{s=ct} = \left(\frac{\partial x_k}{\partial p_h}\right)_{s=ct}
\]
The study of demand functions

We can state this result as follows:

PROPERTY 2. The demand functions are such that the two 'Slutsky coefficients' characterising the substitution effects respectively of \( h \) for \( k \) and of \( k \) for \( h \) are equal.

This property is expressed in terms of the ordinary partial derivatives, which alone are directly observable, as follows:

\[
\frac{\partial x_h}{\partial p_k} + x_h \frac{\partial x_k}{\partial R} = \frac{\partial x_k}{\partial p_k} + x_h \frac{\partial x_h}{\partial R}.
\] (31)

This is the form in which the Slutsky equation is generally written. (E. Slutsky, a Russian economic statistician, published his results in 1915.)

Other interesting properties follow from the way in which equation (28) was derived. First we know that matrix (27) is the inverse of the left hand matrix of system (26). This implies:

\[
p'U = 0
\] (32)

\[
p'v = 1,
\] (33)

equations which may be written as:

\[
\sum_{k=1}^{I} p_k \left( \frac{\partial x_h}{\partial p_k} \right)_{S=c_1} = 0 \quad \text{for } k = 1, 2, ..., (34)
\]

\[
\sum_{k=1}^{I} p_k \left( \frac{\partial x_h}{\partial R} \right) = 1. \quad \text{(35)}
\]

This last equation expresses a simple fact: when all prices remain unchanged, the value of the change of consumption must be equal to the change of income. A similar, although a bit more complex, interpretation may be given of equation (34).

The second order conditions for an equilibrium also imply that the matrix \( U \), or equivalently the matrix of the Slutsky substitution coefficients is semi-definite negative. Indeed, let us write as \( Z^{-1} \) the matrix (27). The second order conditions state that \( a'S'a \leq 0 \) for any vector \( a \) such that \( p'a = 0 \). We may also write this as:

\[
[a' b]Z \begin{bmatrix} a' \\ b \end{bmatrix} \leq 0
\]

for all vectors \([a' b]\) such that \((\text{grad } S)'a = \lambda p'a = 0\); or again

\[
[x' \beta]Z^{-1} \begin{bmatrix} x' \\ \beta \end{bmatrix} \leq 0
\] (36)

for any vector \([x' \beta]\) that may be written as \([a' b]Z\) with a vector \([a' b]\) such that \(p'a = 0\). The correspondence between \([x' \beta]\) and \([a' b]\) implies \(a' = \ldots \)
\( \alpha' U - \beta v' \). Hence \( p'a = 0 \) corresponds to \( p'Ux - p'\beta = 0 \), which in view of (32) and (33) boils down to \( \beta = 0 \). Inequality (36) must therefore hold with \( \beta = 0 \) for any \( \alpha \). It is then simply:

\[
\alpha' Ux \leq 0.
\]

The matrix \( U \) is semi-definite negative, as was to be proved.

In particular its \( h \)th diagonal element must be non positive:

\[
\left( \frac{\partial x_h}{\partial p_h} \right)_{S = C_t} \leq 0. \tag{37}
\]

We can state equivalently:

**Property 3.** The demand for a commodity cannot increase as its price increases when all other prices remain constant and income is raised just enough to compensate for the price increase.

Of course, the expression on the left hand side of (37) is not observable. We shall more commonly be interested in

\[
\frac{\partial x_h}{\partial p_h} = \left( \frac{\partial x_h}{\partial p_h} \right)_{S = C_t} - x_h \left( \frac{\partial x_h}{\partial R} \right).
\]

The additional term is negative when \( \frac{\partial x_h}{\partial R} > 0 \) and \( x_h > 0 \). The decrease in demand as a function of price is therefore a fairly general law which can fail to hold for a positively consumed good only if a rise in income brings about a lower consumption. However, this latter possibility may arise in the case of so-called inferior goods. For the contributions made by the consumer (labour) the substitution and income effects are generally of opposite signs. Demand may therefore increase (and supply decrease) when price (i.e. wage) rises.

Finally, because of property 2, the following definitions are unambiguous:

Two goods \( h \) and \( k \) are said to be **substitutes** in the neighbourhood of an equilibrium point \( x^0 \) if

\[
\left( \frac{\partial x_h}{\partial p_k} \right)_{S = C_t} > 0.
\]

Two goods are said to be **complements** in the neighbourhood of an equilibrium point \( x^0 \) if

\[
\left( \frac{\partial x_h}{\partial p_k} \right)_{S = C_t} < 0.
\]

The goods \( h \) and \( k \) are therefore substitutes if a compensated variation in the price of \( k \) brings about two variations of opposite signs in the demands for \( h \) and \( k \), and therefore some substitution between them. They are complements in the opposite case.
It follows from (34) and (37) that:

$$\sum_{h \neq k} p_h \left( \frac{\partial x_h}{\partial p_k} \right)_{S = \text{ct}} \geq 0.$$ \hfill (38)

J. Hicks has interpreted this relation as implying that substitution between different goods is more common than complementarity.

It now appears to the reader that part of the complexity that occurs in the basic equations of demand theory results from the nature of the independent variables of the demand functions $\xi_h(p, R)$. The partial derivatives are subject to less simple properties than those applying to the Slutsky substitution coefficients occurring for instance in equation (34). Indeed, in some theoretical works, it is found analytically convenient to introduce compensated demand functions $E_h(p, S)$ defining the demands for commodities as functions of the price vector $p$ and the utility level $S$ that is achieved.

These functions are not direct behavioural relations since the utility level is an endogenous variable of demand theory, but once a piece of analysis has been completed with them, it is easy to go back to ordinary demand functions, using the equation:

$$\frac{\partial E_h}{\partial p_k} = \frac{\partial x_h}{\partial p_k} + x_k \frac{\partial x_h}{\partial R}.$$ \hfill (39)

In order to directly study compensated demand functions, one may start from the appropriate system replacing (23), namely:

$$S'_h(x_1, x_2, \ldots, x_l) = \lambda p_h$$

$$S(x_1, x_2, \ldots, x_l) = S.$$ \hfill (40)

Differentiating this system and using the same notation as above, one finds:

$$dx = U dp + v \frac{dS}{\lambda}$$ \hfill (41)

which is similar to (28) and directly shows that:

$$\frac{\partial E_h}{\partial p_k} = U_{hk}$$

$$\frac{\partial E_h}{\partial S} = \frac{\nu_h}{\lambda}.$$ \hfill (42)

Finally, at the end of this study of demand functions, it is appropriate to define the indirect utility function and thus to introduce what is called 'duality' in consumer theory. This function also is found to be analytically convenient in some developments of microeconomic theory, for instance to the theory of taxation.
The indirect utility function \( \hat{S}(p, R) \) defines the maximum utility level that the consumer can achieve when the price vector is \( p \) and his income is \( R \). Clearly this function is homogeneous of degree zero:
\[
\hat{S}(xp, xR) = S(p, R)
\]  
(42)
for any positive number \( x \). One can write:
\[
\hat{S}(p, R) = S[\xi(p, R)].
\]  
(43)

Hence, the partial derivatives of the function \( \hat{S} \) are easily found:
\[
\frac{\partial \hat{S}}{\partial p_h} = \sum_{k=1}^{l} S'_k \frac{\partial x_k}{\partial p_h}, \quad \frac{\partial \hat{S}}{\partial R} = \sum_{k=1}^{l} S'_k \frac{\partial x_k}{\partial R}.
\]

Referring to the expressions given by (28) for the partial derivatives of the demand functions and taking (32) and (33) into account, one easily finds:
\[
\frac{\partial \hat{S}}{\partial p_h} = -\lambda x_h, \quad \frac{\partial \hat{S}}{\partial R} = \lambda.
\]  
(44)

These equations are said to be dual of equations (20). They imply:
\[
\frac{\partial \hat{S}}{\partial p_h} + x_h \frac{\partial \hat{S}}{\partial R} = 0.
\]  
(45)

This relation between the demand function defining \( x_h \) and the indirect utility function is called Roy's identity.

Homogeneity of the indirect utility function requires:
\[
\sum_{h=1}^{l} p_h \frac{\partial \hat{S}}{\partial p_h} + R \frac{\partial \hat{S}}{\partial R} = 0
\]
which is easily checked from equations (44).

Sometimes the indirect utility function is written as having not the \( l + 1 \) arguments \( p_h \) and \( R \), but the \( l \) arguments \( \pi_h \) respectively equal to \( p_h / R \):
\[
\hat{S}(\pi) = \hat{S}(p, R).
\]  
(46)

The validity of this expression follows from the homogeneity property (42).

10. Cardinal utility

We have now concluded the programme which we set ourselves for the study of consumption. We have built up the theory by introducing a
representation of the market constraints and a system of preferences. The system of preferences can be expressed by a purely ordinal utility function, that is, it can be transformed arbitrarily by an increasing function.

However, on reflection, the reader may hold the opinion that, for each consumer, there exists satisfaction or utility which is not only ordinal, but in a real sense cardinal, or, in the words of M. Allais, that there exists an absolute satisfaction. In other words, he may think that, among all the functions $S$ which lead to the same system of preferences, there is one which has deeper significance and which measures better than the others the true utility which the consumer derives from the different consumption complexes. Clearly this point of view does not contradict that adopted in our lectures.

Cardinal utility may possibly give rise to more precise conclusions than simple ordinal utility. In fact, the former allows a type of comparison which is meaningless for the latter, namely the comparison of differences of utility.

More precisely, consider four complexes $x_1, x_2, x_3, x_4$ and suppose, to fix ideas, that $S(x_2) > S(x_1)$ and $S(x_4) > S(x_3)$. Can we determine if the resulting increase in utility when $x_2$ is substituted for $x_1$ is greater than the increase obtained when $x_4$ is substituted for $x_3$? Obviously we can, when we believe in a cardinal utility; we need only find out if the following inequality holds:

$$S(x_2) - S(x_1) > S(x_4) - S(x_3).$$  \hspace{1cm} (47)

On the other hand, we cannot do so when we know only the preference ordering or an ordinal utility since, for the same complexes $x_1, x_2, x_3$ and $x_4$, the direction of an inequality such as (47) varies with the definition of the function $S$ (cf. Figure 14). It depends basically on whether one does or does not accept that comparisons of gains in utility are meaningful, that one should or should not accept the concept of absolute utility.

We note also that inequalities of the type of (47) are unambiguous if $S$ is determined only up to an increasing linear function, that is, if $S^*(x) = aS(x) + b$ can be substituted for $S(x)$ in the representation of utilities ($a$ and $b$ are given constants, $a$ being positive). So those who support the concept of absolute utility generally postulate that the corresponding function can be arbitrarily transformed by an increasing linear transformation.

Clearly the distinction between ordinal and cardinal utility recalls the distinction in physics between attributes which are measurable and attributes which are simply referable.

11. The axiom of revealed preference

Before concluding this chapter, we must say something about a proposed approach for the representation of consumer choices. This approach differs
The consumer

from the one we have adopted, but does not contradict it.

In the discussion of cardinal utility and ordinal utility, or what amounts practically to the same thing, of cardinal utility and preference relation, an argument often invoked is that ordinal utility only would be 'operational'. It can be determined objectively by the simple observation of behaviour. In order to find a consumer's system of preferences, we need only confront him with a sufficient number of choices among complexes, and observe each time which complex he prefers. On the other hand, we could not learn merely from observation whether his gain in utility when he goes from $x^1$ to $x^2$ is greater or less than his gain in utility in going from $x^3$ to $x^4$. Cardinal utility would not be operational. The scientist should not introduce to his theories non-operational concepts which do not lend themselves to objective observation.

In 1938, this preoccupation led P. A. Samuelson to question even the notion of a preference relation as defined above. According to Samuelson, we do not really have the possibility of carrying out the experiments necessary for effective observation of consumer preferences. Confrontation of the abstract concept with actual observations is so difficult and so rare that we should avoid using even the notion of a system of preferences.

On the other hand, there is no difficulty in observing a consumer's actual choices when he has a certain income $R$ and is faced with well defined prices $p_h$. Through his everyday behaviour the consumer 'reveals' his preferences to us without obliging us to think up artificial experiments.

Samuelson recommended therefore that the theory be established directly
on the basis of the consumer demand function,† that is, on the vector function \(\xi(p, R)\) which defines the complex \(x\) chosen by the consumer when the price vector is \(p\) and his income is \(R\). (In this theory it is assumed that the vector \(x\) chosen by the consumer is determined uniquely from \(p\) and \(R\).)

Samuelson suggests that \(x^1\) is revealed to be preferred to \(x^2\) (which differs from \(x^1\)) if there exist \(p^1\) and \(R^1\) such that:

(i) \(x^1 = \xi(p^1, R^1)\),

(ii) \(p^1x^2 \preceq R^1\).

(The consumer, disposing of \(R^1\) and faced with \(p^1\) may acquire either \(x^2\) or \(x^1\); he prefers \(x^1\).)

It may be postulated that these revealed preferences are not mutually contradictory, in other words, that \(x^2\) cannot be revealed to be preferred to \(x^1\) when \(x^1\) is revealed to be preferred to \(x^2\), which is formally expressed by the following condition on the demand function \(\xi(p, R)\).

**AXIOM P.** If, for some vectors \(p^1\) and \(p^2\) and some numbers \(R^1\) and \(R^2\), \(p^1\xi(p^2, R^2) \leq R^1\) and \(\xi(p^2, R^2) \neq \xi(p^1, R^1)\), then \(p^2\xi(p^1, R^1) > R^2\).

In fact, Samuelson himself did not follow this idea to its conclusion since, in his *Foundations of Economic Analysis*, published in 1948, he presented consumption theory on the basis of ordinal utility.

But it did lead him to investigate more closely the conditions to be satisfied by demand functions if they are to be considered as revealing the existence of a preference relation of the type discussed in Section 3. In other words, he asked under what conditions revealed preferences constitute a complete preordering. Mathematical economists since then have shown that such a preordering exists whenever the demand functions satisfy not only axiom P but also some regularity conditions.‡

This result shows that, if the demand laws are perfectly known and if they satisfy the very natural conditions mentioned above, then the

† Previously, G. Cassel put forward a general equilibrium theory based directly on demand functions. But, since he did not require these functions to obey Samuelson's consistency conditions, Cassel could not prove the existence of certain particular properties. For example, he had to postulate the absence of monetary illusion, instead of deducing it as we have done.

preference relation also is perfectly known. Contrary to Samuelson's suggestion, therefore, it is possible to determine this relation from direct observation of consumer behaviour without having to confront the consumer with a series of binary choices.
1. Definitions

We come now to the activity of producers, also called 'firms'. This will be investigated in two successive stages. First of all we shall study the representation of the technical constraints which limit the range of feasible productive processes. We must then formalise the decisions of the firm which must act within a certain institutional context. Our discussion will be carried on mainly in the context of 'perfect competition', which cannot pretend to be an always valid description of real situations. But it is the ideal model on which the study of the problems of general equilibrium arising in market economies has been based so far.

As in our discussion of consumption theory, we shall omit the index \( j \) relating to the particular agent considered. So \( a_h, b_h \) and \( y_h \) will simply denote input, output and net production of the good \( h \) in the firm in question.

For the purposes of economic theory, a detailed description of technical processes is as pointless as knowledge of consumers' motivations. All that matters in this chapter is that we should formalise the constraints which technology imposes on the producer. These can be summarised in a very simple way: certain vectors \( y \) correspond to technically possible transformations of inputs into outputs; other vectors correspond to transformations which are not allowed by the technology at the disposal of the firm.

To take account of this, we need only define in \( \mathbb{R}^l \) the production set \( Y \) as that set containing the net production vectors which are feasible for the producer. Thus the demands of technology are represented by the simple constraint

\[
y \in Y.
\]

(We must not forget that \( Y \) relates to a particular producer; in general equilibrium theory, each producer \( j \) has his own set \( Y_j \).)

Of course, all the technically feasible transformations are not of interest
The producer

*a priori*; some may require greater inputs and yield smaller outputs than others. The firm's technical experts must eliminate the former in favour of the latter. This is why we can often confine ourselves *a priori* to *technically efficient* net productions. By this we mean any transformation which cannot be altered so as to yield larger net production of one good without this resulting in smaller net production of some other good. Relative to such a transformation, therefore, output of one good cannot be increased without increasing input or reducing output of another good.

Formally, the vector $y^1$ is said to be technically efficient if it belongs to the set $Y$ of feasible net productions and if there exists no other vector $y^2$ of $Y$ such that

$$y^2_h \geq y^1_h \quad \text{for} \quad h = 1, 2, \ldots, l.$$ 

So the technically efficient vectors $y$ belong to a subset, or possibly to the whole, of the boundary of $Y$ in the commodity space.*

In the construction of optimum and equilibrium theories we could impose on ourselves to use the production set $Y$ as the sole representation of technical constraints. This is the method adopted in the most modern approaches to the subject. Following a tradition of almost a century, however, mathematical economists often introduce another more restrictive concept, that of the 'production function', which formalises in particular the idea that marginal substitutions between inputs are feasible.

Actually, in their approach to the problems of general equilibrium economists have alternatively used two types of formalisations, which stress two opposing features of production. One feature is the existence of 'proportionalities' or 'coefficients of production': some inputs must be combined in given proportions, like iron ore and coal in the process of producing pig iron. Another feature is the possibility of substituting an input for another: machines can replace men, one fuel can be substituted for another, more or less fertilizer can be put in a given piece of agricultural land and more or less labour can be spent on it, hence the same crop may be achieved with a little less fertilizer and a little more labour.

Economists such as K. Marx or L. Walras in the first editions of his treatise constructed their systems assuming fixed proportionalities, i.e. complementarity between inputs. Others like V. Pareto have used formalisations implying that substitutabilities are everywhere prevalent. The great advantage of the modern set theoretic approach is to cover both complementarities

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* Rigorously, we can confine ourselves to technically efficient vectors only if, corresponding to every $y$ of $Y$, we can find an efficient $y^*$ such that $y^*_h \geq y_h$ for all $h$. This will be the case if $Y$ is a closed set and if, without leaving $Y$, we cannot increase one component of $y$ indefinitely without reducing another. It does not restrict the validity of the theory to assume this.
and substitutions. The definition of $Y$ can take into account simultaneously the substitutability of machines for men and the proportionality between iron ore and coal. Hence the theory built directly on $Y$ is fully general in this respect.

When we want to build models that lend themselves to computation for dealing with questions of applied economics, we have the choice today between two types of more specific formalisation: either production functions, usually allowing for large substitutabilities, or fixed coefficient processes combined into 'activity analysis' models.

Lectures such as the present ones should not ignore the production function concept. In fact it will be used extensively with the aim of making exposition easier and to allow the free use of differential calculus. Some essential proofs will be given under the assumption that the sets $Y_j$ can be represented by production functions, even though this assumption is not required for the validity of the result. Production functions must therefore be defined and discussed with some care. Later on we shall point out in passing those places where the use of such functions conceals some difficulty.

A production function $f$ for a particular firm is, by definition, a real function defined on $R^t$ such that:

$$f(y_1, y_2, \ldots, y_t) = 0$$ (2)

if and only if $y$ is an efficient vector, and such that

$$f(y_1, y_2, \ldots, y_t) \leq 0$$ (3)

if and only if $y$ belongs to $Y$.

For the moment we shall not inquire into the conditions to be satisfied by $Y$ if we are to be able to define such a function. This will be discussed in Section 2.

According to this definition, we can use (1) or (3) equivalently to represent the technical constraints on production† (the function $f$ depends on the particular producer $j$, as does $Y$).

Geometric illustrations of the production set and the production function are often fruitful. Suppose, for example, that there are four commodities, the first two of which are outputs of the firm and the last two inputs. Figures 1 and 2 represent two intersections of $Y$, the first by a hyperplane ($y_3 = y_3^0; y_4 = y_4^0$), the second by a hyperplane ($y_1 = y_1^0; y_2 = y_2^0$). The first therefore represents the set of the productions that are feasible from the quantities

† We may point out that, like the utility function, the production function here is not defined uniquely. For example, if $\phi$ is a real function with the same sign as its argument, and which is zero when its argument is zero, then $\phi(f)$ corresponds to the same set as $f$. Since this has already been discussed sufficiently in consumption theory, we shall not lay further stress on it.
The most general form of a production function is that in (2). Slightly more particular expressions are often used. Thus it is often assumed that the firm has only one output, the good 1, to fix ideas; the production function is then given the form:

\[ f(y_1, y_2, \ldots, y_i) = y_1 - g(y_2, \ldots, y_i). \]  

(4)

The technical constraint is

\[ y_1 \leq g(y_2, \ldots, y_i) \]  

(5)

and the expression 'production function' is also used for the function \( g \) which defines the output resulting from given quantities of inputs. There should be no real possibility of confusion from this ambiguity.

Note that we could show inputs and outputs explicitly in (5). Thus

\[ b_1 \leq g(-a_2, -a_3, \ldots, -a_i) \]  

(6)

or, after an obvious change in notation,

\[ b_1 \leq g^*(a_2, a_3, \ldots, a_i). \]  

(7)

† Obviously this particular form is no longer affected by the indeterminacy already mentioned in relation to the general form (2). Here the function \( g \) representing a given set \( Y \) is determined uniquely. In fact, even if these are several outputs, in most cases we can solve the equality \( f(y) = 0 \) for \( y_1 \) and so revert to (5).
The function $g^*$ will generally be increasing with the $a_h$ and the function $g$ will consequently be decreasing with respect to the $y_h$, or at least non-increasing.

Later on we shall often assume that the function $f$ is twice differentiable. Let $y^0$ and $y^0 + dy$ be two neighbouring technically efficient vectors. We can write

$$
\sum_{h=1}^l f'_h dy_h = 0
$$

(8)

where $f'_h$ denotes the value at $y^0$ of the derivative of $f$ with respect to $y_h$.

In particular, if all the $dy_h$ except two, $dy_r$ and $dy_s$, are zero, then (8) reduces to

$$
f'_r dy_r + f'_s dy_s = 0
$$

(9)

or

$$
-\frac{dy_r}{dy_s} = \frac{f'_s}{f'_r}
$$

(10)

The ratio on the right hand side of (10) can be called the marginal rate of substitution between the goods $s$ and $r$ for the producer in question. This expression is similar to that encountered in consumption theory. To avoid confusion, we shall sometimes speak instead of the marginal rate of transformation.

In the particular case where $f$ takes the form (4), equalities of the type (10) become

$$
-\frac{dy'_s}{dy'_s} = -g'_s \quad \text{for} \quad s \neq 1
$$

(11)

and

$$
-\frac{dy'_r}{dy'_s} = \frac{g'_s}{g'_r} \quad \text{for} \quad s, r \neq 1.
$$

(12)

The ratio (11) measures the increase in production resulting from an increase of one unit in the input of $s$ (note that $y'_s$ is equal to minus the input). It is often called the marginal productivity of $s$. The ratio (12) defines, apart from sign, the additional quantity of input of $r$ which is necessary to compensate in output for a reduction of one unit in the input of $s$. This is, in fact, a marginal rate of substitution.

We note also that the first derivatives $f'_h$ of the production function $f$ must take non-negative values at every technically efficient point $y^0$. Consider a small variation $dy$ all of whose components are zero except $dy_k$, which is assumed positive. Since $y^0$ is technically efficient, $y^0 + dy$ is not technically possible, that is, $f(y^0 + dy)$ is positive. But, since $f(y^0)$ is zero, $f(y^0 + dy)$ can be positive only if $f'_k$ is not negative.
2. The validity of production functions

We must now investigate the conditions to be satisfied by the production set \( Y \) in order that, first of all, there exists a production function \( f \), and in the second place, that this function is differentiable. These conditions are certainly more restrictive than it would appear at first glance.

Differentiability implies that \( f \) is continuous and consequently that \( Y \) is a closed set in \( \mathbb{R}^l \). This property is not restrictive; if the vectors \( \{v^1, v^2, \ldots\} \) of a convergent sequence each define a feasible production then the limiting vector certainly corresponds in reality to a feasible production.

But the continuity of \( f \) implies also that every point \( y^* \) on the boundary of \( y \) satisfies \( f(y^*) = 0 \) since it can be approached both by a sequence of vectors \( y \) such that \( f(y) \leq 0 \) and by a sequence of vectors such that \( f(y) > 0 \). So the definition of \( f \) implies that every point \( y^* \) on the boundary of \( Y \) is technically efficient. Moreover, differentiability assumes that, with respect to any technically efficient vector, the marginal rates of substitution are all well-defined. Taken literally, these consequences are difficult to accept.

(i) In the first place, the domains of variation of all, or some, of the \( y_h \) may be limited. For example, technology may demand that some good \( r \) occurs only as input and some other good \( s \) only as output. So the inequalities \( y_r \leq 0 \) and \( y_s \geq 0 \) appear in the definition of \( Y \). (In fact, the second inequality can be eliminated if we assume that the firm can always dispose of its surplus without cost, since this assumption is naturally expressed as: \( y^0 \in Y \) and \( y_h \leq y^0 \) for all \( h \) implies \( y \in Y \).) Because of the limits on the domains of variation of some \( y_h \), the set \( Y \) has boundaries corresponding to non-technically efficient productions (for example, the half-line ON in Figure 3).

The existence of such boundaries is incompatible with the continuity of \( f \) together with the conditions that \( f(y) < 0 \) is satisfied for every non-technically
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efficient vector of $Y$ and that $f(y) > 0$ is satisfied for every vector $y$ outside $Y$. (At a point such as $N$, $f(y)$ should be equal to a negative number, but should be positive for every point near $N$ whose second coordinate is positive; this is incompatible with the continuity of $f$ at $N$.)

However, we can take account of these limitations by altering the definition of the production function and explicitly adding inequalities to the formal representations of the set $Y$ and the set of technically efficient vectors. For example, to characterise $Y$ we replace (3) by

$$
\begin{align*}
&f(y_1, y_2, \ldots, y_i) \leq 0, \\
&y_h \leq 0 \quad \text{for a specified list of goods } h.
\end{align*}
$$

(13)

To characterise the set of technically efficient vectors, (2) is replaced by

$$
\begin{align*}
&f(y_1, y_2, \ldots, y_i) = 0, \\
&y_h \leq 0 \quad \text{for the same list of goods } h.
\end{align*}
$$

(14)

Thus, for Figure 3, (13) and (14) become

$$
\begin{align*}
&y_1 + \alpha y_2 \leq 0, \\
&y_2 \leq 0,
\end{align*}
$$

(15)

and

$$
\begin{align*}
&y_1 + \alpha y_2 = 0 \\
&y_2 \leq 0.
\end{align*}
$$

(16)

This complication will not be taken into account in our discussion of the general theories. That is, we shall proceed as if the limits on the domains of variation of the $y_h$ are never in force. As we saw in consumption theory, certain new particular features are revealed if we take account of constraints expressed by inequalities, but this does not alter basically the nature of the results. We shall presently return to this point.

(ii) In the second place, in some productive operations the different goods which constitute inputs must be combined in fixed proportions. This is particularly the case for most of the raw materials used in many industrial processes.

When such proportionality ratios exist, the isoquants do not have the same form as in Figure 2. If there is free disposal of surplus, they look like the isoquant in Figure 4. Apart from the surplus of one of the two inputs, $a_3$ and $a_4$ must take values whose ratio corresponds to that defined by the half-line $OA$. Except at the point $A$, the half-lines $AN$ and $AM$ correspond to non-technically efficient productions. At the point $A$, the first derivatives of $f$ with respect to $y_3$ and $y_4$ are not continuous. (The situation is similar to that in Chapter 2, with the utility function (8) illustrated in Figure 7.)

The real situation is sometimes less clear-cut than Figure 4 assumes, since
there may be available to the firm two or more production techniques each requiring fixed proportions of inputs, the proportions differing for the different techniques. Figure 5 relates to an example of two techniques, the first represented by the point $A$, the second by the point $B$. The firm can employ the two techniques simultaneously to produce the same quantities of outputs. For example, if each technique can be employed on a scale reduced by one half relative to that represented by $A$ or $B$ (the assumption of constant returns to scale, to be defined presently) then the same output can be obtained by simultaneous use of the two techniques on this new scale; the point on Figure 5 corresponding to this method of production is the midpoint of $AB$.

![Fig. 4](image-url)

![Fig. 5](image-url)

Similarly, each point on $AB$ defines a possible combination of the two techniques yielding the same output as $A$ or $B$. In this case, the first derivatives of $f$ are in fact continuous at each point within $AB$, but not at $A$ nor at $B$.

In order formally to represent such situations as those of Figures 4 and 5, we can add other constraints to the equation $f(y) = 0$ to characterise the set of technically efficient vectors. For example, if, as in Figure 4, there must be a fixed proportion between $y_3$ and $y_4$, we write:

$$y_4 = \alpha y_3. \tag{17}$$

In the case of two techniques, as in Figure 5, the supplementary constraints may be

$$-\beta y_3 \leq y_4 \leq -\alpha y_3. \tag{18}$$

The theory becomes very complicated if such constraints are taken into account. For this reason, they are better ignored in a course of lectures whose aim is to provide the student with a sound grasp of the general logic of the theories to be discussed rather than the difficulties which are
Assumptions about production sets

encountered in their rigorous exposition. The changes in production theory introduced by their presence will be described briefly.†

Finally, we see that the above-mentioned difficulties can be avoided if we base our reasoning directly on the set \( Y \) of feasible productions and on the set of technically efficient productions rather than on the production function. This is the approach adopted in the most modern treatments of the theories with which we are concerned here.

As when a utility function is substituted for a preordering of consumer choices, the substitution of a production function for a production set makes exposition easier since it allows the use of the differential calculus and of fairly standard types of mathematical reasoning. Moreover, this approach alone leads to certain results which every economist must know. Knowledge of these results is essential for the student, even if their application is somewhat restricted by the simplifications required to justify the production function.

3. Assumptions about production sets

We must now discuss certain assumptions which are frequently adopted about production sets or production functions.

**Additivity.** If the two vectors \( y^1 \) and \( y^2 \) define feasible productions \( y^1 \in Y \) and \( y^2 \in Y \) or \( f(y^1) \leq 0 \) and \( f(y^2) \leq 0 \), then the vector \( y = y^1 + y^2 \) defines a feasible production (therefore \( y \in Y \) or \( f(y) \leq 0 \)).

This appears a natural assumption. For, it seems that we can always realise \( y \) by realising independently \( y^1 \) and \( y^2 \). Additivity fails to hold only if \( y^1 \) and \( y^2 \) cannot be applied simultaneously. *A priori* there seems no reason for this to be the case.

However, it may happen that the model does not identify all the commodities which in fact occur as inputs in production operations. For example, if the land in the possession of an agricultural undertaking does not appear among the commodities, then additivity does not apply to its production set, since, if the available land is totally used by \( y^1 \) on the one hand and by \( y^2 \) on the other, realisation of \( y^1 + y^2 \) requires double the actually available quantity of land. Similarly, if the capacity for work of the head of an industrial firm does not appear among the commodities, and if his capacity limits production, then additivity no longer strictly applies.

† It is the aim of a new branch of economic science, 'activity analysis', to integrate into the theory formalisations which describe technical constraints more accurately than do production functions. A very good account of the resulting modifications is given in Dorfman, *Application of Linear Programming to the Theory of the Firm*, University of California Press, Berkeley 1951. See also Dorfman, Samuelson and Solow, *Linear programming and activity analysis*, McGraw-Hill, New York, 1958.
The producer

DIVISIBILITY. If the vector \( y^1 \) defines a feasible production \( (y^1 \in Y \) or \( f(y^1) \leq 0) \) and if \( 0 < \alpha < 1 \), then the vector \( \alpha y^1 \) also defines a feasible production (therefore \( \alpha y^1 \in Y \) and \( f(\alpha y^1) \leq 0) \).

This assumption is much less generally satisfied than the previous one. It assumes that every productive operation can be split up and realised on a reduced scale without changing the proportions of inputs and outputs. Taken literally, it can be said to be rarely satisfied. For every productive operation there is certainly a level below which it cannot be carried out in unaltered conditions. But this indivisibility may vary in its degree of effectiveness and in many industrial operations it appears negligible.

CONSTANT RETURNS TO SCALE.† If the vector \( y^1 \) defines a feasible production \( (y^1 \in Y \) or \( f(y^1) \leq 0) \) and if \( \beta \) is a positive number, then the vector \( \beta y^1 \) also defines a feasible production (therefore \( \beta y^1 \in Y \) and \( f(\beta y^1) \leq 0) \).

Obviously the constant returns defined by this assumption imply divisibility. Conversely, additivity and divisibility imply constant returns to scale. For, let \( k \) be the integral part of \( \beta \); we can apply the property of additivity repeatedly, taking the vectors \( y^1, 2y^1, \ldots, (k - 1)y^1 \) successively for \( y^2 \) and thus proving that \( 2y^1, 3y^1, \ldots, ky^1 \) are feasible; divisibility shows that \( (\beta - k)y^1 \) is feasible; finally, additivity shows that \( \beta y^1 = (\beta - k)y^1 + ky^1 \) is feasible.

In practice, we shall consider that returns to scale are constant precisely when additivity and divisibility can be considered to hold, although rigorously, additivity is not necessary.

Consider the particular case where the technical constraints are expressed in the form (5). If the function \( g \) is homogeneous of the first degree, then the assumption of constant returns to scale is clearly satisfied.

Conversely, constant returns to scale imply that

\[
g(\beta y_2, \ldots, \beta y_i) = \beta g(y_2, \ldots, y_i)
\]

for every vector \( y \) and every positive number \( \beta \). Indeed, on the one hand, the hypothesis implies, by definition,

\[
g(\beta y_2, \ldots, \beta y_i) \geq \beta y_1 = \beta g(y_2, \ldots, y_i),
\]

since \( \beta y \) is feasible whenever \( y \) is feasible. On the other hand, the same hypothesis implies:

\[
g(y_2, \ldots, y_i) \geq y_1 = g(\beta y_2, \ldots, \beta y_i)/\beta
\]

since \( y = z/\beta \) is feasible whenever \( z \) \((= \beta y) \) is feasible. The two preceding inequalities do imply positive homogeneity, as was to be proved.

† The expression 'constant returns to scale' is explained as follows: if the first good is the sole output, the return with respect to the input \( i \) in the productive transformation \( y^1 \) is, by definition, the ratio \( y^1_k / (-y^1_k) \). This assumption specifies that the volume of output can be changed without changing the return with respect to any of the inputs.
To characterise the second of the above assumptions, we often speak of 'non-increasing returns to scale' rather than of divisibility. The relationship with the assumption of constant returns is obvious from the above formulations. However, there must not be any confusion of the assumption of divisibility, or non-increasing returns to scale, with the assumption of 'non-increasing marginal returns' with which we shall shortly be concerned.

We also speak of non-decreasing returns to scale when \( f(y^1) \leq 0 \) (or \( y^1 \in Y \)) and \( \alpha > 1 \) imply \( f(\alpha y^1) \leq 0 \).

Figure 6 illustrates the three situations for the case of a single input and a single output. The production set bounded by \( \Gamma_1 \) relates to constant returns to scale, that bounded by \( \Gamma_2 \) to decreasing returns and that bounded by \( \Gamma_3 \) to increasing returns (of course, a given production set may come into none of these three categories).

**Convexity.** If the vectors \( y^1 \) and \( y^2 \) define two feasible productions and if \( 0 < \alpha < 1 \), then the vector \( \alpha y^1 + (1 - \alpha)y^2 \) defines a feasible production.

In short, there is convexity if the set \( Y \) contains every segment joining two of its points. Figures 1 and 2 correspond to the intersections of a convex set \( Y \) of \( R^4 \). Similarly, the sets in Figures 3, 4 and 5 satisfy the assumption of convexity. Finally, in Figure 6, the set bounded by \( \Gamma_3 \) is not convex, and the other two sets are.

Obviously divisibility and additivity imply convexity. Since the null vector naturally belongs to \( Y \), convexity implies divisibility in practice. (To show
this, we need only apply the property of convexity, taking the null vector for \( y^2 \).)

Convexity has consequences for the second derivatives of the production function. To investigate these consequences, we shall deal with the case of a function of the form

\[
y_1 = g(y_2, \ldots, y_l).
\]  

(5)

Consider two infinitely close vectors \( y^0 \) and \( y^0 + dy \) which satisfy (5):

\[
y_1^0 = g(y_2^0, \ldots, y_l^0) \tag{19}
\]

and

\[
y_1^0 + dy_1 = g(y_2^0 + dy_2, \ldots, y_l^0 + dy_l). \tag{20}
\]

If \( 0 < \alpha < 1 \), then \( y^0 + \alpha \, dy \) is a possible vector; it therefore satisfies

\[
y_1^0 + \alpha \, dy_1 \leq g(y_2^0 + \alpha \, dy_2, \ldots, y_l^0 + \alpha \, dy_l). \tag{21}
\]

Let us assume that the second derivatives of \( g \) are continuous. Expanding the right hand sides of (20) and (21) up to the second order, and taking account of (19), we obtain

\[
dy_1 = \sum_{h=2}^{l} g'_h \, dy_h + \frac{(1 + \varepsilon)}{2} \sum_{h=2}^{l} \sum_{k=2}^{l} g''_{hk} \, dy_h \, dy_k \tag{22}
\]

and

\[
\alpha \, dy_1 \leq \alpha \sum_{h=2}^{l} g'_h \, dy_h + \frac{\alpha^2 (1 + \eta)}{2} \sum_{h=2}^{l} \sum_{k=2}^{l} g''_{hk} \, dy_h \, dy_k. \tag{23}
\]

Here \( g'_h \) is the value at \( y^0 \) of the first derivative of \( g \) with respect to \( y_h \). Similarly \( g''_{hk} \) is the value at \( y^0 \) of the second derivative of \( g \) with respect to \( y_h \) and \( y_k \). The two numbers \( \varepsilon \) and \( \eta \) are infinitely small with the \( dy_h \).

Subtracting (22) multiplied by \( \alpha \) from (23), and taking account of the fact that \( 0 < \alpha < 1 \), we have

\[
\sum_{h=2}^{l} \sum_{k=2}^{l} g''_{hk} \, dy_h \, dy_k \leq 0 \tag{24}
\]

(the multiplier \( \alpha (\alpha - 1 + \alpha \eta - \varepsilon) \) is certainly negative if the \( dy_h \) are sufficiently small).

Since \textit{a priori} the \( dy_h \) can have any values, \textit{convexity implies that the matrix} \( G'' \) \textit{of the second derivatives} \( g''_{hk} \) \textit{is negative definite or negative semi-definite.}

Conversely, it can be shown that, if \( G'' \) is negative definite for any system of values given to \( y_2, y_3, \ldots, y_l \), then the assumption of convexity holds.

The condition on \( G'' \), which we have just established, is a general form of the assumption of \textit{non-increasing marginal returns}. In particular, this condition implies

\[
g''_{hh} \leq 0 \quad h = 2, \ldots, l,
\]
Equilibrium for the firm in perfect competition

that is,
\[
\frac{\partial (-g_h)}{\partial (-y_h)} \leq 0.
\]

The marginal return to \( h(\partial g/\partial a_h = -g_h) \), also called the marginal productivity, is therefore a decreasing function of the quantity of input \( h \) used \((a_h = -y_h)\).

We should point out that diminishing marginal returns and constant returns to scale are not contradictory, as can be verified from the function 
\( y_1 = \sqrt{y_2y_3} \). Also, additivity and divisibility imply both constant returns to scale and convexity, therefore non-increasing marginal returns.

To conclude our discussion, we return to the two reasons mentioned earlier for departures from additivity and divisibility.

The fact that certain factors available in limited quantities have not been taken into account explicitly in the formulation of the model obviously does not affect the marginal returns to the other factors. On the other hand, this fact may explain why we choose functions for which returns to scale are diminishing, while additivity implies constant returns.

The presence of considerable indivisibilities may explain the appearance of production functions with increasing returns to scale for which the assumption of non-increasing marginal returns is not satisfied.

M. Allais suggests that we distinguish two situations. In some branches of production, divisibility can be considered to be approximately satisfied to a sufficient extent. In this situation we usually find that production is carried on by a relatively large number of technical units functioning in similar conditions. The technology of this branch satisfies the assumption of constant returns to scale. M. Allais uses the term 'differentiated sector' to cover all productive activity of this kind.

In other fields, considerable indivisibilities exist. The market for each of the goods produced is then served by a very small number of very large technical units. To represent this situation, M. Allais assumes that a single firm exists in each such field, all of which constitute what he calls the 'undifferentiated sector'.

This distinction will be taken again later, notably in Chapter 7 when we shall consider economies involving a large number of agents.

4. Equilibrium for the firm in perfect competition

When dealing with the consumer, we reduced the problem of choosing the best consumption complex to that of maximising a utility function. We shall now assume that the firm tries to maximise the net value of its production:

\[
p'y = \sum_{h=1}^{l} p_h y_h = \sum_{h=1}^{l} p_h b_h - \sum_{h=1}^{l} p_h a_h.
\]  

(25)
This expression, which is the amount by which the value of outputs exceeds the value of inputs also defines the ‘profit’ that the firm derives from production. In fact, the microeconomic theory with which we are concerned considers the behaviour of the firm to be motivated by its desire to realise the greatest possible profit subject to the constraints imposed by technology and the institutional environment. This assumption, adopted in all theories of general equilibrium, has been subject to criticism. However, no alternative has so far been suggested which stands up to examination and can provide the basis for a general theory.† Also, some criticisms arise from misunderstanding of the wide generality of the model under study. In order to avoid the same errors, we shall later discuss the definition of ‘profit’ when time and uncertainty are taken into account. For our present purposes it is sufficient that the assumption of profit maximisation seems to afford the best way for a simple systematisation of the behaviour of firms.

Again, we consider the firm to be in a situation of perfect competition if:

— the price of each good is perfectly defined and exogenous for the firm, and therefore independent of its production decisions;

— and if, at this price, the firm can acquire any quantity it requires of a good, or dispose of any quantity it has produced.

Of course, this is an abstract model of real situations. Basically, it assumes that the firm is small relative to the market, so that its actions have no influence on prices. Moreover, it assumes that the demands and supplies emanating from other agents are completely flexible so that they can react instantly to any supply or any demand emanating from the particular firm. This model is clearly inappropriate to the ‘undifferentiated sector’. At the end of this chapter we shall discuss the case of the firm in a monopolistic situation and in Chapter 6 we shall briefly consider the formulations proposed for other situations of imperfect competition. When in Chapters 10 and 11, we shall have explicitly introduced time and uncertainties, we shall also understand that strictly speaking perfect competition implies a much richer market system than the one actually prevailing.

Thus, the hypotheses of profit maximisation and perfect competition have the advantage of being simple, but they lead to an idealisation that may look strong with respect to an essentially complex reality. I repeat that these hypotheses are introduced here in order to permit the building of a general equilibrium theory and that, for this purpose, they may provide an admissible first approximation. They would on the contrary be

† I must, however, mention here the existence of a general equilibrium theory for economies with labour managed firms. The objective of the firm is then said to be maximisation of value added per worker rather than maximisation of profit. On this subject see J. Dreze, ‘Some Theory of Labor Management and Participation’, *Econometrica*, November 1976.
inadequate for building a 'theory of the firm' that could serve as a general conceptual framework for the discussion of the many problems concerning decisions to be taken by business managers. We must remember that the microeconomic representation considered here aims at a theory of prices and resources allocation not at a theory of the management of the firms.†

Adopting the assumptions of profit maximisation and perfect competition, and using a production function representing the technical constraints, we can easily determine equilibrium for the firm. We need only maximise \( p y \) subject to the constraint

\[
f(y_1, y_2, \ldots, y_l) = 0. \tag{26}
\]

(In what follows, we assume that no price \( p_h \) is negative, so that the firm loses nothing by limiting itself to technically efficient net productions. Obviously we also assume that the price vector is not identically zero.)

If we follow the same approach as for consumption theory, we should now investigate the existence and uniqueness of equilibrium. We shall not do this, which in any case raises some difficulties of principle (see the footnote at the start of Section 6). So we shall go straight on to consider the marginal equalities satisfied in the equilibrium.

Maximisation of (25) subject to the constraint (26) is a simple case of the classical problem of constrained maximisation. The necessary first order conditions for a vector \( y^0 \) to be a solution imply the existence of a Lagrange multiplier \( \lambda \) such that

\[
p_h = \lambda f'_h \quad h = 1, 2, \ldots, l \tag{27}
\]

where \( f'_h \) is the value at \( y^0 \) of the derivative of \( f \) with respect to \( y_h \). For the application of theorem VI of the Appendix, it is assumed here that the \( f'_h \) are not all simultaneously zero. It follows from the remark at the end of Section 1 that the \( f'_h \) are not negative and consequently that \( \lambda \) is positive.

Conditions (27) imply

\[
\frac{f'_s}{f'_r} = \frac{p_s}{p_r}. \tag{28}
\]

**In the equilibrium, the marginal rate of substitution between the two commodities \( r \) and \( s \) must equal the ratio of the prices of these commodities.**

In particular, if the production function is

\[
y_1 = g(y_2, y_3, \ldots, y_l), \tag{29}
\]

conditions (27) become

\[
p_1 = \lambda \quad \text{and} \quad p_h = - \lambda g'_h \quad \text{for} \quad h \neq 1,
\]

† Concerning the difficulties faced by the theory of management of firms and the many references dealing with it, see H. Leibenstein, 'The Missing Link: Micro–Micro Theory', *Journal of Economic Literature*, June 1979.
and so
\[ g'_h = \frac{p_h}{p_1} \quad h = 2, 3, \ldots, l. \] (30)

The marginal productivity of commodity \( h \) must equal the ratio between its price and that of the output.

As in consumption theory, we can find the necessary second order conditions for a profit maximum. With the general form of the production function, (26) say, these conditions require
\[ \sum_{h,k=1}^{l} f''_{hk} dy_h dy_k \geq 0 \] (31)
for every set of \( dy_h \) such that
\[ \sum_{h=1}^{l} f'_h dy_h = 0, \] (32)
where, of course, \( f''_{hk} \) denotes the value at \( y^0 \) of the second derivative of \( f \) with respect to \( y_h \) and \( y_k \) (see theorem VIII in the Appendix).

In the particular case of the production function (29), the second order conditions imply more simply that
\[ \sum_{h,k=2}^{l} g''_{hk} dy_h dy_k \leq 0 \] (33)
for every set of \( dy_h \)'s (where \( h = 2, 3, \ldots, l \)). For, we can always associate with these \( dy_h \)'s a number \( dy_1 \) such that (32) is satisfied; (33) then follows from (31). So we come back to the assumption of non-increasing marginal returns, which is therefore satisfied at an equilibrium for the firm.

These second order conditions reveal an important point: the firm cannot be in competitive equilibrium at a point in the production set where returns to scale are locally increasing. Let us take the case of the production function (29) and assume that from \( y^0 \), inputs are increased by the quantities \( y_1^0 d\alpha \), \( \ldots, y_l^0 d\alpha. \) Let \( dy_1 \) be the corresponding increase in output. We can say that the returns to scale are locally increasing if \( dy_1/d\alpha \) is an increasing function of \( d\alpha. \) If we consider a limited expansion of \( dy_1 \) and ignore the case where the second order term is zero, we see that the multiplier of \( d\alpha \) in the expression for \( dy_1/d\alpha \) is
\[ \sum_{h,k=2}^{l} g''_{hk} y_h^0 y_k^0. \]
It cannot be positive without contradicting the necessary second order condition.

Thus competitive equilibrium is incompatible with such increasing returns to scale, which are often characteristic of the sector in which very large production units predominate. The maintenance of equilibrium for this sector demands forms of institutional organisation other than perfect
competition (see, for example, the case of monopoly in Section 9 below, or the management rule for certain public services given in Chapter 6, Section 6).

We can also now consider the inverse problem and prove that the marginal conditions (27) are sufficient for an equilibrium of the firm if the assumption of convexity is satisfied. The following property therefore matches proposition 2 in Chapter 2, relating to the consumer. But its proof is much shorter.

**Proposition 1.** If the technical constraints are represented by a differentiable production function defining a convex set $Y$ and if the vector $y^0$ satisfies (26) and (27) with an appropriate positive number $\lambda$, then $y^0$ is an equilibrium for the firm.

Consider a vector $y^1$ that is technically possible, but apart from that may be any vector:

$$f(y^1) \leq 0.$$  \hspace{1cm} (34)

Let $dt$ be a small positive number. Because $Y$ is convex, the vector $(1 - dt)y^0 + dt y^1$ is technically possible, and so

$$f[y^0 + (y^1 - y^0)\, dt] \leq 0.$$  

But $f(y^0) = 0$, hence:

$$\frac{f[y^0 + (y^1 - y^0)\, dt] - f(y^0)}{dt} \leq 0$$

If $dt$ tends to zero, this inequality holds in the limit, and consequently

$$\sum_{h=1}^{l} (y^1_h - y^0_h) f'_h \leq 0,$$  \hspace{1cm} (35)

where $f'_h$ is the value at $y^0$ of the derivative of $f$ with respect to $y_h$.

In view of (27), and since $\lambda$ is positive, (35) implies

$$\sum_{h=1}^{l} p_h (y^1_h - y^0_h) \leq 0.$$  

The profit associated with $y^1$ cannot exceed the profit associated with $y^0$, which is the required result.

5. The case of additional constraints

We have seen that the production function may be insufficient for complete representation of technical constraints. Without going into details, we shall discuss briefly the treatment of cases where additional constraints must be added.

Suppose first that the constraints are represented by the production function (26) and a second condition:

$$\phi(y_1, y_2 \ldots y_l) = 0$$  \hspace{1cm} (36)
After introduction of a second Lagrange multiplier, the first order conditions become:

\[ p_h = \lambda f'_h + \mu \phi'_h, \quad h = 1, 2, \ldots, l, \]  

(37)

which replaces (27).

Does such a substitution have much effect on our results? Not necessarily. A relatively simple alteration in the properties is sufficient in some cases.

Let us return to the example of four goods and the additional constraint

\[ y_4 = \alpha y_3, \]  

(38)

which expresses strict proportionality between two inputs. System (37) becomes

\[
\begin{cases}
    p_h = \lambda f'_h & \text{for } h = 1, 2. \\
    p_3 = \lambda f'_3 - \mu \alpha \\
    p_4 = \lambda f'_4 + \mu
\end{cases}
\]

Eliminating \( \mu \), we obtain

\[
\begin{cases}
    p_h = \lambda f'_h & h = 1, 2. \\
    p_3 + \alpha p_4 = \lambda (f'_3 + \alpha f'_4)
\end{cases}
\]

(39)

This new system has the same form as (27) provided that goods 3 and 4 are replaced by a composite good one unit of which consists of one unit of good 3 and \( \alpha \) times one unit of good 4; \( f'_3 + \alpha f'_4 \) is then the partial derivative of \( f \) with respect to the composite good.†

Similarly, no insurmountable problem arises if we take account of constraints expressed by inequalities. Suppose, for example, that there are again four goods and, apart from the production function, the two constraints

\[ 0 \leq -y_4 \leq -\alpha y_3. \]  

(40)

(Goods 3 and 4 are inputs, and the proportion of 4 with respect to 3 is bounded above; see Figure 7.)

Here we have a case for application of theorem XI of the Appendix. The function to be maximised is

\[ p_1 y_1 + p_2 y_2 + p_3 y_3 + p_4 y_4; \]

the constraints are

\[
\begin{cases}
    -f(y_1, y_2, y_3, y_4) \geq 0 \\
    -y_4 \geq 0 \\
    y_4 - \alpha y_3 \geq 0.
\end{cases}
\]

† The introduction of such a composite good raises no difficulty when we are considering the firm in isolation; but it is usually inappropriate for the discussion of general equilibrium, since goods 3 and 4 may be produced by two distinct firms, or consumed by other agents in a proportion other than \( \alpha \).
Let $\lambda, \mu_1$ and $\mu_2$ be the corresponding Kuhn-Tucker multipliers. The necessary conditions for a maximum are

$$\begin{cases}
p_h = \lambda f'_h & \text{for } h = 1, 2 \\
p_3 = \lambda f'_3 + \alpha \mu_2 \\
p_4 = \lambda f'_4 + \mu_1 - \mu_2
\end{cases} \quad (41)$$

where each of the multipliers $\lambda, \mu_1$ and $\mu_2$ must be non-negative, and must be zero when the corresponding constraint is a strict inequality.

If $p_1$ or $p_2$ is positive, as we shall assume, the multiplier $\lambda$ must be positive and the equilibrium $y^0$ must strictly satisfy $f(y^0) = 0$. We can then distinguish three cases:

(i) If the equilibrium is such that $0 < -\gamma_4 < -\alpha \gamma_3$ (the point $M$ on Figure 7), the multipliers $\mu_1$ and $\mu_2$ are zero. System (41) reduces to system (27) exactly as if the constraints (40) did not exist.

(ii) If the equilibrium is such that $\gamma_3 = 0$ and $\gamma_3 < 0$ (point $B$ on Figure 7), $\mu_2 = 0$ and $\mu_1 \geq 0$. After elimination of $\mu_1$, system (27) is replaced by

$$\begin{cases}
p_h = \lambda f'_h & h = 1, 2, 3. \\
p_4 \geq \lambda f'_4
\end{cases} \quad (42)$$

In particular, if the production function takes the form (5), the marginal productivity $g_4$ of good 4 is less than or at most equal to the price ratio $p_4/p_1$.

(iii) If the equilibrium is such that $\gamma_3 = \alpha \gamma_3 < 0$ (point $A$ in Figure 7), $\mu_1 = 0$ and $\mu_2 \geq 0$. System (27) becomes

$$\begin{cases}
p_h = \lambda f'_h & h = 1, 2. \\
p_3 + \alpha p_4 = \lambda(f'_3 + \alpha f'_4) \\
p_3 \geq \lambda f'_3 \quad \text{and} \quad p_4 \leq \lambda f'_4
\end{cases} \quad (43)$$
This brings us back to (39); we can introduce a composite good for the interpretation of the last equality; but we can now identify the individual marginal productivities of inputs 3 and 4 with respect to output 1, namely \( f_3/f_1 \) and \( f_4/f_1 \). We see that the marginal productivity of input 3 is at most \( p_3/p_1 \), and that of input 4 is at least \( p_4/p_1 \). In fact, to increase the input of factor 3 without changing the input of factor 4 is possible but not worth while, whereas to increase the input of factor 4 without changing the input of factor 3 might be worth while but is impossible.

In short, consideration of additional constraints entails some modification in the equilibrium conditions but makes no basic change in their nature.

6. Supply and demand laws for the firm

The theory of the firm must lead to some general properties of supply and demand functions, as happened with the theory of the consumer. In the context of the perfect competition model, the supply function for commodity \( h \) defines how the firm's output of this good varies as the prices of all goods vary. Similarly, the demand function for commodity \( h \) defines how the firm's input of this commodity varies. We shall deal with these two functions simultaneously by considering net supply, which, by definition, is equal to supply for an output and to demand with a change of sign for an input.

The net supply law for commodity \( h \) is therefore that law which defines \( y_h \) as a function of the \( p_1, p_2, ..., p_l \), the set \( Y \) of feasible productions, or the production function \( f \), being fixed. We shall write this law \( \eta_h(p_1, p_2, ..., p_l) \), assuming that \( y^0 \) exists, and is unique, for every vector \( p \) belonging to an \( l \)-dimensional domain of \( R^l \).‡ We can easily establish the following three

‡ In fact, this assumption is more restrictive than appears at first sight. For example, if the production function satisfies the assumption of constant returns to scale and is expressed in the form (5) or (29), the derivatives \( g_i^h \) are homogeneous of degree zero and can therefore be expressed as functions of the \( l - 2 \) variables \( y_2y_1, ..., y_{l-1}y_1 \). Now, there are \( l - 1 \) equations (30), necessary for equilibrium and also sufficient in the case of convexity. If the \( p_h \) are chosen freely, these equations will not generally have a solution. In the particular case where the \( p_h \) are such that a solution exists, \( y^0 \) say, then every proportional vector \( \alpha y^0 \) will also be a solution (\( \alpha > 0 \)).

In economic terms these formal difficulties have the following significance. The decision to produce can be split into two stages: (i) the choice of the technical coefficients \( y_1y_i, ..., y_{l-1}y_i \), (ii) the determination of the volume of production. In the case of constant returns to scale, the two stages are independent of each other and, once the best technical coefficients are chosen, profit is proportional to the volume of production. If it is positive, no equilibrium exists since it is always advantageous to increase production. If it is negative, only zero production gives an equilibrium which does not obey the marginal equalities (30). If profit is zero, then any level of production is optimal.

The most modern versions of microeconomic theory take account of these difficulties: net supply functions can be defined only for a subset of the values that are a priori possible for \( p \) and can then be multivalued. So the term 'supply correspondences' rather than 'supply functions' is used.
properties.

(i) The net supply function is homogeneous of degree zero with respect to
\( p_1, p_2, ..., p_t \) and for any multiplication of these prices by the same positive
number. This is an obvious property since the constraint, \( y \in Y \) or \( f(y) = 0 \),
does not involve \( p \) and the function to be maximised is homogeneous in \( p \).
If \( y^0 \) maximises \( p y \) subject to the constraint, it also maximises \( \alpha p y \) when \( \alpha \) is
positive.

Just as in consumption theory, this homogeneity of net supply functions
shows that the choice of numéraire does not affect equilibrium. Again it can be
be described as ‘the absence of money illusion’.

(ii) The substitution effect of \( h \) for \( k \) is equal to the substitution effect of \( k 
\) for \( h \). Consider the increase in the supply of \( h \) when the price of \( k \) diminishes.
When the net supply functions are differentiable, we can characterise this
‘substitution effect’ of \( h \) for \( k \) by the partial derivative of \( \eta_h \) with respect to \( p_k \).
Property (ii) then expresses the following equality:

\[
\frac{\partial \eta_h}{\partial p_k} = \frac{\partial \eta_k}{\partial p_h}, \quad h, k = 1, 2, ..., l. \tag{44}
\]

To establish this property, we differentiate the system consisting of (27)
and (26) and obtain

\[
\begin{align*}
\lambda \sum_{k=1}^{l} f''_{hk} dy_k + f'_h d\lambda &= dp_h, \quad h = 1, 2, ..., l, \\
\sum_{h=1}^{l} f'_h dy_h &= 0,
\end{align*}
\]

which can be written in matrix form:

\[
\begin{bmatrix}
\lambda F'' & f' \\
\{f'}' & 0
\end{bmatrix}
\begin{bmatrix}
dy \\
d\lambda
\end{bmatrix} =
\begin{bmatrix}
dp \\
0
\end{bmatrix}, \tag{46}
\]

with the obvious notation. This equality shows that the left hand side of (44)
is the element on the \( h \)th row and \( k \)th column of

\[
\begin{bmatrix}
F'' & f' \\
\{f'}' & 0
\end{bmatrix}^{-1}
\]

while the right hand side is the element on the \( k \)th row and the \( h \)th column.
Now, the matrix (47), which we assume here to exist, is clearly symmetric,
which proves the equality.

This property shows that we can say unambiguously whether two goods
are substitutes or complements for the particular firm. We need only look at
the sign of the partial derivative \( \frac{\partial \eta_h}{\partial p_k} \). More precisely, we say that two
outputs or two inputs \( h \) and \( k \) are complements if this derivative is positive,
and are substitutes if it is negative.
(iii) *When the price of a good increases, the net supply of this good cannot diminish.* For the proof of this property we can use the second order condition for an equilibrium and establish that the partial derivative of $\eta_h$ with respect to $p_h$ is not negative. The reasoning is similar to that used for consumer demand (cf. property 3 in Chapter 2, Section 9). We can also proceed directly on the basis of finite differences, which makes the result clearer and more general.

Consider two price vectors, $p^1$ and $p^2$ say, and two corresponding equilibria, $y^1$ and $y^2$. Since $y^1$ maximises $p^1 y$ in the set of the feasible $y$'s and since $y^2$ is feasible, we can write

$$p^1 y^2 \leq p^1 y^1$$

and also

$$p^2 y^1 \leq p^2 y^2$$

or equivalently,

$$- p^2 y^2 \leq - p^2 y^1.$$  \hspace{1cm} (49)

Adding (48) and (49), we obtain

$$(p^1 - p^2)y^2 \leq (p^1 - p^2)y^1$$

or

$$(p^1 - p^2)(y^1 - y^2) \geq 0. \hspace{1cm} (50)$$

This is the general form of the relation of *comparative statics*, which must be obeyed in the comparison of two different equilibria for the same firm.

In particular, if $p^1$ and $p^2$ are identical except where price $p_h$ is concerned, the inequality becomes:

$$(p^1_h - p^2_h)(y^1_h - y^2_h) \geq 0.$$  

This establishes property (iii).

7. **Cost functions**

Suppose that the prices $p_h$ of the different commodities are given and that the firm produces only one good, the good 1 to fix ideas. *The cost function relates to the quantity produced $y_1$, the minimum value of the input mix which yields this production.*

The theory of the firm is often built up on the initial basis of the cost function. This greatly simplifies the analysis, but is subject to criticism on two counts.

In the first place, the relationship between the value of input complex and the quantity produced depends on the prices $p_h$ of the different inputs, so that
the cost function changes when these prices change. The production set or production function are more fundamental since they represent the technical constraints independently of the price system.

In the second place, a production theory based on the analysis of costs is out of place in a general equilibrium theory which treats prices as endogenous and not determined a priori. Since our aim is to lead up to the study of general equilibrium, we must start with production sets or functions.

However, an examination of cost functions reveals certain useful classical properties which are simple to establish at this point and may be needed later. We assume here that the markets for inputs are competitive so that the $p_h$ are given for the firm ($h = 2, 3, ..., l$).

Since we restrict ourselves to the case of only one output, we can take the production function as

$$y_1 = g(y_2, y_3, ..., y_l).$$

Before defining the cost function, we must first find the combination of inputs which allows production of a given quantity $\bar{y}_1$ of commodity 1 at minimum cost, so we must maximise profit subject to the constraint that $y_1 = \bar{y}_1$. This is a particular case of the problem discussed at the start of Section 5 where $\phi(y) = y_1 - \bar{y}_1$. Here the system of first order conditions (37) becomes

$$\begin{cases} p_1 = \lambda + \mu \\ p_h = -\lambda g_h' & \text{for } h = 2, 3, ..., l. \end{cases}$$

The first equation allows us to find $\mu$ and is of no further use. If, as we assume here, the first order conditions are sufficient for cost minimisation, the solution is obtained by determining values of $\lambda$ and of $y_2, y_3, ..., y_l$ which satisfy

$$\begin{cases} g(y_2, y_3, ..., y_l) = \bar{y}_1 \\ p_h = -\lambda g_h' & h = 2, 3, ..., l. \end{cases}$$

(52)

When the firm minimises its cost of production, the marginal rates of substitution of inputs are equal to the ratios of their prices; but the marginal productivity of an input, $h$ for example, is not necessarily equal to $p_h/p_1$. It is equal to $p_h/p_1$ if $\bar{y}_1$ is the optimal production for the firm selling on a competitive market. But for freely chosen $\bar{y}_1$, in most cases it is not equal to this ratio.

Cost $C$ is defined as

$$C = \sum_{h=2}^{l} p_h a_h = -\sum_{h=2}^{l} p_h y_h.$$  

(53)

We need only replace the $y_h$ in this expression by their values in the solution of (52) when we want to determine the cost function, which relates the value of the minimum of $C$ with the production level $\bar{y}_1$ (the $p_h$ being
The producer

considered as given). This function is often assumed to have the form of the curve $C$ in Figure 8.

When looking for the equilibrium of the firm, we can work in two stages:

(i) Define the cost function, that is, determine for each value of $\bar{y}_1$ the $y_2, y_3, \ldots, y_l$ which minimise cost and find the value $C$ corresponding to this minimum cost.

(ii) Choose $\bar{y}_1$ so as to maximise profit $(p_1 \bar{y}_1 - C(\bar{y}_1))$.

The solution of stage (ii) is obvious. The first order condition requires

$$p_1 = C'(\bar{y}_1).$$

Equation (54) shows that, in competitive equilibrium, marginal cost is equal to price of the output. The second order condition requires that the second derivative of the profit is negative or zero, that is, that marginal cost is increasing or constant.

We shall verify that, in (52), $\lambda$ equals the marginal cost. When marginal cost is equated to price $p_1$, the first order conditions for cost minimisation, equations (52), are transformed into first order conditions for profit maximisation, equations (29) and (30).

Let us differentiate (53), the expression for cost, keeping prices $p_1$ constant:

$$dC = - \sum_{h=2}^{l} p_h \, dy_h$$

or, taking account of (52) and, in particular, differentiating the first equation,

$\dagger$ The term 'cost function' is sometimes also used for the function that relates $C$ to $\bar{y}_1$ and to $p_2, p_3, \ldots, p_l$. 
This equation establishes that $A$ equals marginal cost.

We can also verify that the assumption of non-increasing marginal returns implies that marginal cost is increasing or constant. Let us differentiate (52), keeping prices constant:

$$
\begin{align*}
dC &= \lambda \sum_{h=2}^{l} g'_h \, dy_h = \lambda \, d\bar{y}_1. \\
\left( \sum_{h=2}^{l} g'_h \, dy_h = d\bar{y}_1 \right) \\
d\lambda g'_h + \lambda \sum_{k=2}^{l} g''_{hk} \, dy_k = 0 & \quad h = 2, 3, \ldots, l. \\
\end{align*}
$$

Multiply the $h$th equation by $dy_h$; sum for $h = 2, 3, \ldots, l$; take account of the first equation: we obtain

$$
d\lambda \, d\bar{y}_1 + \lambda \sum_{h,k=2}^{l} g''_{hk} \, dy_h \, dy_k = 0. 
$$

Since marginal cost $\lambda$ is positive, the assumption of non-increasing marginal returns implies

$$
d\lambda \cdot d\bar{y}_1 \geq 0 \quad \text{or} \quad \frac{d\lambda}{d\bar{y}_1} \geq 0, 
$$

which is the required result.

So a cost curve derived from a production function with non-increasing marginal returns is concave upwards. The classical curve of the cost function, as exhibited in Figure 8, is concave downwards at the start: this corresponds to the range of values of output for which indivisibilities are significant and marginal returns are increasing.

We note also that marginal cost is rigorously constant when the production function satisfies the assumption of constant returns to scale. The function $g$ is then homogeneous of the first degree, and so

$$
\sum_{h=2}^{l} g'_h y_h = \bar{y}_1; 
$$

hence, taking account of the definition of $C$ and the marginal equalities (52),

$$
C = \lambda \bar{y}_1.
$$

This equation, together with (55) shows that $\lambda$, which a priori is a function of $\bar{y}_1$, is in fact a constant (always assuming that the $p_h$ are fixed).†

† We saw that the assumption of constant returns to scale would usually not hold if all the factors of production were not accounted for in the model. When defining marginal cost, we assumed that the quantities of all the factors could be freely fixed. This latter assumption is inappropriate to factors such as the work capacity of the managing director. So the case of constant marginal cost is not necessarily frequent in relation to a firm some of whose factors cannot vary. (See below the distinction between long-term and short-term costs.)
In addition to total cost $C$ and marginal cost $C'$ we often consider *average cost* per unit of output, namely $c = C/\bar{y}$. If we differentiate $c$ with respect to $\bar{y}$, it is immediately obvious that average cost is increasing or decreasing according as it is greater or less than marginal cost (a typical curve $c$ appears in Figure 8).

It is sometimes convenient to give a diagram representing the last stage in profit maximization. Let the curves $c$ and $\gamma$ represent respectively variations in average cost and marginal cost as a function of $y_1$ for given values of $p_2, p_3, \ldots, p_t$. The equilibrium point $y^0$ is determined by the abscissa $y^0_1$ of the point on the curve $\gamma$ whose ordinate is $p_1$. The profit is then $y^0_1$ times the difference in the ordinates of the points on $\gamma$ and $c$ with abscissa $y^0_1$.

Examination of the figure rounds off the preceding analysis, which was limited to finding necessary conditions for a profit maximum at a point $y^0$ for which constraints other than the production function do not operate. Are these conditions also sufficient, as we assumed earlier when we said that $y^0_1$ corresponds to the equilibrium?

Ambiguity may exist if several points on $\gamma$ have $p_1$ as ordinate. In practice, this is likely to arise only in two ways. In the first place, there may be two such points, one on the decreasing part and the other on the increasing part of the marginal cost curve; the first point cannot correspond to an equilibrium since it does not satisfy the second order condition, so that the ambiguity disappears. Also, at the ordinate $p_1$ the curve $\gamma$ may be flat (in particular, we saw that marginal cost is constant if the production function satisfies the assumption of constant returns); all the points on this flat section give the same profit; if one of them corresponds to an equilibrium, then the others also correspond to equilibria.

The point or points with ordinate $p_1$ and lying on the non-decreasing part of $\gamma$ may not correspond to an equilibrium if it is to the interest of the firm to have zero output $y_1$. This situation arises if $p_1$ is less than the minimum average cost $c_m$ and if $y_1 = 0$ implies zero profit, since the points considered then give negative profit.

Finally, if the whole curve $\gamma$ lies below the ordinate corresponding to $p_1$, there is no limit on the increase of profit and it is to the interest of the firm to go on increasing production indefinitely. (Of course, in practice it would come up against a limit sooner or later, but the chosen cost function ignores this fact.)

To sum up, for given values of $p_2, p_3, \ldots, p_t$, the value of $p_1$ may be such that:

(i) the firm should choose $y_1 = 0$ (low price $p_1$);

(ii) the firm should choose a finite output $y^0_1$, which may or may not be defined uniquely;
(iii) the firm should increase production indefinitely (high price $p_1$).

As we said previously, the existence of situations (i) and (iii), together with the multiplicity of equilibria in (ii), are sufficiently real possibilities to make us avoid trying to prove for producer equilibrium a general property of existence and uniqueness corresponding to that stated for consumer equilibrium in proposition I of Chapter 2.

8. Short and long-run decisions

Cost minimisation has just been presented as a stage in profit maximisation. In fact, abandoning the strict model of perfect competition, we sometimes consider that some firms actually behave so as to provide an exogenously determined output and minimise their production cost. System (52) then applies directly to the equilibrium for the firm.

Similarly, in some contexts, the firm does not choose all, but only some of its inputs, the others being predetermined. Thus for the same firm we often distinguish between long-run decisions relating to the entire organisation of production (choice of equipment and manufacturing processes) and short-run decisions relating to the use of an already existing productive capacity. So for short-run decisions, the inputs relating to capital equipment are fixed.

Such situations can easily be analysed using the principles applied above. Suppose, to fix ideas, that capital equipment is represented by a single good, the $l$th. Let $\bar{y}_l$ be the predetermined value of $y_l$. The short-run decision consists of profit maximisation subject to the constraint $y_l = \bar{y}_l$. The short-run cost function relates cost $C$ to the value $\bar{y}_l$ of output when $y_l = \bar{y}_l$, the other inputs $y_h$ being fixed so as to minimise cost. Let this function be $C^*(\bar{y}_l, \bar{y}_l)$.

As before, we see that inputs $y_2, y_3, \ldots, y_{l-1}$, cost $C^*$ and marginal cost $\lambda^*$ obey the system
Differentiating the first and last equations for given $p_h$ and taking account of the intermediate equalities, we obtain

$$ \frac{dC^*}{dy_1} = \lambda^* \frac{d\bar{y}_1}{dy_1} - (\lambda^* g'_1 + p_1) \frac{d\bar{y}_1}{dy_1}, $$

which replaces (55). The short-run marginal cost is again equal to the equilibrium value of the Lagrange multiplier $\lambda^*$. We could also verify that, to determine the value of $y_1$ which maximises profit subject to the constraint $y_1 = \bar{y}_1$, we must add to (59) the condition that the marginal cost $\lambda^*$ equals $p_1$.

Let us illustrate this theory by a diagram in which the different cost functions are represented as a function of $y_1$. Let $cL$ and $yL$ be the long-run average and marginal cost curves. The long-run equilibrium value of production for price $p_1$ is determined as the abscissa $y_1$ of the point on $yL$ whose ordinate is $p_1$. Also let $cC$ and $yC$ be the short-run average and marginal cost curves. The short-run equilibrium is determined by the abscissa $y^*_1$ of the point on $yC$ whose ordinate is $p_1$.

The long and short-run average cost curves generally have a common point corresponding to the value of $y_1$ for which the solution of (52), defining the long-run cost, gives the value $\bar{y}_1$ for $y_1$. For, the solution of (52) then satisfies (59) with $C^* = C$. Let $y^*_0$ be this particular value of $\bar{y}_1$. At $y^*_0$, the equality $p_1 = -\lambda^* g'_1$ is satisfied, so that $dC^* = \lambda^* \frac{d\bar{y}_1}{dy_1} = dC$. At this point, long and short-run marginal costs are equal, long and short-run average costs are tangential. A priori, this may seem an obvious result, since if existing equipment coincides with what the firm would choose in the long run in the same
price situation, then short and long-run equilibria must naturally coincide.

Hence, the long-run average cost curve is the envelope of short-run average cost curves (obviously the same property holds for total cost curves). In any case, the short-run cost cannot be lower than the long-run cost since the minimisation which defines the former is subject to one more constraint than that which defines the latter.

9. Monopoly

The formal approach developed so far is more or less easily transposed to institutional situations that differ from perfect competition. We may briefly examine here the classical theory of monopoly, leaving for Chapters 6 and 8 the analysis of other situations.

In the applied study of market structures a firm is said to have a monopoly position on the market for commodity \( h \) if it supplies alone this commodity and if demand comes from many agents who are individually small and act independently of one another. Classical monopoly theory represents this situation starting from the hypothesis that the same price \( p_h \) will apply to the exchange of all units of commodity \( h \) but that this price will depend on the quantity \( y_h \) that the seller will supply. Thus the monopoly faces a demand whose quantity varies with the price of his product but is otherwise independent of his decision.

The firm facing such a situation necessarily takes account of the fact that the price at which it will dispose of its output depends on the quantity which it puts on the market. We can no longer analyse its behaviour on the assumption that it considers price as exogenous. We have to adopt a formal model other than that of perfect competition.

Suppose, for example, that the firm produces good 1 and sells it on a market where there are many buyers whose demand depends on price \( p_1 \) and not on other prices.† We can represent this demand by a relation between \( p_1 \) and \( y_1 \):\n
\[
p_1 = \pi_1(y_1),
\]

where \( \pi_1 \) is the function defining the price at which the monopolist can dispose of the volume of production \( y_1 \).

It may also happen that a firm is the only one to use a factor \( h \) (for example, when it is the only employer of labour in a town). It is said to be in a situation of 'monopsony'. It knows that price \( p_h \) depends on the quantity \( a_h = -y_h \)

† The assumption of independence of demand with respect to prices \( p_1, ..., p_i \) is made here for the sake of simplicity. It can obviously be eliminated if prices \( p_2, ..., p_i \) are independent of the decisions of the firm, that is, if the markets for all goods except the first are competitive.
which it uses as input. If it takes no account of the possible interdependence of \(p_h\) and the prices of other goods, the firm will fix its decisions as a function of a supply law

\[
p_h = \pi_h(y_h)
\]

representing the behaviour of the agents supplying the factor \(h\) and indicating the price \(p_h\) which the firm must pay to acquire a quantity \(-y_h\) of \(h\).

We note that the case of perfect competition corresponds to the particular situation where \(\pi_1\) and \(\pi_h\) are constant functions. Therefore we can deal simultaneously with monopoly and with monopsonies concerning one or more factors by treating the case where the firm tries to maximise its profit and takes account of functions \(\pi_h\) relating the price of each good \(h\) to its net production \(y_h\) \((h = 1, 2, \ldots, l)\).

As a function of \(y\) the profit, or net value of production, is

\[
\sum_{h=1}^{l} \pi_h(y_h) \cdot y_h.
\]

Maximisation of this expression subject to the constraint expressed by the production function implies the following first order conditions:

\[
\pi_h + \pi_h' y_h = \lambda f_h' \quad h = 1, 2, \ldots, l,
\]

where \(\pi_h'\) is the derivative of \(\pi_h\) and \(\lambda\) is a Lagrange multiplier.

For what follows, we shall consider the case where prices are non-zero and shall write the above conditions in the form

\[
p_h(1 + \varepsilon_h) = \lambda f_h' \quad h = 1, 2, \ldots, l,
\]

taking account of the fact that \(p_h\) is the value of the function \(\pi_h\) and defining \(\varepsilon_h\) as the inverse of the elasticity of demand (or supply) which occurs in the market for the good \(h\) because of agents other than the particular firm under consideration:

\[
\varepsilon_h = y_h \frac{\pi_h'}{\pi_h} = \frac{d \log \pi_h}{d \log |y_h|'}
\]

In the case of perfect competition, market demand and supply are perfectly elastic from the standpoint of the firm; the \(\varepsilon_h\) are zero. Conditions (64) reduce to the first order conditions (27) obtained earlier.

In order to investigate (64), we shall consider the case where the production function takes the form

\[
y_1 = g(y_2, y_3, \ldots, y_l),
\]

the good 1 being the firm's output. Equations (64) imply

\[
\frac{p_h(1 + \varepsilon_h)}{p_1(1 + \varepsilon_1)} = - g'_h \quad h = 2, \ldots, l
\]
provided that $\varepsilon_1 \neq -1$ in the equilibrium, which we assume for simplicity. The marginal productivity of the factor $h$ is no longer equal to the ratio of prices but to this ratio multiplied by a term depending on the elasticities relating to the factor $h$ and to output.

Consider first the case of a monopsony for which all the $\varepsilon_h$ are zero except that relating to a particular input $k$. Equations (66) then reduce to the perfect competition equations except for the $k$th, where $-g_k$ must equal $p_k/p_1$ multiplied by the term $(1 + \varepsilon_k)$ which is usually greater than 1. The equilibrium is therefore the same as in a situation of perfect competition involving the same prices for all the goods except $k$, whose price is greater than that actually asked by suppliers. Since, in the competitive situation, the firm's demand $\eta_k$ can only decrease, the firm in a position of monopsony usually employs a smaller quantity of the factor $k$ than it would employ in competition. For this reason it may be said to be in the interest of the monopsonist to adopt a 'Malthusian policy'.

We could apply the same reasoning to the case of pure monopoly where all the $\varepsilon_h$ except $\varepsilon_1$ are zero. However we shall adopt a rather different approach for an alternative presentation of the analysis, which is thus reinforced.

As in the case of perfect competition, we can maximise profit by means of a two-stage procedure involving first cost minimisation and determination of the cost function. For a pure monopoly, cost minimisation is carried out in exactly the same way as for a perfectly competitive firm and the cost function is exactly the same. So we can confine ourselves to the second stage, and find the value of $\tilde{y}_1$ which maximises

$$\pi_1(\tilde{y}_1) \cdot \tilde{y}_1 - C(\tilde{y}_1).$$

We can write this expression in its usual form

$$R(\tilde{y}_1) - C(\tilde{y}_1),$$

where $R(\tilde{y}_1)$ denotes the firm's receipts from output $\tilde{y}_1$.

Profit maximisation implies that $\tilde{y}_1$ is so chosen that

$$R'(\tilde{y}_1) = C'(\tilde{y}_1)$$

and

$$R''(\tilde{y}_1) \leq C''(\tilde{y}_1).$$

Equation (68) generalises condition (54) obtained for the case of perfect competition.

We can easily compare monopoly equilibrium with equilibrium for the firm in perfect competition. Figure 11 shows the average cost and marginal cost curves $c$ and $\gamma$, as well as the curve $d$ representing the demand function $\pi_1(y_1)$, that is, average revenue, and the curve $\delta$ representing marginal revenue, that is, the function $\pi_1 + y_1\pi'_1$. Suppose that $\pi'_1$ is negative, as will
necessarily be the case except perhaps for an inferior good; \( \delta \) then lies below \( d \). According to (68), monopoly equilibrium is determined by the abscissa \( y^* \) of the point of intersection of \( y \) and \( d \). If the firm behaves as in perfect competition, that is, if it takes no account of the reaction of price \( p_t \) to its supply \( y_t \), the equilibrium point is determined by the abscissa \( y^0 \) of the point of intersection of \( y \) and \( d \).

At the point of intersection of \( y \) and \( d \), the marginal cost must be non-decreasing for \( y^0 \) to correspond to a true competitive equilibrium. It follows from the fact that \( d \) is decreasing and from the respective positions of \( d \) and \( \delta \) that \( y^* \) is necessarily smaller than \( y^0 \). The firm produces less in a position of monopoly than in a situation of perfect competition involving the same prices for it; this result is similar to that encountered earlier for monopsony.

We can consider \( R'' \) as negative in the interpretation of (69) defining the second order condition for a maximum. In particular it will be negative if there is constant elasticity of demand, since then \( \varepsilon_1 \) is a fixed number, \( R' \) is equal to \( \pi_1(1 + \varepsilon_1) \) and \( R'' \) to \( \pi_1(1 + \varepsilon_1) \). The second order condition is therefore satisfied for any situation where marginal cost is increasing.

But we should point out that this condition may also be satisfied in situations where marginal cost is decreasing. More generally, monopoly may sometimes allow an equilibrium to be realised which is not possible in perfect competition. Figure 12 shows an example for a firm with continually decreasing marginal cost, which is possible in the "undifferentiated sector".†

† We should also note that, for the definition of the cost function, second order conditions implying concavity of the isoquants in the neighbourhood of the equilibrium must be satisfied. When this is not so, no equilibrium exists as long as the markets for the factors are competitive: but a monopsony for the firm may allow equilibrium to be realised.
The study of monopoly has taken us outside the field of perfect competition. We shall not pursue this line for the moment, but shall take it up again in Chapters 6 and 7. However, two remarks may usefully be made already at this stage.

In the first place, it is clear that situations of imperfect competition may involve consumers as well as firms. For example, it is conceivable that a particularly wealthy consumer may have such influence on a market that he has a position of near-monopsony.

In the second place, the theory of imperfect competition cannot depend entirely on the constrained maximum techniques which we have used up till now.

Of course, situations other than those we have considered can be dealt with by constrained maximum techniques, for example, the case of a firm that has a monopoly on each of the two or more independent markets in which its output can be sold. In most cases, profit maximisation leads to price differentiation, the firm releasing to each market a quantity of its product such that marginal revenue from each market equals its marginal cost over all its output.

Generally we can say that constrained maximisation is appropriate to the extent that all agents except at most one adopt a passive attitude, taking the decisions of other agents as given. This is just the situation for a monopoly, since those who demand the product accept as given the price which results from the firm's decision on production. They have no other possible attitude if their number is large and they are all of the same relative importance, and if they are unable to band together in opposition to the monopolist.

But imperfect competition is not limited to such situations. On some
markets there are relatively few buyers and sellers; on others, coalitions take place. Other methods of analysis are necessary to deal with such cases.

We shall return to imperfect competition in Chapters 6 and 7 in order to clarify problems of general economic equilibrium. We shall then see how it relates to the theory of games.
Up till now we have been considering the behaviour of a single agent. With the theory of the optimum we approach the study of a whole society. We therefore change our perspective and attack the problems raised by the organisation of the simultaneous actions of all agents.

The classical approach would be first to discuss competitive equilibrium, keeping to the positive standpoint of the previous lectures, and then to go on to the normative standpoint of the search for the optimum. However, we shall reverse the order of these two questions.

Optimum theory involves a rather simpler and more general model than the model on which competitive equilibrium theory is based. It seems plausible that the relationship of the two theories will be more clearly understood if those assumptions which are not involved in optimum theory are introduced in the later discussion of competitive equilibrium.

We are interested, therefore, in the problem of the best possible choice of production and consumption in a given society. Clearly it may appear very ambitious to attempt to deal with this. But it is one of the ultimate objectives of economic science. Preoccupation with the optimum underlies many propositions briefly stated by economists. By providing an initial formalisation and by rigorously establishing conditions for the validity of classical propositions, optimum theory provides the logical foundation for a whole branch of economics.

We must first find out what is meant by the 'best choice' for the society and go on to study the characteristics of situations resulting from this choice.

1. Definition of optimal states

Before fixing a principle of choice, we must again define what are 'feasible' states.

For our present investigation, a 'state of the economy' consists of $m$ consumption vectors $x_i$ and $n$ net production vectors $y_j$. 
We wish to eliminate states which are impossible of realisation whatever the organisation of the society, that is, states which do not obey the physical constraints imposed by nature. So we say that a state is feasible:

(i) if it obeys the physical or technological constraints which limit the activity of each agent; in particular,

\[ x_i \in X_i \quad \text{for the consumer } i = 1, 2, \ldots, m \quad (1) \]

\[ y_j \in Y_j \quad \text{for the firm } j = 1, 2, \ldots, n \quad (2) \]

(note that we do not introduce the budget constraint for the \( i \)th consumer since it is not 'physical', but results from a particular institutional organisation);

(ii) if it also obeys the overall constraints relating to resources and uses for each good, that is, if total consumption is equal to the sum of total net production and of initial resources:

\[ \sum_{i=1}^{m} x_{ih} = \sum_{j=1}^{n} y_{jh} + \omega_h \quad h = 1, 2, \ldots, l. \quad (3) \]

(We recall that \( \omega_h \) represents the available initial resources of commodity \( h \). Here it is considered as given.)

How can a choice be made from all the feasible states? In order to answer this question, which must be understood as abstracting from any other consideration than production, consumption and exchanges, the following two principles are generally adopted.

In the first place, the choice between two states may be based only on the consumption they allow to individuals (the \( x_{ih} \)) and not directly on the productive operations involved in them (the \( y_{jh} \)). According to this widely adopted rule, consumption by individuals is the final aim of production. Production is not an end in itself.

In the second place, the choice between two states may be based on the preferences of the consumers themselves. For, except in particular cases which our present theory does not deal with,† each consumer \( i \) is generally considered to be in the best position to know whether or not some vector \( x_i^1 \) is better for him than another vector \( x_i^2 \).

For a single consumer the choice is simple, depending on his utility function. One state is preferable to another if it gives a greater utility. A multiplicity of consumers obviously complicates things since their preferences between

† In fact, some acts of public intervention are inspired by the concern to protect individuals against their own spontaneous choices (the banning of certain drugs, high duties on alcoholic beverages, compulsory retirement, etc.). Such intervention shows that collective choices do not always respect individual preferences. Public authorities are sometimes said to act for a better satisfaction of 'merit wants' than would result from individual decisions.
Definition of optimal states

Different states may not agree. Within any human society there exist simultaneously a natural solidarity arising from some coinciding interests and a rivalry arising from conflicting interests. Clearly, where such conflicts exist, individual preferences do not agree.

For the moment, we shall not attempt to solve this basic difficulty, but rather to circumvent it by confining ourselves to a partial ordering of states. For, without having to settle the difficulty, we can declare one state preferable to another if all the consumers actually do prefer it. Thus, following a suggestion first made by the Italian economist Vilfredo Pareto, we can set the following definition:

A state \( E^0 \) is called a 'Pareto optimum' if it is feasible, and if there exists no other feasible state \( E^1 \) such that

\[
S_i(x_i^1) \geq S_i(x_i^0) \quad \text{for} \quad i = 1, 2, \ldots, m
\]

where the inequality holds strictly \( (>) \) for at least one consumer. In other words, \( E^0 \) is a Pareto optimum if it is feasible and if, given \( E^0 \), the utility of one other consumer. The word 'optimum' applied in such a definition was often found too strong, but is commonly used.

Generally there is a multiplicity of such optimal states. Each feasible state can be represented by a point in \( m \)-dimensional space, taking \( S_i(x_i) \) as the \( i \)th coordinate (see, for example, Figure 1 representing the case of two consumers). The feasible states generally define a closed set (\( P \) in Figure 1) in this space. The points representing optimal states belong to a part of, or possibly the whole, boundary of this set (points on the boundary to the right of \( A \)).

Optimum theory establishes a correspondence between optimal states and feasible states realised by the behaviour of the different agents confronted with the same price system. These states are called 'market equilibria'. We shall see later that a general equilibrium of perfect competition is a market equilibrium.

More precisely, we say that a 'market equilibrium' is a state defined by consumption vectors \( x_i \), net production vectors \( y_j \), a price vector \( p \) and incomes \( R_i \) (for \( i = 1, 2, \ldots, m; \ j = 1, 2, \ldots, n \)); this state satisfies equations (3) expressing the equality of supply and demand on the markets for goods; in this state, each consumer maximises his utility subject to his budget constraint and each firm maximises its profit, the price vector \( p \) being taken as given by both consumers and producers.

In this chapter we could work directly on the above model. At the risk of some repetition, it seems preferable to start with two particular cases:

\[\uparrow\] In General Competitive Analysis (Holden-Day, San Francisco, 1971), K. Arrow and F. Hahn use the phrase "Pareto efficient".
(i) the case of an economy with no production, where the only problem is the distribution of the initial resources among consumers (the term distribution optimum will denote a Pareto optimum in such an economy).

(ii) The case of an economy in which we are concerned only with the organisation of production and not with the distribution of the product (the term 'production optimum' for this case will have to be defined precisely).

In fact, to determine an optimal state, we must solve simultaneously the problems raised by the organisation of production and of distribution. But it is important that the student should understand fully the multiple aspects of the theory with which we are presently concerned, and he seems more likely to achieve this if we proceed in stages than if we only deal directly with the general model.†

2. Prices associated with a distribution optimum

We now consider the problem of distributing given quantities $\omega_h$ among $m$ consumers, the possibilities and preferences of the $i$th consumer being defined respectively by a set $X_i$ and a utility function $S_i$. A state of the economy is now represented by the $lm$ numbers $x_{ih}$.

First of all we shall discuss necessary conditions for a state $E^0$, defined by consumptions $x_{ih}^0$, to be a distribution optimum. For this we assume first that, in the space $R^l$, each vector $x_i^0$ lies in the interior of the corresponding set $X_i$, and that each function $S_i$ has first and second derivatives, the first derivatives being neither negative nor all simultaneously zero (assumptions 2 and 3 of Chapter 2). We let $S_i^0$ denote the value $S_i(x_i^0)$.

† The fact that the distribution optimum is here discussed before the production optimum implies no priority of the first over the second one. It is a poor objection to 'neoclassical theory' that it neglects the problems concerning production.
For $E^0$ to be an optimum, it must in particular maximise $S_i$ over the set of feasible states subject to the constraint that the $S_i$ are equal to the corresponding $S_i^0$, for $i = 2, 3, ..., m$. In particular, it must be a local maximum under the same constraints. Let us examine the consequences of this property.

Since each $x_i^0$ lies in the interior of its $X_i$, the constraints on the feasible states reduce, in a neighbourhood of $E^0$, to the equalities (3) between total demands and resources, i.e. in this case:

$$\sum_{i=1}^{m} x_{ih} = \omega_h \quad h = 1, 2, ..., l.$$  \hspace{1cm} (4)

In order that $E^0$ should maximise $S_i$ locally subject to the constraints (4) and

$$S_i(x_i) = S_i^0 \quad i = 2, 3, ..., m,$$  \hspace{1cm} (5)

there must exist Lagrange multipliers $-\sigma_h$ (for $h = 1, 2, ..., l$) and $\lambda_i$ (for $i = 2, 3, ..., m$) such that the expression

$$\sum_{i=1}^{m} \lambda_i S_i(x_i) - \sum_{h=1}^{l} \sigma_h \sum_{i=1}^{m} x_{ih}$$  \hspace{1cm} (6)

where $\lambda_1 = 1$ by convention, has zero first derivatives with respect to the $x_{ih}$ in $E^0$. So there must exist $\lambda_i$'s and $\sigma_h$'s such that

$$\lambda_i S'_i(x) = \sigma_h \begin{cases} h = 1, 2, ..., l, \\ i = 1, 2, ..., r, \\ m. \end{cases}$$  \hspace{1cm} (7)

where $S'_i(x)$ is the value at $x_i^0$ of the derivative of $S_i$ with respect to $x_{ih}$. (Since $\lambda_1 = 1$ and the $S'_i(x)$ are not all simultaneously zero, at least one of the $\sigma_h$ is not zero, none of the $\sigma_h$ is negative and consequently all the $\lambda_i$ are positive.)

The equalities (7) imply

$$\frac{S'_{is}}{S'_{ir}} = \frac{S'_{ax}}{S'_{ar}} \begin{cases} r, s = 1, 2, ..., l, \\ i, \alpha = 1, 2, ..., m. \end{cases}$$  \hspace{1cm} (8)

(provided that $S'_{is}$ and $S'_{ar}$ are not zero).

The marginal rate of substitution of $s$ with respect to $r$ must therefore be the same for all consumers, and this must hold for every pair of goods $(r, s)$. This fairly immediate result is easily explained.

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† For the application of theorem 6 of the appendix we must check that the matrix $G^0$ of the derivatives of constraints (4) and (5) has rank $l + m - 1$. Let $u$ be a vector such that $u'G^0 = 0$; let its $h$-th element be $v_h(h = 1, 2 \ldots l)$ and its $(l + i - 1)$-th element be $w_i(i = 2, 3 \ldots m)$. Corresponding to the derivatives with respect to $x_{ih}$, the vector $u'G^0$ has the component $v_h$, hence $v_h = 0$. Corresponding to the derivative with respect to $x_{ih}(for i \neq 1)$, it has the component $v_h + w_i S_{ih}$, hence $w_i S_{ih} = 0$. But, for a given $i$, the $l$ derivatives $S_{ih}$ are not simultaneously zero; hence $w_i = 0$. So the matrix $G^0$ has rank $l + m - 1$. 

Suppose that, for a particular pair of goods \((r, s)\), the marginal rate of substitution of \(s\) with respect to \(r\) is not the same for two consumers \(i\) and \(a\), but is, for example, higher for \(i\). It then becomes possible to alter the distribution of goods so as to increase \(S_i\) and \(S_a\) simultaneously without affecting the situation of any other consumer. We need only increase \(x_{is}\) by the infinitely small positive quantity \(dv\) and increase \(x_{ar}\) by the infinitely small positive quantity \(du\), at the same time decreasing \(x_{as}\) by \(dv\) and \(x_{ir}\) by \(du\). Both utilities actually increase if \(du\) and \(dv\) are chosen so that

\[
\frac{S_{as}}{S_{ar}} < \frac{du}{dv} < \frac{S_{is}}{S_{ir}}
\]

for then \(dS_i = S_{is} dv - S_{ir} du\) and \(dS_a = S_{ar} du - S_{as} dv\) are both positive. By changing the distribution of the commodities \(r\) and \(s\) between the consumers \(i\) and \(a\) we achieve a state preferred by each of the two consumers. So contrary to our initial assumption, the state considered would not be an optimum. (It was by this kind of reasoning that the necessary conditions for a distribution optimum were first established in economic science.)

Equations (7) recall those obtained for consumer equilibrium (see equations (17) and (18) in Chapter 2). If we consider \(\sigma_h\) as the price of commodity \(h\), they imply that, for any consumer, the marginal rate of substitution of a commodity \(s\) with respect to a commodity \(r\) is equal to the ratio between the price of \(s\) and the price of \(r\).

This similarity between the necessary conditions for a distribution optimum and the equations established in consumption theory suggests the existence of a useful property. Could we not prove that, given adequate definition of prices \(p_h\) and incomes \(R_i\), the distribution optimum \(E^0\) is an equilibrium for each consumer? Let us try to do this.

We set \(p_h = \sigma_h\) and \(R_i = px_i^0\). (Instead of setting \(\lambda_i = 1\), as before, we could assign some other positive value to it; this would change proportionately the values of all the \(\sigma_h\). The resulting arbitrariness is unimportant since, in consumption theory, prices and incomes can be defined only up to a multiplicative constant.)

Can we say that \(x_i^0\) maximises \(S_i(x_i)\) subject to the constraint that \(px_i\) is at most equal to \(R_i\)? We can say so, if the equality between the marginal rates of substitution and the corresponding price ratios, together with the budget equation, constitutes a sufficient condition for \(x_i^0\) to be the maximum in question. Proposition 2 in Chapter 2 establishes that this is the case when the function \(S_i\) is quasi-concave. So we can state:

**Proposition 1.** If \(E^0\) is a distribution optimum such that, for each consumer \(i\), \(x_i^0\) lies in the interior of \(X_i\) and if the utility functions \(S_i\) and the sets
A geometric representation

3. A geometric representation

A geometric representation due to Edgeworth may clarify proposition 1, and in our case will be all the more helpful because the above statement is rather too restrictive. In fact, we could have obtained a more general property by using more powerful methods of reasoning (see Section 10).

Consider the case of two goods and two consumers. Assume that $X_i$ is the set of vectors $x_i$ with no negative component, that is, that the two goods are only consumed. Let $x_{11}$ and $x_{12}$ represent as abscissa and ordinate respectively on a Cartesian graph the quantities consumed by the first consumer. These quantities are bounded above by $\omega_1$ and $\omega_2$, the total available amounts of goods 1 and 2. Overall equilibrium implies

$$\begin{cases}
  x_{21} = \omega_1 - x_{11}, \\
  x_{22} = \omega_2 - x_{12}.
\end{cases}$$

If $M$ represents the first consumer's consumption complex in a feasible state, we can read the second consumer's consumption complex directly from the graph as the components of the vector $MO'$, or as the coordinates of the point $M$ with respect to a system of rectangular axes centred on $O'$ and directed from right to left for abscissae and downwards for ordinates (system $x_{21}O'x_{22}$ in Figure 2). The first consumer's indifference curves, $\mathcal{S}_i^0$ and $\mathcal{S}_i^1$ say, can be drawn on this graph. The second consumer's indifference curves can be drawn by using the system of axes centred on $O'$;
they are, for example, $\mathcal{S}_0^1$ and $\mathcal{S}_1^2$.

A point $M$ on this graph defines a distribution optimum if it lies within the rectangle bounded by the two systems of axes, if the indifference curves $\mathcal{S}_1$ and $\mathcal{S}_2$ which contain it are tangential and if no point on $\mathcal{S}_2$ lies on the right of $\mathcal{S}_1$. (Here we take account of the fact that the function $S_1$ increases from left to right and the function $S_2$ increases from right to left.)

On Figure 2, the two points $M$ and $N$ correspond to distribution optima. The curve passing through these points is such that it contains all the optima. In the case of this figure, we see that there are multiple optima, but also that every feasible state is not an optimum. If the state of the economy is represented by a point $P$ which does not lie on $MN$, we could improve the distribution of the goods 1 and 2 between the two consumers and arrive at a new state preferred by both consumers.

If $S_1$ and $S_2$ are quasi-concave, the curves $\mathcal{S}_1$ are concave towards $O'$ and the curves $\mathcal{S}_2$ are concave towards $O$. Given a point $M$, therefore, we need only verify that the two curves $\mathcal{S}_1^0$ and $\mathcal{S}_2^0$, which contain it, are mutually tangential to establish that $M$ represents a distribution optimum.

If $MT$ is the common tangent at $M$, the marginal utilities of the two goods are proportional to the components of a vector normal to $MT$. We can then define $p_1$ and $p_2$ as the components of any vector $p$ normal to $MT$. When the two consumers are assigned the incomes $R_1 = px_1^1$ and $R_2 = px_2^2$ respectively, the consumption zones obeying the budget constraints are bounded by the tangent $MT$, on the right for the first consumer and on the left for the second. If $S_1$ and $S_2$ are quasi-concave, $M$ appears as an equilibrium point for each consumer.

We note also that to two different optima such as $M$ and $N$ on our diagram, there generally correspond different prices and incomes. For the first consumer, the optimum furthest to the right is the most favourable; it is often also the optimum for which the distribution of incomes is most favourable to him (the ratio $R_1/R_2$ is greatest.)

The above geometric representation allows rapid examination of cases where the various assumptions adopted for the statement of proposition 1 are not satisfied. Let us briefly consider three of these assumptions.

(i) We assumed $S_1$ and $S_2$ to be differentiable. Figure 3 illustrates a case where they are not. The indifference curves are not properly speaking tangential at $M$. Nevertheless, there exists a line $MT$ entirely on the left of $\mathcal{S}_1^0$ and on the right of $\mathcal{S}_2^0$. So the property which interests us still exists, the

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† We leave it to the reader to construct an example where the point $M$ is more favourable to the first consumer than the point $N$, while the ratio $R_1/R_2$ is smaller at $M$ than at $N$. 

---
point $M$ appearing as an equilibrium for the two consumers whenever prices define the normal to $MT$ and incomes are suitably chosen.

We note also that, in this case, $MT$ may have several positions and consequently that the direction of the price vector is no longer defined uniquely.

(ii) We assumed that, in the optimum $E^0$, each $x^0_i$ is contained in the interior of the corresponding set $X^*_i$; that is, that the point $M$ of our geometric representation lies within the rectangle with vertices $O$ and $O'$. Figure 4 represents a case where $M$ lies on the boundary of the rectangle (zero consumption of good 2 by the second consumer). The property established by proposition 1 is still valid, with $M$ constituting an equilibrium point for the first and for the second consumer subject to suitably chosen prices and incomes.

Since $S_1$ is taken to be differentiable, the direction of the price vector is defined uniquely and, in the equilibrium, we have

$$\frac{S'_{12}}{S'_{11}} = \frac{p_2}{p_1}.$$ 

But, for the second consumer, the equality is replaced by an inequality

$$\frac{S'_{22}}{S'_{21}} \leq \frac{p_2}{p_1}.$$ 

In this equilibrium, where his consumption of the second good is zero, the second consumer considers the marginal rate of substitution of good 2 relative to good 1 to be less than, or at most equal to, its relative price. We investigated this situation in Chapter 2, Section 7.

(iii) As the above two examples suggest, we could eliminate almost completely from the proof of proposition 1 the assumptions that the $S_i$ are differentiable and that $x^0_i$ is contained in the interior of $X_i$. We also assumed that the indifference curves were concave to the right for the first consumer.
and concave to the left for the second. We can easily construct examples where this condition is not satisfied and the property under discussion still applies. But we could not dispense completely with the assumption in the statement of a general property. This will be demonstrated by the following example.

In Figure 5, the point $M$ is a distribution optimum. At this point, the indifference curve $\mathcal{I}_1^0$ is concave to the left, contrary to our assumption. The two curves $\mathcal{I}_1^0$ and $\mathcal{I}_2^0$ do in fact have a common tangent $MT$ at $M$. The marginal rate of substitution of the second good with respect to the first is the same for both consumers. But the state $E^0$ represented by $M$ can no longer be realised as an equilibrium for each consumer. If a price vector $p$, normal to $MT$, is chosen and if incomes $px_1^0$ and $px_2^0$ are assigned to the two consumers, then the second will choose the point $M$, but the first will choose on $MT$ the point $N$, which, for him, belongs to the most favourable indifference curve. The resulting state will not be feasible since it does not satisfy the necessary equalities of demand and supply, consumption of the first good being too low and consumption of the second too high.

![Fig. 5](image_url)

Of course, this example may be considered to have little relevance if the adopted assumption of concavity is thought to apply to individual indifference curves. We shall return to it in Chapter 7 when discussing the case where there are many consumers.

4. The optimality of market equilibria

We can now establish the converse to proposition 1:

**Proposition 2.** If $E^0$ is a feasible state, if there exist prices $p_h \geq 0$ ($h = 1,$
2, ..., l) such that, for all \( i = 1, 2, \ldots, m \), \( x_i^0 \) maximises \( S_i(x_i) \) in \( X_i \) subject to the constraint \( px_i \leq px_i^0 \), and finally, if the \( S_i \) and the \( X_i \) satisfy assumptions 1 and 2 of Chapter 2, then \( E^0 \) is a distribution optimum.

For the proof of proposition 2 we shall assume that, contrary to this proposition, there exists a feasible state \( E^1 \) which is better than \( E^0 \) in the sense that

\[
S_i(x_i^1) \geq S_i(x_i^0) \quad \text{for} \quad i = 1, 2, \ldots, m
\]

where the inequality holds strictly for at least one consumer, say the last consumer:

\[
S_m(x_m^1) > S_m(x_m^0).
\]

Since \( x_m^0 \) maximises \( S_m \) subject to the constraint that \( px_m \leq px_m^* \), the following inequality holds:

\[
px_m^1 > px_m^0.
\]

We shall show also that

\[
px_i^1 \geq px_i^0 \quad \text{for} \quad i = 1, 2, \ldots, m.
\]

As we have just seen, this inequality certainly holds when \( S_i(x_i^1) \) is greater than \( S_i(x_i^0) \). Suppose that it does not hold for a consumer \( i \) for whom \( S_i(x_i^1) = S_i(x_i^0) \). We then have \( px_i^1 < px_i^0 \). The vector \( x_i^1 \) maximises \( S_i(x_i) \) subject to the constraint \( px_i \leq px_i^0 \). But this contradicts the result of proposition 1 of Chapter 2 which demands that

\[
px_i^1 = px_i^0.
\]

(The proposition stipulates that \( p_h > 0 \) for all \( h \), but \( p_h \geq 0 \) is sufficient for that part of the proof of this proposition with which we are now concerned). This establishes the inequality (12).

The inequalities (11) and (12) imply

\[
p\left[\sum_{i=1}^{m} x_i^1 - \sum_{i=1}^{m} x_i^0\right] > 0,
\]

which contradicts condition (4) for overall equilibrium:

\[
\sum_{i=1}^{m} x_i^1 = \sum_{i=1}^{m} x_i^0 = \omega
\]

since, by hypothesis, \( E^0 \) and \( E^1 \) are two feasible states. This establishes the proof of proposition 2.

We note that the proposition does not involve the assumption that the functions \( S_i \) are quasi-concave. Nor does the proof involve some of the properties spelled out in assumptions 1 and 2 of Chapter 2 (the fact that the \( X_i \) are convex, closed and bounded below, or that they contain the vector \( O \)). So the stated property has wide general validity.
5. Production optimum

We now consider the problem of the organisation of production independently of that of the distribution of goods. We wish to define and characterise situations in which the productive activity of all firms yields the highest possible final productions.

The result of the productive operations is a vector \( y \) of total net productions, the sum of the vectors \( y_j \) relating to the different firms:

\[
y_h = \sum_{j=1}^{m} y_{jh} \quad h = 1, 2, \ldots, l.
\]

(In most cases, the sum on the right hand side contains both positive terms, for the firms \( j \) which have the food \( h \) as output, and negative terms for the firms which use the good \( h \) as input.)

If, as we have assumed, utilities increase as a function of the \( x_{ih} \), it is always advantageous to replace a vector \( y^1 \) of total net productions by another vector \( y^2 \) all of whose components are greater. It is therefore natural to make the following definitions.

(a) A state \( E^0 \), defined here by the \( n \) vectors \( y^0_j \), is feasible if \( y^0_j \in Y_j \) (for \( j = 1, 2, \ldots, n \)).

(b) A state \( E^0 \) is a production optimum (or \( E^0 \) is said to be efficient) if it is feasible, and if there exists no other feasible state \( E^1 \) such that

\[
y^1_h \geq y^0_h \quad \text{for} \quad h = 1, 2, \ldots, l
\]

where the inequality holds strictly for at least one \( h \).

It is immediately obvious that these definitions are rather simplistic. We often assume that commodities can be grouped into three categories: primary goods, intermediate goods and final goods. Only final goods are considered to be used for consumption while initial resources consist only of primary goods.

If this is so, there are additional conditions for a state \( E^0 \) defined by \( n \) vectors \( y^0_j \) to be really feasible. Total net production \( y^0_q \) of the primary resource \( q \) must be at least \(-w_q\); total net production \( y^0_r \) of the intermediate good \( r \) must be non-negative; finally, net productions of final goods must be such that they can be distributed among consumers so that each consumer is given a consumption vector which is feasible for him.

Moreover, it is not always advantageous to increase the net production of a good \( h \). Suppose, for example, that the feasible state \( E^1 \) differs from the feasible state \( E^0 \) only in the respect that \( y^0_s = 0 \) and \( y^1_s > 0 \) for a (non-stockable) intermediate good \( s \). Then \( E^1 \) is not really more advantageous than \( E^0 \); if \( E^1 \) is declared to be optimal, so also should \( E^0 \).

This classification of goods into three categories, primary, intermediate
Production optimum

and final, has been introduced in detailed theories of the production optimum. It obviously complicates the exposition, but has little effect on the logical structure. So, for simplicity, we shall keep to the definition given above.

As in the case of the distribution optimum, we shall first try to find necessary conditions for a vector \( y^0 \) to be a production optimum. For this we shall assume that \( y_j \) is restricted only by a differentiable production function

\[
f_j(y_j) = 0,
\]

that is, we ignore the additional constraints that possibly limit production.†

As we have seen, the mathematics becomes very heavy if we take account of these constraints, and in fact, other methods of reasoning are then required. We shall return to this point in Section 10, which gives the elements for a modern proof of the property under discussion.

If \( E^0 \) is a production optimum, then it maximises \( \sum_j y_{j1} \) subject to the constraints

\[
\sum_{j=1}^m y_{jh} = y^0_h \quad h = 2, 3, ..., l
\]

\[
f_j(y_j) = 0 \quad j = 1, 2, ..., n.
\]

Therefore there exist Lagrange multipliers‡

\[
\sigma_1 = 1, \quad \sigma_h \quad \text{and} \quad -\mu_j (h = 2, 3, ..., l; j = 1, 2, ..., n)
\]

such that the expression

\[
\sum_{h=1}^{l} \sigma_h \sum_{j=1}^{n} y_{jh} - \sum_{j=1}^{n} \mu_j f_j(y_j)
\]

has zero first derivatives with respect to the \( y_{jh} \); or such that

---

† We can write the technical constraint directly in the form of (14) by confining ourselves to 'technically efficient' productions for each firm. In fact, a state \( E^0 \) in which \( f_j(y^0_j) < 0 \) for a firm \( j \) is not a production optimum since \( y^0_j \) can be replaced by a feasible vector \( y^0_j \) with larger components, without changing the other firms' productions.

‡ For the application of theorem VI of the annex, we require that the \( f_j \) are not all zero, which is always the case perhaps after a relabelling of the commodity index (the \( f_j \) are not all zero). Indeed, consider the matrix \( G^0 \) of the derivatives of the constraints (15) and the equation \( u'G^0 = 0 \) where the vector \( u \) has the components \( u_h(h = 2 ... l) \) and \( w_j(j = 1, 2 ... n) \). It may be written as:

\[
\begin{align*}
w_j f'_j &= 0 \quad j = 1, 2 ... n \\
u_h + w_j f'_h &= 0 \quad j = 1, 2 ... n; h = 2 ... l
\end{align*}
\]

If \( f'_j \neq 0 \) then \( w_h = 0 \), hence \( u_h = 0 \) for all \( h \); hence also \( w_j = 0 \) for all \( j \) (not all derivatives of \( f_j \) are zero). The matrix \( G^0 \) has rank \( l + n - 1 \) as is required.
Optimum theory

\[ \sigma_h = \mu_j f'_{jh} \quad \begin{cases} h = 1, 2, \ldots, l \\ j = 1, 2, \ldots, n, \end{cases} \]  

(17)

where \( f'_{jh} \) denotes the value at \( y^o_j \) of the derivative of \( f_j \) with respect to \( y_jh \). No \( f'_{jh} \) is negative, as we saw at the end of the first section of Chapter 3. Since \( \sigma_1 = 1 \) and \( f'_{j1} \geq 0 \), then \( \mu_j \) is necessarily positive.\( ^{\S} \)

For the existence of numbers \( \sigma_h \) and \( \mu_j \) satisfying (17), it is necessary that

\[ \frac{f'_{js}}{f'_{jr}} = \frac{f'_{bs}}{f'_{br}} \quad \begin{cases} r, s = 1, 2, \ldots, l \\ j, \beta = 1, 2, \ldots, n. \end{cases} \]  

(18)

Whenever \( f'_{jr} \) and \( f'_{br} \) are non-zero, the marginal rate of substitution of the good \( r \) with respect to the good \( s \) must be the same in all firms, and this must hold for any pair of goods \((r, s)\).

This condition can be obtained directly by showing that, if it is not satisfied for a pair of commodities and a pair of firms, then global net productions can be increased for the two commodities in question by means of infinitely small appropriate variations in the corresponding \( y_{js}, y_{jr}, y_{bs}, y_{br} \). It is sufficient to apply the reasoning used in the discussion of the distribution optimum.

Equations (17) recall those obtained in the investigation of equilibrium for the firm (see equations (27) in Chapter 3). If \( \sigma_h \) is interpreted as the price of commodity \( h \), they imply that, for each firm, the marginal rates of substitution are equal to the corresponding price-ratios.

If we set \( p_h = \sigma_h \), equations (17) together with the production functions (14) are equivalent to the first order conditions that \( y^o \) should satisfy in order to be an equilibrium for the firm \( j \) in a competitive situation. Now, these first-order conditions are also sufficient for an equilibrium if the production set \( Y_j \) satisfies the assumption of convexity (see proposition 1, Chapter 3). We can therefore state the following result which transposes proposition 1 to the theory of the production optimum.

**Proposition 3.** If \( E^o \) is a production optimum and if, for each firm \( j \), the technical constraints satisfy the assumption of convexity and imply only \( f_j(y_j) \leq 0 \), where \( f_j \) is a differentiable function all of whose first derivatives are not simultaneously zero at \( y^o_j \), then there exist prices \( p_h \) such that \( y^o_j \) maximises \( p_y_j \) over the set of all technically feasible \( y_j \), and this is true for all \( j \).

In a certain sense, this statement is too restrictive, since it makes assumptions about the technical constraints which could be partly eliminated if a

\( ^{\S} \) We note that the \( \sigma_h \) and \( \mu_j \) continue to exist if the arguments of the production functions are quantities only of those goods which are of interest to the corresponding firms, rather than quantities of all goods. Equations (17) must be written only for the \( h \)'s in which the \( j \)th producer is interested; but this does not affect the rest of the proof.
different type of mathematical reasoning were adopted (see Section 10).

The importance of the assumptions for the stated property will be made intuitively obvious if we refer to a convenient geometric representation. Suppose there are only two goods and two firms. To simplify the figure, we shall assume that each firm can produce the two goods simultaneously. (In fact, this can only be advantageous if the firms dispose of inputs which are not represented in the model.)

Consider a Cartesian graph with \( y_{j1} \) as abscissa and \( y_{j2} \) as ordinate. The vector \( y \) with components \( y_{11} \) and \( y_{12} \) is restricted to belong to a set \( Y_1 \) whose boundary \( \bar{Y}_1 \) only is represented on the diagram (the feasible vectors lie on or below \( \bar{Y}_1 \)). Similarly \( y_2 \) is restricted to belong to the set \( Y_2 \) whose boundary is \( \bar{Y}_2 \). The vector \( y \), the sum of \( y_1 \) and \( y_2 \), is restricted to belong to a set \( Y \) which can be constructed, point by point, from \( Y_1 \) and \( Y_2 \) (this set is said to be the 'sum' of \( Y_1 \) and \( Y_2 \); it should not be confused with the union of \( Y_1 \) and \( Y_2 \)). The boundary \( \bar{Y} \) of \( Y \) is clearly the envelope of the curve \( Y_1 + y_2 \) as \( y_2 \) varies along \( \bar{Y}_2 \) (the curve \( Y_1 + y_2 \) is deduced from \( Y_1 \) by a translation of the origin to \( y_2 \)).

A production optimum is represented by a pair of vectors \((y_1^0, y_2^0)\) whose sum \( y^0 \) belongs to the boundary \( \bar{Y} \) of \( Y \). For such a state, the tangents to \( Y_1 \) at \( y_1^0 \), to \( Y_2 \) at \( y_2^0 \), and to \( Y \) at \( y^0 \) are all parallel. (This is a well-known result in geometry which we arrive at easily from our proof of proposition 3.) The marginal rate of substitution of good 2 with respect to good 1 is the same for both firms. The price vector is therefore defined (apart from a multiplicative constant) by the common normal to the three tangents.

\[ \text{Fig. 6} \]

It is obvious from this type of figure that the assumption of differentiability,
necessary for unambiguous definition of the marginal rates of substitution, is not necessary for the existence of prices with respect to which the production optimum corresponds to competitive equilibria for the firms. Figure 7 provides an example of this. For the pair \((y_1^0, y_2^0)\), the direction of the price vector is defined uniquely; for the pair \((y_1^0, y_2^0)\), this direction may vary within a small angle; but in both cases, the property stated in proposition 3 holds. Similarly, it is intuitively obvious that the existence of rigid proportionalities between inputs in certain firms does not affect the property, since its only effect is to give a particular form, illustrated by Figure 4 in Chapter 3, to the corresponding sets \(Y_j\).

Figure 8 refers to the case where a production set \((Y_1)\) is not convex (this set contains the points lying on or below the curve passing through \(y_1^0\)). The pair \((y_1^0, y_2^0)\) defines a production optimum. The marginal rates of substitution are the same in both firms. With the corresponding price vector, \(y_2^0\) is an equilibrium point for the second firm; but \(y_1^0\) is not an equilibrium point for the first, since it does not maximise profit \(p y_1\) in \(Y_1\) (in fact, it corresponds to a minimum of \(p y_1\) along the boundary \(Y_1\)).

This diagram illustrates the difficulty faced by firms in the 'undifferentiated sector' whose production functions do not satisfy the assumption of convexity. A given production optimum may be expressed, for firms in this sector, by vectors \(y_j^0\) which do not maximise their profits. The realisation of such an optimum is incompatible with the purely competitive management of such firms. We shall return to this point in Section 6.
Like proposition 1, proposition 3 has a converse which does not involve the assumption of convexity. We shall prove the following result:

**Proposition 4.** If the $y^*_j$ are technically feasible, if there exist prices $p_h$ ($h = 1, 2, \ldots, l$) which are all positive and such that each $y^*_j$ maximises $py_j$ over the set $Y_j$ of technically feasible $y_j$'s, then the state $E^0$ defined by the $y^*_j$'s constitutes a production optimum.

For, suppose that there exist technically feasible $y^*_j$'s such that

$$\sum_{j=1}^{n} y^*_{jh} \geq \sum_{j=1}^{n} y^*_j \quad h = 1, 2, \ldots, l,$$

where the inequality holds strictly at least once. Since the $p_h$ are all positive, it follows that

$$\sum_{j=1}^{n} py^*_j > \sum_{j=1}^{n} py^*_j,$$

which obviously contradicts the assumption that each $y^*_j$ maximises the corresponding quantity $py_j$ over the set of technically feasible $y_j$.

### 6. Increasing returns and concave isoquants

Proposition 3 relating to the production optimum excludes indivisibilities or increasing returns, which are in fact important in some branches of industry and some public services. We must clearly investigate the conditions for the efficient participation of such firms in an economy that otherwise uses prices to regulate production decisions.

For this, we shall consider a particular case where a firm (the first) operates in technological conditions which are not compatible with convexity of the set of feasible net productions. The only output of this firm is the good 1; its isoquants are concave upwards, as is required by convexity, but a doubling of all inputs results in more than doubled output. The other firms satisfy the assumptions of the previous section.

This case is particular even for the first firm in that it completely excludes indivisibility of inputs. By examining it, we shall, however, see how the property stated in proposition 3 is affected by 'non-convexities'. We shall also discuss another example of non-convexity in Chapter 9, Section 4.

Let us write the production function of the first firm in the form

$$y_{11} = g_1(y_{12}, y_{13}, \ldots, y_{1l}),$$

where the function $g_1$ is assumed to be quasi-concave but not concave (the isoquants are convex upwards but returns to scale are increasing).

If $E^0$ is a production optimum, there exist $\sigma_h$'s and $\mu_j$'s such that equations
(17) are satisfied, since the first part of the proof of proposition 3 does not involve the assumption of convexity. If prices $p_h$ are defined as equal to the $\sigma_h$, the marginal productivities of the different inputs in firm 1 are proportional to the prices of these inputs. Since $g_1$ is quasi-concave, this implies that the vector $y_1^0$ minimises the cost of production in the set of all feasible vectors $y_1$ containing the same output $y_1^0$. Moreover, the fact that the $-g_{1h}$ are equated to the ratios $p_h/p_1$ ensures that the marginal cost is $p_1$ (see Chapter 3, Section 7).

Thus, the prices associated with the production optimum $E^0$ are such that the following two properties hold:

(i) The vector $y_1^0$ is an equilibrium if the firm acquires its inputs at the price in question and if it is restricted to produce the quantity $y_1^0$ contained in the optimum considered.

(ii) The price of the output is equal to the marginal cost when the quantity produced is $y_1^0$, and the prices of the inputs are the $p_h$.

So the realisation of the optimum $E^0$ is compatible with the following management rule for the firm: it should (i) produce an output $y_1^0$, which is fixed for it, (ii) minimise its cost calculated from the prices $p_h$ associated with $E^0$ (for $h = 2, ..., l$), (iii) sell its product at marginal cost. This management rule is in fact often suggested for public undertakings.

Clearly, this case can be generalised and appropriate management rules found for more complex situations. If, for example, the last input, the good $l$, is subject to indivisibilities, but if convexity holds for the set of possible vectors $y_1$ such that $y_{11} = y_{11}^0$ and $y_{11} = y_{11}^0$, the rule must specify not only the quantity of output, but also the quantity of the last input. Thus cost minimisation must often be restricted to short-run decisions when longer-run decisions involve indivisibilities.

Also, for any firm with a single output, marginal cost must equal the price of this output, the cost being computed from the vector of the $p_h = \sigma_h$ associated with the production optimum, and this must be so independently of any assumption relating to convexities. The only condition is that marginal cost must be well defined, that is, that the function $C_1(y_{11})$ expressing variations in cost at given prices should be differentiable.

Here we shall conclude our rapid investigation of a case where convexity is lacking.† The management rules we have established are less simple than those for market equilibrium. They would certainly be less spontaneously adopted by the firm. They assume previous determination not only of prices, but also of certain quantitative data (the production target $y_{11}^0$, for

---

† To attempt a generalisation of this case, or even a study of other aspects than the one discussed here, would reveal how complex are the problems raised by increasing returns. See R. Guesnerie, 'Pareto Optimality in Non-Convex Economies', *Econometrica*, January 1975.
example). After the following chapters, the reader will be in a better position to judge how far the presence of indivisibilities prejudices the efficient, decentralised organisation of production.

7. Pareto optimality

We have considered in some detail the theories of the distribution optimum and the production optimum. We can now deal rapidly with the theory of Pareto optimality, which supersedes the previous two analyses.

Suppose then that a state $E^0$ is a Pareto optimum and that the $x_i^0$ contained in it lie in the interior of the corresponding $X_i$. The function $S_i$ must be locally maximised over the set of feasible states subject to the constraint that the $S_i$ are equal to the $S_i(x_i^0)$ for $i = 2, 3, ..., m$. For maximisation, the following constraints apply:

\[ S_i(x_i) = S_i(x_i^0) \quad i = 2, 3, ..., m \]  
\[ f_j(y_j) = 0 \quad j = 1, 2, ..., n \]  
\[ \sum_{i=1}^{m} x_{ih} = \sum_{j=1}^{n} y_{jh} + \omega_h \quad h = 1, 2, ..., l \]

(21)  
(22)  
(23)

There necessarily exist Lagrange multipliers\(\dagger\) $\lambda_i = 1$, $\lambda_i$ (for $i = 2, 3, ..., m$), $-\mu_j$ (for $j = 1, 2, ..., n$), $-\sigma_h$ (for $h = 1, 2, ..., l$) such that

\[ \sum_{i=1}^{m} \lambda_i S_i(x_i) - \sum_{j=1}^{n} \mu_j f_j(y_j) - \sum_{h=1}^{l} \sigma_h \left[ \sum_{i=1}^{m} x_{ih} - \sum_{j=1}^{n} y_{jh} \right] \]

(24)

has zero derivatives with respect to the $x_{ih}$ and $y_{jh}$ in $E^0$. In other words, there necessarily exist $\lambda_i$'s, $\mu_j$'s and $\sigma_h$'s such that $E^0$ satisfies the system

\[
\begin{cases}
\lambda_i S'_i = \sigma_h & \text{for } h = 1, 2, ..., l \\
\mu_j f'_j = \sigma_h & \text{for } i = 1, 2, ..., m
\end{cases}
\]

(25)

These equalities correspond to (7) and (17) above. They imply

\[ \frac{S'_s}{S'_r} = \frac{S'_a}{S'_r} = \frac{f'_s}{f'_r} = \frac{f'_s}{f'_r} \quad r, s = 1, 2, ..., l \]

\[ \frac{S'_a}{S'_r} = \frac{f'_s}{f'_r} = \frac{f'_s}{f'_r} \quad i, \alpha = 1, 2, ..., m \]

\[ j, \beta = 1, 2, ..., n \]

(26)

The marginal rate of substitution of $s$ with respect to $r$ must be the same for all consumers; it must equal the marginal rate of transformation of $s$ with respect to $r$, which must be the same for all firms.

\(\dagger\) Following the same line of argument as for the distribution optimum, one can prove that the matrix $G^0$ giving the derivatives of the constraints has rank $l + m + n - 1$, so that theorem VI of the appendix applies.
This necessary equality of substitution rates and transformation rates can be proved directly by showing that, if the ratio $S_i/S_i'$ exceeds the ratio $f_j/y_j$, then $S_i$ can be increased, without changing the utilities of the other consumers, by increasing $x_{is}$ and $y_{js}$ by $f_j du$ and by simultaneously decreasing $x_{is}$ and $y_{js}$ by $f_j du$, where $du$ is a small enough positive quantity.

If we consider $\sigma_h$ as the price of commodity $h$, we can interpret equations (25) as necessary first-order conditions for equilibria for the different consumers and the different firms. So the state $E^0$ appears as a market equilibrium with prices $p_h = \sigma_h$ if these first-order conditions are sufficient as well as necessary.

We can now state the following result, which synthesizes propositions 1 and 3:

**PROPOSITION 5.** If $E^0$ is a Pareto optimum, such that, for each consumer $i$, the vector $x_i^0$ is contained in the interior of $X_i$, if the utility functions $S_i$ and the $X_i$ obey assumptions 1 to 4 of Chapter 2, and if, for each firm $j$, the technical constraints obey the assumption of convexity and imply only $f_j(y_j) \leq 0$, where $f_j$ is a differentiable function all of whose first derivatives are not simultaneously zero at $y_j^0$, then there exist prices $p_h$ for all goods and incomes $R_i$ for all consumers such that

(i) $x_i^0$ maximises $S_i(x_i)$ subject to the constraint $px_i \leq R_i$, for $i = 1, 2, \ldots, m$.
(ii) $y_j^0$ maximises $p y_j$ subject to the constraint $f_j(y_j) \leq 0$, for all $j = 1, 2, \ldots, n$.

A geometric representation of the case of a single consumer and a single firm will round off Figures 1 and 5 and may clarify proposition 5.

Let the quantities consumed by the consumer, $x_1$ and $x_2$ say, be represented on a graph as abscissa and ordinate respectively. Let $\overline{Y} + \omega$ be the boundary of the set of vectors of realisable consumption, that is, the vectors which can be written $y + \omega$ where $y$ is a vector belonging to $Y$.

![Fig. 9](image-url)
Let the point \( x^0 \) represent the consumption vector of an optimal state. An indifference curve \( \mathcal{S}^0 \), which must contain no point on the left of \( \bar{Y} + \omega \), passes through \( x^0 \). If, as is assumed by proposition 5, \( \mathcal{S}^0 \) is concave upwards and \( \bar{Y} + \omega \) is concave downwards, these two curves have a common tangent at \( x^0 \) and lie on either side of this tangent. The vector \( x^0 \) appears as an equilibrium point for the firm and for the consumer; the price vector is the normal to the tangent and the consumer's income is \( px^0 \).

Obviously proposition 5 has a converse.

**Proposition 6.** If \( E^0 \) is a feasible state, if there exist prices \( p_h \geq 0 \) (\( h = 1, 2, \ldots, l \)) such that, for all \( i = 1, 2, \ldots, m \), the vector \( x_i^0 \) maximises \( S_i(x_i) \) over \( X_i \) subject to the constraint \( px_i \leq px_i^0 \) and also that, for all \( j = 1, 2, \ldots, n \), the vector \( y_j^0 \) maximises \( p y_j \) over \( Y_j \), if finally, the \( S_i \) and the \( X_i \) satisfy assumptions 1 and 2 of Chapter 2, then \( E^0 \) is a Pareto optimum.

For, suppose that there exists a possible state \( E^1 \) such that

\[
S_i(x_i^1) \geq S_i(x_i^0) \quad \text{for} \quad i = 1, 2, \ldots, m,
\]

where the inequality holds strictly for at least one consumer. In the proof of proposition 2 we saw that this implies

\[
p \left[ \sum_{i=1}^{m} x_i^1 - \sum_{i=1}^{m} x_i^0 \right] > 0. \tag{27}
\]

Also, since \( y_j^0 \) maximises \( p y_j \) in \( Y_j \) and \( y_j^1 \) belongs to \( Y_j \), we can state

\[
p y_j^1 \leq p y_j^0 \quad j = 1, 2, \ldots, n
\]

and so

\[
p \left[ \sum_{j=1}^{n} y_j^1 - \sum_{j=1}^{n} y_j^0 \right] \leq 0. \tag{28}
\]

Now, it is clear that (27) and (28) are incompatible with the equilibrium condition

\[
\sum_{i=1}^{m} x_i^1 - \sum_{j=1}^{n} y_j^1 = \sum_{i=1}^{m} x_i^0 - \sum_{j=1}^{n} y_j^0 = \omega. \tag{29}
\]

This completes the proof of proposition 6.

8. Optimum and social utility function

Except in the trivial case of a single consumer, there are generally multiple optimal states, as is shown in Figure 2. This results from the fact that we have only a partial ordering of the set of feasible states.

To eliminate this indeterminacy, we must introduce a complete ordering of states. It is desirable in logic that this new ordering should be compatible
with the ordering so far used, in the sense that a state \( E^1 \) preferred to another state \( E^2 \) after the partial ordering should still be preferred to it after the complete ordering.

Starting from this principle, it has sometimes been suggested that states be classified according to the values they give for a social utility function, that is, a real function whose arguments are the \( m \) values of the individual utilities of the \( m \) consumers:

\[
U(S_1, S_2, \ldots, S_m).
\]

Then, by definition, the social utility which the community in question attributes to a state \( E \) is

\[
U[S_1(x_1), S_2(x_2), \ldots, S_m(x_m)].
\]

The function is usually considered to be differentiable. Let \( U'_i \) denote its derivative with respect to \( S_i \). Compatibility of the complete ordering with the partial ordering requires that the \( U'_i \) should all be positive, for all possible values of the \( S_i \).

Two particular cases of social utility functions are often discussed: the ‘utilitarian function’ equal to the sum of \( S_i \) and the ‘Rawls function’ equal to the minimum of the \( m \) individual utilities \( S_i \), and therefore non-differentiable.

It is obviously a bold step to assume the existence of a social utility function. To define such a function, we must first assign a completely specified utility function to each consumer. We must therefore choose a particular form for \( S_i \), we can no longer be content with ‘ordinal utility’, but must refer to ‘cardinal utility’, without which the definition of \( U \) becomes ambiguous.†

(Note also that a simple increasing linear transformation applied to one of the \( S_i \) changes the ordering of states which is implied by \( U \). So the term ‘cardinal utility’ has a narrower meaning here than in Chapter 2.)

In the second place, a social utility function establishes some judgment between different consumers’ gains in utility. Thus, let us consider two states \( E^1 \) and \( E^2 \) such that

\[
S_i^1 = S_i(x_i^1) = S_i(x_i^2) = S_i^2
\]

for all consumers except the first two, and such that \( S_1^1 = S_2^1 + dS_1 \), \( S_2^1 = S_2^2 + dS_2 \), where \( dS_1 \) and \( dS_2 \) are infinitely small. The function \( U \) will declare these two states equivalent if

\[
U'_1 \, dS_1 + U'_2 \, dS_2 = 0.
\]

† We could dispense both with individual utility functions and with the social utility function by defining directly a preordering relation in the \( m \)-dimensional space of the \( x_{ih} \) (for \( i = 1, 2, \ldots, m; h = 1, 2, \ldots, l \)). This collective preordering ought to be compatible with the preorderings of individual preferences. However, such an approach does not eliminate the necessity to arbitrate between consumers.
So a social utility function assumes that, in some sense, a marginal rate of substitution between the individual utilities of different consumers exists at the collective level. The choices represented by such a function are not based solely on consideration of the efficiency of production and distribution; they also express a value judgment on the just distribution of welfare among individuals. In other words we may say that a social utility function represents the accepted ethical principles about equity.

Most theoretical economists balk at the idea of such an intercomparison of individual utilities, asserting that the utilities of two distinct individuals cannot be compared, and there is no way of going from the one to the other. This is the 'no bridge' principle. On the other hand, the partisans of the social utility function claim that, in fact, it is necessary to choose one particular state from all Pareto optimal states. Such a choice implies, explicitly or implicitly, that there are marginal rates of substitution between the utilities of different consumers; explicit introduction of the function $U$ makes for a clearer choice. (We shall come back at the end of Chapter 8 to the logical difficulties raised by the characterisation of collective choices.)

We shall now examine the particular condition to be satisfied by a state which is optimum according to some social utility function. Here we shall confine ourselves to the first-order conditions for a local maximum of $U$, and shall assume that the $x_i$ are contained in the interiors of the respective $X_i$.

We must find the conditions for a maximum of (31) subject to the constraints (22) and (23) already considered in the section on the Pareto optimum. If $-\mu_j$ (for $j = 1, 2, ..., n$) and $-\sigma_h$ (for $h = 1, 2, ..., l$) represent the corresponding Lagrange multipliers, equation to zero of the appropriate derivatives gives:

$$\begin{cases}
U_i' S_{ih} = \sigma_h & \text{for } h = 1, 2, ..., l \\
\mu_j f_{jh} = \sigma_h & \text{for } j = 1, 2, ..., m
\end{cases}$$

The second system of equations is identical with that in the conditions (25) for a Pareto optimum. In the first system, the Lagrange multipliers $\lambda_i$ which, except for $\lambda_1$, were indeterminate a priori, have been replaced by the known functions $U_i$.

For a state to be an optimum according to the function $U$, not only must the conditions (26) relating to the marginal rates of substitution be satisfied, but also, for each good, the product $U_i' S_{ih}$ must take the same value for all consumers. (It is sufficient that this condition be satisfied for one good, the numéraire $l$ for example; in view of (25), it is then satisfied for all goods.)

---

† It is again easy to check that the matrix $C^o$ of the derivatives of the constraints has rank $l + n$, so that theorem VI of the appendix applies here.
We say that the marginal utilities of the different individuals† must be inversely proportional to the \( U_i \), that is, to the weight with which the \( dS_i \) relating to these individuals occur in the calculation of \( dU \).

The product \( U_i S_{ih} \) can then be interpreted as the price \( p_h \) of commodity \( h \) (clearly we could also take for \( p_h \) a multiple, independent of \( h \), of \( U_i S_{ih} \)). Under these conditions,

\[
dU = \sum_{ih} U_i S_{ih} \, dx_{ih} = \sum_{ih} p_h \, dx_{ih}.
\]  
(33)

Therefore the variation in social utility for any infinitely small deviation from the optimum is equal to the variation in the value of global consumption, this value being calculated with the prices associated with the optimum. Conversely we can easily show that, if the social utility function is a quasi-concave function of the \( x_{ih} \), if the \( X_i \) are convex, if a feasible state \( E^0 \) is a market equilibrium such that‡:

\[
U_i S_{il} = U_j S_{jl} \quad i, \alpha = 1, 2, \ldots, m,
\]  
(35)

then this is an optimal state according to the social utility function \( U \).

In works of applied economics, different variants of a project are frequently compared on the basis of the increase which each brings about in the value of final consumption, or in the value of national income, one or other of these aggregates being calculated at constant prices. The foregoing analysis justifies such a procedure only where the reference state, with respect to which variations are defined, is approximately optimal, particularly in respect of the equity of distribution among consumers.§

For, if two variants of the same project cannot be classified by the Pareto criterion, then one must benefit some consumers while the other benefits other consumers. To refer to the value of global consumption is to assume implicitly that a decrease of 1 in the value of one individual's consumption must be accepted whenever this leads to an increase of more than 1 in the value of any other individual's consumption. This point of view is rejected whenever a variant is chosen on the grounds that it leads to more equitable distribution among individuals.

† When the good \( l \) is the numéraire, \( S_{il} \) is sometimes called the 'marginal utility of money'. We then say that the marginal utilities of money must be inversely proportional to the \( U_i \).

‡ It is sometimes said that, for a market equilibrium satisfying (35), 'the distribution of incomes is optimal'. It is important to avoid confusion about the meaning of this expression and to understand clearly that the criterion of optimality does not relate directly to incomes, but to individual utilities.

§ It should also be mentioned that the justification applies only for comparisons between feasible variants. If the labour resources are fully employed, the two variants should use the same labour inputs. Changes in the labour costs, properly valued, have often to be taken into account.
9. The relevance of optimum theory

Let us now discuss the contribution of optimum theory to the understanding of the problems raised by the production and distribution of goods in society. We are no longer particularly concerned with the assumptions adopted for the proof of the results, but only with the significance of the results themselves.

Proposition 6, preceded by propositions 2 and 4, establishes, under what are in fact very general conditions, that a market equilibrium is a Pareto optimum. So in a certain sense, such an equilibrium is an efficient solution to the problem of organisation of the production and distribution of goods.

This property has sometimes been held to justify the institutions promoted by conservative parties in economies in which free markets are said to have a major part. This is not very convincing. For a start, actual markets fall a long way short of ensuring the achievement of a perfectly competitive equilibrium like that described in the next chapter. There are, in fact 'market failures'. We shall encounter several in the course of these lectures: imperfect competition in Chapter 6, external effects in Chapter 9, restriction of the actual number of markets in Chapters 10 and 12. In the second place, even if a perfectly competitive equilibrium could be established, it might still not necessarily be preferred.

Indeed, a market equilibrium $E^0$ may conceivably be rejected in favour of another state $E^1$ or $E^2$. This may happen if the distribution of goods among consumers in $E^1$ or in $E^2$ is held to be preferable on grounds of social justice to that in $E^0$. Of course, for some individuals these new states entail less satisfactory consumption than does $E^0$. But on the other hand, they afford more satisfactory consumption to other individuals and appear on the whole better according to the social ethic of the particular community (see Figure 10, where the shaded set $P$ corresponds to the feasible states).

Thus, if this ethic is represented by a social utility function, there is no reason a priori for the market equilibrium $E^0$ to coincide with the state $E^1$ which maximises social utility. The state $E^1$ will naturally be preferred to $E^0$ provided that the community's institutions do not prevent its realisation. If it turns out that $E^1$ is institutionally incapable of realisation, then it is still conceivable that another state $E^2$ may be preferred to $E^0$, although $E^2$ is not a Pareto optimum. In Chapter 9 we shall investigate 'the second best optima' which appear socially best given the institutional constraints which prevent $E^1$ from being realised.

But welfare theory also states that, under certain conditions, any Pareto optimum is a particular market equilibrium (see proposition 5, preceded by propositions 1 and 3). This is particularly the case with the socially best optimum, $E^1$ in our example. Of course, in most cases this market equilibrium
need not coincide with the perfect competition equilibrium realised where there is private ownership of primary resources and firms. But can one not conceive of institutions which allow the preferred state $E^1$ to be realised as a market equilibrium?

![Diagram](image)

Fig. 10

Proposition 5 associates with $E^1$ prices $p_h$ and incomes $R_i$. These incomes do not generally coincide with the value of the resources held by the different individuals. For $E^1$ to be established, a *redistribution* must therefore be carried out. For example, if the $i$th individual possesses quantities $\omega_{ih}$ of the different goods, his ‘primary income’ is $p\omega_i$ when prices $p_h$ apply; under redistribution, ‘disposable income’ must be $R_i$.

We cannot disguise the fact that redistribution raises difficult problems related to fiscal theory which we shall not tackle here. Almost all systems of taxation affect prices; for example, those individuals whose services are most highly valued have a high primary income but taxation of these highly qualified incomes amounts to introducing a gap between the price paid for these services by an employer and the price received by the employee. So it may become impossible to establish the market equilibrium corresponding to $E^1$ because of the conflict between the requirements of redistribution and the condition that a given commodity should have the same price for all those dealing with it. So we may be forced to settle for an approximation to $E^1$, that is, for a second best optimum.

In addition, we must not overestimate the power of the important general result derived by welfare theory. Proposition 5 establishes that with $E^1$, the state of maximum welfare, we can associate a price vector $p$ such that, if prices $p_h$ are chosen, if consumers receive incomes $R_i = px_i^1$ and if $E^1$ is realised, then it is to the advantage of no agent to change the consumption vector or the net production vector which the state assigns to him. T. Koopmans suggests that the price vector be said to ‘sustain’ the state in question.
Separation theorem

Strictly speaking we have no guarantee that, if prices are fixed at the appropriate $p_h$ and incomes at the $R_h$, the behaviour of consumers and firms will lead to the automatic realisation of $E^1$. This would be so only if, for these prices and incomes, the equilibria pertaining to each consumer and to each firm were all determined uniquely. As we have seen, this property of uniqueness may fail to hold, especially for firms. If we wish to realise $E^1$, and if some of the corresponding individual equilibria are multiple, we must devise some procedure which ensures that each agent chooses the particular vector $x_i$ or $y_j$ which not only constitutes an equilibrium for him but also allows the overall equilibrium $E^1$ to be realised. (Figure 11 illustrates the difficulty; like Figure 2, it represents a distribution equilibrium $M$. The particular feature here is that the indifference curve $S^0_2$ passing through $M$ coincides with the common tangent $MT$ along $AB$. All the points on $AB$ are therefore equilibria for the second consumer; but only $M$ is compatible with overall equilibrium.)

More generally, it is important to establish a procedure for determining prices, or a procedure for finding simultaneously the preferred state $E^1$ and its associated prices. This question, which is discussed by the 'economic theory of socialism' will be more conveniently dealt with after the investigation of competitive equilibrium. Chapter 8 will be devoted to it.

![Fig. 11](image)

10. Separation theorem justifying the existence of prices associated with an optimum

In the preceding pages, various figures illustrate the fact that an optimum may appear as a market equilibrium. There is great similarity between these figures, and this suggests that the property results from a single mathematical theorem capable of simple geometric representation. This is in fact true.

So to end this chapter, we shall give another proof of the central property of proposition 5. For this we use the modern formulation which does not
involve the use of the differential calculus and which makes the theory more obvious† because of its conceptual simplicity. The crux of the proof is a theorem which will not be proved, but for which some preliminary definitions must be introduced.

A hyperplane in $R^l$ is the set $P$ of vectors $z$ such that $pz = a$ where $a$ is a fixed number and $p$ a non-null fixed vector said to be normal to the hyperplane. The hyperplane $P$ is said to be bounding for the set $U$ if either $pu \leq a$ for all the vectors $u$ of $U$, or $pu \geq a$ for all the $u$ of $U$. The hyperplane $P$ is said to separate the two sets $U$ and $V$ if $pu \geq a$ for all the $u$ of $U$ and $pv \leq a$ for all the $v$ of $V$, or if $pu \leq a$ for all the $u$ of $U$ and $pv \geq a$ for all the $v$ of $V$ (cf. Figure 12).

Given $q$ sets $U_r$ (where $r = 1, 2, \ldots, q$) the sum of these sets, $\sum_{r=1}^{q} U_r$, is the set $U$ whose elements are all the vectors $u$ which can be written $u = \sum_{r=1}^{q} u_r$ where the $u_r$ are vectors belonging respectively to the sets $U_r$. Similarly, $-U$ is the set of vectors which can be written $-u$, the vector $u$ then belonging to $U$ (note that $U - U$ contains elements other than the null-vector except when $U$ has a single element).

![Fig. 12](image)

We can immediately establish

**Proposition 7.** If $p$ is normal to a hyperplane $pz = a$ which is bounding for the set $U = \sum_{r=1}^{q} U_r$, then it is also normal to hyperplanes $pz = a_r$ bounding for the $U_r$ ($r = 1, 2, \ldots, q$). If, moreover, $pw = a$ where $w$ is a vector of $U$ corresponding to the vectors $w_r$ of the $U_r$, then we can take $a_r = pw_r$.

For, consider a particular set $U_r$ and an element $u_r^0$ in each of the other

† The proof follows almost exactly the argument in Chapter 6 (Section 4) of Debreu, *Theory of Value*, John Wiley and Sons, Inc., New York, 1959.
Suppose, to fix ideas, that $pu \leq a$ for every $u$ of $U$. We know that

$$pu_r \leq -\sum_{s \neq r} pu^0_s + a;$$

(36)

$pu_r$ is therefore bounded above in $U_r$; let $a_r$ be the smallest of its upper bounds. The hyperplane $pz = a_r$ is bounding for $U_r$. In the case where $w$ is known to be such that $pw = a$, the number $a_r$ is equal to $pw$, since if it is greater than $pw$, there exists in $U_r$ a vector $u^*_r$ such that $pu^*_r > pw$; therefore

$$pu^*_r + \sum_{s \neq r} pw_s$$

is greater than $pw$ and therefore than $a$. But, by hypothesis, this is impossible, since $u^*_r + \sum_{s \neq r} w_s$ belongs to $U$. If a vector $w$ with the above property is not known, we can still conclude $\sum a_r \leq a$.

**Proposition 8.** The sum $U$ of $q$ convex sets $U_r$ is a convex set. If $V$ is convex, so also is $-V$.

To prove that $U$ is convex, we must establish that the vector

$$u = \alpha v + (1 - \alpha)w$$

belongs to $U$ whenever $v$ and $w$ belong to $U$ and that $0 < \alpha < 1$. Let $v_r$ and $w_r$ be the vectors of $U_r (r = 1, 2, \ldots, q)$ which occur in the sums $v = \sum_r v_r$ and $w = \sum_r w_r$. Convexity of $U_r$ implies that $u_r = \alpha v_r + (1 - \alpha)w_r$ belongs to $U_r$. In addition, the respective expressions for $u$ and the $u_r$ imply $u = \sum u_r$. Therefore the vector $u$ belongs to $U$.

Similarly we can immediately establish the convexity of $-V$ from the convexity of $V$.

**Minkowski’s Theorem.** Let $U$ be a convex set and $z^*$ a vector which is not contained in $U$. There exists a hyperplane bounding for $U$ and passing through $z^*$ (that is, such that $pz^* = a$).

This theorem, which we shall not prove,† belongs to a group of mathematical results some of which are known as ‘separation theorems’. Let us consider two disjoint convex sets $U_1$ and $U_2$. In view of proposition 8, the set $U_1 - U_2$ is convex; it does not contain the null-vector since $U_1$ and $U_2$ are disjoint. Therefore, by Minkowski’s theorem, there exists a hyperplane

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Optimum theory

$pz = 0$ containing the null vector and bounding for $U_1 - U_2$. According to proposition 7 and the remark at the end of the corresponding proof, there exist two numbers $a_1$ and $-a_2$ such that $a_1 - a_2 \leq 0$, $p \geq a_1$ for every $u_1$ of $U_1$ and $p(-u_2) \leq -a_2$ for every $u_2$ of $U_2$. A fortiori, $pu_2 \geq a_1$ for every $u_2$ of $U_2$, so that $pz = a_1$ separates $U_1$ and $U_2$ (Figure 12 illustrates this property). This reveals the relationship between Minkowski's theorem and separation theorems of convex sets.

We are now in a position to use Minkowski's theorem to prove proposition 5 without using differential calculus.

Let $E^0$ be the optimum state. Let $X^0$ be the set of vectors $x_i$ which the $i$th consumer considers as at least equivalent to $x_f$, that is, the subset of $X_i$ composed of the $x_i$'s such that $S_i(x_i) \geq S_i(x_f)$. The convexity of $X_i$ and the quasi-concavity of $S_i$ imply that $X^0_i$ is convex.

Then let

$$Z^0 = \sum_{i=1}^m X^0_i - \sum_{j=1}^n Y_j - \{\omega\},$$

where $\{\omega\}$ is the set consisting of the single vector $\omega$. The set $Z^0$ is convex when the convexity of the $Y_j$ is added to the convexity of the $X_i$ and the quasi-concavity of the $S_i$ (cf. proposition 8). Since $E^0$ is feasible, the null-vector belongs to $Z^0$ (cf. (23) and the fact that $x_f$ is in $X_f$); but it is not contained in the interior of $Z^0$; otherwise $Z^0$ would contain a vector $u$ all of whose components would be negative and there would exist a state $E^1$ such that $x^1_i \in X^0_i; y^1_j \in Y_j$ and $\sum_j y^1_j + \omega = \sum_i x^1_i - u$ for all $h$. The state $E^2$,

defined by $x^2_i = x^1_i - u$, $x^2_i = x^1_i$ ($i = 2, ..., m$), $y^2_j = y^1_j$ ($j = 1, 2, ..., n$) would be feasible and preferred to $E^0$, which contradicts the optimality of $E^0$.

Minkowski's theorem therefore establishes the existence of a vector $p$ such that $pz \geq 0$ for all $z$ of $Z^0$. Proposition 7, together with the fact that the $x^0_i$ and $y^0_j$ correspond to the null vector in (37), implies

(i') $px_i \geq px^0_i$ for all $x_i$ of $X_i$ such that $S_i(x_i) \geq S_i(x^0_i)$.

(ii) $py_j \leq py^0_j$ for all $y_j$ of $Y_j$.

To complete the proof of proposition 5 we need only show that it follows from (i') that

(i) $S_i(x_i) \leq S_i(x^0_i)$ for all $x_i$ of $X_i$ such that $px_i \leq px^0_i$.

In fact an additional condition is required for (i') to imply (i). If we adopt the condition that $x^0_i$ is contained in the interior of $X_i$, we can repeat exactly the reasoning in the second part of the proof of proposition 2 of Chapter 2 (after 'consider now a vector $x^i$...'), and the reader may refer back to this.

We can therefore state
PROPOSITION 9. If $E^0$ is an optimal state such that, for each consumer $i$, $x_i^0$ is contained in the interior of $X_i$, if the $S_i$ and the $X_i$ satisfy assumptions 1, 2 and 4 of Chapter 2, and if the sets $Y_j$ are convex, then there exist prices $p_h$ for all goods and incomes $R_i$ for all consumers such that $E^0$ appears as a market equilibrium with these prices and incomes.

Comparison with the statement of proposition 5 shows that this is a much more general property, which no longer involves certain rather awkward assumptions which were introduced in order that the usual techniques for dealing with problems of constrained maximisation could be applied.
1. Introduction

We are now about to make an investigation of the conditions under which the independent decisions of the different agents are finally made compatible and lead to overall equilibrium, called general equilibrium. Our context here is that of a competitive economy and we shall have to discuss some more specific assumptions that are necessary for the validity of the proofs to be given or outlined.

The theory that we shall discuss attempts to describe this major phenomenon, which has occupied economists since their science began: in complex societies like ours, how are the division of labour, production, exchange and consumption arrived at without some directing agency to ensure that all the individual actions are consistent? What is the 'invisible hand' ensuring this consistency?

It is also the aim of general equilibrium theory to explain the determination of the prices that are established in the markets and apply in exchanges. These prices are taken as data when consumers' and producers' decisions are being formalised. On the other hand, they are endogenous in any investigation of general equilibrium, which must therefore lead to a theory of price, or a 'theory of value'. So in this chapter we must also answer the question, 'What are the main factors determining price?'

Obviously competitive equilibrium theory does not give exhaustive answers to these two types of question. It is based on a particular representation of social organisation and individual behaviour, and this representation is limited in more than one respect. It ignores situations of imperfect competition; it relates to an economy without money and without under-employment. It therefore gives an imperfect explanation of the consistency of individual decisions, and also as may be of their inconsistency (the case of under-employment). It provides an imperfect picture of price determination. However, it has the great advantage of providing a system and a frame of
reference by means of which we can understand the essential articulation, in economies with no central direction, of production, distribution and consumption on the one hand, and of price-formation on the other.

In the study of general equilibrium, as in that of the consumer or the firm, there is said to be *perfect competition* if the price of each good is the same for all agents and all transactions, if each agent considers this price as independent of his own decisions, and if he feels able to acquire or dispose of any quantity of the good at this price (he is then said to have a 'price taking behaviour'). The assumptions defined previously for consumers' and producers' behaviour will again be adopted.†

To simplify the presentation and discussion of the theory, our approach will be similar to that adopted in the chapter on optimum theory. We shall first discuss an economy with no production, and go on to discuss a situation where the productive sphere can be dealt with in isolation. Finally, we shall consider a complex economy with the greatest degree of generality possible in this course of lectures.

There are two advantages in this approach. In the first place, it must reduce the complexity of the mathematics, and lead to better understanding of the problems and the results. In the second place, it leads to the successive discussion of two price theories which were formerly held to conflict, and so allows us a clearer grasp of the synthesis which has now been achieved.

A complete study of general equilibrium theory demands the discussion in turn of questions of economics and questions of logic. We shall try to distinguish them as clearly as possible. For this reason in particular, mathematically difficult problems concerning the existence and stability of equilibrium will be dealt with at the end of the chapter.

2. Equilibrium equations for a distribution economy

We first consider an economy of \( m \) consumers, the consumption of the \( i \)th consumer being \( x_{ih} \). Overall consistency of the individual decisions is ensured if

\[
\sum_{i=1}^{m} x_{ih} = \omega_h \quad h = 1, 2, \ldots, l, \tag{1}
\]

where \( \omega_h \) represents the resources of the good \( h \) which *a priori* are available in this economy.

There will be market equilibrium if there exist prices \( p_h \) and quantities \( x_{ih} \) satisfying (1) and if, in addition, each consumer \( i \), considering the \( p_h \) as given,

† This definition of perfect competition is sufficient for the theoretical model to be discussed, but not for a typology of real situations, since it does not define the required conditions for a competitive equilibrium to tend naturally to be realised. We shall return to this question later (cf. Chapter 7).
maximises his utility $S_i(x_i)$ subject to his budget constraint. So the unknowns of the equilibrium are the $(m + 1)f$ variables $p_h$ and $x_{ih}$. We must show how the values of these variables are determined.

To do this, we need only return to the theory of consumer equilibrium. Each vector $x_i$ must be an equilibrium for the consumer $i$ with the prices $p_h$ in question; moreover, conditions (1) must be satisfied. We saw how $x_i$ is determined, given the price vector $p$. Let us assume for the moment that it is determined uniquely. To each price vector there correspond well defined values for the left hand sides of (1). The $l$ conditions (1) can therefore be considered as $l$ equations on the $l$ components of $p$.

To make this more precise, we must indicate more clearly which variables are exogenous in the equilibrium. We shall do this in two different ways, dealing successively with two non-equivalent systems called the 'distribution economy' and the 'exchange economy' respectively.

In the distribution economy, each consumer $i$ disposes of an 'income' $R_i$, which is given exogenously. (It is permissible to speak of 'wealth' or 'assets' instead of income.) The consumer $i$ then maximises $S_i(x_i)$ subject to the constraints

$$x_i \in X_i$$

$$px_i \leq R_i.$$  \hspace{1cm} (2)

In order to visualise such an economy, we can assume that, besides the $m$ consumers, and independent of them, there are one or more agents in possession of the initial resources $\omega_h$ who release these resources at prices such that the consumers demand exactly the quantities $\omega_h$. We can call these new agents 'distributors' and assume, for simplicity, that there is one distributor for each good. Thus the distribution economy is an idealised picture of commercial operations in a society where production and the distribution of incomes are taken out of the market, while prices are fixed so as to ensure that consumers' demands, competitively manifested, absorb exactly the total quantity of goods available after production.

The theory of the consumer is directly applicable in the study of equilibrium for a distribution economy. We can let

$$\xi_{ih}(p; R_i)$$

denote the demand function of the $i$th consumer for commodity $h$, this function being assumed to be determined uniquely. The aggregate demand function of all $m$ consumers for commodity $h$ is the sum of the $\xi_{ih}$. We can write it $\xi_h(p)$, leaving out from the arguments the $R_i$, which are exogenous data;

$$\xi_h(p) = \sum_{i=1}^{m} \xi_{ih}(p; R_i).$$  \hspace{1cm} (4)
The equilibrium conditions (1) are then expressed by a system of \( l \) equations on the \( p \) prices \( p_h \):

\[
\xi_h(p) = \omega_h \quad h = 1, 2, \ldots, l.
\]

(5)

Solution of this system gives the equilibrium prices \( p_h \), the corresponding values of the \( x_{ih} \) being given by the functions \( \xi_{ih} \).

Each equation (5) implies that global demand \( \xi_h(p) \) equals global supply \( \omega_h \) in the market for commodity \( h \). The system therefore expresses the requirement that the \( l \) prices be determined so as to ensure simultaneous equilibria in the \( l \) markets. Let us assume for the moment that this condition defines the vector \( p \) uniquely. Let \( p^0 \) and \( x^0_i \) denote the equilibrium values of \( p \) and \( x_i \).

Like consumer theory, the theory of a distribution economy can provide some general indications of the characteristics of equilibrium and of the changes that occur in it when some of the exogenous data vary.

Suppose, for example, that all the incomes \( R_i \) are multiplied by the same number \( \lambda \). The vectors \( \lambda p^0 \) and \( x^0_i \) (for \( i = 1, 2, \ldots, m \)) define a new equilibrium. Indeed, the functions \( \xi_{ih} \) are homogeneous of degree zero with respect to \( p \) and \( R_i \) (see property 1 in Chapter 2). The number \( x^0_{ih} \), which is equal to \( \xi_{ih}(p^0; R_i) \), is therefore also equal to \( \xi_{ih}(\lambda; \lambda p^0 R_i) \). Moreover, by hypothesis, the \( x^0_{ih} \) satisfy conditions (1). Again we find that a change in the unit of account in which the \( R_i \) and the \( p_h \) are measured does not affect the equilibrium (no money illusion).

Unfortunately it is impossible to obtain more specific results at this level of generality. When discussing the consumer we saw that there are very few general results relating to individual demand functions. The effect of aggregation is to eliminate the general validity of the Slutsky equations (cf. property 2 in Chapter 2).

However, we shall now suggest the probable existence of a particular property of individual demand, a property which may allow aggregation and which will be assumed in Section 10 for the proof of an important result.

By considering infinitely small variations \( dp \) and \( dR_i \) in \( p \) and in \( R_i \), we established that the corresponding variation \( dx_i \), in the equilibrium consumption vector \( x_i \) satisfies:

\[
dx_i = \lambda_i U_i \, dp + v_i (dR_i - x_i \, dp),
\]

(6)

where \( \lambda_i \) is a positive number, \( U_i \) is a negative semi-definite matrix and \( v_i \) is a vector; in addition, \( \lambda_i, U_i \) and \( v_i \) depend on the equilibrium under consideration (see equation (28) in Chapter 2).

Suppose now that \( dR_i = 0 \), and consider the scalar product

\[
dp' \, dx_i = \lambda_i \, dp' \, U_i \, dp - dp' \, v_i \cdot x_i \, dp.
\]
The first term on the right hand side represents the substitution effect; it is negative or zero, since \( U_i \) is negative semi-definite. Actually this term is zero either when \( dp \) is proportional to \( p \), or under rather special specifications of the utility function \( S_i \) (specifications implying that \( a' S_i a = 0 \) for some non-zero vector \( a \) such that \( p' a = 0 \)). The second term is the income effect. It is certainly negative when \( dp \) is proportional to \( p \) since \( p' v_i = 1 \) and \( x_i' p = R_i \). It would always be negative if the marginal propensities \( v_{ih} \) were proportional to the consumptions \( x_{ih} \) (that is, if the income elasticities were all equal, and therefore all equal to 1). To the extent that these elasticities do not vary much from 1, it may appear probable that the scalar product \( dp' dx_i \) is negative for any \( dp \). Now, if this is so for each \( dp' dx_i \), it also holds for their sum over all consumers. This is why we sometimes find it admissible to set the following assumption, which recalls the relation of comparative statics established in the theory of the producer (cf. Chapter 3, Section 6), and which, as we have just seen, applies when substitution effects are stronger than income effects:

**Assumption 1.** The collective demand functions \( \xi_h(p) \) are such that, for any given values of the \( p_h \) and the \( R_i \),

\[
\sum_{h=1}^{l} d\xi_h(p) \, dp_h < 0
\]

for any infinitely small variations \( dp_h \), not all zero, which are applied to prices \( p_h \) in the neighbourhood of the equilibrium.

This assumption allows us to establish an immediate result concerning changes of equilibrium in the distribution economy. If, when the \( R_i \) remain fixed, the initial resources are subject to small variations \( d\omega_h \), then the corresponding variations in equilibrium prices must satisfy the following inequality:

\[
d\omega \, dp < 0.
\]

In particular, if only the quantity \( \omega_k \) relating to a particular good \( k \) increases while the other \( \omega_h \) remain constant, the equilibrium price \( p_k^0 \) must decrease.

3. Equilibrium equations for an exchange economy

The model of equilibrium in a distribution economy has the advantage of simplicity. The proofs of its properties are relatively straightforward. However, the descriptive value of this model is debatable. The assumption that the 'distributors' are independent of the consumers may be sufficient to describe collectivist societies where there is central direction of production and the markets for consumer goods. On the other hand, it does not appear satisfactory for the representation of societies where the institution of
private ownership is predominant. In such societies, incomes depend on prices, while the consumers are also in possession of the primary resources \( \omega_h \).

In order to construct a more realistic model in this respect, we shall assume that the \( i \)th consumer possesses certain quantities, given \textit{a priori}, of the goods \( h, \omega_{ih} \) say, and that the consumers own all the initial resources:

\[
\sum_{i=1}^{m} \omega_{ih} = \omega_h \quad h = 1, 2, \ldots, l.
\]

We shall say that \( \omega_h \) is the initial resource holding or 'endowment' of consumer \( i \) in commodity \( h \). To determine the consumptions \( x_{ih} \) is therefore equivalent to determining the quantities of the different goods acquired or disposed of by each individual consumer and owner. The \( i \)th consumer acquires \( x_{ih} - \omega_{ih} \) if this difference is positive; in the opposite case, he disposes of \( \omega_{ih} - x_{ih} \). Here we are dealing with an 'exchange economy'.

For formal purposes, there is only a minor difference between the distribution economy and the exchange economy. While the \( R_i \) are exogenous in the former, in the latter they are defined by

\[
R_i = \sum_{h=1}^{l} p_h \omega_h \quad i = 1, 2, \ldots, m
\]

where the \( \omega_{ih} \) are themselves exogenous.

It follows, however, that the \( i \)th consumer's demand is a different function of the price vector \( p \):

\[
\xi_{ih}(p; \omega_i)
\]

\( \omega_i \) being the exogenous vector of the \( \omega_{ih} \). So this demand has properties other than those appropriate to the distribution economy. In particular, the \( \xi_{ih} \) are now homogeneous functions of degree zero of the \( p_h \) for fixed \( \omega_{ih} \), where they were not homogeneous functions of the \( p_i \) for fixed \( R_i \). Assumption 1 no longer applies, since, in the first place, it was introduced on the assumption that \( dR_i = 0 \), and no longer holds when \( dR_i = \omega_i \, dp \); in the second place, homogeneity of the \( \xi_{ih} \) implies that \( dx_i \) is zero when \( dp \) is a vector collinear with \( p \). Therefore there exist non-null vectors \( dp \) such that the scalar product \( dp \cdot dx_i \) is zero, which is contrary to assumption 1.

We again let \( \xi_h(p) \) denote the global demand for the good \( h \), that is, the function of \( p \) which is the sum of the \( m \) functions (10) for \( i \) varying from 1 to \( m \), the \( \omega_{ih} \) being fixed. This will not be the same function of \( p \) as in the previous section, but this should not cause any confusion.

The equilibrium equations are then similar to those for the distribution economy:
Competitive equilibrium

\[
\begin{align*}
    x_{ih} &= \xi_{ih}(p; p\omega_i) & \text{for } i = 1, 2, \ldots, m \\
    \xi_h(p) &= \sum_{i=1}^{m} \xi_{ih}(p; p\omega_i) = \omega_h & \text{for } h = 1, 2, \ldots, l
\end{align*}
\]

or \((m + 1)l\) equations for the determination of the same number of quantities, the \(x_{ih}\) and the \(p_h\).

However, the system of the last \(l\) equations determining the \(p_h\) does not have the same properties as the corresponding system (5) in the previous section. The \(\xi_h(p)\), homogeneous functions of degree zero, actually depend only on the \(l - 1\) relative prices \(p_h/p_i\) for \(h = 1, 2, \ldots, l - 1\). So system (11) can only determine relative prices, one of the \(p_h\) being arbitrary.

Are not these \(l\) equations involving \(l - 1\) variables incompatible? No, since realisation of \(l - 1\) of them entails realisation of the last one. Since each consumer necessarily obeys his budget constraint, the demand functions satisfy

\[
\sum_{h=1}^{l} \left[ p_h[\xi_{ih}(p; p\omega_i) - \omega_{ih}] \right] = 0
\]

differently with respect to the \(p_h\); therefore

\[
\sum_{h=1}^{l} \left[ p_h[\xi_h(p) - \omega_h] \right] = 0
\]

differently also with respect to the \(p_h\). (This identity is often called Walras' Law). In short, the count of the equations and the unknowns together with the homogeneity of the demand functions suggest that the equilibrium equations (11) determine relative prices and consumptions.

Note also that the distribution economy equilibrium and the exchange economy equilibrium are two examples of what we called market equilibria in Chapter 4. There are great similarities between the two models, but they are not identical. This bears out the remark made at the beginning of our investigation of the optimum. Models relating to competitive equilibrium are more strictly specified than those relating to the optimum.

Certain characteristics of equilibrium in an exchange economy will be more clearly understood if we consider more directly the case of two commodities and two consumers whose behaviour accords with the rules of perfect competition. When there are only two consumers, we are confronted \(a\ priori\) with a game situation of the type to be discussed later (Chapter 6); perfect competition does not appear likely. So the case of two consumers will be discussed solely as a simple illustration of a theory applying to situations where there are many consumers.

Starting from the first consumer's indifference curves, we can easily determine the equilibrium \((x_{11}, x_{12})\) corresponding to given prices \((p_1, p_2)\) and given initial resources \((\omega_{11}, \omega_{12})\) (see Figure 1, where the quantities of the two goods are given as abscissa and ordinate respectively). We need only
Equilibrium equations for an exchange economy

Equilibrium equations for an exchange economy

draw the budget line $PT$ normal to the price vector and passing through $P$, which represents initial resources. The equilibrium point $M$ is the point of $PT$ which lies on the highest indifference curve. When prices vary and $P$ remains fixed, the point $M$ moves along a curve $D_1$ which can be called the 'demand curve' of the first consumer.

On the same coordinate axes we can construct an Edgeworth box diagram similar to that in Figure 2 of Chapter 4 (see Figure 2). The curve $D_1$ represents the first consumer's demand; a curve $D_2$ constructed from the second consumer's indifference curves represents the latter's demand in the system of axes centred on $O'$ (with coordinates $\omega_1', \omega_2'$). The curves $D_1$ and $D_2$ both pass through $P$; any other point of intersection $M$ of these curves represents an equilibrium since it corresponds to the same price vector for both consumers, the vector normal to $PM$. At such a point $M$ the indifference curves $\mathcal{S}_1$ and $\mathcal{S}_2$ are tangential, so that $M$ does in fact lie on the locus $MN$ of distribution optima.

The same type of 'Edgeworth diagram' can be applied to the distribution economy, since we see that the price vector of an exchange economy can be normalised by the rule $p \omega = R$ where $R$ is a given number (the case where the $p_h$ are zero for all non-zero $\omega_h$ is of little practical interest). We shall not use this normalisation rule in our investigation of the process by which equilibrium is realized; but there is nothing to prevent its introduction when equilibrium equations only are being considered. Now, every distribution economy is identical with an exchange economy in which prices are normalised in this way; the vector $\omega_i$ of resources possessed by the $i$th consumer is then taken as proportional to the vector $\omega$ of total resources, the proportionality coefficient being the ratio between this consumer's income $R_i$ and total income $R$, the sum of individual incomes. (To attribute the income $R_i$ to the $i$th consumer is equivalent to giving him a property right over the part
$R, \omega_{h}/R$ of each primary resource $\omega_{h}$. In the case of a distribution economy with only two consumers, we can construct a figure similar to Figure 2. The point $P$ representing resources is then on the diagonal $OO'$ and divides this diagonal in the proportions $R_{1}/R$ and $R_{2}/R$.

Which general properties can one prove for the aggregate demand functions $\xi_{h}(p)$ of an exchange economy? We saw two of them: homogeneity (absence of money illusion) and Walras' Law, which is identity (12). Knowing how aggregate demand functions are derived from individual demand functions that fulfil properties 2 and 3 of Chapter 2, we might hope to be able to find for the functions $\xi_{h}(p)$ some similar properties, which would have interesting implications for the theory of prices.

Unfortunately, the properties of Chapter 2 only imply homogeneity and Walras' Law. One has shown that any $l$-tuple of functions $\xi_{h}(p)$ (for $h = 1, 2, \ldots, l$) which are continuous, homogeneous of zero degree and fulfil identity (12) can be obtained as the aggregate demand functions of an exchange economy, as soon as one is free conveniently to choose the number of its consumers and the specification of their preferences.$^{1}$

Conversely, if all consumers were alike, having identical utility functions $S_{i}$ and identical endowment vectors $\omega_{i}$, the global functions $\pi_{u}(p)$ would exactly enjoy the properties studied in Chapter 2 for individual demand functions.

Considering that individual preferences and endowments are actually less disperse than may be assumed in a general theory and wishing to exhibit sufficient conditions for some commonly accepted results, one is often ready to suppose that some particular properties hold for the functions $\xi_{h}(p)$. The most convenient hypothesis for the theory of prices, but not the most realistic one, is defined as follows:

ASSUMPTION 2 (Gross substitutability). The global demand functions \( \xi_h(p) \) are differentiable and such that

\[
\frac{\partial \xi_h(p)}{\partial p_k} > 0
\]

for every \( p \) with no negative component, for all \( h \) and for all \( k \neq h \). (Homogeneity of \( \xi_h(p) \) then implies that its derivative with respect to \( p_h \) is negative.)

Although it is satisfied with certain utility functions, this is a fairly restrictive assumption. For example, it is not satisfied by the demand function represented in Figure 1 since, for small values of \( p_1/p_2 \), the ordinate \( x_2 \) decreases as \( p_1 \) increases. This happens although, when the model contains no other goods, the two goods are necessarily substitutes, in the sense of the definition given in Chapter 2. The phrase 'gross substitutability' refers to the fact that the hypothesis does not isolate the substitution effects but directly bears on aggregate demand functions, in the determination of which income effects also occur.

4. Value, scarcity and utility

Let us pause to consider the 'theory of value' that follows from the preceding formalisation of an economy with no production. The prices which realise general equilibrium are held to depend on the exogenous elements contained in the model, namely the available resources \( \omega_h \), the demand functions \( \xi_{ih}(p) \), incomes \( R_i \) or the initial possessions \( \omega_{ih} \) of individuals. In short, prices depend on three factors:

— the degree of scarcity of the different goods, as expressed by the quantities \( \omega_h \) of resources;
— the varying utility of these goods, which determines the demand functions \( \xi_{ih} \);
— the distribution among consumers of claims on collective resources, either direct distribution through the \( \omega_{ih} \) or indirect distribution through the \( R_i \).

It is the simultaneous interplay of these three factors which conditions the determination of prices.

Can we go further than this general statement and find out how each factor influences the value system? The most natural approach is to see how price reacts to small variations in the exogenous elements of the model. We must first consider the effects of an increase in scarcity of a particular good \( r \), that is, a small negative variation \( \delta \omega_r \) in the available quantity of this good, all the other exogenous elements remaining unchanged. We must then consider an autonomous variation \( \delta \xi_r \) in the demand function for the good \( r \). Finally we must find the implications of a small change in the distribution of claims.

We shall start by examining conditions under which the following proposition is valid.
Proposition 1. As a good \( r \) becomes scarcer, its price increases.

We have already answered this question at the end of Section 2 when we showed that assumption 1 implies this proposition in a 'distribution economy'. For an exchange economy the proposition is ambiguous for two reasons: in the first place, equilibrium prices are determined only up to a positive multiplicative constant; in the second place, a variation \( \partial \omega_r \) in the resources of the good \( r \) must necessarily be accompanied by a variation in the claims of the different consumers (the \( \omega_{ir} \)). However, we can still give a valid interpretation of the property if we adopt the gross substitutability of assumption 2.

The problem will be tackled with sufficient generality to lead up to the investigation of the other two properties to be discussed later. Suppose therefore that there are variations \( \partial \omega_{ir} \) in the quantities \( \omega_{ir} \) of a particular good \( r \), and that a change in consumers' needs causes variations \( \partial \xi_h \) in the values \( \xi_h(p^0) \) taken by the global demand functions at the previous equilibrium prices \( p^0 \), which are all assumed positive.

These variations will bring about variations \( \partial p_k \) in the equilibrium prices, which will themselves react on global demands. The maintenance of equilibrium requires that the final variation \( \partial \xi_h \) in \( \xi_h \) is equal to the variation \( \partial \omega_h \) in available resources (the latter is zero for all goods other than \( r \)). Consequently we can write

\[
\partial \xi_h = \partial \xi_h + \sum_{k=1}^l \frac{\partial \xi_h}{\partial p_k} \partial p_k + \sum_{i=1}^m \frac{\partial \xi_h}{\partial \omega_{ir}} \partial \omega_{ir} = \partial \omega_h,
\]  

which can also be written as:

\[
\sum_{k=1}^l \frac{\partial \xi_h}{\partial p_k} \partial p_k = \partial u_h \quad h = 1, 2, ..., l
\]

with:

\[
\partial u_h = \partial \omega_h - \partial \xi_h - \sum_{i=1}^m \frac{\partial \xi_h}{\partial \omega_{ir}} \partial \omega_{ir}.
\]

The coefficients of the \( \partial p_k \) in system (15) must constitute a singular matrix since the \( p_k \) are determined only up to a multiplicative constant. In fact, the identity

\[
\sum_{k=1}^l p_k \frac{\partial \xi_h}{\partial p_k} = 0
\]

follows from the homogeneity of \( \xi_h \) (to see this we need only differentiate with respect to \( \lambda \), in the neighbourhood of \( \lambda = 1 \), the equality \( \xi_h(\lambda p) = \xi_h(p) \), which follows from the theory of the consumer).

Although system (15) is not sufficient for the determination of the \( \partial p_k \), it must enable the variations \( \partial \pi_h/\pi_h = \partial p_h/p_h - \partial p_r/p_r \) in relative prices \( \pi_r = p_h/p_r \) to be determined. Indeed, let us replace in (15) the term
\[ \frac{\partial \xi_h}{\partial p_r} \, dp_r \quad \text{by} \quad - \sum_{k \neq r} p_k \frac{\partial \xi_h}{\partial p_k} \cdot \frac{dp_r}{p_r}, \]

which is equal to it in view of (17). We obtain the system

\[ \sum_{k \neq r} p_k \frac{\partial \xi_h}{\partial p_k} \cdot \frac{d\pi_k}{\pi_k} = \partial u_h \quad h \neq r \quad (18) \]

written for all values of \( h \) other than \( r \).

If we adopt assumption 2 of gross substitutability, the matrix of order \( l - 1 \) whose elements are the coefficients of the \( \frac{d\pi_k}{\pi_k} \) has special properties. Its non-diagonal terms are positive. In view of (17), each diagonal term \( p_h(\partial \xi_h/\partial p_h) \) is negative and smaller in absolute value than the sum of the non-diagonal terms in the same row. Such a matrix has an inverse whose elements are all negative.† We can therefore write:

\[ \frac{d\pi_h}{\pi_h} = \sum_{k \neq r} a_{hk} \partial u_k \quad \text{for} \quad h \neq r, \quad (19) \]

where the \( a_{hk} \) are negative numbers.

Let us now return to the case where the good \( r \) becomes scarcer \((\partial \omega_r < 0 \text{ and } \partial \omega_h = 0 \text{ for } h \neq r)\), the demand functions remaining unchanged \((\partial h = 0 \text{ for all } h)\). Equation (16) becomes

\[ \partial u_h = - \sum_{i=1}^{m} \frac{\partial \xi_{ih}}{\partial \omega_{ir}} \partial \omega_{ir} \quad \text{for} \quad h \neq r. \quad (20) \]

Now, we can assume that the \( \partial \omega_{ir} \) are all negative since their sum is negative, and an obvious change in the distribution of claims would be introduced by the assumption that one of them is non-negative.

Ignoring the possible existence of inferior goods, we can say that the \( \frac{\partial \xi_{ih}}{\partial \omega_{ir}} \) are positive and therefore also that the \( \partial u_h \) are positive for all \( h \)'s other than \( r \). In view of (19), the \( d\pi_h/\pi_h \) are all negative, and so

\[ \frac{dp_r}{p_r} > \frac{dp_h}{p_h} \quad \text{for} \quad h \neq r. \quad (21) \]

All relative prices with respect to the good \( r \) decrease. Price \( p_r \) increases relatively more than all other prices.

Consider now the case of an increase in the utility of the good \( r \), all the other exogenous elements of the model remaining unchanged. This is naturally expressed by an increase \( \partial \xi_r > 0 \) in the demand for \( r \). Walras' law requires that other demands decrease correspondingly. It is therefore appropriate to consider the case where \( \partial \xi_h < 0 \) for all \( h \)'s other than \( r \).

† See, for example, McKenzie, 'Matrices with dominant diagonals' in Arrow, Karlin and Suppes, Mathematical Methods in the Social Sciences, Stanford University Press, 1959.
In the context of the exchange economy, with, in this case, \( \partial \omega_{ir} = 0 \), equation (16) shows that \( \partial u_h \) is then positive for all \( h \neq r \). If there is gross substitutability, the \( d\pi_h/\pi_h \) are all negative, the equality (21) is again satisfied, which justifies

**PROPOSITION 2.** If the utility of a good \( r \) increases, its price increases.

How are prices liable to be affected by a change in the distribution of claims? If one consumer \( x \) gains at the expense of another consumer \( \beta \), global demand will move towards the goods for which \( x \)'s individual demand is less inelastic than \( \beta \)'s. The prices of these goods will then increase.

**PROPOSITION 3.** If the individuals benefiting from a change in distribution have a particularly high propensity to spend an increment in their resources on the good \( r \), then its price increases.

Let us consider this statement still in the context of an exchange economy. Suppose \( \partial \xi_h = 0 \) and \( d\omega_h = 0 \) for all \( h \), \( \partial \omega_s > 0 \), \( \partial \omega_{s} = - \partial \omega_{a} < 0 \) and \( \partial \omega_{ih} = 0 \) for all other pairs \( (i, h) \). We assume that

\[
\frac{\partial \xi_{sr}}{\partial \omega_{as}} > \frac{\partial \xi_{pr}}{\partial \omega_{ps}}
\]

and correspondingly

\[
\frac{\partial \xi_{sh}}{\partial \omega_{as}} < \frac{\partial \xi_{ph}}{\partial \omega_{ps}} \quad \text{for} \quad h \neq r
\]

An equation like (16), with the \( \omega_{ir} \) replaced by the \( \omega_{is} \), shows that then the \( \partial u_h \) are positive for all \( h \)'s other than \( r \). If there is gross substitutability, the equality (21) is again satisfied.

This concludes for the moment our discussion of price determination in economies with no production. We have investigated three propositions which are often considered to summarise the 'laws of the market'. However, they have been established on the basis of a certain number of restrictive assumptions, which suggests that they cannot have complete generality. In fact, it is possible to construct examples where they do not hold. Their validity is further limited when possibilities of production exist. However, they apply to the most common situations in practice.

---

\( \dagger \) If we adopt assumption 1 in the context of the distribution economy and assume the demands for only two goods, \( r \) and \( s \), vary \( (\partial \xi_r > 0 \) and \( \partial \xi_s < 0 \)), it is easy to prove that \( d\omega_r > 0 \) and \( d\omega_s < 0 \).
5. Value and cost

Whenever production is taken into account, price must satisfy other properties, which did not come into the above discussion. When dealing with the firm, we saw that, in perfect competition equilibrium, the price-ratios must equal the technical marginal rates of substitution \( \lambda_{j}^{s} \) and that the price of each good must equal its marginal cost. This shows that the value system also depends on the technical conditions of production. Also, it is to be expected that the price of a good will decrease when discovery of a new process facilitates its manufacture.

In order to understand this other aspect of price formation we shall first consider a case where values depend only on technical conditions. Where it applies, this case justifies the 'labour theory of value'.

We make the following assumptions:

(i) Each firm \( j \) specialises in the production of a single good \( r_{j} \) (and therefore \( y_{jh} \leq 0 \) for all \( h \neq r_{j} \)). We let \( q_{j} \) denote \( j \)'s production of the good \( r_{j} \).

(ii) Production is carried on under constant returns to scale. We can then characterise the technical conditions of production by referring to the quantities of inputs yielding an output \( q_{j} = 1 \), these quantities being

\[
\frac{-y_{jh}}{q_{j}} = a_{jh} \quad \text{for} \quad h \neq r_{j}
\]  

(24)

(It is customary to let \( a_{jh} \) denote the unit input of \( h \) here. I have sometimes used this notation to denote the total input of \( h \), and the reader should guard against confusion.)

Let \( a_{j} \) be the vector of the \( a_{jh} \), the component \( r_{j} \) being taken as zero, by convention. The production set can be defined by the condition that \( y_{j} \in Y_{j} \) if and only if the vector \( a \) defined by (24) satisfies

\[
a_{j} \in A_{j}.
\]  

(25)

The new set \( A_{j} \) is therefore the set of input combinations yielding a unit output of \( r_{j} \).

(iii) All the goods are produced with the exception of one (labour), which we can assume to be the \( l \)th good. All production requires this good \( (a_{jl} > 0 \) for every vector of \( A_{j} \).

These three assumptions, and especially the last, are obviously restrictive. The last assumption ignores the existence of natural raw materials and the fact that there are many types of labour (in a time analysis, it would be necessary in particular to take account of the fact that two equal quantities of labour provided at two different dates are not substitutable for one another). However, the model based on these assumptions is often very
useful as a first approximation. It is in fact a generalisation of the classical model of Leontief.†

Without specifying either the volume and distribution of resources, or consumers’ preferences, let us consider a general competitive equilibrium \( E^0 \) in an economy whose productive activity satisfies the above conditions. We assume that \( p^0_h \geq 0 \) for all \( h \) and \( p^0_l > 0 \) (this is not very restrictive). We also assume that every commodity other than labour is actually produced: for all \( h \neq l \) there exists a firm \( j \) such that \( r_j = h \) and \( q^0_j > 0 \). To simplify notation, we take the last commodity as numéraire \( (p_l = 1) \) and also let \( p^0_j \) denote the price of \( r_j \) and \( f_j \) the unit input of labour \( (f_j = a_{jl}) \).

Since \( E^0 \) is an equilibrium, we can write

\[
\sum_{h=1}^{l-1} p^0_h a^0_{jh} + f^0_j = p^0_j \quad \text{if} \quad q^0_j > 0 \tag{26}
\]

\[
\sum_{h=1}^{l-1} p^0_h a^0_{jh} + f^0_j \geq p^0_j \quad \text{if} \quad a_j \in A_j. \tag{27}
\]

The left hand sides represent the unit costs of production. Equation (27) excludes the case where a possible vector \( a_j \) allows production of \( r_j \) at a cost less than its price, which conflicts with equilibrium since to go on increasing output of \( r_j \) using this input combination is technically feasible for \( j \) (constant returns to scale) and is associated with infinitely increasing profit. Equation (26) expresses the fact that the price of \( r_j \) must cover its cost if the good is produced by \( j \), otherwise it is to the advantage of the firm not to produce at all.

Equation (26) implies that \( p^0_h > 0 \) for all \( h \), since, for the firm producing this good, \( a^0_{jh} \geq 0 \) and \( f^0_j > 0 \) and therefore \( p^0_j > 0 \).

Since every good other than the last is produced by at least one firm, we can write a system of \( l - 1 \) equations similar to (26), the \( h \)th equation corresponding to a \( j \) for which \( r_j = h \). We can then write this system in matrix form:

\[
A^0 p^0 + f^0 = p^0 \tag{28}
\]

where \( A^0 \) is the square matrix of order \( l - 1 \) of the \( a^0_{jh} \) chosen in this way, while \( f^0 \) and \( p^0 \) are the column vectors with \( l - 1 \) components defined by the \( f^0_j \) and the \( p^0_h \). Equation (28) can also be expressed by

\[
(I - A^0)p^0 = f^0. \tag{29}
\]

Now, the matrix \( I - A^0 \) has special properties. Its diagonal elements are positive (we set \( a_{jh} = 0 \) for \( h = r_j \)); its other elements are either negative or

zero. Moreover, when the elements in the same row are multiplied by the respective positive numbers \( p^0_j \), then the absolute value of the diagonal term is greater than the sum of the others (according to (26), the difference is the positive number \( f^0_j \)). It follows that \( I - A^0 \) has an inverse all of whose elements \( \alpha_{hj} \) are non-negative\(^\dagger\) and which we can write

\[
p^0_h = \sum_j \alpha_{hj} f^0_j. \tag{30}
\]

The right hand side of this equality involves only quantities relating to the technical conditions of production. It can be interpreted as expressing the labour theory of value: price \( p^0_h \) is equal to the quantity of labour (the last good) which is used in the production of the good \( h \), either directly in the firm \( j \) which manufactures it (\( r_j = h \)) or indirectly in the firms manufacturing the inputs used by \( j \). This interpretation is clearly revealed in (26) considered as defining price \( p^0_j : f^0_j \) corresponds to the amount of labour used per unit of output in \( j \), while \( p^0_h a^0_{jh} \) corresponds to the amount of labour which has been used, directly or indirectly, to produce the quantity \( a^0_{jh} \) of unit input of the good \( h \) in the production of \( r_j \).

This interpretation may be more fully justified as follows. Let \( q \) be a \((l - 1)\)-component output vector having components \( q_j \) for those \( j \) occurring in the construction of \( A^0 \). Let \( P \) be the program defined by these \( q_j \), the respective technical coefficients of \( A^0 \) and a zero output for all other producers. Let us moreover choose \( q \) in such a way that the final net output \( x_h \) is precisely zero for all \( h \) (from 1 to \( l - 1 \)) except for \( h = r \) for which it is equal to one.

In order to find this vector \( q \), we can first compute \( x_h \) as follows:

\[
x_h = q_h - \sum_{j=1}^{l-1} q_j a^0_{jh}
\]
or, denoting by \( x' \) and \( q' \) the row vectors having \( x_h \) and \( q_h \) as components:

\[
x' = q'(I - A^0)
\]
hence

\[
q' = x'(I - A^0)^{-1}
\]
or, equivalently:

\[
q_j = \sum_{h=1}^{l-1} x_h \alpha_{hj}.
\]

The particular specification chosen for \( x \) implies

\[
q_j = \alpha_{rj}.
\]

\(^\dagger\) See, for example, the article by McKenzie referred to on p. 115.
The total labour input in program $P$ is then equal to:

$$\sum_{j=1}^{l-1} f_j q_j = \sum_{j=1}^{l-1} \alpha_{r_j} f_j^0.$$ 

which is precisely $p^0_r$ according to equation (30). The price $p^0_r$ is the total labour input necessary for a final net output consisting of just one unit of commodity $r$.

Is this genuinely a case where prices depend solely on the technical conditions of production, that is, on the sets $A_j$? Yes, for we shall see that two competitive equilibria $E^0$ and $E^1$ necessarily have the same prices, labour being taken as numéraire, if they involve the same technical sets, and this is so even if they have different vectors $\omega$ of resources or different demand functions $\xi_a(p)$. We need only assume that, in $E^1$ as in $E^0$, the first $l - 1$ goods are all produced and have non-negative prices.

We first write a system similar to (29) for $E^1$:

$$ (I - A^1) p^1 = f^1. \tag{31} $$

We note also that (27) applied to the $a_j$ involved in the construction of $A^1$ implies

$$ (I - A^1) p^0 \leq f^1 \tag{32} $$

Similarly, inverting the roles of $E^0$ and $E^1$,

$$ (I - A^0) p^1 \leq f^0, \tag{33} $$

(29) and (33) on the one hand, and (31) and (32) on the other imply

$$ (I - A^0)(p^1 - p^0) \leq 0, \tag{34} $$

$$ (I - A^1)(p^0 - p^1) \leq 0. \tag{35} $$

Since $I - A^0$ and $I - A^1$ have inverses with no negative component, (34) implies $p^1 \leq p^0$ and (35) implies $p^0 \leq p^1$. These two inequalities are compatible only if $p^1 = p^0$.

We can now consider the following property:

**PROPOSITION 4.** If technical improvement occurs in the production of the good $r$, its price decreases relative to the price of labour. Prices of the other products also decrease, or at least do not increase.

A technical improvement is the discovery of a better method of production of the good $r$. Let $k$ be the firm in which this improvement occurs ($r_k = r$) and $a^*_{k}$ the new input vector to which it gives rise.

Let $E^0$ and $E^1$ denote the equilibria before and after the introduction of this improvement. We can write

$$ \sum_{h=1}^{l-1} p^0_h a^*_{kh} + f^*_k < p^0_r $$

since the new method allows production of $r$ at lower cost than the previous cost $p^0_r$. We define the matrix $A^*$ and the vector $f^*$ as identical to $A^0$ and $f^0$
except where the production of \( r \) is concerned, where we take the \( a_{kh}^* \) and \( f_k^* \). As before, the relations (26) apply to the production of the other goods. Taking account of (36), we can write

\[(I - A^*)p^0 \geq f^*.
\]

By the same reasoning as for (33), we have

\[(I - A^*)p^1 \leq f^*.
\]

Therefore

\[(I - A^*)(p^1 - p^0) \leq 0.
\]

Since \( I - A^* \) has an inverse with no negative element, \( p^1 - p^0 \) has no positive component:

\[p^1_h \leq p^0_h \quad \text{for all} \ h.
\]

Taking the \( r \)th row of (38) and adding it to (36), we have

\[p^1_r - p^0_r < \sum_{h=1}^{t-1} a_{kh}^*(p^1_h - p^0_h).
\]

Now, in view of (40), the right hand side cannot be positive. Therefore price \( p^1_r \) is strictly less than \( p^0_r \). This completes the proof of proposition 4.

The model on which our discussion has been based is fairly specialised. It has enabled us to find out how prices are determined without involving the system of quantities produced or consumed in the equilibrium; only unit inputs have been involved.

Obviously things are not so simple if we relax one or other of the three assumptions at the beginning of this section. For example, if there is diversity of non-producible primary factors, their respective prices must be included in relations similar to (26) and (27). Consideration of these relations would no longer alone be sufficient for the determination of prices. The relative scarcity of the different factors would be involved as would the respective utilities of the different products since they require different proportions of the factors; so also would the distribution of claims, since this influences collective demands.

Of course, under different restrictions, properties replacing proposition 4 can be established. But the question clearly becomes more complex. So we shall not attempt to generalise the model step by step by finding out simultaneously how the properties of the price-system are affected.

Instead, we shall proceed directly to general formulation of the equilibrium equations. Then it will be possible for prices to depend simultaneously on the scarcity of resources, the technical conditions of production, the distribution of claims among individuals, and finally, on individual preferences.
But they will depend more or less on these various factors, and not always according to simple schemas.

Considering a graphical representation of a very simple case may, however, be a useful complement to the preceding developments. Let us suppose there are just two produced commodities and one consumer. The shaded area of Figure 3 represents the set of feasible consumption vectors when assumptions (i), (ii) and (iii) of page 123 hold. A competitive equilibrium $E^0$ is a production optimum. Its image $M^0$ on Figure 3 must therefore be on the boundary $AB$ of this area. The boundary must be a straight line since the price vector does not depend on the input-output combination. The budget line of the consumer must coincide with $AB$ (a line distinct from $AB$ but parallel to it would lead the consumer to demand more or less than is supplied). Hence at $M^0$ the indifference curve is tangent to $AB$ (see the unbroken line). The price vector $p^0$ is collinear with the common normal at $M^0$ to the indifference curve and the production boundary $AB$. If commodity 2 becomes more useful, the indifference map is transformed and a new equilibrium point $M^1$ is found where more of commodity 2 is produced (see the broken indifference curve). The price vector does not change.

Let us now consider a distribution economy of the type studied in Section 2, an economy with again only two commodities and one consumer. The equilibrium point is imposed by the resources $\omega_1$ and $\omega_2$. For a competitive equilibrium the price vector must be normal at $M$ to the indifference curve containing $M$. If commodity 2 becomes more useful, this curve shifts and the price vector rotates so as to increase the relative price of commodity 2 (see Figure 4).

The two preceding cases are extreme polar cases. In the first one quantities change but not prices; in the second one prices change but not quantities. Many models involve an economy where production exists but does not satisfy the assumptions of page 123. If there are just two commodities and
Equilibrium equations in a private ownership economy

When discussing equilibrium for the firm, we let \( \eta_{jh}(p) \) represent the net supply function of the firm \( j \) for the good \( h \). We must now include the net supply functions of the individual firms \( (j = 1, 2, \ldots, n) \) in the equilibrium equation relating to the good \( h \). So we write:

\[
\sum_{i=1}^{m} \xi_{ih}(p; R_i) = \omega_h + \sum_{j=1}^{n} \eta_{jh}(p) \quad h = 1, 2, \ldots, .
\]

These equations replace equations (5) for equilibrium in an economy with no production.

As before, we must show how consumers' incomes \( R_i \) are determined. We shall do this by finding a representation of a private ownership economy where primary resources and firms are owned only by individual consumers. Thus we shall generalise our previous exchange economy.

Suppose that the \( i \)th consumer owns the quantity \( \omega_{ih} \) of the resources of the good \( h \), and a share \( \theta_{ij} \) of the firm \( j \) (for the goods \( h = 1, 2, \ldots, l \) and the firms \( j = 1, 2, \ldots, n \)). Since the consumers own all the resources and all the firms, we must have

\[
\sum_{i=1}^{m} \omega_{ih} = \omega_h \quad h = 1, 2, \ldots, l;
\]

\[
\sum_{i=1}^{m} \theta_{ij} = 1 \quad j = 1, 2, \ldots, n.
\]
Under these conditions, the \( i \)th consumer's income \( R_i \) will be the sum of the values \( p_h \omega_{ih} \) of resources and the shares \( \theta_{ij} \) of the profits of firms. If \( \pi_j \) denotes the profit of the firm \( j \), income \( R_i \) is\footnote{The last term in (44) represents the 'return to enterprise' received by consumers. It is usual to distinguish the return to labour in the first term. Remaining income corresponds to other natural resources and is called 'rent'. It is useful to recall here that the term 'income' can be replaced by the term 'wealth' in this model that does not involve time explicitly. This explains the absence of the 'return to capital' which will be introduced in Chapter 10, Section B.3.}

\[
R_i = \sum_{h=1}^{l} p_h \omega_{ih} + \sum_{j=1}^{n} \theta_{ij} \pi_j \quad i = 1, 2, \ldots, m. \tag{44}
\]

Finally, profit \( \pi_j \) is equal to the total value of the firm \( j \)'s net supplies:

\[
\pi_j = \sum_{k=1}^{l} p_h \eta_{jh}(p) \quad j = 1, 2, \ldots, n. \tag{45}
\]

In this private ownership economy, the exogenous data are the \( \omega_{ih} \) and \( \theta_{ij} \), the unknowns are the prices \( p_h \), incomes \( R_i \) and profits \( \pi_j \), that is, there are \( l + m + n \) variables. We can consider (41), (44) and (45) as 'the equations of equilibrium'. The system thus defined contains as many equations as there are unknowns.

To find its properties, we must take account of the fact that the functions \( \xi_{ih} \) and \( \eta_{jh} \) derive from the behaviour of the consumers and firms. A complete theory must be based on assumptions about the sets \( X_i \) and \( Y_j \) and the functions \( S_i \). Here we shall confine ourselves to one general remark.

When investigating the behaviour of the consumer and the firm, we found that the demand functions \( \xi_{ih} \) are homogeneous of degree zero with respect to \( p \) and \( R_i \), and the supply functions \( \eta_{jh} \) are homogeneous of degree zero.
Prices and income distribution

with respect to $p$. Under these conditions, the system (41), (44), (45) is homogeneous of degree zero with respect to the unknowns, the $p_h$, the $R_i$ and the $\pi_j$. It determines them only up to a multiplicative constant. Once again we find that the unit of account can be chosen arbitrarily.

But is not this system of $l + m + n$ equations then overdetermined? No, because one of the equations can be deduced from the others. This is 'Walras' law'. In fact, the functions $\xi_{ih}$ satisfy

$$\sum_{h=1}^{l} p_h \xi_{ih}(p; R_i) = R_i \quad i = 1, 2, \ldots, m$$

identically. Let us replace $R_i$ by its value as a function of the $p_h$, this value being obtained from (44) and (45); let us, for simplicity, omit the arguments of the functions. We can write the above equation in the form

$$\sum_{h=1}^{l} p_h \left[ \xi_{ih} - \omega_{ih} - \sum_{j=1}^{n} \theta_{ij} \eta_{jh} \right] = 0 \quad i = 1, 2, \ldots, m.$$ 

Summing over $i$ and taking account of (42) and (43), we have

$$\sum_{h=1}^{l} p_h \left[ \sum_{i=1}^{m} \xi_{ih} - \omega_h - \sum_{j=1}^{n} \eta_{jh} \right] = 0,$$

which is satisfied identically with respect to $p$ and which implies that realisation of $l - 1$ of the equations (41) entails realisation of the last equation.

7. Prices and income distribution

Every theory of general equilibrium implies a theory of distribution. This will become clear if we examine a particular case of the general model just discussed.

Leaving aside transfer incomes about which they have little to say, theoretical economists have long looked on income as the return for some kind of participation in production. The individuals who own the factors of production—labour of various kinds, land, natural resources, etc.—place quantities of these factors at the disposal of producers and receive their value in return—wages, rent, etc. Since a general equilibrium theory explains how the prices of the factors are determined as well as the prices of the products, it has implications for the distribution of incomes. It shows how the different levels of wages, rents, etc. are fixed relative to each other and allows relative changes in them to be investigated.

In particular, the theory of competitive equilibrium contains a distribution theory. To see this more clearly, let us consider a model involving two factors of production, for example, 'skilled labour' and 'unskilled labour'. We might equally well consider 'labour' and 'land'. Often 'labour' and 'capital' are chosen in such cases. But, in so far as a considerable part of
capital is itself produced, time should properly be introduced for a satisfactory
theory of the return to capital, and we shall not do this before Chapter 10.

We assume that each individual \( i (i = 1, 2, \ldots, m) \) possesses quantities \( \omega_{i1} \) and \( \omega_{i2} \) of the two factors; \( \omega_{i1} > 0 \) and \( \omega_{i2} = 0 \) for skilled workers, \( \omega_{i1} = 0 \) and \( \omega_{i2} > 0 \) for unskilled workers. In addition, \( n \) consumable goods are produced \( (h = 1, 2, \ldots, n) \). Production is carried on under constant returns to scale and each firm manufactures one and only one product \( (j = 1, 2, \ldots, n) \). We also assume that the products are obtained directly from the factors; as we shall see, this is not really restrictive.

Then let \( q_h \) be the quantity of \( h \) produced, and \( f_{h1} \) and \( f_{h2} \) the two technical coefficients which represent the quantity of each of the two factors used in producing one unit of \( h \). These coefficients are not fixed \textit{a priori}; but they must satisfy a condition which follows directly from the production function

\[
g_h = g_h(f_{h1}, f_{h2})
\]

\( g_h \) being a homogeneous function of degree 1. We also assume that \( g_h \) is concave, twice differentiable and even more precisely, that the second derivatives \( g''_{h11} \) and \( g''_{h22} \) are strictly negative (decreasing marginal returns).

Let us take the second factor as numéraire; let \( p_h \) denote the price of \( h \) and let \( s \) be the price of the first factor. In competitive equilibrium, the price of each product must be equal to its cost, since returns to scale are constant:

\[
p_h = f_{h1}s + f_{h2} \quad h = 1, 2, \ldots, n.
\]

The marginal productivity of each factor must equal its price:

\[
p_h g'_{h1} = s \quad p_h g'_{h2} = 1 \quad h = 1, 2, \ldots, n
\]

where \( g'_{h1} \) and \( g'_{h2} \) denote the derivatives of \( g_h \) with respect to each of its arguments. We can also write

\[
s g'_{h2} = g'_{h1} \quad h = 1, 2, \ldots, n.
\]

The system of \( 3n \) equations, (47) and (48), is equivalent to the system (46), (47), (49), since the homogeneity of \( g_h \) implies \( f_{h1}g'_{h1} + f_{h2}g'_{h2} = 1 \). Either of these systems defines the \( 3n \) variables \( f_{h1}, f_{h2} \) and \( p_h \) as a function of \( s \).

If we had used a more general model in which the production of each good requires inputs not only of factors but also of products, we should have reached exactly the same result by a reasoning process similar to those in Section 5. For this case, the symbols \( f_{h1} \) and \( f_{h2} \) in the following equations should be interpreted as the quantities of the factors used directly or indirectly to obtain one unit of final net output of \( h \), where \( q_h \) denotes this final output.
Prices and income distribution

In any case, the equalities between resources and uses are

\[
\sum_{i=1}^{m} \xi_{ih}(p; R_i) = q_h \quad h = 1, 2, \ldots, n \tag{50}
\]

\[
\sum_{h=1}^{n} q_h f_{h1} = \omega_1 \tag{51}
\]

\[
\sum_{h=1}^{n} q_h f_{h2} = \omega_2 \tag{52}
\]

where \(\omega_1\) and \(\omega_2\) denote the total resources of the factors 1 and 2, the \(\xi_{ih}\) are individual demands, and the \(R_i\) are the incomes:

\[
R_i = \omega_{1i}s + \omega_{2i} \quad i = 1, 2, \ldots, m \tag{53}
\]

(since returns to scale are constant, returns to enterprise are zero). The \(m + n + 2\) equations (50) to (53) are not independent of the previous equations since the \(\xi_{ih}\) satisfy the budget identity

\[
\sum_{h=1}^{n} \theta_h \xi_{ih}(p; R_i) = R_i,
\]

and therefore Walras' law

\[
\sum_{h=1}^{n} \sum_{i=1}^{m} \theta_h \xi_{ih}(p; R_i) = \sum_{i=1}^{m} R_i = \omega_1 s + \omega_2,
\]

as can be verified by taking account of (47), (50), (51) and (52). So the situation is as if the equalities (50) to (53) constitute \(m + n + 1\) additional equations for the determination of the \(R_i\), the \(q_h\) and \(s\).

Let us now see how the level of skilled wages, \(s\), varies relative to the level of unskilled wages. We can imagine changes of various kinds in the exogenous elements of the equilibrium. Here we need only consider two types of change, one affecting the scarcity of the factors and the other the needs or tastes of consumers. We shall adopt the same method as in Sections 4 and 5 and trace the effects of variations \(\partial \omega_{1i}, \partial \omega_{12}\) or \(\partial \xi_{ih}\).

Since the technical conditions, the functions \(g_h\), are now fixed, we can use the system of equations (46), (47) and (49) to express the variations \(dp_h, df_{h1}\) and \(df_{h2}\) as a function of \(ds\). We obtain immediately

\[
dp_h = f_{h1} ds, \tag{54}
\]

since, when (47) is differentiated, the term \(s df_{h1} + df_{h2}\) becomes zero: the marginal equations (48), which determine the choice of technical coefficients, imply \(s df_{h1} + df_{h2} = p_h [g_{h1} df_{h1} + g_{h2} df_{h2}]\); the term in square brackets is zero in view of the production function (46).
Differentiating (46) and the second of equations (48), we have
\[
\begin{align*}
- g_{h1} \frac{df_{h1}}{dh} + g_{h2} \frac{df_{h2}}{dh} &= 0 \\
g_{h12} \frac{df_{h1}}{dh} + g_{h22} \frac{df_{h2}}{dh} &= - \frac{g_{h2}}{p_h}.
\end{align*}
\]

Now, \( g_{h2} \) is homogeneous of degree zero, which implies
\[g_{h12} f_{h1} + g_{h22} f_{h2} = 0.\]

Taking account of (54), the above system becomes
\[
\begin{align*}
- g_{h1} \frac{df_{h1}}{dh} + g_{h2} \frac{df_{h2}}{dh} &= 0 \\
f_{h2} \frac{df_{h1}}{dh} - f_{h1} \frac{df_{h2}}{dh} &= \frac{g_{h2}(f_{h1})^2}{g_{h22}} \cdot \frac{ds}{p_h}
\end{align*}
\]
which gives
\[
\begin{align*}
\frac{df_{h1}}{dh} &= \frac{(g_{h2})^2(f_{h1})^2}{g_{h22} p_h} \frac{ds}{p_h} \\
\frac{df_{h2}}{dh} &= - \frac{g_{h2} g_{h1}(f_{h1})^2}{g_{h22} p_h} \frac{ds}{p_h}
\end{align*}
\]
(55)

(the homogeneity of \( g_h \) implies \( f_{h1} g_{h1} + f_{h2} g_{h2} = 1 \)). The second derivative \( g_{h22} \) is negative since \( g_h \) is concave. Thus \( df_{h1} \) has the opposite sign to \( ds \) and \( df_{h2} \) has the same sign as \( ds \). An increase in the price of the first factor relative to the price of the second brings about substitution of the second factor for the first.

We now turn our attention to the equations defining quantities, and more precisely, to (50), (51) and (53). Using the notation of equation (27) in Chapter 2, and letting \( \xi_i \) and \( f_i \) denote the vectors of the \( \xi_{ih} \) and the \( f_{ih} \), we can write
\[
d\xi_i = \partial \xi_i + \lambda_i U_i f_i \, ds + v_i (dR_i - x_i f_i \, ds).
\]
By differentiating (51) we obtain
\[
q' \, df_i + f_i' \, dq = \partial \omega_i
\]
where \( f_i' \) is obviously the row vector, the transpose of \( f_i \). If we let \( u_h \) denote the (negative) multiplier of \( ds \) in the expression for \( df_{h1} \), take account of \( dq = \sum_i d\xi_i \) and differentiate (53), we obtain
\[
\left[ q' u + \sum_{i=1}^m \lambda_i f_i' U_i f_i + \sum_{i=1}^m f_i' v_i (\omega_{i1} - x_i f_i) \right] \, ds
\]
\[
= \partial \omega_{i1} - f_i' \sum_{i=1}^m \partial \xi_i - \sum_{i=1}^m f_i' v_i (s \partial \omega_{i1} + \partial \omega_{i2}).
\]
(56)

This expresses \( ds \) as a function of the exogenous variations \( \partial \omega_{i1}, \partial \omega_{i2} \) and \( \partial \xi_i \). It is the required equation. Consider first the expression in square brackets
which multiplies $ds$. Its first term is negative, according to our earlier discussion. Its second term cannot be positive since the theory of consumer equilibrium shows that $U$ is negative semi-definite. We can neglect the third term, since it is zero when the $v_i$ are the same for all consumers (equation (51) shows that the sum of the $\omega_{it} - \chi_i f_i$ is zero); for it to be positive, the income-effect for goods which largely use the first factor must be systematically greater among individuals owning this factor than among the rest. Except in very exceptional cases, the expression which multiplies $ds$ must be negative.

We are now in a position to state the effects of exogenous changes on the distribution of incomes.

(i) If the second factor becomes scarcer, $(\partial \omega_{i2} < 0$ for all $i$, where $\partial \omega_{i1} = 0$ and $\partial \xi_i = 0)$, then the right hand side of (56) is positive and $ds$ is negative; the relative return to the first factor decreases.

(ii) If the first factor becomes scarcer $(\partial \omega_{i1} < 0$ and $\partial \omega_{i1} < 0$ for all $i$, where $\partial \omega_{i2} = 0$ and $\partial \xi_i = 0$), then the right hand side of (56) is negative (in practice, $p'v_i = 1$ implies here $sf_i v_i = 1 - f^2_i v_i < 1$); $ds$ is positive; the return to the first factor increases.

(iii) If consumers' demands transfer to goods using more of the first factor, then the return to this factor increases. The budget equation implies $p' d\xi_i = 0$, that is, $sf_i d\xi_i + f_i^2 d\xi_i = 0$. The assumption adopted here reduces to $f_i d\xi_i > 0$ and $f_i^2 d\xi_i < 0$; since the $\partial \omega_{ih}$ are all zero, it follows that $ds > 0$. For example, if only one consumer's demands for $r$ and $s$ vary, with $d\xi_r > 0$ and $d\xi_s = -(p_r/p_s) d\xi_r$, then

$$f'_1 d\xi = \left[\frac{sf_{r1}}{p_r} - \frac{sf_{s1}}{p_s}\right]p_r^2 \frac{\partial \xi_r}{s}$$

will be positive precisely when the first factor represents a greater part of the value of $r$ than it does of the value of $s$.

The conclusions we have just reached recall those obtained for an economy with no production. Apart from their interest for distribution theory, they contribute to the understanding of the way in which general models synthesize the two price theories discussed in Sections 4 and 5 respectively.

8. The existence of a general equilibrium

In the preceding sections we have discussed the equations of equilibrium, but have not rigorously examined the question whether this system of equations has a solution. We were content to verify that there were as many equations as there were unknowns: $(m + 1)l$ in the distribution economy, $(m + 1)l - 1$ in the exchange economy, after elimination of one equation deducible from the others, $l + m + n - 1$ in the private ownership economy.
with production. (In the particular case of Section 5 we did not even set out all the equilibrium equations.)

Until recently, microeconomic theory found this sufficient. However, it was known that equality of the number of equations with the number of unknowns was neither necessary nor sufficient for the existence of a solution. But it seemed impossible to establish the existence of a solution for general models in which the relevant functions were not specified exactly.

Mathematical economists have been aware of this gap for about twenty years; they have given rigorous proofs of the existence of equilibrium in a number of general models. Given the mathematical level of these lectures, we cannot ignore such proofs, and shall illustrate their nature by means of a very simple case.

But first, we must demonstrate the importance of existence properties for the microeconomic theory which is our main concern. Suppose we have established that a system of equations representing equilibrium has a solution, however the exogenous elements of the model may be specified. Then we can be certain that our model always provides a representation of equilibrium, a representation which may be true or false but exists in any case. On the other hand, if equilibrium does not exist for certain specifications of the exogenous elements, then the model is not valid in these cases; in a certain sense, it is inconsistent. We see why theoreticians, preoccupied with logic, ensure the existence of solutions to the systems of equations by which they represent competitive equilibrium.

The proofs with which we shall be concerned are not trivial. They all depend on the application of 'fixed point theorems' to the models considered. We must say something about these theorems.

Consider, in $l$-dimensional Euclidean space, the 'parallelepiped' $Z$ of all the points in this space which satisfy the inequalities

$$u_h \leq z_h \leq v_h,$$

where the $u_h$ and $v_h$ are fixed numbers (obviously $u_h \leq v_h$). A simple fixed point theorem can be stated as follows:

**Brouwer's Theorem.**† Given a continuous mapping $\phi(z)$ of a parallelepiped $Z$ into itself, there exists a vector $z^0$ of $Z$ such that $\phi(z^0) = z^0$. The vector $z^0$ is said to be the fixed point of the function $\phi$.

The simplest case is that of a real function $\phi$ defined on the set of real numbers, where $Z$ is an interval, for example $[0, 1]$. The theorem then states that the graph of this function contains at least one point lying on the first bisector.

† This is an intentionally restrictive statement of the theorem. For an introduction to fixed point theorems, see C. Berge, *Espaces topologiques, Fonctions multivoques*, Dunod Paris, 1959, Chapter VIII, Section 2.
There have been many extensions of Brouwer's theorem in mathematics. In particular, Kakutani's theorem has often been used in equilibrium theory; but for our present purposes, we do not need to go into such extensions of the theorem.

In fact, we can now prove the existence of equilibrium for a distribution economy.

THEOREM 1. Given non-negative incomes \( R_i \) and initial resources \( \omega_h \) that are all positive, assume that, for every price-vector \( p \) with no negative component and for all \( i \), a (partial) equilibrium exists for the \( i \)th consumer and is defined uniquely by non-negative functions \( \xi_{ih}(p; R_i) \), which are continuous with respect to \( p \). Then there exists a vector \( p^0 \) with no negative component and such that

\[
\sum_{i=1}^{m} \xi_{ih}(p^0; R_i) \leq \omega_h \quad \text{for} \quad h = 1, 2, \ldots, l,
\]

the inequality being replaced by an equality for all \( h \) such that \( p^0_h > 0 \).

For the proof, we can use directly the global demand functions \( \xi_{ih}(p) \) defined by (4) and clearly continuous when the \( \xi_{ih} \) are continuous. In \( l \)-dimensional space, we shall consider the parallelepiped \( P \) defined by

\[
0 \leq p_h \leq \frac{R}{\omega_h},
\]

where \( R \) denotes the sum of the \( m \) incomes \( R_i \).

Given some vector \( p \) of \( P \), consider the functions†

\[
\Psi_h(p) = p_h + \lambda_h[\xi_h(p) - \omega_h]
\]

where \( \lambda_h \) is some fixed positive number.
Consider the vector mapping $\phi(p)$ whose $l$ components are the $\phi_h(p)$ defined above. In going from $p$ to $\phi(p)$, the components that increase correspond to goods for which demand exceeds supply, while the components that decrease correspond to goods for which supply exceeds demand. The mapping $\phi$ can therefore be considered to describe a fairly natural process of realisation of equilibrium (compare equation (64) given below in Section 10).

This mapping is obviously continuous since $\psi_h$ is a continuous function of $p$ and $\phi_h$ is a continuous function of $p$. It transforms every vector of $P$ into a vector of $P$. Brouwer’s theorem states that it has a fixed point $p^*$, that is, that there exists a vector $p^*$ such that

$$\phi_h(p^*) = p^*_h \quad h = 1, 2, \ldots, l.$$ 

Let us examine each of the three possibilities (60) and the corresponding three possibilities for $p^*_h$ (see Figure 7).

(i) If $p^*_h = 0$, then $\psi_h(p^*) \leq 0$, and so $\xi_h(p^*) \leq \omega_h$; (57) is satisfied.

(ii) If $0 < p^*_h < R/\omega_h$, then $p^*_h = \psi_h(p^*)$, and so $\xi_h(p^*) = \omega_h$, as is required by theorem 1 in this case.

(iii) If $p^*_h = R/\omega_h$, then we must have $\psi_h(p^*) \geq R/\omega_h = p^*_h$, and therefore $\xi_h(p^*) \geq \omega_h$ and $p^*_h \xi_h(p^*) \geq p^*_h \omega_h = R$; therefore

$$\sum_i [p^*_i \xi_{ih}(p^*) - R_i] \geq 0.$$ 

But, since the $l$ demands $\xi_{ih}$ of the $i$th consumer are non-negative, the value
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$p^0_h \xi_{ih}$ of each of them must be at most equal to $R_i$. Therefore the expression in square brackets in the last inequality is negative or zero, which means that the inequality becomes an equality, and therefore that $\xi_h(p^0) = \omega_h$ (since $p^0_h > 0$).

This completes the proof of theorem 1.

The property stated in this theorem differs slightly from the definition of equilibrium given in Section 2. However, the difference is only minor since (57) must always take the form of (5), except perhaps when the price of $h$ is zero. But then the good has zero marginal utility for all consumers. If we assume that there is free disposal of surplus, we can still speak of an equilibrium since no-one is interested in the surplus of $h$, which can be destroyed without cost. In fact, we could take the property stated in theorem 1 as the definition of equilibrium; this has often been done in mathematical economics.

Theorem 1 is weak not in its conclusion, but in its assumptions, which are formulated directly on the demand functions. Their validity could be better assessed if they related to the utility functions $S_i$ and the consumption sets $X_i$.

We note in passing that, since the $\xi_{ih}$ are non-negative, the theorem ignores services provided by consumers, which are not the object of the distribution operations under consideration.

The most serious assumption relates to the existence and uniqueness of consumer equilibrium, which must be satisfied for any price vector $p$ provided that the latter has no negative component. We proved the existence and uniqueness of an equilibrium for the consumer, subject to certain assumptions (proposition 1 of Chapter 2). Thus we have ourselves determined sufficient conditions for the existence of the $\xi_{ih}$. However, these conditions assumed that the $p_h$ were all positive while, for theorem 1, we require only that the $p_h$ are not negative. Thus we can deduce the existence of an equilibrium directly from the properties assumed for the $X_i$ and the $S_i$ only if we strengthen the assumptions made in Chapter 2 and carry out slightly heavier proofs.

We note also that, to establish the continuity of the $\xi_{ih}$, we assumed the $X_i$ to be convex and the $S_i$ to be quasi-concave. Without some such condition, the proof could not be established, as will be shown later in a counter-example.

An assumption used in consumer theory for the proof of the existence of the $\xi_{ih}$ is important for correct appreciation of the relevance of general equilibrium theory. The time has come to say a few words about this.

In Chapter 2 we assumed that the set $X_i$ of possible consumptions for the $i$th individual contains the null-vector. This ignored the existence of a subsistence standard. It is granted in every society that each individual must be assured of some minimum consumption that depends on the society's stage of development. The set $X_i$ must contain only vectors obeying this
subsistence standard; it no longer contains the null-vector.

Under these conditions, equilibrium for the consumer exists only if prices $p_h$ and income $R_i$ are such that $X_i$ has at least one common point with the set of the $x_i$ satisfying $px_i \leq R_i$. A new condition, called the survival condition must be satisfied for the existence of general equilibrium.

In the distribution economy, a survival condition can be defined as follows. Let $\lambda_i$ be the smallest number such that the vector $\lambda_i \omega$ belongs to $X_i$ (we assume the existence of such a number, which is certainly not restrictive in practice). A survival condition is:

$$R_i \geq \lambda_i R \quad i = 1, 2, \ldots, m$$

where, as previously, $R$ denotes the sum of the $R_i$. Incomes must be so distributed that the part of global income due to each individual gives him the right to a part of the resources which is at least equal to his subsistence standard. In the equilibrium, we necessarily have

$$\sum_{i=1}^{m} p^0 x_i = p^0 \omega,$$

and therefore $R = p^0 \omega$; the survival condition implies $R_i \geq p^0 \lambda_i \omega$; the consumer can acquire at least the vector $\lambda_i \omega$ of $X_i$.

If we wish to take account of this survival condition in the proof of the existence of demand functions (cf. Chapter 2), we must obviously introduce new assumptions which complicate the proof of theorem 1.

Let us now consider a case where no equilibrium exists, namely the case of two identical consumers and two goods ($m = 2; l = 2$). The consumption sets $X_i$ contain all the vectors with no negative component.

The indifference curves are the quarter-circles centred on the origin:

$$S_i(x_{i1}, x_{i2}) = x_{i1}^2 + x_{i2}^2,$$

so that the utility functions do not satisfy the assumption of quasi-concavity. The initial resources are $\omega_1 = 4$ and $\omega_2 = 2$. Incomes are such that $R_1 = R_2 = 3$.

We can easily determine the two consumers' demands for each possible price-vector.

(i) If $p_1 < p_2$, then each consumer demands only the good 1, or more precisely,

$$x_{i1} = x_{21} = 3/p_1 \quad x_{i2} = x_{22} = 0.$$

This combination maximises $S_i$ over the set of the $x_i$ in the first quadrant which satisfy the budget constraint

$$p_1 x_{i1} + p_2 x_{i2} = 3.$$
There is no equilibrium corresponding to such prices since the global demand for 1 is \(6/p_1\); the limitation on resources \(\omega_1 = 4\) implies that \(p_1\) is positive; therefore \(p_2\) is also positive, which is incompatible with an excess supply of 2 for the second good.

(ii) If \(p_2 < p_1\), the consumers demand only the good 2:

\[
\begin{align*}
x_{11} &= x_{21} = 0, \\
x_{12} &= x_{22} = 3/p_2.
\end{align*}
\]

No equilibrium exists for such a combination of prices.

(iii) If \(p_1 = p_2\), then each consumer chooses one or other of the following demands:

\[
\begin{align*}
ex_{11} &= 3/p, & x_{i1} &= 0 & x_{i2} &= 3/p. \\
ex_{12} &= 0.
\end{align*}
\]

We then have three possibilities for global demand:

\[
\begin{align*}
x_1 &= 6/p & x_1 &= 3/p & x_1 &= 0 \\
x_2 &= 0 & x_2 &= 3/p' & x_2 &= 6/p.
\end{align*}
\]

No equilibrium is possible with any of them since global available resources are \(\omega_1 = 4, \omega_2 = 2\).

In this case there is no competitive equilibrium possible for the distribution economy.

We have spent some considerable time in proving the existence of equilibrium in a distribution economy since this proof is a simple prototype of others which are often much heavier and which have been established for other formulations of equilibrium. Such proofs had to be established, once and for all, in economic science, but we cannot devote more time to them than they deserve in a general course.

Indeed, we encounter fairly severe difficulties if we try to apply the approach used so far in these lectures to a closer look at the existence problem for a
private ownership economy with production.

One of the difficulties arises when we become aware of the restrictive nature of the assumption that a (partial) equilibrium exists for the firm and is unique for any price vector $p$. We then want to treat the functions $\eta_j(p)$ as defined only for vectors $p$ that belong to subsets of $\mathbb{R}^l$, and then as being multivalued. This obviously complicates the theory.

However, our conclusions from the investigation of the distribution economy remain basically valid for this more general model. Subject to conditions which, in particular, imply convexity but apart from that are fairly unrestrictive, we can establish the existence of a competitive equilibrium.

As we have already observed when studying the firm, the presence of considerable indivisibilities or increasing returns to scale may prevent the realisation of a competitive equilibrium. This is the major limitation on the theories examined here in so far as they aim to provide a positive analysis of observed reality in decentralised economies. We have already seen that imperfections in competition may facilitate the realisation of an equilibrium. We shall return on several later occasions to the difficulty raised by non-convexities.

9. The uniqueness of equilibrium

By establishing that an equilibrium exists, we fulfil the need to check up on the logical consistency of the theory. But if there exist several equilibria that satisfy the model, the theory provides only a partial explanation; it does not indicate which of the equilibria will be realised. A relevant question is therefore to find conditions under which the uniqueness of equilibrium can be proved.

Here we shall confine ourselves to a brief discussion in the context of the distribution and of the exchange economy. Note, however, that in the course of Section 5, when discussing a particular model related to production, we established the uniqueness of the equilibrium price-vector.

That the question is not meaningless is revealed by Figure 9, which reproduces an Edgeworth diagram ($m = 2; l = 2$). The two points $M$ and $M'$ both correspond to competitive equilibria since $PM$ and $PM'$ are tangents, at $M$ and $M'$ respectively, to the indifference curves of the two consumers. If prices corresponding to the budget line $PT$ are established, then both consumers accept the point $M$. If prices corresponding to $PT'$ are established, then the point $M'$ is realised.† It has already been pointed out that perfect

† It has been proved that, when several competitive equilibria exist, their number is odd, except in exceptional limit cases. Among these equilibria there then exists at least one which appears as unstable according to the definition of the next section and often has somewhat paradoxical properties. See for instance Y. Balasko, 'The Transfer Problem and the Theory of Regular Economies', *International Economic Review*, October 1978.
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competition, assumed here, does not hold when there are only two exchanging agents. But obviously the case \( m = 2 \) is not special for the uniqueness property.

Such situations do not arise in the exchange economy if the demand functions are defined uniquely and if they satisfy assumption 2 of gross substitutability. Clearly the equilibrium price-vector is fixed only up to a multiplicative constant. So we shall say that uniqueness exists if, given two equilibria \( E^0 \) and \( E^1 \), then \( x_i^1 = x_i^0 \) for all \( i \) and there exists \( \lambda \neq 0 \) such that \( p^1 = \lambda p^0 \). Whenever demand functions are uniquely defined, checking the last equation is sufficient for proving uniqueness of equilibrium.

Suppose then that uniqueness as thus described is not realised. Let \( p^1 \) and \( p^0 \) be two non-collinear equilibrium vectors. Let \( r \) be the good for which the ratio \( p_h^0/p_h^1 \) is minimised:

\[ p_h^0 \geq \frac{p_r^0}{p_r^1} p_h^1 \quad \text{for all } h, \quad (62) \]

where the inequality holds strictly for at least one \( h \), since \( p^0 \) and \( p^1 \) are not collinear. Consider now the vector \( p^* \), collinear with \( p^1 \), and whose components are the numbers on the right hand side of \((62)\). Gross substitutability implies that the demand for \( r \) is higher with prices \( p^*_h \) than with prices \( p^0_h \), which contradicts the fact that it equals \( \omega_r \) in both equilibria \( E^1 \) and \( E^0 \). In order to show that gross substitutability does in fact have this effect, we need only consider a continuous transformation of the prices of \( p^0 \) up to \( p^* \), along which transformation no price increases, and therefore the price of \( r \) remains constant. So the demand for \( r \) will never decrease; at certain times it must increase, since the price of at least one other good must decrease.
Similarly, we see immediately that equilibrium is unique in the distribution economy if the demand functions are defined uniquely and if a rather more specific assumption than assumption 1 is satisfied:

**Assumption 1'**. The collective demand functions $\xi_h(p)$ are such that, for every pair of different vectors $p^0$ and $p^1$,

$$\sum_{h=1}^l [\xi_h(p^0) - \xi_h(p^1)](p_h^0 - p_h^1) < 0. \tag{63}$$

For, if $p^0$ and $p^1$ are the price-vectors of two different equilibria $E^0$ and $E^1$, they must be different and must imply the same demands $\omega_h$ for each of the goods $h$. This is contrary to (63).

10. The realisation and stability of equilibrium

Having established the equilibrium equations, Walras, to whom the present theory is essentially due, explains how equilibrium tends naturally to be realised. The following quotation illustrates the importance which he attributes to this explanation. Having just defined a system representing equilibrium in an economy with a productive sector, he writes: 'It remains only to show, for production equilibrium as for exchange equilibrium, that this problem to which we have given a theoretical solution is just that problem which in practice is solved in the market-place by the mechanism of free competition.†

In fact, the theory as presented up to this point shows how the consistency of individual decisions can be ensured if markets are competitive and if equilibrium prices are realised in these markets. But nothing in our previous discussions guarantees that competition tends to establish equilibrium prices. This is the question which now concerns us.

According to Walras, price-adjustments can be formally represented by a 'tâtonnement' process. He suggests that the way prices are determined on Commodity Exchanges or Stock Exchanges is typical of the competitive mechanism. So, systematic analysis of the way an Exchange functions in his view provides systematic analysis of any market.

In an Exchange, all buyers and sellers are present or are at least represented. They come with the intention to buy or to sell, and it depends on the price proposed whether their intentions are realised or not. An initial price is 'called' by someone we shall name 'the auctioneer'. Offers to buy and sell are made at this price. If total supply does not equal total demand, a second price is called which may be less than or greater than the first.

The realisation and stability of equilibrium

according as supply exceeds or falls short of demand; and so on, until all
the buyers and sellers have been able to deal at a price which suits them.

To round off general equilibrium theory from our present standpoint,
we must therefore first give a formal definition of the process of tâtonnement,
and then find the conditions under which it does in fact lead to equilibrium,
that is, we must investigate the ‘stability’ of equilibrium.

For simplicity, we again confine ourselves to an economy which involves
only consumers. If prices are defined by the vector \( p \), the amount by which
total demand exceeds total supply is \( \xi_h(p) - \omega_h \) for the good \( h \). For a formal
representation of the tâtonnement process, it is often assumed to be con-
tinuous over time and the rate of revision of \( p_h \) is assumed proportional to
excess demand \( \xi_h - \omega_h \):\(^\dagger\)

\[
\frac{dp_h}{dt} = a_h[\xi_h(p) - \omega_h] \quad h = 1, 2, \ldots, l,
\]

where \( a \) is a positive constant and \( t \) denotes time for the realisation of the
tâtonnement process.\(^\ddagger\)

A particular feature of this formulation is that it assumes that the mani-
fested demands depend on the prices called at each moment of time, and not
on the way prices move throughout the various adjustments, which is
equivalent to assuming that in fact no exchange takes place before equilibrium
price is determined. This is not the case in Commodity and Stock Exchanges,
since, without exception, contracts are made at each of the prices called. So
the demands which are satisfied at the beginning do not appear later, and this
modifies equilibrium prices.

To make this last point clear, we need only consider the example of the
distribution economy. Suppose that the initial prices \( p^i_1 \) are lower than the
equilibrium prices \( p^e_1 \). Suppose also that only the first consumer’s demand
is satisfied at the prices \( p^e_1 \). He receives quantities \( \omega^i_1 \) of resources, such that
\( p^i_1 \omega^i_1 = R_1 \). By hypothesis, \( p^i_1 \omega^i_1 < p^e_1 \omega^e_1 \) and \( p^0 \omega = R \), where \( R \) denotes the
total income of all consumers. Thus

\[
p^0(\omega - \omega^1) < R - R_1.
\]

The initial equilibrium prices \( p^e_1 \) are therefore too small to ensure equality of
demand and supply for the remaining \( m - 1 \) consumers. New equilibrium

\(^\dagger\) Of course, (64) applies only so long as \( p_h \) is positive, or as the right hand side is positive
when \( p_h \) is zero. When, at \( p_h = 0 \), supply is still excessive, there is generally assumed to be
no further variation in \( p_h \).

\(^\ddagger\) When the theory of the stability, or realisation, of market equilibrium is applied to
an economy involving several periods of time, it is assumed that the duration of the
tâtonnement process is an infinitesimal fraction of the basic period. This is clearly restrictive
because of the lags involved in revisions of supplies by firms. Walras emphasised this point
(see Walras, op. cit.).
prices, differing from the $p^0_h$ because of the deal concluded by the first consumer, must be defined.

Thus this formulation of the tâtonnement process suggested by Walras and repeated since by most writers in this field,† is a fairly extreme idealisation of the mechanism by which prices are determined. However, it is based on the essential idea that the price of a product must increase or decrease according as the demand for it is greater than or less than the supply.

Some economists have criticised this process on the grounds that the agents responsible for effecting price-revisions are not generally specified in its statement. The criticism obviously does not apply to Commodity Exchanges, but may carry more weight in other cases. In the distribution economy, it is natural to assume that the ‘distributors’, owners of or agents for the goods to be distributed, themselves alter prices upwards or downwards in the light of the difference they observe between demand and available supply. In the exchange economy, it is necessary to assume the existence of ‘auctioneers’ between the exchanging parties. This assumption sometimes appears artificial. This is why we shall discuss later on a different approach intended to explain how a competitive equilibrium emerges (see Chapter 7, Section 4).

Equations (64) representing the tâtonnement process constitute a system of $l$ differential equations in the $l$ unknowns $p_h$. A value $p^0$ of $p$ which satisfies equations (5) expressing the equality of global supply and global demand, is an equilibrium value for this system of differential equations. Generally the solution of (64) is a set of $l$ functions $p_h(t)$ which are defined given their initial values $p_h(0)$.

**Definitions.** An equilibrium price vector $p^0$ is said to be stable or ‘globally stable’, if, for any initial prices $p_h(0)$, each price $p_h(t)$ tends to $p^0_h$ as $t$ tends to infinity, for $h = 1, 2, ..., l$. An equilibrium $p^0$ is said to be locally stable if the $p_h(t)$ tend to the corresponding $p^0_h$ when the initial values $p_h(0)$ are sufficiently near the $p^0_h$.

If (64) relates to a single good, the decrease in demand as a function of price is sufficient to ensure local stability of the equilibrium. The question becomes complicated when there are several goods. An adjustment to $p_h$ which seems a correction in the market for $h$ may increase disequilibrium in the markets for other goods. Therefore it is conceivable a priori that the adjustments described by (64) may not ensure stability of competitive equilibrium. However, a certain number of results relating to stability have been established. We shall prove one of them for the distribution economy and then state one for the exchange economy.

---

THEOREM 2. If the collective demand functions are differentiable and satisfy assumption 1, every equilibrium for the distribution economy comprising prices \(p_h\) which are all positive, is locally stable when the price-adjustments satisfy (64). If the demand functions satisfy assumption 1', there is also global stability.

Consider such an equilibrium \(p^0\). In view of assumption 1, there exists a number \(\varepsilon > 0\) such that \(|p_h - p_h^0| < \varepsilon\) (for all \(h\)) implies

\[
\sum_{h=1}^{l} \left[ \xi_h(p) - \xi_h(p^0) \right][p_h - p_h^0] < 0
\]  \hspace{1cm} (65)

except when \(p = p^0\). (The inequality holds for all \(p \neq p^0\) if assumption 1' is satisfied.)

Moreover, since the \(p_h^0\) are positive, \(\varepsilon\) can be chosen so that

\[|p_h - p_h^0| < \varepsilon \quad \text{implies} \quad p_h > 0.\]

Let us consider the \(p_h(0)\) such that

\[|p_h(0) - p_h^0| < \eta \quad h = 1, 2, \ldots, l,\]  \hspace{1cm} (66)

where \(\eta\) is a positive number to be defined later. Let us assume that \(p(0)\) differs from the equilibrium vector \(p^0\), otherwise the stability condition is obviously satisfied, with the \(p_h(t)\) being continually equal to the \(p_h^0\).

Let \(D(t)\) be the positive quantity defined by:

\[D(t)^2 = \sum_{h=1}^{l} \frac{1}{a_h} [p_h(t) - p_h^0]^2.\]  \hspace{1cm} (67)

We can immediately find

\[
\frac{d}{dt}[D(t)^2] = 2 \sum_{h=1}^{l} \frac{1}{a_h} [p_h(t) - p_h^0] \frac{dp_h}{dt}
\]

or, in view of (64),

\[
\frac{d}{dt}[D(t)^2] = 2 \sum_{h=1}^{l} \left[ p_h(t) - p_h^0 \right] \xi_h(p) - \xi_h(p^0).\]  \hspace{1cm} (68)

This equality, together with (65), shows that, outside the equilibrium, the distance \(D(t)\) is decreasing. However, to establish this point we must take account of the fact that the inequality (65) in question is only locally applicable.

Suppose now that \(\eta\) is chosen so that

\[a_k \eta^2 \sum_{h=1}^{l} \frac{1}{a_h} < \varepsilon^2 \quad \text{for} \quad k = 1, 2, \ldots, l \quad \text{and} \quad \eta < \varepsilon.\]

Under these conditions, \(|p_h(0) - p_h^0| < \varepsilon\) for all \(h\); (65) applies for \(p = p(0)\) and (68) shows that \(D(t)\) is decreasing for \(t = 0\).

We can also show that \(D^2(t)\) is continually decreasing so long as \(p(t) \neq p^0\). For, suppose that \(D^2(t)\) is no longer decreasing for the first time at the value \(t_0\) of \(t\). The relations (67), (66) and the condition on \(\eta\) show that \(D^2(0)\),
and consequently also \( D^2(t_0) \), are smaller than all the \( e^2/a_k \) (for \( k = 1, 2, \ldots, l \)). But it follows from the definition of \( D^2(t) \) that \( |p_h(t) - p^0_h|^2 \) is at most equal to \( a_hD^2(t) \); thus \( |p_h(t_0) - p^0_h| < \varepsilon \) for all \( h \). It follows therefore from (65) and (68) that \( D^2(t_0) \) is decreasing except when \( p(t_0) = p^0 \), in which case equilibrium is reached.

Thus the non-negative and never increasing quantity \( D^2(t) \) tends to a limit. If the limit is zero, \( p_h(t) \) tends to \( p^0_h \) for all \( h \), which is what we have to prove. Let us assume that the limit is \( D^2 \neq 0 \). Then there exists a sequence of values \( t_s \) (where \( s = 1, 2, \ldots \)), such that \( p(t_s) \) tends to a vector \( p^1 \) which differs from \( p^0 \). (Here we apply the property that every function defined on the set of positive real numbers and taking values in a compact set of Euclidean space has a point of accumulation; the function is \( p(t) \), the compact set is the set of vectors \( p \) such that \( D^2 \leq D^2 \leq D^2(0) \). If we consider the sequence of values \( t_s \) in (68), then by continuity, we can write

\[
0 = 2 \sum_{h=1}^{l} [p^1_h - p^0_h][\xi_h(p^1) - \xi_h(p^0)].
\]

In view of the reasons discussed in the previous paragraph, \( |p^1_h - p^0_h| < \varepsilon \) for all \( h \). The above equality is therefore incompatible with (65); this completes the proof of theorem 2.

For the exchange economy, the tâtonnement process described by (64) differs a priori from that just discussed since price-revisions entail changes in the value of the resources at the disposal of each consumer. If the good 1 becomes dearer relative to the other goods, there is a resulting change in the distribution of incomes in favour of those consumers for whom the ratio \( \omega_1/\omega_i \) is particularly high. Also, we have already seen that assumption 1, used in the proof of theorem 2, does not hold for the exchange economy.

However, we can immediately deduce a useful result from Walras' law, as expressed by (12). If we take account of (12) in the differential system (64), it implies

\[
\sum_{h=1}^{l} \frac{1}{a_h} \frac{dp_h}{dt} = 0,
\]  

or

\[
\sum_{h=1}^{l} \frac{1}{a_h} [p_h(t)]^2 = C,
\]

where \( C \) is a fixed number. Given the \( p_h(0) \), the evolution of the \( p_h(t) \) is restricted to (70), which can be considered as fixing a natural normalisation rule for the vector \( p(t) \).

We saw that, in the exchange economy, the equilibrium price-vector is defined only up to a multiplicative constant. No equilibrium price-vector \( p^0 \)
appears stable, or even locally stable, if we keep strictly to the definition of 
stability given before the statement of theorem 2. But this would be a mistake. 
When discussing stability in the context of the exchange economy we shall 
replace the phrase 'for any initial prices $p_n(0)$' by the following: 'for any 
initial prices $p_n(0)$ satisfying

$$\sum_{k=1}^{t} \frac{1}{a_k} \{[p_n(0)]^2 - (p_n^0)^2\} = 0.' \tag{71}$$

We can then state the following result†:

**Theorem 3.** If the global demand functions are differentiable and satisfy 
assumption 2 of gross substitutability, every equilibrium in the exchange 
economy is locally stable when the price-adjustments obey (64).

This concludes our investigation of adjustments towards equilibrium. 
Obviously there must be many possible variants of the theory, but we would 
gain relatively little in understanding of the real phenomena by digressing 
for too long in this course on such variants.

† For the proof, see, for example, T. Negishi, op. cit.
Imperfect competition and game situations

We have just made a study of general economic equilibrium on the assumption that perfect competition regulated the relations between agents. We must now continue with this investigation in the context of different institutional assumptions which represent other aspects of economic organisation as it actually exists. The latter is obviously very complex; not only does it involve the rules and customs governing contracts, but also certain objective situations which allow to individuals or to firms the possibility of contracting on particularly favourable terms.

Unfortunately, economic science has not yet established other general theories whose explanatory power is comparable to that which can be claimed for competitive equilibrium theory. Recent research is active and produces a number of useful results but exposing all of them here would be very lengthy and not very rewarding.

In these lectures, whose aim is the theoretical study of general equilibrium rather than of the multiple possible situations on the individual level, we therefore deal mainly with perfect competition. However, the theory of monopoly has been discussed briefly (see Chapter 3, Section 9). Similarly, we shall now devote some time to some other models of imperfect competition. We shall not attempt a thorough investigation, but only to say enough to clarify the bearing of the theory of competitive equilibrium, to present the main notions of the theory of imperfect competition, and to prepare the student who wants to follow the coming progress in the study of this large field.

The common feature of the different situations now to be discussed is that, when deciding on his own actions, each agent must form some precise idea of the decisions of each of the other agents taken individually. In perfect competition a consumer or a producer has to know only the prices of the different commodities, as these prices summarise for him the results of the decisions of all the other agents. Similarly, it is enough for a non-discriminating monopolist to know the aggregate demand function for his product without his having to understand the motivations behind the decisions of the various
consumers. This is no longer the case in the situations with which we are now concerned.

The theoretical study of these situations was initiated by A. Cournot and J. Bertrand in the mid-nineteenth century. It has been greatly advanced by the recent appearance of the theory of games, which offers a general conceptual framework that can accommodate the most widely varying cases. Before embarking on the study of particular situations, we shall introduce some notions borrowed from games theory. Just as we shall not attempt to give a systematic treatment of imperfect competition, so we shall not try to put forward the main body of this theory, but only what is strictly useful for a sound understanding of general economic equilibrium.

1. The general model of the theory of games

Suppose that a certain number of players take part in a game where they act according to certain rules. The gains that each player will make from the game depend on his own actions and also on those of the other players. If we consider the logical characteristics of the game and ignore the particular social context in which it is usually placed, we find an obvious analogy with the situations we have been discussing. Our agents correspond to the players, our physical or institutional constraints to the rules of the game, and our utilities or profits to the gains from the game. Hence the general concepts of the theory of games apply closely to the study of the economic world.

Let each player or agent be represented by an index \( r \) or \( s \) (\( r, s = 1, 2, ..., n \)). The action of \( r \) can be represented by a suitable mathematical entity \( a_r \), which is generally a vector in a certain space. The rules or constraints imply that \( a_r \) belongs to a set \( A_r \) which is given a priori:

\[
a_r \in A_r, \quad r = 1, 2, ..., n.
\]  

Finally, the pay-off \( W_r \) that the agent \( r \) makes from the game is a real function of the actions of all the agents:

\[
W_r(a_1, a_2, ..., a_n). \tag{2}
\]

This is a very summary representation of a game. But, contrary to appearances perhaps, it does not assume that the game consists of a single move in which all the players act simultaneously. In fact, \( a_r \) must be interpreted as a

\[\dagger\] On the theory of games, see, for example, D. Luce and H. Raiffa, *Games and Decisions*, John Wiley, New York, 1957.

\[\ddagger\] Here we ignore chance drawing, or the other random processes of which most games are composed, since they are not involved in the imperfect competition situations in which we are interested. Subject to an assumption about the nature of pay-off functions, the theory of games shows that the logical structure defined above applies to games of chance as well as to purely deterministic games.
'strategy' defining what the player r will do on each turn, in each of the situations in which he may find himself because of the actions of the other players. Suppose, for example, that the game consists of three moves and there are two players A and B, the former coming in on the first and third moves and the latter on the second move; suppose that B must choose between only two actions 1 and 2, and his choice is known to A on the third move. There are then three components in an action \( a_i \) by A: what A does on the first move, what he does on the third when B has chosen 1, what he does on the third when B has chosen 2. In fairly complex games, \( a_r \) obviously has a very large number of components; the representation by the \( A_r \) and \( W_r \) may be very complicated. But this in no way hinders an abstract, general study.

Given this logical structure, the theory of games proposes to determine which actions the n players adopt, or should adopt, when each of them knows the sets \( A_s \) and the pay-off functions \( W_s \) of the others together with his own set and his own function.

Note that the assumption that all the agents know the \( A_s \) and the \( W_s \) may appear restrictive when applied to the study of economic phenomena. It is a natural assumption to adopt for situations where there are few agents and each can without too much difficulty find out the conditions under which each of the others acts. But clearly this assumption makes the theory of games inadequate for the treatment of the problems raised by the organisation of exchanges of information within large communities (cf. Chapter 8).

If it had been able to provide a general solution to the problem which it set for itself, the theory of games would have become the basis for a large part of microeconomic theory. Unfortunately, it has not fully succeeded in doing so. Its special contribution has been a very considerable clarification of concepts in the questions that it has tackled and in the exhaustive treatment of some simple cases. In particular, the theory of the zero sum two person game,† has great elegance. But it scarcely applies to economic situations, and will therefore be ignored here.

A basic distinction throughout the theory of games is whether or not there is cooperation among agents. This distinction is of fundamental importance for formal theory as well as for deciding on the relevance of particular models in particular situations.

In the case of formal theory, the difficulties mentioned earlier are concerned precisely with the choice of general concepts to describe the result of cooperation among agents. It will become clear in the following sections why this is a difficult choice. On the other hand, the situation is easy if cooperation is excluded. The concept of non-cooperative equilibrium,

† We have a zero sum two person game if \( n = 2 \) and if \( W_1(a_1^1, a_1^2) \geq W_1(a_1^2, a_1^2) \) when and only when \( W_2(a_2^1, a_2^1) < W_2(a_2^2, a_2^2) \).
The general model of theory of games is a natural concept which can be applied to many different situations. By definition, such an equilibrium $E^0$ is a feasible state, that is, a particular specification $a^0_1, a^0_2, \ldots, a^0_n$ of the $a_1, a_2, \ldots, a_n$ belonging to their respective $A_r$'s such that

$$W_r(a^0_1, \ldots, a^0_{r-1}, a_r, a^0_{r+1}, \ldots, a^0_n) \leq W_r(a^0_1, \ldots, a^0_{r-1}, a^0_r, a^0_{r+1}, \ldots, a^0_n)$$

for all $a_r \in A_r$ and this for all $r$. In other words, $E^0$ is a non-cooperative equilibrium if each agent has no interest in changing his action when he considers the actions of the other agents as given.

But the problem of how to distinguish cases where it is more appropriate to assume cooperation rather than non-cooperation is still largely an open question. As we shall see from two examples, a non-cooperative equilibrium is not very likely to be realised in many situations where there are few agents since each agent is then aware that his decision reacts on the decisions of the others. On the other hand, where there are many individually small agents and where each agent has little information about the opportunities open to the others, non-cooperative equilibrium is obviously appropriate, since its occurrence does not require that each agent has much information.

So the population structure of agents appears to be an important factor in choosing between these two major hypotheses. But it is not the only one. For example, the degree of cooperation among agents is affected by the degree of continuity in the relationships which connect them (whether they are partners or competitors, suppliers and customers, employers and personnel, etc.).

Be that as it may, we shall begin our study of imperfect competition by looking at some apparently very simple cases such as bilateral monopoly, duopoly and bargaining. We shall go on to consider the formation of coalitions and try to find a general concept to describe the outcome of cooperative games. We shall study transactions in the exchange economy. The chapter will conclude with a discussion of monopolistic competition. In the next chapter we shall discuss other major problems of imperfect competition concerning situations where the number of agents is large.

Before embarking on this discussion we should note that many of the models of economic theory involve a complicating factor relative to the general model of the theory of games: the set $A_r$ of possible actions by the $r$th agent is not completely given $a$ priori; it depends partly on the actions of the other agents. So the general formula must take account of the fact that $A_r$ depends on the actions of agents other than $r$; hence we have an expression such as

$$a_r \in A_r(a_1, \ldots, a_{r-1}, a_{r+1}, \ldots, a_n) \quad r = 1, 2, \ldots, n.$$
However this complication has no substantial effect on the definition of the main concepts such as the Nash equilibrium. (Of course it is assumed that the $n$ conditions (4) are not mutually contradictory.)

2. Bilateral monopoly

Bilateral monopoly exists in the market for a commodity when there is just one buyer and one seller.

In this brief theoretical study we shall assume that the commodity in question is the first ($h = 1$), while all the other markets are competitive. We also assume that both the buyer and the seller are firms, the commodity 1 being an intermediary product, input for the first firm and output for the second. For the buyer ($j = 2$) and the seller ($j = 1$), the prices of goods other than the first are given. These two participants must decide the price $p_1$ and the quantity exchanged $y_1$.

Let $C_1(y_1)$ be the cost of production of $y_1$ for the seller, let $R_2(y_1) = p_1 y_1$ be the buyer's profit from his own activity when he uses the quantity $y_1$. The pay-offs for the two participants are respectively

$$W_1 = p_1 y_1 - C_1(y_1),$$
$$W_2 = R_2(y_1) - p_1 y_1.$$ (5)

We shall assume that $C_1$ and $R_2$ are twice differentiable and that $C_1 > 0$ and $R_2' < 0$.

In order to specify a model of the type introduced in the theory of games, we must also specify the actions $a_1$ and $a_2$ of the two firms and the corresponding domains $A_1$ and $A_2$. We can conceive of various models representing as many variants of bilateral monopoly, each containing a particular determination of the pair $(p_1, y_1)$ as a function of the actions $(a_1, a_2)$ adopted. We shall keep to a simple case, which is certainly relevant to some actual cases. We shall assume that the first firm, $A$, determines the price $p_1$, and the second firm, $B$, determines the quantity that it acquires, the domains $A_1$ and $A_2$ being then defined by $p_1 \geq 0$ and $y_1 \geq 0$.

Let us first examine the possibility of a non-cooperative equilibrium. If it takes price $p_1$, fixed by $A$, as given, the firm $B$ behaves as in perfect competition; it chooses $y_1$ so that

$$R_2'(y_1) = p_1,$$ (6)

or chooses $y_1 = 0$ if $R_2'(0) < p_1$.

If the firm $A$ takes $y_1$ as given, it is to its advantage to choose the highest possible value of $p_1$ (this value is infinitely large if $A_1$ is not bounded) except when $y_1 = 0$, when $p_1$ can have any value. Strictly speaking, the only possible non-cooperative equilibria correspond therefore to $y_1 = 0$ and $p_1 \geq R_2'(0)$, that is, to zero production of the good in question.
Bilateral monopoly

This shows that, when the firm $A$ is choosing $p_1$, it cannot ignore the possible repercussion of its choice on $B$'s demand. Too high a price eliminates the demand altogether.

It could try to maximise profit on the basis that $B$ fixes $y_1$ according to (6); it would then behave like a monopolist whose demand is defined by this equation. One can easily show that firm $A$ would then produce the quantity $y_*^1$, the solution of

$$C'_1(y_1) - y_1 R'_2(y_1) = R'_2(y_1)$$

and sell it at the price $p_1^* = R'_2(y_*^1)$.

But $B$ has basically no reason to behave according to (6) since it knows that it has only $A$ to deal with. For instance, it may refuse to buy the total output $y_*^1$ at price $p_1^*$, having every reason to believe that this attitude will induce $A$ to lower the price.

Before deciding on its behaviour, it is obviously to the advantage of each firm to discover the other's rule of action. It can do this by putting itself in the other's situation and determining its most profitable course of action.

Thus the two firms must realise, either immediately or after some probing, that it is to their mutual advantage to reach some explicit or implicit agreement acceptable to both. It is then of little importance that in principle the first firm fixes $p_1$ and the second $y_1$, since they do this jointly with a view to establishing a satisfactory combination $(p_1^0, y_1^0)$.

What will such a combination be? It appears that it must satisfy the following conditions:

(i) it must lead to a value of $W_1$ at least equal to $-C_1(0)$, since otherwise $A$ has no interest in any exchange with $B$;

(ii) it must give a value of $W_2$ at least equal to $R_2(0)$;

(iii) it must maximise $W_1$ subject to the constraint that $W_2$ retains the value $W_2^0$, since otherwise $A$ could suggest to $B$ a combination more satisfactory to itself, and equally satisfactory to $B$;

(iv) it must maximise $W_2$ subject to the constraint that $W_1$ retains the value $W_1^0$.

To make this more precise, let us first consider (iii).

If $y_1^0 \neq 0$, as we shall assume in order to avoid bringing in the Kuhn-Tucker conditions, then (iii) is expressed by the existence of a number $\lambda$ such that the derivatives of

$$[p_1 y_1 - C_1(y_1)] + \lambda [R_2(y_1) - p_1 y_1]$$

with respect to $p_1$ and $y_1$ are simultaneously zero.

The derivative with respect to $p_1$ is zero exactly when $\lambda = 1$. Equating to zero the derivative with respect to $y_1$ then implies

$$C'_1(y_1^0) = R'_2(y_1^0),$$

which determines $y_1^0$ uniquely since $C'_1$ is increasing and $R'_2$ is decreasing.
Imperfect competition and game situations

We obviously arrive at the same result by considering (iv). Finally it appears that (i) and (ii) fix an interval to which \( p_1^{0} \) must belong, namely

\[
\frac{C_1(y_1^0) - C_1(0)}{y_1^0} \leq p_1^0 \leq \frac{R_2(y_1^0) - R_2(0)}{y_1^0}.
\]  

(8)

In short, the combinations \((p_1^{0}, y_1^{0})\) that allow the parties to be in agreement all entail the same production, but price is restricted only to belong to (8). There are usually many such combinations. Their set is said to constitute the core of bilateral monopoly.

This set can be represented on a graph with \( y_1 \) as abscissa and \( p_1 \) as ordinate (cf. Figure 1). Each dotted curve groups the combinations for which \( W_1 \), or \( W_2 \), has the same given value. The curves \( W_1 = \text{const.} \) are tangential to the curves \( W_2 = \text{const.} \) along the vertical with abscissa \( y_1^{0} \). The core is represented by the interval \( RS \) on this vertical, contained between the two curves passing through the origin.

How can \( p_1 \) be determined within the interval (8)? Firm \( A \) wants the highest price, firm \( B \) the lowest price. Within the core, their interests are strictly opposed, and therefore the combination finally established is often said to depend on the respective powers of the two contracting parties.

Each may threaten to disregard the agreement in order to induce the other to accept his demands. But neither has a threat that guarantees him greater gain than he would realise if no exchange took place. So threats are only effective if an agreement is finally obtained.

We conclude this discussion by stating the following conclusions:

(i) non-cooperative equilibrium does not appear to be a useful solution to bilateral monopoly;

(ii) it is to the interest of the parties involved to come to an understanding, so that one of the combinations belonging to the core may be established;
(iii) the use of threats as a means of obtaining a particularly favourable combination involves the risk of disagreement, which may finally result in a combination outside the core.

3. Duopoly

Let us now consider the theory of duopoly, that is, of a market served by two producers, where demand originates from many individually small agents. Economic theory most often represents this situation under the assumption that the same price will apply to the exchange of all units of the commodity concerned† and that demand is competitive in the following sense: the total quantity sold depends on the price of the commodity but on nothing else (buyers' strategy is therefore not involved here).

Let us assume, for convenience, that the market is for the good 1, and that the demand law is decreasing and can be written.

\[ p_1 = \pi_1(y_1) \]  

(9)
as for monopoly. Total production \( y_1 \) is realised by the firms 1 and 2 whose outputs are \( y_{11} \) and \( y_{21} \) respectively.

For this investigation of duopoly, we assume that the prices \( p_2, p_3, \ldots, p_l \) of the other goods are fixed, for example on competitive markets, and that they are independent of \( p_1 \) and \( y_1 \). Strictly speaking, this can only happen if the good 1 is relatively unimportant so that, in particular, the demands of firms 1 and 2 on the markets for other goods are a negligible part of the market. The function \( \pi_1 \) is obviously defined with reference to the particular values of \( p_2, p_3, \ldots, p_l \).

Let \( C_1(y_{11}) \) and \( C_2(y_{21}) \) denote the cost functions of firms 1 and 2. Their respective profits are therefore

\[
\begin{align*}
W_1(y_{11}, y_{21}) &= y_{11}\pi_1(y_{11} + y_{21}) - C_1(y_{11}) \\
W_2(y_{11}, y_{21}) &= y_{21}\pi_1(y_{11} + y_{21}) - C_2(y_{21})
\end{align*}
\]  

(10)
The outputs \( y_{11} \) and \( y_{21} \) appear as the action variables of the two firms, \( W_1 \) and \( W_2 \) as their respective pay-off functions.

A. Cournot, who first investigated the theory of duopoly, suggested the solution of non-cooperative equilibrium defined in general terms in Section 1 above and which, when applied to duopoly, is known as the Cournot equilibrium. This solution assumes that each firm passively observes the other

† We shall not consider here the case in which the two producers could choose different prices and thus would enter into a price competition. This case leads to the paradox that, if demand is completely mobile between the two producers and therefore goes to the one proposing the lower price, this price must be set at the value it would have under perfect competition ('Bertrand paradox'). The relevance of this case ought to be discussed, which would lead us too far astray.
and takes its decision as given, then makes its own decision so as to maximise its gain. The equilibrium is then a pair \((y_1^0, y_2^0)\) such that \(y_1^0\) maximises \(W_1(y_1^0, y_2^0)\) considered as a function of \(y_1\), and \(y_2^0\) maximises \(W_2(y_1^0, y_2)\) considered as a function of \(y_2\).

But it is not at all obvious that, any more than in bilateral monopoly, the firms in this situation will adopt passive attitudes. Figure 2 will make this clear.

![Figure 2](image)

The curves which are concave downwards represent the contours \(W_1 = \text{const.}\), the curves which are concave to the left the contours \(W_2 = \text{const.}\). The curve \(AA'\) is the locus of the highest points on the contours \(W_1 = \text{const.}\). It defines, for each value of \(y_2\), the decision of firm 1 if it adopts a passive attitude. Profit \(W_1\) is obviously increasing downwards along a vertical, so that, on a horizontal (\(y_2\) given), it is to the advantage of firm 1 to choose the point which is tangent to one of the contours \(W_1 = \text{const.}\). Similarly, the curve \(BB'\) joining the points furthest to the right on the contours \(W_2 = \text{const.}\) defines the decision of firm 2 when it adopts a passive attitude. The Cournot equilibrium is then defined by the point of intersection \((y_1^0, y_2^0)\) of \(AA'\) and \(BB'\).

But firm 1 is usually assumed to know not only its own function \(W_1\) but also its competitor's function \(W_2\). It can then determine \(BB'\), which describes the behaviour of firm 2 when the latter is passive. In this situation, it is to the

\[\dagger\] We shall not discuss here conditions for the existence of such an equilibrium, not even for the continuity of reaction curves \(AA'\) and \(BB'\). Such questions are not well clarified for the various imperfect competition models. See for instance J. Roberts and H. Sonnenschein, 'On the Foundations of the Theory of Monopolistic Competition', *Econometrica*, January 1977.
advantage of firm 1 to choose on \( BB' \) the point at which it is tangential to a curve \( W'_1 = \text{const.} \), that is, the output \( y'_1 \), which in the case of our figure is clearly greater than \( y^0_1 \).

The firm 1 will probably be aware that it can realise a higher profit than its profit in the Cournot equilibrium. It may therefore decide on the output \( y'_1 \), for example. But the same reasoning applies to firm 2, which gains by choosing output \( y'_2 \), when it sees that its competitor has a passive attitude. Now, for each producer, the pair \((y'_1, y'_2)\) entails profits that are much lower than those in the Cournot equilibrium.

As in bilateral monopoly, when each participant is aware of the other's situation they must sooner or later reach an explicit or implicit agreement with each other, since only through such an agreement can a struggle damaging to both be avoided, provided that one of them does not think he can eliminate the other from the market. The latter case is excluded here.

What pairs \((y'_1, y'_2)\) allow such an agreement to be reached? Those which, in the first place, assign to each firm a profit at least equal to what it would obtain if it withdrew from the market, and which, in the second place, maximise each firm's profit for a given value of the other's profit. These pairs are represented in Figure 2 by the points on the curvilinear segment \( RS \) belonging to the curve joining the points of contact of the curves \( W'_1 = \text{const.} \) and the curves \( W'_2 = \text{const.} \), the point \( R \) lying on \( W'_1 = -C'_1(0) \) and \( S \) on \( W'_2 = -C'_2(0) \). As in bilateral monopoly, the set of pairs represented by the points on \( RS \) can be called the core.

Within the core, it seems \textit{a priori} that the position of \((y'_1, y'_2)\) is indeterminate. Each firm may try to obtain a particularly advantageous combination by threatening not to observe the agreement. But this pays only if the threat does not have to be carried out.

![Fig. 3](image)

The realisation of a combination belonging to the core objectifies the agreement between the two firms who do not generally behave, however, as a
monopolist would. The latter would try to maximise the total gain $W_1 + W_2$, which in most cases determines a unique pair $(y_{1*}, y_{2*})$ within the core.

This distinction is made clear in Figure 3, where $W_1$ and $W_2$ are abscissa and ordinate respectively. The core is represented by $RS$, which is the right upper boundary of the set of combinations $(W_1, W_2)$ resulting from all the possible choices of $y_{1*}$ and $y_{2*}$. (The Cournot equilibrium $C$ is represented by a point which lies inside $RS$.) The sum $W_1 + W_2$ is maximised for a particular combination $M$ where the tangent to $RS$ is parallel to the second bisector. Now, $M$ is not necessarily equally favourable to both firms; it may very well be rejected by one firm hoping to obtain a more advantageous point on $RS$.

However, it must be understood that if there is complete collusion between the two firms, they may realise any point on the tangent at $M$ to $RS$, for example $N$. They need only agree that one firm should make a direct payment to the other. In the case of our figure, the first pays the second a sum defined by the length of the projection of $NM$ on one or other of the coordinate axes.

Where there is complete collusion, the two firms behave like a single monopolist. The only issue between them is in the division of the total profit, that is, in the discussion of the collateral payment to be made by one to the other. Obviously each can use threats in the course of this discussion, at the risk of breaking the agreement.

4. The bargaining problem

The two previous sections both lead to the determination of a core in which the agreement between two participants who can benefit from reaching an understanding should be embodied. But the core has multiple elements and there is some doubt as to which can be the final choice.

Economic theory may be satisfied to stop at this point. In our two examples, which are fairly representative of the present problem, the final choice appears to be strongly dependent on the particular circumstances of the specific case considered; the relative strengths of the two participants, the duration of their confrontation or collaboration must be clearly understood and analysed in their real context.

But it may also appear relevant to find a clearly defined solution for cases where there are no additional circumstances and where the problem is defined completely by the model, such as the model of bilateral monopoly, of duopoly, or whatever. In fact, every logical analysis of the complications involved in each particular situation is liable to lead to the same difficulty, that is, to multiple possible solutions. It is therefore worthwhile to see if we can distinguish principles which govern a final choice. If such principles can be found then a solution is determined which generally covers a whole category of situations.
The so-called 'bargaining' problem sets the context of this research. Its definition is straightforward. The vector \( w \) of gains \( w_1 \) and \( w_2 \) of the two participants must be contained in a set \( P \); we know also that it takes the value \( v \) (which obviously belongs to \( P \)) if they do not reach agreement: on which vector \( w^* \) of \( P \) must agreement be reached? A general solution must describe how \( w^* \) depends on \( P \) and on \( v \) and is therefore a solution function:

\[
 w^* = \mu(v, P) \tag{11}
\]

whose value lies in \( P \).

Thus, in the case of bilateral monopoly, \( P \) can be defined by the set of values given for \( W_1 \) and \( W_2 \) by equations (5) when \( y_1 \) and \( p_1 \) are non-negative; \( v_1 \) is \(-C_1(0)\) and \( v_2 \) is \( R_2(0) \). In the case of duopoly without collateral payment the set \( P \) is bounded above by the curve \( SR \) on Figure 3 and the vector \( v \) can correspond to the Cournot point \( C \) on that diagram. Obviously we could choose other specifications; for example, the vector \( v \) which is realised in the absence of agreement may not be the vector corresponding to the Cournot equilibrium, but some other well-defined vector.

We must also take note of an important feature of many game situations or of imperfect competition, which does not appear in examples of bilateral monopoly and duopoly; the gains \( w_1 \) and \( w_2 \) are not always commensurable and may not even be defined uniquely. This happens where the participants are consumers and the gain \( w_i \) is the utility \( S_i \) which the \( i \)th consumer finally derives from his participation in the game.

So the gains \( w_1 \) and \( w_2 \) are not comparable if we assume the 'no bridge' principle discussed in Chapter 4, Section 8. The gains can also be said to be 'non-transferable' between participants.

Moreover it appears in this case that the same bargaining problem is defined by \((v^1, P^1)\) and \((v^2, P^2)\) if we can go from one pair to the other by applying a monotonic transformation to individual gains. For, suppose there exist two increasing functions \( \phi_1 \) and \( \phi_2 \) such that

\[
 v_i^2 = \phi_i(v_i^1) \quad i = 1, 2 \tag{12}
\]

and

\[
 w \in P^1 \quad \text{iff} \quad \phi(w) \in P^2 \tag{13}
\]

(where \( \phi(w) \) has components \( \phi_i(w_i) \) for \( i = 1, 2 \)).

We could then say that \((v^1, P^1)\) and \((v^2, P^2)\) correspond to exactly the same problem but with two different specifications of the same individual preferences.

Be that as it may, we set out to find the solution function \( \mu(v, P) \). We
should consider the desirable properties of this function and examine the resulting specifications for $\mu$. So we have to adopt a general axiomatic approach.

A completely defined solution was given by J. Nash who suggested the following four axioms:†

A.1. The solution must be a Pareto optimum; in other words $\mu(v, P)$ must lie on the North-East boundary of $P$.

A.2. The solution must be 'individually rational' in the sense that each participant's gain is at least equal to his gain in the situation where there is no agreement, that is, $\mu(v, P) \geq v$.

A.3. The solution must not be affected if $P$ is replaced by a set $Q$ which is contained in $P$ and which contains $\mu(v, P)$.

A.4. If there exist two linear increasing functions $\varphi_1$ and $\varphi_2$ such that conditions (12) and (13) hold, then the solutions of $(v^1, P^1)$ and $(v^2, P^2)$ must be essentially the same in the sense that $\mu(v^2, P^2) = \varphi[\mu(v^1, P^1)]$.

Given fairly unrestrictive conditions on $(v, P)$, Nash showed that there is only one solution function which satisfies these four axioms. More precisely, $\mu(v, P)$ is the vector which maximises in $P$ the product $(\mu_1 - v_1)(\mu_2 - v_2)$ of the additional gains derived by the two participants from their collaboration.

This result, which is surprising a priori, gives food for thought. We see that on the one hand, there is a very particular solution function meeting the four axioms while on the other hand, generally no solution function exists if the system of axioms is strengthened.

In fact, we might want to eliminate from A.4 the conditions that the functions $\varphi_1$ and $\varphi_2$ are linear (thus making A.4 more restrictive). But we see that then the Nash solution function no longer satisfies this axiom. In short, for this function to be acceptable, the existence of cardinal utilities must be assumed and while some economists think they can accept this, not all think so (see Chapter 2, Section 10).

We may also wish to add a fifth axiom expressing the fact that bargaining is usually carried out in successive stages, where at the end of each stage there is considered to be a reduction of the initial disagreement; to find $\mu(v, P)$ from $v$, we can proceed by determining the solution $\mu(v, Q)$ of a more restricted problem ($Q \subseteq P$). Hence the axiom

A.5. If $Q \subseteq P$, then $\mu[\mu(v, Q), P] = \mu(v, P)$.

We see that the Nash function does not satisfy this axiom either.

Consideration of this function has led most theoreticians to the final conclusion that axiom 4 is unacceptable since it is inconsistent with the fact that the outcome of bargaining depends on what the participants can regard as fair. Now this notion of fairness or justice does in fact imply some comparison of the gains in utility derived by both participants from their agreement. In short, the 'no bridge' principle is too restrictive if we want to understand bargaining. Let us discuss this.

Consider Figure 4 where the gains $w_1$ and $w_2$ are measured along the abscissa and ordinate respectively, where the vector $v$ is at the origin and $P$ is the triangle $OAB$. The Nash function leads to the midpoint $w^N$ of $AB$; it appears 'invariant' to a change of scale on the axes.

However this solution does not appear fair in terms of monetary gains since the first participant gains much more from collaboration than the second does; so it appears that they are much more likely to reach agreement on the fair outcome $w^f$ represented by the point where the bisector meets $AB$. Even if it is not a question of monetary gains the notion that the solution must be fair loses none of its force; it clearly requires a comparison of the gains in utility resulting from an agreement.

Hence it appears natural to require that the solution $w^*$ should satisfy

$$S_1(w^*_1) - S_1(v_1) = S_2(w^*_2) - S_2(v_2)$$

(14)

where $S_1$ and $S_2$ are two (increasing) cardinal utility functions associated with the two participants, functions which are completely defined (except
possibly for a constant term). Together with axiom A.1 condition (14) defines the solution function completely. Clearly this function satisfies A.2, A.3 and A.5 (but obviously not A.4).

5. Coalitions and solutions

The examination of the two particular cases of bilateral monopoly and of duopoly has led to conclusions that appear generally valid in any situation where there is a small number of participants. First, it is doubtful that a non-cooperative equilibrium will be realised. Second, whenever tacit or explicit agreements are made, we can base our reasoning on them, ignoring the action variables proper to each participant; all we are concerned with are the possible combinations of gains at the outcome of the game, which may vary according as collateral payments do or do not enter into consideration.

On the other hand, a common feature of these two cases is that they involve only two players and therefore every agreement necessarily involves all participants. In a situation where there are three or more agents, coalitions may be formed which group together only some of the agents. A priori the study of such coalitions appears relevant to the clear analysis of the interdependences between the actions of multiple individuals.

Let us consider this question in general terms.

An imputation is a set of $n$ real values $(w_1, w_2, \ldots, w_r, \ldots, w_n)$ which represents the gains of the players at the outcome of the game. An imputation is 'feasible' if there exists a set of possible actions of the $n$ players which allows the gains of this imputation to be realised. We can find the set of feasible imputations by taking account of the constraints (4) on the $a_r$ and the definitions (2) of the gains $W_r$.

In most cases there exists a minimum gain $v_r$ which each agent $r$ can ensure whatever the actions of the other agents. For example, in the exchange economy it is his utility $S_r(o_r)$ if he makes no exchange at all. (It would be tedious to try to define in general terms how the $v_r$ can be determined from the data (2) and (4) given for the problem.)

So an imputation $(w_1, \ldots, w_n)$ is said to be individually rational if $w_r \geq v_r$ for all $r$. For, it appears that we can exclude a priori an outcome in which a particular agent does not obtain his minimum ensurable gain. The imputation $w$ can also be said to be rejected by $i$ or 'blocked by $i$' if

Coalitions

By definition, a coalition is a subset \( C \) of the set \( I \) of \( n \) players: \( I = \{1, 2, \ldots, n\} \). From the theoretical standpoint it is convenient to keep the term coalition to apply possibly to the whole of \( I \) and also to the set \( \{r\} \) consisting of a single player \( r \).

The possibility of coalitions affects the outcome of the game either because only a coalition can achieve a certain result or because a particular coalition may prevent some other result from being realised. We introduce a simple formulation for our discussion of this problem.

An imputation \((w_1, w_2, \ldots, w_n)\) is 'feasible for the coalition \( C \)' if \( C \) can ensure for its members the gains \( w_r \) (for \( r \in C \)) however the players who are not in \( C \) may act. We note that an imputation is obviously 'feasible' if it is feasible for a coalition \( C \) and also for the complementary coalition of \( C \). (We shall not attempt to define here how the set of feasible imputations for \( C \) can be determined from relations (2) and (4) which define the game.)

A coalition may prevent the realisation of a particular imputation if it can procure for its members higher gains than those attributed to them by this imputation. This explains the following formal definition:

The coalition \( C \) blocks the imputation \((w_1^0, w_2^0, \ldots, w_n^0)\) if there exists an imputation \((w_1^1, w_2^1, \ldots, w_n^1)\) that is feasible for \( C \) and such that \( w_r^1 \geq w_r^0 \) for every player \( r \) of \( C \) and \( w_r^1 > w_r^0 \) for at least one player of \( C \).

Consider, for example, the case of bilateral monopoly, the firm \( A \) being player 1 and the firm \( B \) player 2. The coalition \( \{1\} \) consisting only of player 1 blocks every imputation that assigns to 1 a gain less than \(-C_1(0)\); the coalition \( \{2\} \) blocks every imputation that assigns to 2 a gain less than \(R_2(0)\); the coalition \( \{1, 2\} \) formed by the two firms blocks every imputation that does not maximise \( W_1 \) for a given value of \( W_2 \), or that does not maximise \( W_2 \) for a given value of \( W_1 \). We see that the core then consists of all the combinations \((p_1, y_1)\) corresponding to imputations that are not blocked by any coalition. We can establish the same for duopoly; hence the following general definition:

The core consists of the set of feasible imputations which are not blocked by any coalition.

The value of this definition derives from the idea that the game should naturally lead to an imputation belonging to the core.

However, there are three situations where this is not the case.

(i) As we saw earlier, the use of threats by some players may destroy the agreements reached and lead to unfavourable results for all the participants.

(ii) When there are more than a few players, the information which each possesses about the situation of the others often becomes very incomplete,
and the conclusion of agreements which are fruitful a priori may demand long and costly negotiations. Hence we talk of ‘information costs’ and ‘communication costs’, which may sometimes cause the agents to remain with an imputation that does not belong to the core.

(iii) Finally, it may be the case that the core is empty. For every possible imputation there may be a coalition capable of blocking it. We shall not encounter such situations in our discussion of economic theory. However, the fact that they may arise should be borne in mind.†

Clearly, in order to deal with cooperation and confrontation in situations involving several agents, games theory has not been restricted solely to the concept of the core, although this is the most frequently used concept in economic theory. A description of all the proposed concepts would be too much of a digression here, since most are rarely applied to the questions with which this book is concerned. However, a few brief remarks may be useful.

Clearly, games theory has tried to establish concepts by means of which the probable outcome of a game can be defined. The solution should be regarded as satisfying three conditions: it must be intuitively realistic, it must be applicable to all or most cases and must in most cases be unique. It has proved impossible to satisfy these three conditions simultaneously. So the various proposed concepts are the result of theoretical compromise.

We have seen that the core does not satisfy the last two conditions very well. It appears to satisfy the first; however, in certain circumstances the blocking coalitions which have to be considered may appear unlikely because they assume cooperation among agents for whom communication appears difficult. Now, all blocking coalitions are treated in the same way, however likely or not they are to be realised.

It was precisely to avoid the most extreme consequences of this situation that a principle has been adopted for finding the solution, which consists of simultaneous consideration of all coalitions in which each player may take part, thence to deduce some notion of the respective contractual strengths of the players, and to conclude that the outcome of the game must follow naturally and fairly from these contractual positions. This principle is due to L. S. Shapley and was later developed by him in collaboration with M. Shubik.‡ This solution is said to be the ‘Shapley value’, or simply ‘the value’.

Let us consider the rth individual’s contribution \( g_r(C) \) to the gain of coalition \( C \) if he enters it; for every \( C \) which does not contain \( r \) the

† For an example of a game with an empty core see Shapley and Shubik, ‘Quasi-cores in a Monetary Economy with Nonconvex Preferences’, *Econometrica*, October 1966.

‡ See, for example, Shapley and Shubik, ‘Pure Competition, Coalitional Power and Fair Division’, *International Economic Review*, October 1969.
contribution is equal to the gain for \( C \cup \{r\} \) minus the gain for \( C \). (It is easy to define this contribution when gains are transferable between individuals so that the total gain of a coalition is immediately meaningful; by an analysis similar to that carried out for the bargaining problem, the contribution of \( r \) to \( C \) can also be precisely defined in cases where gains are not transferable \textit{a priori}). Shapley takes the 'value' of what \( r \) finally obtains as equal to a suitably defined average \( \bar{g}_r \) of the \( g_i(C) \) over the set of coalitions \( C \) which do not contain \( r \). In the game, this average provides a natural measure of the contractual power of the \( r \)th individual; this measure must appear acceptable to himself and to the others so that, by common agreement, he should finally receive precisely \( \bar{g}_r \), which determines the imputations that ought to be chosen.

This concept has proved efficient for dealing with certain economic problems and often provides a useful alternative to the core when the solution requires cooperation among agents. We shall refer to it briefly in the next chapter.

We must bear in mind that in each case we must always ask whether non-cooperative equilibrium is not most relevant. The greater the number of agents, the more difficult it is for them to communicate, the more problematical becomes the penalty to those who would break an agreement, and the more likely it becomes that a non-cooperative equilibrium is established. On the other hand, when there are few agents who have to operate in a steady, regular fashion in a context whose evolution is slow, then they tend naturally to cooperate.

6. Arbitrage and exchange between individuals

We again turn our attention to general economic models. The introduction of production raises particular problems, which will be referred to at the end of this chapter. So we shall now confine ourselves to the exchange economy defined in Chapter 5. Consumers \( (i = 1, 2, \ldots, m) \) are in possession \textit{a priori} of quantities \( \omega_{ih} \) of the different commodities \( (h = 1, 2, \ldots, l) \). Following exchanges, they consume quantities \( x_{ih} \) such that each vector \( x_i \) belongs to the corresponding set \( X_i \). The vector \( x_i \) is the more advantageous the higher the value it gives for the utility function \( S_i(x_i) \), which is assumed to be continuous.

We have studied competitive equilibrium in an exchange economy. We can now find the states that are liable to be realised when perfect competition does not necessarily regulate exchanges. Every kind of imperfect competition being permitted \textit{a priori}, we wish to try to discover which states are capable of being established.
We approach this question with no preconceived ideas, as Edgeworth did at the end of the 19th century, and shall follow his line of reasoning.† This discussion will help towards a clearer understanding of some aspects of the formation of equilibrium. We shall use part of the terminology adopted by M. Allais for this topic.‡

Let there be two individual consumers $i$ and $\alpha$ who own respectively the quantities $x_{ih}$ and $x_{ah}$ of the various goods ($h = 1, 2, \ldots, l$). These are either the quantities $\omega_{ih}$ and $\omega_{ah}$ they owned originally or quantities they have acquired after some exchanges. We assume that they would both benefit from a transaction between them; let $z_h$ denote the quantity of $h$ that $i$ would give to $\alpha$ in this transaction, or $-z_h$ the quantity of the same good given by $\alpha$ to $i$. Since the operation would be mutually advantageous, $S_i(x_i - z) > S_i(x_i)$ and $S_\alpha(x_\alpha + z) > S_\alpha(z_\alpha)$.

The individuals $i$ and $\alpha$ may be unaware of this possibility of exchange. In this case, any third party who intervenes to enable them to carry out the operation has the possibility of profiting from it. Since $S_i$ is continuous, there exists a non-zero vector $w$ with no negative component and such that $S_i(x_i - z - w) > S_i(x_i)$. So the three individuals will benefit from a transaction where the quantities of $h$ in their possession will vary by $-(z_h + w_h)$ for $i$, by $z_h$ for $\alpha$ and by $w_h$ for the middle-man. Such a transaction is called an arbitrage.

In the above example, two consumers are involved in the possibility of exchange; this is bilateral arbitrage. In the same way, we can conceive of multilateral arbitrage where the possible exchange involves several consumers. The middleman in the arbitrage is able to profit by it. In what follows, we shall assume either that he is himself one of the agents or that his deducted proceeds $w_h$ are sufficiently small to be ignored.

Here we shall use the term ‘stable allocation’ for a state in which no further arbitrage, bilateral or multilateral, is possible; all market dealings are concluded and there is no further possibility of exchange. Obviously there is no reason for such a state to coincide with a competitive equilibrium.

A stable allocation $E^0$ as thus defined is clearly a distribution optimum. Otherwise there exists another feasible state $E^1$ preferred by one consumer and judged at least equally good by all the others. To say that $E^1$ is feasible is equivalent to saying that passage from $E^0$ to $E^1$ constitutes an exchange. The

‡ Allais, ‘Les conditions de l'efficacité dans l'économie'; a paper read to the Rapallo Seminar (Centro Studi e Richerche su Problemi Economico-Sociali) September 1967, parts IV-VI.
possibility of arbitrage (perhaps involving all the consumers) therefore exists. This is contrary to the fact that $E^0$ is a stable allocation.†

The notion of arbitrage can also be used to describe the process of exchange. If the initial situation, with each consumer owning quantities $\omega_{ik}$ is not a stable allocation, certain exchanges and arbitrages take place. The quantities owned by the different individuals are therefore changed as often as necessary for the realisation of a stable allocation. The utility functions $S_i$ cannot decrease during these exchanges. If we also assume that no advantageous possibility remains ignored indefinitely‡ then the process in question is convergent.§

However, the theory as thus constructed is not very specific; it is compatible with multiple paths to a stable allocation. This is illustrated for example by Figure 5, applying to the case of two goods and two agents and assumed to have been constructed within an Edgeworth diagram. $PR$ and $PS$ are the indifference curves passing through $P$, the point of initial resources. $RS$ is the locus of Pareto optima. A path implying three exchanges has been shown ($P$ to $E^1$, $E^1$ to $E^2$, $E^2$ to $E^0$). Each exchange improves the utilities of the two consumers. But there are many other possible paths and the final state can be represented by any point within $RS$.

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† In the definition of arbitrage, strict inequalities have been set for the comparisons of utility levels. If the exchange consisting of going from $E^0$ to $E^1$ implies some equalities, small modifications can be made in $E^1$ and thus a state $E^2$ can be defined such that all utilities increase in the passage from $E^0$ to $E^1$. This possibility is guaranteed by the fact that the functions $S_i$ are continuous and that they can increase in the neighbourhood of $E^0$ (needs are not completely satiated).

‡ As in the discussion of the core, we assume here that, in the first place, information is sufficiently well transmitted that an informed middleman always exists to undertake an arbitrage, and, in the second place, that no agent absolutely rejects a transaction that is to his advantage, as he might do after having put forward demands unacceptable to the others.

§ It is left to the reader to formulate and prove this property. For a very similar approach to that used here, see Hahn and Negishi, 'A Theorem on Non-Tâtonnement Stability', *Econometrica*, July 1962.
7. The core in the exchange economy

The segment RS in Figure 5 recalls similar segments in Figures 1 and 2. So we may ask if the set of stable allocations does not define a 'core', similar in conception to that introduced by the theory of games.

This is not a purely formal question, since the exchange economy has the same basic nature as a game: in the context of certain constraints, the agents choose actions or strategies which, when taken together, result finally in utility levels \( S_i \), which are completely analogous to the pay-offs \( W_r \), in the theory of games.

Of course, we should find it hard to give a formal description of the initial actions of the parties to an exchange—approaches, propositions, counterpropositions, etc. The concept of a 'transaction', which implies an agreement between two parties, is likely to be more fruitful. But this is relatively unimportant. By far the largest part of the theory of games can be built up without reference to the initial actions of the players. It is sufficient to determine the sets of feasible imputations for each of the coalitions.

In the exchange economy, the imputations are the utility levels which result from the consumption vectors. We can therefore reason directly on the basis of the concepts of 'state' or 'allocation': the set of \( m \) vectors \( x_i \). The general definitions given previously can easily be transposed.

A coalition is a subset \( C \) of the set of \( m \) consumers. The state \( E^0 \) is feasible for the coalition \( C \) if:

\[
\begin{align*}
    x_i^0 & \in X_i & \text{for } & i \in C \\
    \sum_{i \in C} (x_i^0 - \omega_{ih}) &= 0 & \text{for } & h = 1, 2, \ldots, l.
\end{align*}
\]

Conditions (15) and (16) guarantee that it is possible for the members of \( C \) acting in common, independently of those who do not belong to \( C \), to obtain the \( x_i^0 \).

A state \( E^0 \) is 'feasible' if it is feasible for the coalition comprising all the consumers. The feasible state \( E^0 \) is 'blocked by the coalition \( C \)' if there exists a state \( E^1 \) that is feasible for \( C \) and is such that:

\[
S_i(x_i^1) \geq S_i(x_i^0) \quad \text{for} \quad i \in C,
\]

where the inequality holds strictly for at least one consumer in \( C \). Condition (17) guarantees that the \( x_i^1 \) are preferable to the \( x_i^0 \) for the members of \( C \).

The 'core' of the exchange economy is naturally the set of feasible states \( E \) which are not blocked by any coalition. We can immediately establish for it the following two properties:

**Proposition 1.** Every state \( E \) belonging to the core is a distribution optimum.

If, in fact, a feasible state \( E \) is not an optimum, then it is blocked by the coalition of all consumers.
PROPOSITION 2. If the $X_i$ and the $S_i$ satisfy assumptions 1 and 2 of Chapter 2, then every competitive equilibrium $E^0$ belongs to the core.

For, let $p$ be the price vector corresponding to $E^0$. Suppose that there exists a coalition blocking $E^0$. The inequalities (17), of which at least one holds strictly, and the consumers' rule of behaviour then imply:

$$\sum_{i \in C} (px_i - p\omega_i) > 0$$

(the detail of the proof is exactly the same as for proposition 2 of Chapter 4, relating to the optimality of market equilibria). The above inequality contradicts (16), which must be satisfied by $E^1$ for the existence of $C$.

Thus propositions 1 and 2 establish that the core is contained in the set of all the distribution optima, but it contains the unique or multiple competitive equilibria.

We can again consider the graphical representation of the core in the case of only two goods and two consumers (see Figure 6, constructed like an Edgeworth graph).

We know that the core is represented by a part of $MN$, on which lie the distribution optima, that is, the points where the two consumers' indifference curves are mutually tangential. The states represented by points outside $MN$ are just those blocked by the coalition $\{1, 2\}$. The states blocked by the coalition $\{1\}$ are represented by the points on the left of the indifference curve $\mathcal{S}_1^*$ passing through the point $P$ representing the initial distribution of resources between the consumers. Similarly, the states blocked by the coalition $\{2\}$ are represented by the points on the right of the indifference curve $\mathcal{S}_2^*$ passing through $P$. So finally, the core is the part $RS$ of $MN$, from the point $R$ of intersection with $\mathcal{S}_1^*$ to the point $S$ of intersection with $\mathcal{S}_2^*$. We see that the competitive equilibrium point $M$, where the common tangent to two indifference curves passes through $P$, belongs to the core.

![Fig. 6](image-url)
The similarity between Figure 6 and Figures 1 or 2 shows that we could go on to discuss the exchange of two infinitely divisible commodities between two consumers along the same lines as we discussed bilateral monopoly and duopoly. But enough has already been said about this kind of question.

In the diagram, the set of stable allocations coincides with the core except for the bounding points \( R \) and \( S \) (but this difference results from a different treatment of the inequalities). We can easily understand the reason for this. Every allocation that does not belong to the core defines a state in which, by hypothesis, there is a possibility of arbitrage. Conversely, every state \( E^0 \) of the core (with the exception of \( R \) and \( S \)) is a stable allocation for the economy in question since to go from the initial state \( P \) to \( E^0 \) is an advantageous arbitrage, and, once \( E^0 \) is reached, no possibility of arbitrage exists.

Is this coincidence general? We shall see that it does not apply to cases of more than two agents because of a difference in point of view for the process through which equilibrium is realised. Let us start by considering a particular case.

Suppose that there are two goods and three agents who initially possess the resources defined by the following vectors:

\[
\omega_1 = \begin{bmatrix} 0 \\ 2 \end{bmatrix}, \quad \omega_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \quad \omega_3 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.
\]

(18)

We assume that the three agents have identical preferences represented by the utility function

\[
S_i(x_i) = x_{i1} x_{i2} \quad (x_{ih} \geq 0).
\]

(19)

The following two exchanges define a possible path to a stable allocation:

(i) Agents 1 and 2 conclude a transaction in terms of which the second gives \(1/4\) of good 1 while the first gives \(3/2\) of good 2. The utility of the first goes from 0 to \(1/8\), while the second's goes from 1 to \(15/8\). The quantities in their possession after the exchange are

\[
x_1 = \begin{bmatrix} 1/4 \\ 1/2 \end{bmatrix}, \quad x_2 = \begin{bmatrix} 3/4 \\ 5/2 \end{bmatrix}, \quad x_3 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.
\]

(20)

(ii) Agents 2 and 3 then conclude a transaction in terms of which 3 gives \(1/4\) of the first good while 2 gives \(1/2\) of the second good. The utility of 2 goes from \(15/8\) to 2, and that of 3 from 1 to \(9/8\). The quantities finally in the possession of the agents are:

\[
x_1^o = \begin{bmatrix} 1/4 \\ 1/2 \end{bmatrix}, \quad x_2^o = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad x_3^o = \begin{bmatrix} 3/4 \\ 3/2 \end{bmatrix}.
\]

(21)

We could check that this resulting state \( E^0 \) is a stable allocation; it is also a distribution optimum with which we can associate the prices \( p_1 = 2, \ p_2 = 1 \). Under our definitions, the state \( E^0 \) does not belong to the core since it is
The core in the exchange economy

If they combine their initial resources defined by (18), these two agents can realise the allocation

\[ x_1^* = \begin{bmatrix} 1/4 \\ 1 \end{bmatrix}, \quad x_2^* = \begin{bmatrix} 3/4 \\ 2 \end{bmatrix} \] (22)

which is clearly better for them than that defined by (21).

As this example shows, the difference between a core and a set of stable allocations does not lie in the distinction between two methods of approach using the central notions of ‘arbitrage’ and ‘coalition’ respectively. Arbitrage can be defined as the operation by which a coalition goes from one allocation to another which is better for its members. The difference lies in the description of the process by which exchanges are carried out.

The idea that the chosen allocation must belong to the core makes the implicit assumption that no operation is concluded which leads to a state outside the core, or that any operation of this type which is concluded can be rescinded in favour of others. Edgeworth introduced the assumption that agents are free to recontract, that is, that the contracts agreed at the start of the exchanging process can always be annulled later if more advantageous contracts appear. In our example, agent 1, who initially agreed to the exchange leading to (20) would be free to reverse this decision when agent 3 suggests the more advantageous exchange leading to (22).

A priori, the assumption that contracts are not binding until a state belonging to the core is reached does not appear at all realistic. But it must not be taken too literally. Its meaning is rather that the agents do not commit themselves definitely before they have explored the various contracts that may be offered to them. In fact, looking at the data in our example, we cannot but feel that it is equally unrealistic to assume that agent 1 commits himself definitely to the exchange (i) with agent 2 on such relatively unfavourable terms.

The possibility of recontracting assumed by Edgeworth and by the theory of games is basically similar to Walras’ assumption of tâtonnement where contracts are not concluded until equilibrium prices are reached. It assumes that there is a high degree of concerted action among agents, and therefore the theory to which it leads is relatively specific.†

If this possibility is rejected, the stable allocations that can be realised from a given initial situation appear very indeterminate, particularly in economies with a large number of agents. Of course, we know that such an allocation is

† It may be mentioned here that Walras’ assumption has been rejected by some researchers into dynamic processes for an economy where there exist prices known by all the agents, and where definite contracts are concluded between some buyers and sellers before equilibrium prices are determined. These have been called ‘non-tâtonnement’ processes. See Negishi, ‘The Stability of a Competitive Economy; a Survey Article’, *Econometrica*, October 1962.
an optimum and is preferred to the initial situation by each agent for whom it differs from the initial situation. But nothing more precise can be said on the basis of general logical analysis. So, as always, we must choose between the unrestricted but unspecific theory of stable allocations and the more specific but more restrictive theory of the core.

However, we must again take note here that, if there is a large number of agents, information costs and communication costs may make it difficult to discover an allocation belonging to the core. To assume that the state finally chosen is an element of the core is to assume solution of the problem of optimality with which a large part of microeconomic theory is concerned.

In the last two sections we confined ourselves for simplicity to exchange economies. The concepts introduced and discussed can be generalised in various ways to an economy containing producers. The difficulty stems from the fact that profit maximisation is no longer suitable as a criterion of choice for producers since they no longer consider prices as given. The theory must therefore specify how decisions are taken in firms. It is certainly natural to assume that consumers control the firms. But a priori, there are various conceivable ways in which this control and its implications may be specified. The simplest is to assume that each firm is the property of a single consumer who is in full control of it and may use its net output either for his consumption or for the exchanges in which he becomes engaged.

Given this personalisation of firms, the theories of the last two sections can be generalised in a very natural way. Less elementary specifications have also been studied.†

8. Market games

The representation that was given of exchange in the two preceding sections may appear as somewhat inadequate for most trades taking place in modern economies. Indeed, prices of the commodities do not appear explicitly, although terms of trade can of course be found whenever the exchange of a quantity of one commodity against a quantity of another occurs. Actually, prices are often posted and announced, usually by sellers, sometimes also by buyers, these prices being then offered to anyone who turns out to be interested.

On the other hand, when explaining how competitive equilibrium is reached, one is used to refer to an auctioneer who would propose and revise the price that sellers and buyers then have to accept (see Chapter 5, Section 10). This again is somewhat inadequate, since auctioneers actually

† See P. Champsaur, 'Note sur le noyau d'une économie avec production', *Econometrica*, September 1974.
exist only on special markets, such as those concerning stock exchange or commodity future exchange.

It is possible to come closer to reality and to specify a 'market game' in which the actions of potential traders concern for each commodity both a price and a quantity offered. The rule of the game is expressed by an 'outcome function' stating the exchanges that will then result.

Let us make this precise.† In the market game of an exchange economy, an action of consumer \( i \) will consist of two vectors \( p^i \) and \( z^i \), the component \( p^i_h \) being the price at which individual \( i \) offers to sell up to the quantity \( z^i_h \) (if \( z^i_h > 0 \)) or to buy up to the quantity \( -z^i_h \) (if \( z^i_h < 0 \)). In order for this action to be feasible it is of course required that \( z^i_h \leq \omega_{ih} \).

The outcome function defines the actual trades following from the actions \((p_i, z_i)\) chosen by the \( m \) individuals. It represents how the markets are supposed to operate. This is then the crucial part in the specification of the market game.

In the first place, it is assumed that each market operates independently of the others. This means that the outcome function is made of \( l \) separate vector functions \( g_h \). The function \( g_h \) concerning commodity \( h \) has \( 2m \) arguments, namely the numbers \( p^i_h \) and \( z^i_h \) announced for this commodity by the \( m \) individuals; this function defines the trades on commodity \( h \). We may as well say that, for each individual \( i \), it defines:

(i) the consumption \( x_{ih} \) obtained from his initial endowment \( \omega_{ih} \) and his net purchase,

(ii) the return \( r_{ih} \) of his exchange on this market; this return is an entry in an account, the unit being the numeraire in which prices are being quoted (we may say that \( r_{ih} \) is a quantity of 'money'); it is positive if \( i \) sells some of his endowment, negative if he is a buyer for commodity \( h \). Hence, the function \( g_h \) takes its values in the \( 2m \) dimensional space. How is this function specified? Equivalently, how are the trades \( \omega_{ih} - x_{ih} \) and the returns \( r_{ih} \) determined from the propositions \( p^i_h \) and \( z^i_h \)?

The natural answer is to say simply that the trades are determined by the intersection of a supply and a demand curve. The proposals of the various agents are classified; supply proposals \( z^i_h \) are ranked and cumulated in the order of increasing corresponding prices \( p^i_h \); demand in the order of decreasing prices. An ascending supply step function may be thus graphed in the \((z_h, p_h)\) plane and a descending demand step function is similarly graphed (see Figure 7). Examination of these two graphs shows which trades the outcome function should declare as occurring.

† This section draws directly from P. Dubey, 'Price–Quantity Strategic Market Games', *Econometrica*, January 1982.
Limiting ourselves here to the simple case of Figure 7 in which there is one and only one point of intersection between the supply line $SS'$ and the demand line $DD'$, we see that the ordinate $p^*_h$ of this point must give the answer. Supply proposals for which $p'_h < p^*_h$ are fully realised, those for which $p'_h > p^*_h$ not at all, the opposite being true for demand proposals. The proposal for which $p'_h = p^*_h$ are realised to the extent required for balancing trades between sellers and buyers. The specification of the outcome function must still say how the returns $r_{ih}$ are determined; one specification may be that sellers sell at the prices they quote whereas buyers are served by sellers in the order exhibited by the supply and demand graphs, the buyers proposing the highest price being first served from the seller announcing the smallest price. Other conventions are of course possible for the specification of the outcome function.

In order to complete the definition of the game, we must still specify the pay-off $W_i$ to consumer $i$. Quite naturally it is a function of the $2l$ outcomes concerning him: $x_{ih}$ and $r_{ih}$ for $h = 1, 2, \ldots, l$. One particular specification is given by:

$$W_i = \lambda_i S_i(x_i) + \text{Min} \left\{ 0, \sum_{h=1}^{l} r_{ih} \right\}$$

in which $S_i$ is the utility derived from consumption whereas $\lambda_i$ is a given positive number. This simply says that the balance of the account of consumer $i$ has no value for him if it is positive but imposes a utility penalty if it is negative.
Laboratory experiments

What kind of insight results from the consideration of market games? It is too early for a complete answer, since the subject appeared in mathematical economics only recently. Already now, it has been proved that the Nash equilibrium of a market game coincides with the competitive equilibrium of the exchange economy for which it is specified (or the Nash equilibria coincide with the competitive equilibria if several of them exist). The characterization of the Nash equilibrium proceeds in two steps:

(i) at such an equilibrium all trades are made at the same prices, namely \( p_h^i = p_h^* \) for all \( i \) selling commodity \( h \),

(ii) these prices are the ones appearing in the competitive equilibrium.

Whether such a result supports the view that perfect competition tends to emerge on free markets crucially depends on whether the Nash equilibrium is considered to be the appropriate concept to which one should refer. As was argued in Section 1 when the concept of the Nash equilibrium was introduced and defined, cooperation is likely when few agents only are involved in the game, in which case knowing the Nash equilibrium may have little interest for knowing the actual outcome of the game. On the contrary when many agents participate, none of them being comparatively too big, the Nash equilibrium has a good chance of being appropriate. Hence, the result concerning market games gives some support to the idea that perfect competition should prevail on atomistic markets, an idea that will be discussed again in the next chapter.

9. Laboratory experiments

Although these lectures concern theory only, it is appropriate to make here a quick reference to a line of experimental research concerning the formation of prices in various situations where the number of individuals, their relative sizes and the market institutions ruling the exchange of goods among them are given. Formation of prices is such a recurring theme throughout the lectures that special interest attaches to systematic confrontation of theoretical constructs against what real people do when they act within a real process whose outcome means real gains for them. This is precisely the object of laboratory experiments, which were recently surveyed by C. R. Plott.†

As usual, a careful experimental procedure is required if one wants to reach significant results that remain valid upon replication by other experimenters. Explaining here how this condition is now met by re-

† Charles R. Plott, 'Industrial Organization Theory and Experimental Economics', Journal of Economic Literature, December 1982. This section directly draws from it.
searchers dealing with the present subject would require more space than

One clear conclusion seems to be that the exact nature of market

tions matters for the determination of prices. For instance, our
discussion of arbitrage and of the core of an exchange economy in

instrumental cases. In oral double auction markets each partici-
pant may make a public offer to buy or sell a number of units of the good
at the price he wants; each participant may accept any one of such offers
which remain outstanding for a period and under conditions made precise
by the rules of the experiment. The overwhelming result is that in these
markets the price of transactions converges fast to the competitive price,
even with very few traders.

In posted-price markets, sellers publicly announce the price they will
charge, before buyers decide what to do. As a result it appears that sellers
tend to post at first a price exceeding the competitive price. Depending on
the experiment, when the same situation is repeated, convergence to the
competitive price is more or less fast; it may even fail to occur. In any case
the efficiency of this form of institution is lower than that of oral double

Taken all together, these results suggest that the competitive equilib-
rium is a fairly reliable guide for assessing what can happen in exchange
economies. No other concept emerges that would be proved superior, even
for a particular class of situations of some general relevance.

Experiments were also conducted for the purpose of confronting
monopoly and oligopoly theories to actual behaviour. Here, the results are
not always favourable.

When a monopolist has to post his price and serve buyers, the
theoretical equilibrium determined by equality between marginal cost and
marginal revenue seems to appear, at least after a few repetitions of the
same situation. But with oral double auction the standard monopoly model does not do so well and the price is often definitely smaller than the monopoly equilibrium price; on occasion, it actually approaches the competitive equilibrium.

It is not surprising then to find that for oligopoly, about which theory is much less definite, experimental results are still less clearcut. Depending on details of the experiment and in particular on the type of market process that is chosen, one obtains results of one kind or another. Tendency towards the competitive equilibrium appears more often than most economists would have thought; but cases of instability also appear. With duopoly one sometimes finds the full cooperation equilibrium and, as the number of oligopolists increases, the frequency of occurrence of the Cournot–Nash equilibrium also seems to increase. This whole area obviously is a domain for more research.

10. Monopolistic competition

The main interest of theories of imperfect competition and of economic applications of the theory of games must clearly lie in the analysis of large firms' decisions since in most cases the latter are arrived at in contexts far removed from that of perfect competition. The study of such decisions, of their motives and their results now follows an empirically based approach which concentrates on the following three aspects: (1) the situation of the firm, that is, the market structures within which it buys its factors and sells its products, structures which are more or less competitive or oligopolistic; (2) its conduct, that is, its behaviour as buyer, producer, seller and investor, and the strategies which it adopts; (3) its performance, that is, its profitability, its solvency, its gains of market share, etc.†

In general, the many investigations which adopt this approach have taken little advantage of developments in games theory. The basic reason is that the situations which this theory deals with are far too simple


Some measures are now commonly used to characterize market structures. If \( s_j \) is the share of firm \( j \) in the market of a particular good (its output divided by the aggregate output of the \( m \) firms producing this good), concentration measures are functions of the \( m \) numbers \( s_j \). For instance the \( k \)-firm concentration ratio \( C_k \) is the sum of the \( k \) biggest \( s_j \), the Herfindahl index \( C_H \) is the sum of the \( m \) squares \( s_j^2 \). Simple relations have been proved to hold between any one of these concentration measures, the demand elasticity of the good and some average of the 'degree of monopoly'. The degree of monopoly enjoyed by a firm was defined long ago by A. Lerner as being equal to the margin between price and marginal cost, divided by the price. On these relations see D. Encaoua and A. Jacquemin, 'Degree of Monopoly, Indices of Concentration and Threat of Entry', International Economic Review, February 1980.
relative to the complex real world. For economics the theory of games appears to be more directly useful in the development of theoretical foundations than in dealing with applications.

The alternative view of the context in which firms operate, a view which for long has frequently been preferred to perfect competition, regards each firm as having 'its market', as having formed a clear idea of the demand for its product and as taking advantage of possible inelasticity of this demand. In short, some firms see themselves as having some degree of monopoly in their markets while others have competitive markets for their products. Most firms have factor prices imposed on them but some monopsony situations may also exist.

This is what we refer to as 'monopolistic competition'. It is assumed that each firm decides on its actions without identifying individually the various partners with which it trades or competes. It considers only the demand and supply functions with which it is faced and takes no account of its partners' reactions to its behaviour. So this is basically a case of 'non-cooperation' which is very different from that discussed in most of the previous sections.

The point of departure for a formal description of monopolistic competition is obviously to be found in the partial equilibrium monopoly theory (see Chapter 3, Section 9). But this theory must be integrated into a general equilibrium model. There are various conceivable methods and some do not require that the demand functions as they are perceived by firms should coincide with the true demand functions. Here we shall only discuss the principles on which one possible model is based.

Agents are represented as in Chapter 5 for the general competitive equilibrium. In particular, the $j$th firm has a production set $Y_j$ and the $i$th consumer receives a share $\theta_{ij}$ of the firm's profit. In equilibrium a price $p_h$ exists for each good $h$ and this price applies in all transactions involving this good. Consumers are unaware of any influence they can exert on prices and so they behave exactly as they would in perfect competition.

We then have the global consumer demand function

$$\xi(p; y_1, \ldots, y_m) = \sum_{i=1}^{m} \xi_i(p_i; R_i)$$

(24)

where

$$R_i = p_0 + \sum_{j=1}^{n} \theta_{ij} p y_j$$

(25)

(obviously the number of components of the vectors \( p, y_j, \omega_i \) and the vector functions \( \xi \) and \( \xi_i \) is the same as the number of goods). We can define an 'exchange equilibrium' \((p; y_1, \ldots, y_n)\) as a set consisting of a price vector \( p \) and production vectors \( y_j \) such that

\[
\xi(p; y_1, \ldots, y_n) = \sum_{i=1}^{m} \omega_i + \sum_{j=1}^{n} y_j
\]  

(25)

where obviously the \( y_j \) belong to their respective \( Y_j \).

Let us assume that the set of exchange equilibria is such that one, and only one, equilibrium corresponds to each \( n \)-tuple of vectors \( y_j \in Y_j \) (this will not always be so, but this assumption is made here for simplicity). We can then say that in the equilibrium, the price vector is a function of the vectors \( y_j \)

\[
p = \pi(y_1, \ldots, y_n).
\]  

(27)

The assumption which underlies the formal model of monopolistic competition here discussed is that each firm \( j \) knows the function \( \pi \) and takes as given the vectors \( y_k \) of the other firms \((k \neq j)\). In other words, the demand or supply function with which it is confronted for the good \( h \) results from the \( h \)th component of the vector equation (27) when all the \( y_k \) other than \( y_i \) are taken as fixed. If the firm does not represent an appreciable part of the market for commodity \( h \) it is to be expected that \( \pi_h \) does not vary much as a function of \( y_j \) so that, to all intents and purposes in this model, price \( p_h \) is imposed on the firm.

Under the assumption so specified the \( j \)th firm maximises its profits, that is it chooses the vector \( y_j \) of \( Y_j \) which maximises

\[
y_j \pi(y_1, \ldots, y_j, \ldots, y_n)
\]  

(28)

considered as a function only of \( y_j \). It follows that \( y_j \) is a function of the vectors \( y_k \) chosen by the other firms:

\[
y_i = H_j(y_1, \ldots, y_{j-1}, y_{j+1}, \ldots, y_n).
\]  

(29)

A monopolistic competition equilibrium can then be deduced directly from any solution of the system of \( n \) equations (29).

There is not much point in emphasising the mathematical difficulties which may arise here; for example, the proof that solutions to (29) exist is not straightforward and it is also easy to produce cases where the functions \( H_j \) are not continuous. Nor do we propose to discuss how the 'theory of value' is affected if a perfect competition equilibrium is replaced by a monopolistic competition equilibrium.

On the other hand we see that, from the standpoint of games theory, the 'solution' adopted is in fact a non-cooperative equilibrium; hence it is sometimes called a 'Cournot–Nash equilibrium'. (We saw earlier that the
Cournot equilibrium for duopoly is non-cooperative and that Nash discussed non-cooperative equilibria before tackling the bargaining problem, which is of quite a different kind.)

11. What firms exist?

The theories discussed so far take as given both the population of consumers and the population of firms. Now, if the emergence and disappearance of households, which constitute by far the greatest part of consumers, are essentially governed by non-economic factors, this is certainly not the case where firms are concerned. An economic theory which fails to describe how firms are created and how they disappear is obviously incomplete.

So the assumption that the $n$ firms $j$ and their production sets $Y_j$ are given from the outset must be questioned. It appears inappropriate for a complete theory of the allocation of resources.

However we must note that, in the formalisations discussed up till now, there is nothing to exclude the possibility that the $j$th firm is inactive ($y_j = 0$). So we can think of the population of $n$ firms as comprising not only actually existing firms, but also all those capable of existing in the context under discussion. Since the number $n$ of firms is arbitrary, this interpretation raises no difficulty.

However the question remains as to whether the theories described so far are adequate to explain which firms are active ($y_j \neq 0$) and which firms remain purely potential ($y_j = 0$). We must discuss this question briefly.

In the real world, the number of firms appears to be limited especially by the size of the market. At a given moment, technical knowledge can be applied efficiently only in production units of a certain size. But undue size can also lead to inefficiencies in organisation, in the division of labour and in the transmission of information. In short, to schematisse actual production conditions, it may be assumed that the global cost curve takes a form like curve $C$ in Figure 8 of Chapter 3. The size of the market, defined as the required volume of production for the good under consideration, then determines the order of magnitude of the number of firms which can take part in supplying the market.

Certainly the actual number of firms and their respective sizes, which are characteristics of 'market structure', also depend on the competitive conditions prevailing on the market, which are other characteristics of its structure. But these conditions themselves depend on the number of firms. The determination of active firms must therefore be regarded as following from consideration of a general equilibrium.
What firms exist?

For an accurate formal description of such an equilibrium we must take account of economies of scale, that is, the non-convexities which characterise the production sets within a more or less extensive region in the neighbourhood of the origin. The possible types of competition must also be represented.

The most satisfactory approach appears to be to adopt the assumption of monopolistic competition and the Cournot–Nash equilibrium defined in the previous section.† Then we must simply remember that the solution is liable to be rather inadequate where there is cooperation or even collusion among some firms. This cooperation may be implicit in the case of oligopoly where the number of units is very small; it may be explicit in the case of cartels where there are other contractual or regulatory methods of dividing up the market (in most cases market sharing is intended to halt the elimination of firms).

Economies with an infinite number of agents

1. 'Atomless' economies

We have so far been arguing on the basis of a general model which can have any number of agents. In particular, the theories of the optimum and of competitive equilibrium have been established without restriction on the integers $m$ and $n$ representing the number of consumers and the number of producers respectively. For simplicity, some of the examples chosen for discussion involved only two agents.

In fact, modern societies are made up of a very large number of individuals, and it is this multiplicity that explains the complexity of the problems raised by the organisation of production and distribution. Economic science must pay great attention to this complexity, which enforces the search for original solutions that are very different from those in technological sciences. In order to appreciate the relevance of the results given in previous chapters, the student must therefore consider them in relation to concrete situations where there are very many consumers and producers.

In addition, we must see whether the multiplicity of agents leads to new results which do not hold for more restricted communities. When $m$ and $n$ are very large, the model has a particular nature, not so far allowed for, which may prove interesting.

In fact we shall see that, under certain conditions, the assumptions of convexity adopted in the previous chapters lose their usefulness, and this obviously increases the validity of optimum theory. Similarly, we shall be able to give precise content to the classical idea that perfect competition tends naturally to be achieved when there is a large number of agents each of whom individually represents only a small part of the market. Finally we shall consider again from a new viewpoint some questions concerning imperfect competition.

For our present purposes we shall give the elements of theories whose complete proofs are too heavy to be included in this course of lectures. However, it is hoped that the origin and the nature of the results will become clear enough.
The name *atomistic economies* has been given to those containing many consumers and producers, none of whom is of sufficient weight for his decisions to have a perceptible effect on general equilibrium. Modern technical literature speaks of *atomless economies*. In spite of appearances, these two expressions mean the same, since the first refers to the fact that there is a very large number of units which individually are small, and the second to the fact that no unit is an undissociable entity of appreciable size relative to the whole. If actual economies do not satisfy these abstract conditions, then this is essentially because of the presence of large firms which are naturally in a situation of imperfect competition. The discussion that follows will then apply fairly well to consumers and to branches of industry where the number of firms is large (M. Allais' differentiated sector); on the other hand, it may have little relevance to sectors where there is a very large degree of concentration. This should be borne in mind.

Let us now examine a mathematical formulation of the atomless economy. Suppose that consumers and producers are grouped into categories so that all individuals in the same category are identical.

Changing our previous notation slightly, we let $i$ denote a particular category of consumers and assume that there are $m$ such categories ($i = 1, 2, ..., m$). A particular consumer in the $i$th category is now denoted by the double index $(i, q)$ (where $q = 1, 2, ..., r_i$). Similarly $j$ denotes a category of producers $(j = 1, 2, ..., n)$ while $(j, t)$ refers to a producer in this category (where $t = 1, 2, ..., s_j$).

The economy can then be defined as follows:

(i) The $(i, q)$th consumer has a consumption set $X_i$ and a utility function $S_i(x_{iq})$ which, by hypothesis, depend only on the category to which he belongs. Similarly, if consumers have incomes that are fixed exogenously or if they own certain primary resources, then the corresponding numbers $R_i$ or vectors $w_i$ are identical for all individuals in the same category.

(ii) The $(j, t)$th producer has a production set $Y_j$ or a production function $f_j(y_{jt})$ which, by hypothesis, depend only on the category $j$ to which he belongs. The numbers $r_i$ and $s_j$ of individuals composing the different categories are large, since we are dealing with an atomistic economy. In fact, the results which we shall discuss are valid only in the limit when the number of agents tends to infinity. Therefore $r_i$ and $s_j$ will tend to infinity. For simplicity, we shall also assume that this tendency is uniform in all categories, for example that the $r_i$ and $s_j$ are all equal to the same number $r$, which tends to infinity.†

† Obviously there are other possible mathematical formulations of atomless economies. For example, recent researches assume that the agents form a continuum on which a measure is defined. The assumption that the agents are identical within certain categories is then replaced by another which can roughly be described as follows: 'We can find as many agents as we want who differ as little as we want from any given agent $\alpha$, except perhaps for a negligible proportion of agents $\alpha$.'
2. Convexities

In economies as thus defined, the assumptions of convexity become pointless for welfare theory as well as for competitive equilibrium theory. This becomes clear if we consider groups of identical agents and substitute for individual sets or individual preferences, which may be non-convex,† group sets or preferences which are necessarily convex. The group activity is then represented by a vector that is the arithmetic mean of the vectors representing the activities of the agents who make up the group.

The meaning of this substitution will become clear if we consider in succession the three mathematical entities on which convexity assumptions have been introduced for the proof of certain properties: the consumption sets $X_i$, production sets $Y_j$ and utility functions $S_t$.

Suppose first that the set $X_i$, to which the consumption vector $x_{iq}$ of the agents $(i, q)$ must belong, is not convex. A priori, this may be any set; in particular, it may consist of a discrete collection of points if the quantities $x_{iq}$ must be given as integral numbers of units. In fact, the absence of convexity may signify the absence of divisibility. (Figure 1 reproduces Figure 6 of Chapter 2 and applies to the case of two locations, where the consumer is free to choose his domicile but must carry out all his consumption in the same place.)

Then let the mean consumption vector $x_i$ for consumers in the $i$th category be given by,

$$
x_{ih} = \frac{1}{r_i} \sum_{q=1}^{r_i} x_{iqh} \quad h = 1, 2, \ldots, l.
$$

† Here we mean that preferences are convex if the corresponding utility functions are quasi-concave.
The fact that the $x_{iq}$ belong to $X_i$ imposes on $x_i$ only one condition, namely that $x_i$ must belong to the set $\overline{X}_i$, the convex hull\(\dagger\) of $X_i$. Formula (1) shows that $x_i$ belongs to $\overline{X}_i$. Conversely, every vector of $\overline{X}_i$ corresponds to feasible average consumptions for the consumers in the $i$th category, provided that the latter is infinitely large.

For, consider any vector $x_i$ of $\overline{X}_i$. By hypothesis, there exist non-negative numbers $\lambda^s$ whose sum is 1 and vectors $x^s_i$ belonging to $X_i$ such that

$$x_i = \sum_{s=1}^{\sigma} \lambda^s x^s_i.$$  \(2\)

The vector $x_i$ can therefore be realised in the $i$th category if the activity of a proportion $\lambda^s$ of the consumers in this category is defined by the vector $x^s_i$, for $s = 1, 2, \ldots, \sigma$.

The proportion $\lambda^s$ is realisable, at least in the limit as $r_i$ tends to infinity. To verify this, let us write $r$ instead of $r_i$. For every value of $r$ we define $\sigma$ integers $m^s_r$ such that $|m^s_r - r\lambda^s| < 1$ and the sum of the $m^s_r$ is equal to $r$. (To define the $m^s_r$ we need only consider the integral parts $n^s_r$ of the $r\lambda^s$. The difference between $r$ and their sum $n_r$ is integral and less than the number of indices for which $r\lambda^s$ is not integral. We can then take $m^s_r = n^s_r + 1$ for $r - n_r$ of these indices and $m^s_r = n^s_r$ for all the other $s$.) Consider the mean vector $x^s_r$ obtained for the category when $x^s_i$ is attributed to $m^s_r$ consumers ($s = 1, 2, \ldots, \sigma$). We can find directly:

$$|x^s_r - x^s_i| = \left| \sum_{s=1}^{\sigma} \left( \frac{1}{r} m^s_r - \lambda^s \right) x^s_i \right| \leq \sum_{s=1}^{\sigma} \left| \frac{1}{r} m^s_r - \lambda^s \right| \cdot |x^s_i|.$$  \(3\)

As $r$ tends to infinity, $|(1/r)m^s_r - \lambda^s|$, which is less than $1/r$, tends to zero. Consequently $|x^s_r - x^s_i|$ also tends to zero. The vector $x_i$ of $\overline{X}_i$ can therefore always be considered as the limit of a sequence $\{x^s_r\}$ of feasible mean vectors for the $i$th category (as $r$ tends to infinity).

Now, the set $\overline{X}_i$, the convex hull of $X_i$, is necessarily convex.\(\ddagger\) To the extent that we can reason directly on the basis of the mean consumption vectors for the various categories, it becomes pointless to assume convexity of the $X_i$.

\(\dagger\) By definition, the convex hull $\overline{A}$ of a set $A$ of $R^1$ is the set of all the elements $a$ of $R^1$ which can be written in the form:

$$a = \sum_{s=1}^{\sigma} \lambda^s a^s,$$

where the $\lambda^s$ are positive numbers whose sum is 1 and the $a^s$ are elements of $A$.

\(\ddagger\) In general, let $a$ and $b$ be two vectors:

$$a = \sum_{s=1}^{\sigma} \lambda^s a^s, \quad b = \sum_{r=1}^{\tau} \mu^r b^r,$$

of the convex hull $\overline{A}$ of a set $A$ to which the $a^s$ and the $b^r$ belong, the $\lambda^s$ and the $\mu^r$ being
The same reasoning can be applied to the production set $Y_j$ of a branch where there is an infinitely large number of firms. If this set is not convex, it can be replaced by its convex hull $\bar{Y}_j$ which is necessarily convex. (Figure 2 represents an example of two goods. The set $\bar{Y}_j$ comprises the dotted area beyond $Y_j$. The vector $y_j^0$, which belongs to $\bar{Y}_j$ but is outside $Y_j$, may be realised, with two thirds of the firms having zero activity and the activity of the remaining third being represented by the vector $y_j^1$ of $Y_j$.

Consider now the case of a non-quasi-concave utility function $S_i$ (cf. Figure 3). Can we associate with it another function $\bar{S}_i$ which is quasi-concave and represents the preferences of the $i$th category among the various mean consumption vectors which can be attributed to this category? In fact, it is possible to do so if we make the following two fairly natural assumptions:

(i) In the $i$th category, goods are so distributed that the utility function $S_i(x_{iq})$ has the same value for all the consumers $q$. (To make this assumption tenable, we may have to break up the category $i$ into smaller sub-categories.)

(ii) Within the $i$th category goods are efficiently distributed in the sense that a redistribution cannot be favourable to one consumer without being unfavourable to at least one other consumer; a distribution optimum is realised in the category.

We now ask the question: what is the set of mean consumption vectors $x_i$ in $R^l$ which ensure to the individual consumers a utility level at least equal positive numbers whose sums are respectively 1. Also let $a$ and $b$ be any two positive numbers whose sum is 1. The vector $a\lambda + \beta b$ necessarily belongs to $A$ since we can write it

$$\sum_{s=1}^{\sigma} a\lambda^s a^s + \sum_{r=1}^{\tau} \beta \mu^r b^r,$$

with the $\sigma + \tau$ vectors $a^s$ and $b^r$ of $A$ and the numbers $a\lambda^s$ and $\beta \mu^r$, all positive, whose general sum is 1.
to a given value $S_i^0$? These are the vectors $x_i$ to which correspond some $x_{iq}$ satisfying (1) and such that

$$S_i(x_{iq}) \geq S_i^0. \quad (3)$$

Let $U_i^0$ be the set of the $x_{iq}$ satisfying (3). We come back to a similar problem to that encountered for $X_i$. The only difference is that $X_i$ is replaced by $U_i^0$. So we can conclude that the required set of $x_i$'s is the convex hull $U_i^0$ of $U_i^0$, provided that there is an infinitely large number of consumers in the $i$th category. (In Figure 3, $U_i^0$ is the set of vectors on or above the indifference curve $\mathcal{I}_i$. The point $M$ belonging to the convex hull of $U_i^0$ although below $\mathcal{I}_i$ ensures the utility level $S_i^0$ to the consumers if the mean consumptions to which it corresponds are distributed between two subgroups of consumers so that the activity vectors of these subgroups are represented by $A$ and $B$.)

In short, to the function $S_i$ we can find a corresponding family of sets such as $U_i^0$. The family of convex hulls $\overline{U}_i^0$ of the $U_i^0$ defines a system of preferences, which we can represent by a new utility function $\overline{S}_i$ that is necessarily quasi-concave.\dagger This function can be chosen so as to coincide with $S_i$ for every vector $x_i$, which, uniformly attributed to the consumers of $i$, realises a distribution optimum in the $i$th category; $\overline{S}_i$ is then greater than $S_i$ for those vectors $x_i$ that do not satisfy the latter condition.

3. The theory of the optimum

We shall now briefly discuss welfare theory, in order to see how the above concepts apply. The assumption of convexity was necessary for the proof that every optimum is a market equilibrium, but not, as we recall, for the converse property. In an atomistic economy we can dispense with the assumption completely, at least as long as we limit attention to an optimum in which an infinite number of individuals have the same consumption vector as any given consumer.

Consider a Pareto optimum $E^0$ in which all agents in the same category act identically; the vector $x_{iq}^0$ does not depend on $q$ and can be written $x_i^0$, while the vector $y_{jt}^0$ does not depend on $t$ and can be written $y_j^0$. This assumption may require the subdivision of some of the initial categories, but this is obviously no inconvenience. For simplicity, we also assume that there is the same number of agents in each category ($r_i = s_j = r$). Without adopting the assumption of convexity for the sets $X_i$ and $Y_j$ or for the functions $S_i$, we can

\dagger Assumption 4 of Chapter 2 stipulates that $S_i$ is strictly quasi-concave. Given two vectors $x^0$ and $x^1$ such that $S_i(x^0) < S_i(x^1)$, it implies that $S_i(x) > S_i(x^0)$ for every vector $x$ within the segment $[x^0, x^1]$. Ordinary quasi-concavity however implies only that $S_i(x) \geq S_i(x^0)$. Only this weaker property holds for $\overline{S}_i$. However, it is sufficient for a certain number of properties, in particular for those relating to the optimum.
show that the optimum $E_0$ is a market equilibrium, at least when $r$ can be considered as infinitely large.

In fact, we can associate with the economy under study an imaginary economy comprising $m$ consumers and $n$ producers each representing a particular category. By hypothesis, the $i$th consumer of the imaginary economy has an activity vector $x_i$, corresponding to a feasible mean consumption vector for the $i$th category; therefore $x_i$ must belong to the convex hull $X_i$ of $X_i$. Similarly, the $j$th producer has a vector $y_j$ corresponding to feasible average net output vectors for the $j$th category, and therefore belonging to the convex hull $Y_j$ of $Y_j$. In addition, the $i$th consumer has a utility function $S_i$, necessarily quasi-concave, constructed as was shown earlier. Finally, the primary resources vector of the imaginary economy is $\omega/r$. (It is permissible for us to assume that $\omega$ increases with $r$ so that the ratio $\omega/r$ remains constant as $r$ tends to infinity.)

To the state $E^0$ of the initial economy there obviously corresponds a state $E^0$ of the imaginary economy; the latter is defined by the vectors $x_i^0$ and $y_j^0$. We can establish that this is a Pareto optimum for the imaginary economy.

In fact it is a feasible state since $x_i^0$ belongs to $X_i$, which is contained in $X_i$. Similarly $y_j^0$ belongs to $Y_j$ contained in $Y_j$. Finally, the equilibrium between resources and uses in the initial economy can be written

$$\omega + r \sum_j y_j^0 = \omega + \sum_j \sum_i x_i^0 = r \sum_i x_i^0,$$

or

$$\frac{\omega}{r} + \sum_j y_j^0 = \sum_i x_i^0,$$

which expresses equilibrium between resources and uses in the imaginary economy.

Moreover, no feasible state $E^1$ preferable to $E^0$ exists for this economy, since this would imply a feasible state $E^1$, preferable to $E^0$, for the initial economy, contrary to our original assumption. For, let $x_i^1$ and $y_j^1$ be the activity vectors defined by $E^1$; since they belong to their respective sets $X_i$ and $Y_j$, there are corresponding vectors $x_i^0$ and $y_j^0$ belonging to the $X_i$ and $Y_j$, such that, in the limit for infinitely large $r$,

$$\frac{1}{r} \sum_q x_i^0 = x_i^1, \quad \frac{1}{r} \sum_t y_j^0 = y_j^1.$$

The $x_i^0$ can be chosen so that

$$S_i(x_i^0) \geq S_i^0 = S_i(x_i^0),$$

since this is just what the assumption that

$$S_i(x_i^1) \geq S_i(x_i^0) = S_i^0$$

implies.
implies. (Since $E^0$ is a Pareto optimum, the $x_{iq}^0 = x_i^0$ define a distribution optimum in the $i$th category, so that $\bar{S}_i(x_{iq}^0) = S_i(x_i^0)$). Since at least one of the inequalities (8) holds strictly, we can deduce that at least one of the inequalities (7) also holds strictly. (For brevity, we omit the proof of this.) To verify that $E^1$, preferred to $E^0$, is also feasible, we now need only to examine the equilibrium of resources and uses. We see immediately that $E^1$ is feasible, since an equation similar to (5) holds for $E^1$ and, in view of (6), an equation similar to (4) then holds for $E^1$.

Since $E^0$ is optimal in the imaginary economy where the required convexity assumptions are satisfied by $X_{i}, Y_{j}$ and $S_{t}$, there corresponds to $E^0$ a price-vector $p$ such that:

(i) the vector $x_i^0$ maximises $\bar{S}_i(x_i)$ in $X_i$ subject to the constraint $px_i \leq px_{iq}^0$ (for $i = 1, 2, \ldots, m$);

(ii) the vector $y_j^0$ maximises $py_j$ in $Y_j$ (for $j = 1, 2, \ldots, n$).

We can deduce that $E^0$ and $p$ also define a market equilibrium in the initial economy; that is,

(i') the vector $x_i^0$ maximises $S_i(x_{iq})$ in $X_i$ subject to the constraint $px_{iq} \leq px_i^0$ (for all $i$ and all $q$);

(ii') the vector $y_j^0$ maximises $py_jt$ in $Y_j$ (for all $j$ and all $t$).

Let us verify by *reductio ad absurdum* that, for example, (i) implies (i'). If there exists a vector $x_{i}^{q}$ of $X_{i}$ such that $S_i(x_{iq}^0) > S_i(x_{iq}^0)$ and $px_{iq}^0 \leq px_i^0$, we can set $x_i^0 = x_{iq}^0$ and note that $x_i^0$ belongs to $X_{i}$, and that it satisfies

$$px_i^0 \leq px_{iq}^0$$

and

$$\bar{S}_i(x_i^0) > S_i(x_i^0) = \bar{S}_i(x_i^0),$$

which is contrary to (i).

4. Perfect competition in atomless economies

It has long been thought that competitive imperfections tend naturally to disappear in atomistic economies. When they are numerous and individually small, agents could not achieve a better situation than their situation in competitive equilibrium; competitive behaviour would become completely rational for consumers and producers, and no other measures would be necessary except those intended to facilitate the exchange of information and communication between agents.

Mathematical economic theory has recently taken up this idea which has mostly been confirmed in the context of the various models against which it can be tested. Clearly it must be shown that competitive equilibria can be achieved in a model which does not assume *a priori* that
perfect competition is realised. So the general concepts of games theory and of imperfect competition provide a suitable frame of reference.

A first approach is to consider the model of monopolistic competition defined at the end of the previous chapter and to find out if the Cournot-Nash non-cooperative equilibrium tends to a perfect competition equilibrium as the size of the market tends to infinity with the number of firms (active and potential) increasing simultaneously.†

A second approach relates to solutions where behaviour is cooperative. To keep the theory simple, attention is often concentrated on the exchange economy and on the conditions under which solutions tend to competitive equilibrium in such an economy. The theory has been worked out mainly for cases where the chosen solution is the core and for cases where it is the solution conforming to the Shapley value.‡

To understand the nature of these theoretical results we shall confine ourselves here to investigating how the core of the exchange economy tends to the set of competitive equilibria as the number \( r \) of consumers in each category tends to infinity.§

To the previous assumptions relating to the similarity of consumers within categories, we now add the assumption that the vector of the initial resources owned by the agent \((i, q)\) depends only on the category to which he belongs, and is therefore denoted simply by \(\omega_i\). For simplicity, we also assume that the utility functions \(S_i\) are strictly quasi-concave and increasing (quasi-concavity, but not strict quasi-concavity, can be deduced from the fact that there is an infinite number of consumers).

Under these conditions, every state belonging to the core contains exactly the same consumption vector \(x_i^q\) for all the consumers in the same category \(i\). To establish this property, we shall consider some feasible state \(E\) and let \(x_{i-}\) denote that vector among the \(x_{iq}\) of \(E\) (\(q = 1, 2, \ldots, r\)) which gives the smallest value of \(S_i\), or any vector of the \(x_{iq}\) which minimises \(S_i\), if there are several. It follows that

\[
S_i(x_{i-}) \leq S_i(x_{iq}) \quad q = 1, 2, \ldots, r
\]

and, in view of the properties assumed for \(S_i\),

---


‡ See Aumann, 'Values of Markets with a Continuum of Traders', *Econometrica*, July 1975, for results based on the Shapley value.

§ We shall essentially follow the presentation of this problem by Debreu and Scarf in 'A Limit Theorem on the Core of an Economy', *International Economic Review*, September 1963.
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\[ S_i(x_i) \leq S_i \left[ \frac{1}{r} \sum_{q=1}^{r} x_{iq} \right] \]  

(9)

where the inequality holds strictly if at least two of the \( x_{iq} \) are distinct. Moreover, since \( E \) is feasible,

\[ \sum_{i=1}^{m} \left[ \frac{1}{r} \sum_{q=1}^{r} x_{iq} - \omega_i \right] = 0. \]  

(10)

Consider the coalition \( C \) consisting of \( m \) consumers, one from each category, the consumer from the \( i \)th category being the one, or one of those, that receive \( x_i \) in \( E \). If there are two distinct \( x_{iq} \)'s in the same category, then \( C \) blocks \( E \) since, in view of (10), \( C \) can attribute the consumption \( 1/r \sum x_{iq} \) to its \( i \)th member and in view of (9), this consumption is never less, and sometimes more advantageous than \( x_i \). Therefore the state \( E \) can belong to the core only if all the \( x_{iq} \) in the same category are equal.

In short, to represent a state in the core, we need only, for any \( r \), specify \( m \) vectors \( x_i \) each corresponding to the consumption vectors attributed to all the individuals in the same category. Since this is a feasible state, we must have

\[ \sum_{i=1}^{m} (x_i - \omega_i) = 0. \]  

(11)

In this representation we no longer have to involve the consumers individually.

It is now almost obvious that if, when \( r = r^0 \), \( m \) vectors \( x_i^0 \) define a state in the core, then when \( r = r^0 - 1 \), these vectors also define a state belonging to the core (which we again denote by \( E^0 \)). Otherwise, for \( r = r^0 - 1 \), there exists a coalition \( C \) blocking \( E^0 \); then for \( r = r^0 \), the same coalition exists and blocks \( E^0 \). We can therefore say that \textit{the core for \( r^0 \) is contained in the core for \( r^0 - 1 \).}

The property we are aiming at can now be stated as follows: if assumptions 2 and 4 of Chapter 2 are satisfied, \textit{a state which belongs to the core for all \( r \) is a competitive equilibrium.}

This property will first be illustrated by the particular case of two goods and two categories of consumers.†

We can return to Figure 4 in Chapter 6 where the elements relating to the first category of consumers are given with reference to the system of axes centred on \( O \), and those related to the second are given with reference to the system centred on \( O' \). Assuming that \( M \) is the only competitive equilibrium

† Edgeworth put forward the following analysis in 1881 in \textit{Mathematical Psychics}, Kegan Paul, London.
point, we must show that, for every other point $E^1$ there exists a value $r^1$ of $r$ and a coalition $C$ blocking $E^1$ in the economy where $r = r^1$. We can obviously confine ourselves to a point on the arc $RS$ representing the core when $r = 1$. Every point outside $RS$ is already blocked when $r = 1$.

Then let $E^1$ be a point on $RS$, let $\mathcal{S}^1_1$ and $\mathcal{S}^1_2$ be indifference curves passing through $E^1$ and let the point $P$ represent the distribution of initial resources. The line $PE^1$ contains points on the right of $\mathcal{S}^1_1$ and on the left of $\mathcal{S}^1_2$, otherwise $E^1$ becomes a competitive equilibrium. Suppose, for example, that $PE^1$ cuts $\mathcal{S}^1_1$ at a point $Q$ lying between $P$ and $E^1$.

Consider now a coalition $C$ comprising $m_1$ consumers from category 1 and $m_2$ consumers from category 2. Suppose that such a coalition attributes the consumption vector $x_1$ to its category 1 members and $x_2$ to its category 2 members. It can do this only if these vectors satisfy the equality between global resources and uses within the coalition:

$$m_1x_{1h} + m_2x_{2h} = m_1\omega_{1h} + m_2\omega_{2h} \quad h = 1, 2. \tag{12}$$

But also, in the state $E^1$ which by hypothesis belongs to the core and so attributes the same consumption vectors to all the individuals in the same category:

$$x_{1h}^1 + x_{2h}^1 = \omega_{1h} + \omega_{2h}.$$  

Eliminating $\omega_{2h}$, we can write (12) in the form:

$$m_1x_{1h} = (m_1 - m_2)\omega_{1h} + m_2x_{1h}^1 + m_2(x_{2h}^1 - x_{2h}) \quad \text{for} \quad h = 1, 2. \tag{13}$$
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Suppose also that, in order to block \( E^1 \), the coalition \( C \) makes category 2 consumers impartial by attributing to them quantities \( x_{2h} \) equal to the \( x_{1h} \). Equations (13) then become

\[
x_{1h} = (1 - \alpha)\omega_{1h} + \alpha x_{1h}^{1} \quad h = 1, 2
\]

where

\[
\alpha = \frac{m_1}{m_2}
\]

The equalities (14) determine the quantities which remain available for the other agents once category 2 agents become impartial.

In Figure 4 it is assumed that \( r = 3 \), and points representing the consumption vectors attributed by different coalitions of this type to category 1 consumers (for \( 0 \leq m_1, m_2 \leq 3 \)) are shown. These points are the N.E. vertices of the stepped line \( KL \). (The points corresponding to \( m_1 = 1 \) and \( m_2 = 2 \) or 3 lie outside the figure.)

The coalition \( C \) will effectively block \( E^1 \) if the point \( E \), whose coordinates are defined by (14), lies on the right of \( \mathcal{S} \). Now, \( E \) is a point on the line \( PE^1 \).

To construct the coalition blocking \( E^1 \), we need only find a point on the segment \( E^1 Q \) which is the weighted mean of \( P \) and \( E^1 \), weighted respectively by the masses \( 1 - \alpha \) and \( \alpha \), where \( \alpha \) is a rational number. Since \( Q \) does not coincide with \( E^1 \), there always exists a point on \( E^1 Q \) which satisfies this condition. The blocking coalition \( C \) is a coalition of the previous type for which \( m_1 \) and \( m_2 \) are the integral numerator and denominator respectively of \( \alpha \). Since \( m_1 > m_2 \), we need only take \( r^1 = m_1 \) to have an economy with a number of agents that is sufficient for the blocking coalition to exist.

Figure 4 shows the point \( E \) corresponding to \( \alpha = 1/3 \). In this figure, the state \( E^1 \) lies outside the core for \( r \geq 3 \), since it is blocked by the coalition comprising three category 1 and two category 2 consumers. Thus, in this case only the competitive equilibrium \( E_0 \) belongs to the core for every possible value of \( r \), which is what we had to prove.

The generalisation to any numbers of goods and consumers is made easy by the following remark.† Consider a state \( E^1 \) belonging to the core. We know that it gives the same consumption vector \( x_i^1 \) to all consumers of category \( i \) and that it is a Pareto optimum. Hence it is sustained by a price vector \( p \). If \( E^1 \) is not a competitive equilibrium, \( p(x_i^1 - \omega_i) \) differs from zero for some categories; more precisely it must be negative for at least one cate-

† This remark is due to P. Champsaur and G. Laroque, who have been able to generalise the same proof to the case of non-differentiable preference relations. See ‘Une nouvelle démonstration de l’équivalence entre le noyau et l’ensemble des équilibres concurrentiels’, Cahiers du séminaire d’économétrie, No. 16, 1975.
gory, \( k \) say, because \( E^1 \) fulfils (11). Using this remark and differentiability of \( S_k \) one easily finds that \( E^1 \) is blocked by a coalition containing \( r_0 + 1 \) consumers of category \( k \) and \( r_0 \) consumers of each of the other categories, \( r_0 \) being a sufficiently large number. (The proof follows the same approach as for the case of two goods and two consumers; it is left to the reader).

5. Domination and free entry

(i) General remarks

We have just seen that, in certain contexts, perfect competition naturally has a special rôle. The same positive approach can be used to investigate this problem more deeply as well as to consider differing contexts.

What happens when 'atoms' are present, that is, when there are agents who each plays an important part in certain markets? Are not these agents in a position to dominate the markets in question so long as the other participants are numerous and individually small? Here we interpret this question as follows: in this situation, is the core not systematically favourable to these agents?

In addition, domination does not necessarily result from natural situations; it may arise because of collusion among agents who, taken individually, are small but unite to act as a single agent. They are said to form a 'syndicate'.

In the context of our methodology, the members of a syndicate agree that they will under no circumstance enter a coalition that does not contain them all. So the effect of the formation of a syndicate is to restrict the set of realisable coalitions and probably also the set of coalitions capable of blocking a given imputation. So it may possibly lead to enlargement of the core. This is in fact the reason for forming a syndicate: some of the imputations thus introduced to the core may be favourable to the members of the syndicate, which tries to obtain one of them by means of actions that, however, are not revealed by investigation of the core.

The possibility of collusion is the source of a certain institutional instability in perfect competition. Even when there is a large number of individually small agents, there is the risk of their grouping together so that situations of monopoly, bilateral monopoly, oligopoly, etc., appear.

In order to combat natural monopolies and to avoid what are considered to be the injurious effects of collusion, the advocates of competition have emphasised the importance of 'free entry'; there must be the legal guarantee that each individual wishing to engage in productive or exchange operations has freedom to do so; in a market where a monopolist is operating, the appearance of some independent individuals should be sufficient to prevent the monopolist from exploiting the favourable situation in which he is placed. The concept of free entry is justified theoretically if, even when atoms are present, the core reduces to the competitive equilibrium (or to the set of
competitive equilibria) whenever there exists a proportion, however small, of independent agents in competition with the atoms.

It is impossible as yet to give complete circumstantial answers to the many questions raised by the above remarks. Such answers would require examination of the differing situations that can arise in the productive sphere where the main situations of monopoly and oligopoly occur. They demand investigation of indivisibilities and increasing returns, which are the most frequent causes of such situations. For these reasons, the theory is not straightforward.

However, if we adopt the context of the exchange economy, we can carry out two simple analyses whose results provide the basis for reflection and illustrate two ideas which certainly are much more widely valid.†

(ii) A simple model

Consider an exchange economy with only two goods and two categories of consumers \( m = 2 \). Category 2 is composed, as before, of a number \( r \) of identical consumers \( (\omega_{2q} = \omega_2 \) and \( S_{2q} = S_2 \), where \( q = 1, 2, ..., r \)), and \( r \) can be an arbitrarily large number. But category 1 has a structure that may tend to favour the effects of domination: it contains an atom controlling a large part \( k \) of the resources at the disposal of this category.

More precisely, the atom owns the resources defined by the vector \( k r \omega_1 \) and has a utility function \( S_1 \) while each of the other \( (1 - k)r \) individuals has the same utility function \( S_1 \) and owns the vector \( \omega_{1q} = \omega_1 \) (the number \( k \) is assumed to be such that \( kr \) is integral, and the indices \( q \) of the other individuals in question are \( q = kr + 1, ..., r \)). Two cases will be examined: that in which the atom is the only agent in category 1 (the case of 'monopoly', \( k = 1 \)), and that in which \( k < 1 \) and each of the other \( r(1 - k) \) agents is individually small (the case of free entry).

As before, an Edgeworth box diagram provides a useful picture of these two cases. However, it does not apply directly to our initial formulation of the model.

In the first place, the Edgeworth diagram in the previous section was conceived in terms of a situation where there is the same number \( r \) of agents in each of the two categories. It was possible to confine the diagram to the indifference curves of a representative individual of each category, given that the number \( r \) was arbitrarily large. We shall continue to represent the second category in this way, but for the first category we must adopt the convention that the same graph may apply for varying values of \( r \).

Now, the limiting process in which \( r \) tends to infinity is meaningful only if

the respective importance of the two categories remains the same. The first
category's resources must increase as quickly as the resources $r\omega_{2h}$ of the
second. Thus, in the case of a single type 1 individual, his initial resources and
his consumption of the good $h$ will be written $r\omega_{1h}$ and $rx_{1h}$ and no longer
$\omega_{1h}$ and $x_{1h}$.

To the extent that $r$ is arbitrary, the figure can be established only if the
same indifference curves of agent 1 apply to the vectors $x_i$ for all values of
the number $r$ by which they are multiplied. Therefore the indifference curves
must be homothetic with respect to the origin. This is obviously a restrictive
assumption (in the context of the consumption theory in Chapter 2, it implies
that the income-elasticities of demand are all equal to 1). However, it is
essential for the simple graphical method adopted here.†

In the second place, in order to reason directly from the Edgeworth diagram,
we first established that every imputation belonging to the core attributed
precisely the same consumptions to the different individuals in the same
category. So two vectors $x_1$ and $x_2$, respectively for the consumptions of the
individuals in the two categories, were sufficient to represent an imputation of
the core. It is now a more delicate operation to reduce the model in this way.
So we shall first confine ourselves to imputations of the core that attribute the
same vector $x_2$ to all agents in category 2, a vector $r k x_1$ to the atom and the
vector $x_1$ to the other agents in category 1. We shall later consider the question
of finding out if the core contains imputations that do not have this
property.

In both cases we shall study the limit of the core when $r$ increases
indefinitely. We shall do it admitting somewhat restrictive hypotheses so
as to avoid cases in which the limit core has unusual features. Considering
other solution concepts would also be interesting. In particular the limit
non-cooperative equilibrium leads to conclusions that are somewhat
different from the ones reached in this section.‡

(iii) Preliminary study of the core

Consider a state $E^1$ that is assumed to be contained in the core and has
the particular property defined above. This state is represented by a point on
the Edgeworth diagram. It is blocked neither by the coalition composed of all
the individuals nor by coalitions consisting of a single individual. It therefore
belongs to the curvilinear segment $RS$ representing the core when $r = 1$.
We wish to find out if it is restricted to belong to only a part of $RS$.

† If this analysis for the exchange economy is transposed to a model of production, the
assumption that the indifference curves are homothetic is replaced by the assumption of
constant returns to scale, which appears less restrictive.
‡ See M. Okuno, A. Postlewaite and J. Roberts, 'Oligopoly and Competition in Large
Characterisation of this part of RS will be simplified if we introduce the additional assumption that, when \( r = 1 \), the competitive equilibrium \( M \) is unique and that at a point \( E \) on RS the common tangent to the two indifference curves lies on the left of \( P \) if \( E \) is on the left of \( M \), and on the right of \( P \) if \( E \) is on the right of \( M \) (the diagrams introduced up till now have this property except Figure 10 of Chapter 5).

The quasi-concavity of \( S_1 \) and \( S_2 \) implies that, if a coalition \( C \) blocks \( E^1 \), it can do so by attributing the same vector \( x^*_2 \) to all the individuals in category 2 and the same vector \( x^*_1 \) to those in category 1, the atom then receiving \( krx^*_1 \). The reasoning can be based on either category, but the notation is simpler for the second, whose first \( m_2 \) individuals can always be assumed to belong to \( C \). Since \( C \) blocks \( E^1 \), there exist vectors \( x_{2q} \) such that

\[
S_2(x_{2q}) \geq S_2(x^*_2) \quad q = 1, 2, \ldots, m_2.
\]

Let

\[
x^*_2 = \frac{1}{m_2} \sum_{q=1}^{m_2} x_{2q}.
\]

The quasi-concavity of \( S \) implies

\[
S_2(x^*_2) \geq S_2(x^*_1)
\]

where the inequality holds strictly if at least one of the inequalities (16) holds strictly. In view of (17), it is possible for \( C \) to replace the \( x_{2q} \) by the same vector \( x^*_2 \) attributed to all members of category 2, and this does not affect the fact that \( C \) blocks \( E^1 \).

Thus, by confining ourselves to imputations defined by two vectors \( x^*_1 \) and \( x^*_2 \) we can make a complete study of the additional conditions that \( E^1 \) must satisfy in order to belong to the core. In particular, this shows that \( E^1 \) cannot be blocked by a coalition whose members all belong to the same category \( i \), which requires \( x^*_i = \omega_i \) and therefore is contrary to \( S_i(x^*_i) > S_i(x^*_1) \geq S_i(\omega_i) \).

Consider a coalition \( C \) composed of \( m_2 \) members of category 2 (\( m_2 \leq r \)) and either \( m_1 \) members of category 1 if the atom is excluded (\( 0 < m_1 \leq (1 - k)r \)), or \( m_1 + 1 - kr \) if the atom is included (\( kr \leq m_1 \leq r \)). In both cases, \( C \)'s resources are then \( m_1 \omega_1 + m_2 \omega_2 \); they impose the constraints

\[
m_1x^*_1 + m_2x^*_2 = m_1\omega_1 + m_2\omega_2 \quad h = 1, 2
\]

similar to (12). Proceeding as at the end of section 4 and assuming in particular that the type 2 consumers have been made impartial by \( x^*_2 = x^*_1 \), which is not restrictive, we obtain equations similar to (14) and (15) defining the consumptions which \( C \) can attribute to its type 1 members:

\[
x^*_1 = x^*_1 + (1 - \alpha)(\omega_1 - x^*_1) \quad h = 1, 2
\]

\[
\alpha = \frac{m_2}{m_1}.
\]
(iv) **Monopoly and competition**

When category 1 contains only the atom (when \( k = 1 \)), then \( m_1 \) necessarily equals \( r \) so that \( \alpha \) is at most 1. On the other hand, for sufficiently large \( r \), the proportion \( \alpha \) can be as near as we please to any number between 0 and 1. In order that \( E^1 \) should belong to the core, it is necessary and sufficient that the segment \( PE^1 \) contain no point lying above \( \mathcal{S}^1 \), the indifference curve through \( E^1 \). Under our adopted assumption this implies that the core does not contain points lying on \( RS \) on the left of \( M \), but contains all the points of \( RS \) on the right of \( M \) (see Figure 5).

Here again we find the idea of domination: the atom can obtain more than in the state of competitive equilibrium while the type 2 agents cannot, at least so long as they do not come to an agreement to set up an opposing syndicate.

In the latter case, we revert to an exchange economy with two contracting parties and the core \( RS \) already represented in Figure 4 of Chapter 6.

The situation is different if the atom is not the only member of its category \( (k < 1) \). Here \( m_1 \) can not only equal \( r \) but can take positive integral values at most equal to \( r - kr \). If \( r \) is arbitrarily large, \( \alpha \) can have any positive value. For example, \( \alpha^0 \leq 1 \) when \( m_1 = r \) and \( m_2 = \alpha^0 r \), and \( \alpha^0 > 1 \) when \( m_1 = (1 - k)r/\alpha^0 \) and \( m_2 = (1 - k)r \). This brings us back exactly to the case at the end of Section 4. The core contains only the competitive equilibrium \( M \).

To obtain this result we need only be able to realise the values of \( \alpha^0 \) contained in an open interval containing 1. We can therefore confine ourselves without restriction to \( \alpha^0 \leq 1/(1 - k) \) and realise a number \( \alpha^0 > 1 \) through \( m_1 = (1 - k)r \) and \( m_2 = \alpha^0 (1 - k)r \leq r \). The coalition which blocks the states represented by points on \( RS \) to the right of \( M \) then contains the set of type 1 individuals other than the atom and an adequate number of type 2 individuals. The set of these other type 1 individuals can therefore constitute another atom without this causing any change in the core.

The idea of free entry is therefore confirmed also. When the resources of category 1 are not wholly owned by a single agent, and the category 2 individuals are numerous and individually small, the only state that is not blocked by any coalition is the competitive equilibrium.
(v) **Further study of the core**

To obtain the above results we assumed the states of the core to be defined simply by two vectors $x^1$ and $x^2$, each type 2 individual receiving $x^1$, the atom $krx^1$ and the other type 1 individuals $x^2$. Are there not other states in the core? We shall eliminate this possibility by considering the situation $k < 1$ (the case of monopoly would require a limiting argument which will not be given here).

Let us therefore consider a possible state $E$. Let $krx^1$ denote the consumption of the atom, whereas $x_{1q}$ and $x_{2q}$ are the consumptions of the other agents of both types, respectively for $q = kr + 1 = t, ..., r$ and $q = 1, ..., r$. Since $E$ is feasible, we can write

$$kx^1 + \frac{1}{r} \sum_{q=t}^{r} x_{1q} + \frac{1}{r} \sum_{q=1}^{r} x_{2q} = \omega_1 + \omega_2. \tag{22}$$

Let us define the two possibilities:

$$S_1(x^1_t) < S_1(x_{1q}) \quad \text{for all} \quad q = t, ..., r, \tag{23}$$

$$S_1(x^1_t) > S_1(x_{1q}) \quad \text{for all} \quad q = t, ..., r. \tag{24}$$

If (23) does not hold, let $x^1$ and $x^2$ be vectors chosen respectively from the $x_{1q}$ and the $x_{2q}$, and satisfying:

$$S_1(x^1_t) \leq S_1(x_{1q}) \quad \text{for} \quad q = t, ..., r, \tag{25}$$

$$S_2(x^2_2) \leq S_2(x_{2q}) \quad \text{for} \quad q = 1, ..., r. \tag{26}$$

Consider the coalition $C^1$ formed of the (or a) type 1 consumer who receives $x^1$ in $E$ and the type 2 consumer who receives $x^2$ in $E$. Equation (22) shows that this coalition can realise

$$x_t^0 = kx^1_t + \frac{1}{r} \sum_{q=t}^{r} x_{1q} \tag{27}$$

for its first member and

$$x_2^0 = \frac{1}{r} \sum_{q=1}^{r} x_{2q} \tag{28}$$

for its second member. The quasiconcavity of $S_t$ and $S_2$ shows that, since (23) does not hold,

$$S_1(x^0_t) \geq S_1(x_t^1) \quad \text{and} \quad S_2(x^0_2) \geq S_2(x_2^2)$$

($x^0_t$ is a convex combination of $x^1_t$ and the $x_{1q}$ since there are $r - t + 1 = (1 - k)r$ type 1 individuals apart from the atom). The *strict quasiconcavity* of $S_1$ and $S_2$ implies that $C^1$ blocks $E$ except when the $x_{1q}$ are all equal to $x^1_t$ and the $x_{2q}$ are all equal to each other, which we can write
Economies with an infinite number of agents

\[
\begin{align*}
  x_{1q} &= x_1^q & \text{for } q = t, \ldots, r \\
  x_{2q} &= x_2^q & \text{for } q = 1, \ldots, r.
\end{align*}
\]

(29)

If \(E\) is in the core, then either (23) or (29) holds.

Suppose that (23) holds; this implies that (24) does not hold. Then let \(\bar{x}_1\) and \(\bar{x}_2\) be the vectors chosen respectively from the \(x_1^q\) and the \(x_2^q\) and such that

\[
\begin{align*}
  S_1(\bar{x}_1) &\geq S_1(x_1^q) \quad \text{for } q = t, \ldots, r \\
  S_2(\bar{x}_2) &\geq S_2(x_2^q) \quad \text{for } q = 1, \ldots, r.
\end{align*}
\]

(30) (31)

Consider the coalition \(C^2\) formed of all the individuals except the type 1 individual (or one of the type 1 individuals) who receives \(\bar{x}_1\) in \(E\) and the type 2 individual who receives \(\bar{x}_2\). Equation (22) multiplied by \((r - 1)\) shows that this coalition can assign the following consumptions to its members:

\[
\begin{align*}
  k[(r - 1)x_1^q + \bar{x}_1] & \quad \text{to the atom,} \\
  \frac{1}{r}[(r - 1)x_1^q + \bar{x}_1] & \quad \text{to the other type 1 individuals,} \\
  \frac{1}{r}[(r - 1)x_2^q + \bar{x}_2] & \quad \text{to the other type 2 individuals.}
\end{align*}
\]

Since (30) and (31) hold, but (24) does not, the strict quasi-concavity of \(S_1\) and \(S_2\) implies that \(C^2\) blocks \(E\) except when all the \(x_1^q\) and \(x_1^q\) equal \(\bar{x}_1\), and when all the \(x_2^q\) equal \(\bar{x}_2\), in which case (29) holds with an appropriate vector \(x_2^q\). The reasoning makes use of the homothetic nature of the type 1 indifference curves since it assumes that \(S_1(x_1^q) \leq S_1(\bar{x}_1)\) implies \(S_1(krx_1^q) \leq S_1(kr\bar{x}_1)\).

Therefore (29) certainly holds, which is our required result.

6. Return to the theories of monopoly and duopoly

We have just investigated two market situations which are very similar to those previously discussed for monopoly in Chapter 3 and for duopoly in Chapter 6. How do our results relate to the results of these previous more classical theories? We shall see that the essential difference stems from the assumption adopted earlier, that all exchanges took place at the same prices.

Consider first the case of a single type 1 agent \((k = 1)\), that is, in our illustrative case, a single supplier of the good 2. We can validly speak of monopoly here. Using the construction in Chapter 5, we can draw on the Edgeworth diagram the curve \(D_2\) representing the consumptions demanded by the type 2 agents when exchanges take place at given prices (see Figure 6). At each point \(N\) on \(D_2\) the budget line \(PN\) is tangential to the indifference curve \(S_2\) containing \(N\).
Return to the theories of monopoly and duopoly

Fig. 6

If the monopolist must accept that all units are exchanged at the same price, the curve $D_2$ represents the locus of the points which he can realise, his consumption then being $r$ times that defined by these points. Under these conditions, the monopolist chooses on $D_2$ the point $N$ that is highest according to his system of preferences.

This point is analogous to the monopoly equilibrium investigated in Chapter 3. It does not belong to the core defined by the curvilinear segment $MS$. Relative to the locus of Pareto optima, it involves smaller-scale exchanges, which confirms the result of Chapter 3.

Obviously, the agents could agree to substitute for $N$ a state $E$ that is more favourable to all, a state chosen, for example, so that $NE$ is tangential to the curve $S_2$ passing through $E$. But this state cannot be realised if the agreement must consist in the choice of a price-vector applicable to all exchanges, a price vector that is to be adopted without obligation as to the quantities exchanged by the agents. On the budget line $PE$, the type 2 individuals would in fact choose a point other than $E$ and less favourable than $N$ to the monopolist.

Some other institutional arrangement is necessary for the state $E$ to be realised. For example, the monopolist might conceivably fix the following tariff: for each buyer, the price of the good 2 relative to the good 1 is $p_2$ for a quantity less than or equal to $\bar{e}_2$ and $p_2^*$ for every unit bought in excess of $\bar{e}_2$. If $p_2$ is defined by the normal to $PN$, $p_2^*$ by the normal to $NE$ and $\bar{e}_2$ by the projection of $NP$ on the vertical axis, then the type 2 individuals will in fact choose $E$.

It is not surprising to find that the monopolist benefits from the right to introduce a tariff varying with the quantity exchanged. In fact, the monopolist with freedom to fix his tariff at will could regulate it by the indifference curve $S_2$ passing through $P$ and thus realise the state $S$ (or at least, a state very near $S$). Need we add that, by too obviously exploiting the situation, he risks the formation of a buyers' syndicate and of finally having to accept a less
favourable state than $E$? Once more we see the difficulty in defining an equilibrium in certain situations of imperfect competition.

Further considerations arise in the case of 'duopoly' where there are two type 1 atoms supplying good 2 and faced with a large number of buyers of good 1. To fix ideas, we can assume that the two atoms are of the same size ($k = 1/2$).

Let us look in particular at the Cournot equilibrium. In order to represent it by a point $Q$ on the Edgeworth diagram, we have to draw the demand curve $D'_2$ considered by one duopolist when he takes the other's supply as given and in conformity with $Q$ (see Figure 7). The highest point on this curve according to the indifference curves $y^*$ is the point $Q$. (The construction of $D'_2$ from $D_2$ can be done iteratively and is not described here.) The point $Q$ involves exchanges on a scale larger than the monopoly equilibrium point $N$ but smaller than the competitive equilibrium point $M$.

We must take care not to confuse the core $M$ obtained here with that discussed for duopoly in the previous chapter. We assumed then that all units were to be sold at the same price and that buyers took no part in forming any coalition. The core then referred to the 'game' between the two duopolists alone. On the other hand, our present core involves all the agents.

In particular, we can define the coalition that, according to the theory in Section 5, blocks the Cournot equilibrium. It consists of one of the duopolists, the first for example, and of more than half the type 2 agents. These agents agree to carry out their exchanges with the first duopolist, who therefore finds himself realising a point beyond $Q$ to the right of $PQ$, and preferable to $Q$. To regain his 'share of the market', the second duopolist can only propose more favourable terms to the type 2 agents, terms with which the first duopolist must come into line. Competitive equilibrium alone then appears as stable.
Who are price takers?

Although it concerns an exchange economy and not the case of two producers supplying the same market, the above discussion reveals an aspect of things which we ignored in Chapter 6.

7. Who are price-takers?

Sections 4 and 5 of this chapter raise the question of evaluating the real scope of general competitive equilibrium. Obviously there is no clear cut or definitive answer. Economists will always be preoccupied with it. But the question is sufficiently important to justify a brief return to it.

The basic assumption of perfect competition is that the prices of the various goods are given for each agent so that he can buy and sell as much as he wants at these prices, that is, we talk of 'price-taking behaviour' and say that agents are 'price-takers'. The problem is to decide when such behaviour can be assumed, that is, to decide in which cases we can expect such behaviour to be prevalent.

Consideration of the core provides a partial answer but is certainly not sufficient since it completely ignores information costs and communication costs among agents, which means in particular that the resulting state must be a Pareto optimum. Now, such costs are often very high and inefficiencies are obvious.

The study of non-cooperative equilibria assumes that agents do not act in concert; so it provides a useful alternative which in certain respects runs counter to that of the core; in particular, it often leads to situations which are not Pareto optima. In the case of atomistic economies it also leads to a justification of the assumption of perfect competition. But in these cases where atoms exist it attributes much less effectiveness to freedom of entry.†

Thus the presence of monopolistic or oligopolistic structures is naturally accompanied by 'price-making' behaviour; the dominant firms do not take prices as given. On the contrary, they enjoy some freedom of action on their prices.

There is little point in emphasising the fact that such structures may result from technological requirements, that is, from the economies of scale appropriate to certain processes, nor the fact that they may be imposed by public authority. On the other hand it must be asked if, in the absence of economies of scale, they can spring from spontaneous and stable collusion among agents. The formation of a cartel can certainly

† See above, Okuno, Postlethwaite and Roberts.
eliminate competition in its sector; but can the cartel itself survive if there is a continuing possibility of free entry?

We shall now leave this question, which has long given rise to lively controversy. The reader may refer to a recent example formulated precisely in the terminology of modern microeconomic theory.†

† See Johansen, 'Price-taking Behaviour', *Econometrica*, October 1977; Postlethwaite and Roberts, 'A Note on the Stability of Large Cartels', *Econometrica*, November 1977. Note that the origin of this controversy was not the attempt to prove that perfect competition must naturally be established but rather to show that, if it is established, then it is to no-one's advantage, in atomistic economies, not to conform with it.
1. The problem

The theory of the optimum is concerned with the definition and properties of certain states which are of particular interest from the point of view of the production and distribution of goods. Its results suggest certain advantages of market economies, but do not constitute an exhaustive investigation of the organisation of production and exchange. In fact they do not show how the optimum chosen by the community can in fact be established.

Of course, there is a possible formal solution to the problem. In Chapter 6 we established various systems of equations to be satisfied by states of maximum welfare. Conversely, the solutions of these systems all defined such states under conditions that did not generally appear very restrictive. For example, given a social utility function, and if the convexity assumptions are satisfied, the optimum can in principle be found by solving the system constituted by (22), (23), (26) and (35) in Chapter 6. But such a method cannot be used directly in a real situation. The central planning bureau responsible for applying it would have to know, apart from the social utility function \( U \) and primary resources \( \omega_h \), all the production functions \( f_j \) and all the utility functions \( S_i \). The definition of each of these functions is liable to be complex, and there are very many of them; the central bureau would need an inconceivable mass of information and would be faced with impossible calculations. It is therefore necessary to consider less direct ways of determining the optimum.

Another conceivable solution is to institute a system of perfect competition\[†\] since, under the conditions discussed earlier, such a system leads to the

\[†\] It goes without saying that no actual social organisation can exactly realise perfect competition, which assumes the existence of a very large number of very well organised markets. It is therefore a question of judgment rather than of theory whether some particular set of institutions approximates sufficiently to perfect competition to have comparable efficiency.
establishment of an equilibrium which also maximises social welfare. This is in fact the aim of some reformers. But others think that the necessarily concomitant liberalism will be incapable of eliminating monopolies and other forms of imperfect competition. Still others consider that perfect competition results in an unacceptable distribution of wealth among consumers.

Most socialists have therefore proposed a more or less high degree of planning of production. Since they were faced with the impossibility of direct solution of the general equilibrium equations, the question arose of how the actual planning should be carried out. This is the object of 'the economic theory of socialism',† which has been investigated by some writers since the beginning of the century but has not yet produced very complete results. Its most important sections relate to the characterisation of the optimum, that is, to the properties discussed in Chapter 6. But some writers have also been concerned with the means by which an optimum can be determined and established.

The theory is much less fully worked out on this point than on the questions considered in previous chapters. Here we shall only state the problem and show various suggestions for solving it. We shall not attempt a deep investigation since we could not in any case put forward any very conclusive general results.

Yet the question is of obvious interest. It is basic to the understanding of the problems raised by the allocation of resources in societies subject to authoritarian planning. It is of interest to those who wish to make a full comparison of the performances of the competitive system and other systems of organisation. It necessarily arises in the institution of a mixed régime combining the price system with a certain degree of public intervention or with a guiding plan, which aims to provide all agents with a consistent and precise view of future economic development.

2. General principles‡

To the model used so far we must add a central agent, which we shall call the planning bureau, or simply the bureau. We must also define the information available to each agent a priori.

† This expression should not be taken as covering the economic analyses of socialist thinkers who were almost exclusively concerned with the capitalist society which they wished to reform or destroy. By far the best reference for our context in recent Russian literature is Kantorovich, The Best Use of Economic Resources, 1959, English Harvard University Press, 1965.

‡ This chapter is based fairly directly on Malinvaud, 'Decentralised Procedures for Planning', in Malinvaud and Bacharach eds., Activity Analysis in the Theory of Growth and Planning, MacMillan, 1967, in which detailed references to other original contributions to this subject can be found. One may also read G. Heal, The Theory of Economic Planning, North-Holland Pub. Co., Amsterdam, 1973.
It is natural to suppose that each firm and each consumer knows his own particular constraints. The firm $j$ knows its own production function $f_j$ or its set $Y_j$. The consumer $i$ knows to which set $X_i$ his consumption vector must belong, and is perfectly aware of his preferences, that is, he knows his utility function $S_i$. In a private ownership economy, the $i$th individual also knows what resources $\omega_{ih}$ of the good $h$ he owns.

A priori, the planning bureau knows little—the quantities $\omega_h$ of primary resources, if they are collectively owned. But it knows that feasibility demands equality of global supply and global demand for each good. Moreover, it has a criterion by which it can settle the problems raised by the distribution of incomes among consumers.

The bureau’s task is to fix or to predict ‘the plan’, that is, the state to be achieved by the community: the consumption vectors $x_i$ and production vectors $y_j$ for each agent. In order to do so, it initiates a procedure that allows it to gather the necessary information.

In order to define and examine different procedures, we shall assume that the bureau transmits to the agents certain information about the plan that it is preparing, and we shall call this information prospective indices. On the basis of these indices, each agent sends a reply, called a proposition, to the bureau, this reply being determined by the application of certain rules fixed by the bureau. After several exchanges of this kind, the central bureau chooses the plan.

If we let an index $s$ denote the different stages of the procedure, letting $A^s$ denote the agents’ propositions, $B^s$ the indices transmitted by the bureau at stage $s$ and $P^5$ the plan, we can represent a procedure as follows:

$$B^1 \rightarrow A^1 \rightarrow \ldots \ B^s \rightarrow A^s \rightarrow B^{s+1} \rightarrow \ldots \ B^{S-1} \rightarrow A^{S-1} \rightarrow P^S.$$ 

To define each procedure of this kind, we must say how the prospective indices, the propositions and the plan are determined. More precisely, in each case we must answer the following questions:

(i) To which quantities do the prospective indices relate? To which quantities do the agents’ propositions relate? How does the procedure start?

(ii) What rules determine the agents’ propositions at stage $s$?

(iii) How does the bureau calculate the prospective indices transmitted at stage $s$?

(iv) How does the bureau determine the plan $P^S$?

† Note that this formulation assumes the direct exchange of information between bureau and agents. Contrary to what generally happens in practice, the agents are not combined in representative groups. Similarly, the various procedures considered in existing theories assume that the bureau works on an unaggregated list of products and services. These obviously very severe simplifications affect the relevance of the results, but in a way that cannot for the moment be specified.
When a procedure has been defined in this way, when we are sure that the
agents and the bureau can at each stage apply unambiguously the rules
fixed for them, we can study the properties of the procedure, that is, the
properties of the plan to which it leads. In particular, we ask if the plan $P^S$
is near an optimum. An indication will be given in this direction if it is
established that the plan $P^S$ tends to an optimum in the obviously hypo-
thetical case where the number $S$ of exchanges of information tends to infinity.†

Up until recently those interested in the problem of determination of an
optimum have suggested procedures based on the tâtonnement process that
describes the adjustments to equilibrium in market economies (see Chapter 5,
Section 5). The recent development of mathematical programming, and in
particular of decomposition algorithms of solution, have led to other methods
being suggested.

To illustrate the present state of knowledge, we shall go on to discuss three
procedures, the first two in the context of the distribution economy (see
Chapter 5, Section 2) and the third in relation only to the determination of a
production programme. These three examples do not exhaust the extent of
present knowledge, but are certainly adequate for the purposes of these
lectures.

3. Tâtonnement procedure

The economists who first suggested procedures for determination of
optimal plans in socialist economies started from the following idea. There
is nothing to prevent the planning organism from simulating the operations
that are held to take place in perfect markets. It may be guided directly by the
models constructed for the theoretical description of competitive equilibrium
and of the process by which it is realised. In order to determine an equilibrium
corresponding to a satisfactory distribution of incomes, it need only obtain
from the agents the information that they would spontaneously provide in
the markets, and carry out the calculations describing the functioning of
these markets.

To consider this solution to our problem in detail, we shall examine a
distribution economy with $m$ consumers among whom given quantities $ω_k$
of the $l$ commodities, quantities known to the central agency, are to be
distributed. Let us assume that the planning bureau has instructions to realise a given distribution of incomes or, in other words, that the incomes $R_i$
of the different consumers ($i = 1, 2, ..., m$) are fixed. We shall subsequently
assume also that the $R_i$ are known initially by the consumers.

† It is well known that science has often made effective use of the method consisting
of the investigation of asymptotic properties when it is impossible to establish general
results from finite formulations that are more representative of the real situation.
We can imagine the following way of simulating the tâtonnement process:

(i) The 'prospective indices' are prices and the individual consumers' 'propositions' are consumption programmes. At stage $s$ the bureau communicates a vector $p^s$ of the prices of the different commodities. The consumer $i$ replies with a vector $x^s_i$ whose components $x^s_{ih}$ represent his individual demands for the various goods. The first price vector $p^1$ can be chosen arbitrarily; common sense suggests, however, starting with a vector that gives a value for the available resources which is exactly equal to the sum of incomes:

$$p^1 \omega = \sum_{i=1}^{m} R_i = R.$$  \hspace{1cm} (1)

For example, $p^1$ may conceivably be based on past prices or on observed prices in other communities. (Equality between $p^s \omega$ and $R$ will not be rigorously maintained throughout the procedure, but achieved again in the limit.)

(ii) The $i$th consumer determines his proposition $x^1_i$ as if the vector $p^s$ were to be realised in markets where the individual consumers could acquire the different commodities. In other words, he must indicate which is his preferred vector $x^s_i$ among all those vectors obeying the budget constraint

$$p^s x_i \leq R_i.$$  \hspace{1cm} (2)

(As usual, we can also say that $x^s_i$ maximises $S(x_i)$ subject to the constraint (2).)

(iii) At stage $s$, the bureau revises the price vector $p^{s-1}$ so as to increase the prices of commodities that are too much in demand and to decrease the prices of commodities that appear to be over-supplied. This is in fact what happens in tâtonnement, which we formulated as a process continuous over time. We wrote

$$\frac{dp_h}{dt} = a_h \left[ \sum_{i=1}^{m} x_{ih} - \omega_h \right] \hspace{1cm} h = 1, 2, \ldots, ,$$  \hspace{1cm} (3)

with $t$ denoting time during the adjustment process and $a_h$ a positive constant.

By analogy, we can set the following rule for the bureau's price revisions:

$$p^s_h - p^{s-1}_h = a_h \left[ \sum_{i=1}^{m} x^s_{ih} - \omega_h \right] \hspace{1cm} h = 1, 2, \ldots, l.$$  \hspace{1cm} (4)

Obviously this rule must no longer be applied if it leads to a negative value for $p^s_h$, when a zero price is chosen.†

(iv) The supporters of this procedure have never indicated clearly how the plan is determined at the final stage $S$ of the iterations. They seem to have

† If we wish to maintain the equality $p \omega = R$ throughout the procedure, it must not be based on (3), but on a very similar process

$$\frac{1}{p_h} \frac{dp_h}{dt} = \frac{1}{\omega_h} \sum_{i=1}^{m} x_{ih} - 1.$$
assumed that the last demands $x_{h}^{n-1}$ to be notified will define it satisfactorily. Of course, it will only then be by chance that global demands equal supplies $\omega_{h}$. But a certain degree of inconsistency in the plan is allowable, either because existing stocks make supply relatively flexible, or because the many random factors involved in the future make perfect consistency to some degree illusory.

What are the possible properties of such a procedure? Formula (4) shows that if at any stage the demands proposed by the consumers correspond exactly to the supplies then the procedure is halted. The plan achieved is in fact the required optimum since, as a market equilibrium, it defines a Pareto optimum and satisfies the income-distribution that was laid down a priori.

The discussion in Chapter 5 of the stability of the continuous process defined by (3) suggests that the iterative procedure resulting from (4) converges. In fact a property of this kind has been proved under certain conditions. However, it establishes only approximate convergence, which can be expressed more or less as follows:

Given any arbitrarily small positive $\varepsilon$, there exist numbers $a_{h}$ (for $h = 1, 2, \ldots, l$) and $S^0$ such that the distance between the terminal price-vector $p^{n-1}$ and the price-vector associated with the required optimum is less than $\varepsilon$ when the number $S$ of iterations exceeds $S^0$. As $\varepsilon$ decreases, the $a_{h}$ must decrease and $S^0$ must increase.

This property reveals a difficulty, which has also appeared in various experimental attempts to simulate the tâtonnement procedure. The desire for fairly rapid convergence favours the choice of values of the $a_{h}$ that imply appreciable price revisions at each stage. But on the other hand, the need for precise convergence requires small values of these coefficients of adjustment.

The whole extent of the difficulty appears when we consider that the planning bureau does not have the available information to allow it to make a balanced assessment a priori of these two conflicting claims and to choose satisfactory values for the $a_{h}$. If the procedure is actually to be applied, then of course values of the $a_{h}$ are chosen which decrease from one stage to the next. But this does not make the choice of these values any easier. Only experience can lead to good judgment.

We note also that this inherent difficulty in the iterative tâtonnement process may affect not only the planning procedures based on it but also the advantages attributed to the spontaneous mechanism of competitive markets.† When they are faced with essentially new situations, are not these markets liable either to over-adjust, or to adjust too slowly?

† Some economists also question the ability of the tâtonnement process to describe correctly the adjustments that take place in existing markets. They hold that other processes such as those we are about to discuss are capable of describing the functioning of markets as well as planning procedures.
4. A procedure with quantitative objectives

According to the method described above, the bureau indicates prices to the agents and receives back propositions in terms of demands (or supplies) expressed in quantities. An alternative method has been suggested where the bureau indicates to each agent a quantitative programme concerning him.

He must then declare which marginal rates of substitution between the different goods the proposed programme implies for him. If the marginal rate for \( r \) with respect to \( q \) is higher for agent \( i \) than for agent \( \alpha \), this shows that it is advantageous to give \( i \) a little more of \( r \) and a little less of \( q \), the inverse change being made in \( \alpha \)'s programme. Thus the bureau knows in which directions it has to modify the programmes of the different agents.

Let us consider this procedure in detail for the distribution economy, again assuming that income coefficient \( R_i \) for consumers are given \( a \ priori \). It is convenient to assume that \( R_i \) represents not the \( i \)th consumer's income, but his share of the global income of the community, so that

\[
\sum_{i=1}^{m} R_i = 1. \tag{5}
\]

(i) The 'prospective indices' are consumption vectors; the individuals' 'propositions' are vectors of relative prices. At stage \( s \) the bureau informs \( i \) of the vector \( x_i^j \) which it proposes for him. The consumer \( i \) responds with a vector \( \pi_i^j \) whose component \( \pi_{ih}^j \) represents his marginal rate of substitution between commodity \( h \) and commodity \( l \) chosen as numéraire. The first vectors \( x_i^j \) can be chosen arbitrarily subject only to the condition that they define a feasible plan:

\[
\sum_{i=1}^{m} x_{ih}^j = \omega_h \quad \text{for} \quad h = 1, 2, \ldots, l. \tag{6}
\]

For example, the \( x_i^j \) may assume a proportional distribution of available resources among the different individuals (\( x_{ih}^j = R_i \omega_h \)).

(ii) The consumer \( i \) determines his proposition \( \pi_i^j \) as if he received the vector \( x_i^j \) and were free to state the terms on which he would be willing to exchange quantities of the different goods. He must therefore state his marginal rates of substitution between the different goods when he has \( x_i^j \), namely:

\[
\pi_{ih}^j = \frac{S_{ih}(x_i^j)}{S_{ii}(x_i^j)} \quad \text{for} \quad h = 1, 2, \ldots, l - 1. \tag{7}
\]

(Here we assume that the numéraire has been chosen so that its marginal utility \( S_{ii} \) is always positive for all agents.)

(iii) At stage \( s \), the bureau revises the indices \( x_i^{j-1} \) on the basis of the propositions \( \pi_i^{j-1} \) of the different consumers. It first calculates the weighted
mean of the marginal rates of substitution between any commodity $h$ and the numéraire:

$$\pi_{i,h}^{s-1} = \sum_{i=1}^{m} R_i \pi_{i,h}^{s-1} \quad \text{for} \quad h = 1, 2, \ldots, l - 1. \quad (8)$$

For each consumer and each commodity it then defines

$$\phi_{i,h}^{s-1} = R_i (\pi_{i,h}^{s-1} - \pi_{i,h}^{s-1}), \quad (9)$$

which is positive or negative according as the $i$th consumer attributes to the commodity $h$ a higher or lower marginal utility than all the other consumers do on average. It follows from the definition of the $\pi_{i,h}^{s-1}$ that

$$\sum_{i=1}^{m} \phi_{i,h}^{s-1} = 0. \quad (10)$$

The bureau then calculates for each consumer a new vector $x_{i}^{s}$ whose first $l - 1$ components are defined by

$$x_{i}^{s} - x_{i}^{s-1} = b_{h} \phi_{i,h}^{s-1} \quad h = 1, 2, \ldots, l - 1, \quad (11)$$

the $b_{h}$ being fixed positive coefficients.

Thus the allocation of $h$ to the $i$th consumer is increased or reduced according as his marginal rate of substitution for $h$ is higher or lower than the average rate of the other consumers. (Here we ignore the fact that, in some cases, (11) may lead to a negative $x_{i}^{s}$, which is clearly inadmissible. The procedure for finding the $\phi_{i,h}^{s-1}$ would then need to be changed.)

It is clear that the $x_{i}^{s}$ as thus defined constitute a feasible programme for the distribution of the goods among the agents. For, (11), (10) and (6) imply that, for every commodity $h$ other than $l$,

$$\sum_{i=1}^{m} x_{i}^{s} = \sum_{i=1}^{m} x_{i}^{s-1} = \ldots = \sum_{i=1}^{m} x_{i}^{1} = \omega_{h}. \quad (12)$$

It remains to allocate the numéraire for the complete definition of the new vector $x_{i}$. Consider

$$w^{s} = \sum_{i=1}^{m} \sum_{h=1}^{l-1} \pi_{i,h}^{s-1} (x_{i}^{s} - x_{i}^{s-1}). \quad (13)$$

We shall see later that this quantity can be interpreted as a 'social surplus' emerging from the revision of the programme. We then set

$$x_{ii}^{s} - x_{i}^{s-1} = R_i w^{s} - \sum_{h=1}^{l-1} \pi_{i,h}^{s-1} (x_{i}^{s} - x_{i}^{s-1}). \quad (13)$$

It follows from (5) and the definition of $w$ that the sum of the $x_{ii}$ is invariant and always equals $\omega_{i}$, as is required.
(iv) Since the $x_i^t$ define a feasible programme, the plan will naturally be determined at the last stage $S$ of the iteration as the set of $m$ vectors $x_i^t$ defined as above on the basis of the $x_i^{t-1}$ and the $\pi_i^{t-1}$.

Obviously if it happens in the course of this procedure that all the $\phi_{ih}$ are zero at a certain stage, then no change is made in the $x_i^t$, which then define an optimum since the marginal rates of substitution between the different goods are the same for all consumers. (Here we assume that the utility functions are quasi-concave.) The common value $p_h$ of the $\pi_{ih}$ then defines the price of $h$.

To this iterative procedure we can find a corresponding continuous process in which the $x_i^t$ are revised continuously according to the rules transposing (11) and (13). It is then easy to prove that this process converges, and does so in an interesting way. Let us see why.

Let $\dot{x}_{ih}$ and $\dot{S}_i$ denote the rates at which $x_{ih}$ and $S_i$ vary as a function of $s$, which is now considered to range from zero to infinity. We can write (12) and (13) as

$$w = \sum_{i=1}^{m} \sum_{h=1}^{l-1} \pi_{ih} \dot{x}_{ih},$$

$$\dot{x}_{il} = R_i w - \sum_{h=1}^{l-1} \pi_{ih} \dot{x}_{ih}.$$  \hspace{1cm} (12')

(We no longer state that the $\pi_{ih}$ and $w$ depend on $s$). We can find directly

$$\frac{\dot{S}_i}{S_{il}'} = \sum_{h=1}^{l-1} \frac{S_{ih}'}{S_{il}'} \dot{x}_{ih} + \dot{x}_{il} = \sum_{h=1}^{l-1} \pi_{ih} \dot{x}_{ih} + \dot{x}_{il} = R_i w.$$  \hspace{1cm} (13')

Therefore the utilities of all the individuals vary in the same direction; the revisions treat the different consumers equitably. Moreover, taking account of (9) and (11), we can write

$$\dot{x}_{ih} = b_h R_i (\pi_{ih} - \pi_{ih})$$

and

$$\sum_{i=1}^{m} \pi_{ih} \dot{x}_{ih} = b_h \sum_{i=1}^{m} R_i (\pi_{ih} - \pi_{ih}) \pi_{ih} = b_h \sum_{i=1}^{m} R_i (\pi_{ih} - \pi_{ih})^2,$$

the last equality following from (8). Referring to the definition (12') of $w$, we see that $w$ cannot be negative and is positive as long as the $\phi_{ih}$ are not simultaneously zero.

In short, the effect of the revisions is that the consumers’ utility levels are all increasing so long as an optimum has not been attained. There is therefore no difficulty in principle in proving that the procedure converges. This property of the continuous process does not apply just as it is to the suggested
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iterative procedure. Remarks similar to those made on 'tâtonnement' could be made here, but repetition would be tedious.

On the other hand, we must certainly pause to compare the two procedures which we suggested for the distribution economy and can be generalised to less particular models.

Some authors try to contrast them as formulations of two different types of economic organisation. The tâtonnement procedure is taken as an idealisation of market functioning, where the central control needs only to know net demands and supplies and acts blindly to revise prices as a function of these global observations only. The second procedure is taken to represent the organisation of authoritarian economies where the planning bureau issues orders to the different agents and imposes precise programmes on them.

This is certainly an exaggerated contrast. At least in the present state of knowledge, there is no question of taking sides in the debate between the market system and planning on the basis of a comparison between the two types of suggested procedures. In principle, both can be applied for the preparation of a plan, which may in either case be imposed by authority or regarded as making public a collection of information that agents are left free to use as they wish together with the indications given by the market. The two procedures assume a certain degree of decentralisation in the preparation of the plan and a systematic exchange of information between agents and central authority. For the moment, their respective advantages should be investigated in the neutral and relatively technical context adopted for this chapter.

Since no other conclusions are possible, we shall only point out here that the second procedure involves a much greater burden of computation for the planning bureau since the prospective indices must be personalised. At each stage, the bureau must calculate the \( ml \) quantities \( x_{ih} \) while the \( l \) prices \( p_i \) are sufficient for tâtonnement. This difference is obviously particularly outstanding in the distribution economy since the number of consumers in it is generally high. It would be a less significant drawback in planning for the sphere of production, using a similar procedure, where the number of branches or the number of large firms is much smaller.†

5. A procedure involving the use of a model by the planning board

The two cases so far discussed have the common characteristic that they imply fairly direct calculations by the central board unaccompanied by any

† Note that the bureau's calculations may be somewhat decentralised. The determination of global demands in the first procedure, and of average rates of substitution \( \pi_{ih} \) in the second, may be carried out in stages by intermediate bodies responsible for certain subgroups of agents.
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attempt to represent the conditions in which each agent acts. In countries
where there is some planning of production, the central agency usually works
on a direct representation of the technology used by firms. It uses a model that
is a simplified schema of both the equilibrium constraints on supply and
demand and the technical constraints proper to each industry. The object of
exchanging information with the agents is the progressive improvement of the
central model and the plan that results from it.†

If we think of the detailed organisation of national production in terms of a
vast mathematical programme, we can say that this programme is 'de-
composed' into as many partial programmes as there are producers, the whole
being coordinated by a relatively simple central programme. Each partial
programme takes as data elements determined by solution of the central
programme. On its part, the central programme is continually revised as a
function of the answers provided by the partial programmes. In the literature
on mathematical programming, such methods for finding the solution come
under the heading of 'decomposition methods'.

Here we shall confine ourselves to a simple example for which a quick and
efficient procedure can be defined. This example is fairly typical of the more
complex situations arising in the organisation of production.

We return to the model introduced in Section 5 of Chapter 5 for the discus-
sion of the labour theory of value and we give it a slightly stricter specification.
Each firm specialises in the production of a single commodity, under constant
returns to scale. The last commodity is assume to be a primary factor
(labour), which is non-consumable and available in a fixed quantity ω₁.
We suppose further that each of the other commodities h is produced by a
single firm and that ω₉ = 0. Finally, we assume the existence of a utility
function S(x₁, x₂, ..., xₙ₋₁) relating directly to the global consumptions xₙ,
which is equivalent to assuming that the central board knows the collective
demand functions and represents them by a utility function (see the remarks
on revealed preferences at the end of Chapter 2).

Such a model is obviously a schematic representation of production, where
each 'firm' corresponds to a branch of production and the distribution of
global consumptions among individuals is not taken into account.

It is convenient to number the firms (j = 1, 2, ..., l-1) so that the hth firm
produces commodity h. Then yᵢ,j is the output of the jth firm while yᵢ,h
is its input of h for all h ≠ j. Returning to the notation of Chapter 5, Section
5, we let qᵢ denote the output yᵢ,j of the good j and let aᵢ,j be the technical
coefficient of the input h in the production of j:

\[ a_{i,j} = \frac{-y_{i,h}}{y_{i,j}} \quad h \neq j. \]  (15)

† The guiding principle applied in soviet planning was formalized in M. Manove, 'Soviet
By convention, \( a_{jj} \) is zero. Let \( a_j \) be the \( l \)-vector corresponding to the \( j \)th firm's technical coefficients; let \( A \) be the square matrix of order \( l - 1 \) consisting of the \( a_{hj} \) relating to the goods produced \((h, j = 1, 2, \ldots, l - 1)\); finally, let \( f \) be the \((l - 1)\)-vector consisting of the technical coefficients relating to the primary factor \((f_j = a_{ij})\).

With this notation, the equality conditions for supply and demand become

\[
x_h + \sum_{j=1}^{l-1} a_{hj}q_j = q_h \quad h = 1, 2, \ldots, l - 1
\]

\[
\sum_{j=1}^{l-1} f_j q_j = \omega_l,
\]

or, using more compact matrix expressions,

\[
x + Aq = q \quad \text{or} \quad x = (I - A)q
\]

\[
f'q = \omega_l.
\]

(The vectors are considered as column matrices, \(f'\) denotes the transpose row matrix of \(f\), and \(I\) denotes the unit matrix of order \(l - 1\).) System (16') is called the 'Leontief model', the matrix \(A\) being known as the 'Leontief matrix'.

Since production is carried on under constant returns to scale in the \( j \)th firm, the technical constraints can be expressed directly in the vector \(a_j\) of its technical coefficients. We write them in the form

\[
a_j \in A_j \quad j = 1, 2, \ldots, l - 1,
\]

where \(A_j\) is a set of \(l\)-dimensional space. These constraints must obviously be obeyed by the pair composed of the matrix \(A\) and the vector \(f\).

A fairly natural planning procedure for such an economy is that where, at stage \(s\), each firm informs the central bureau of a vector \(a_j^s\) of technical coefficients. From these vectors the bureau first constructs a matrix \(A^s\) and a vector \(f^s\), then reasons on the basis of the corresponding Leontief model as if \(A^s\) and \(f^s\) were completely fixed by technical exigences. Before defining this procedure in more detail, let us see how the bureau uses the Leontief model in question.

\[
S(x) \text{ is to be maximised subject to the constraints}
\]

\[
x = (I - A^s)q
\]

\[
[f^s]'q = \omega_l.
\]

We assume that the Lagrange multiplier relating to (20) is not zero in the optimum, which can be proved if, for example, all the \(f_j^s\) are positive. The first-order conditions then require the existence of a number \(\lambda\) and an

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\(\dagger\) Leontief models are currently used in theoretical and applied macroeconomics. See, for example, H. Chenery and P. Clark, *Interindustry Economics*, New York, 1959.
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The procedure is as follows:

1. The planning board states a vector \( p \) of \((l - 1)\)-vectors such that the first derivatives with respect to the \( x_h \) and the \( q_j \) of

\[
\lambda S(x) - p'[x - (I - A^*)q] - [f^*]'q + \omega_t
\]

are zero. These conditions are respectively

\[
\lambda S' = p_h \quad (h = 1, 2, ..., l - 1) \quad (21)
\]

\[
p'(I - A^*) = [f^*]'. \quad (22)
\]

Conditions (21) are exactly the same as the conditions for maximisation of \( S(x) \) subject to the constraint that \( p'x \) has a suitable value given in advance. Also (19), (20) and (22) show that \( p'x \) must equal \( \omega_t \). It is therefore fairly obvious that the bureau must

(a) solve (22) to find the vector \( p \),
(b) determine \( x \) so as to maximise \( S(x) \) subject to the constraint \( p'x = \omega_t \),
(c) find the corresponding vector \( q \) by solving (19).

Note that the \( p_h \) can be interpreted as the prices that the goods \( h \) must have when the primary factor is taken as numéraire. System (22) can be written:

\[
p_j = \sum_{j=1}^{h-1} p_h a_{hj} + f^*_j.
\]

It expresses the fact that the price of \( j \) must be equal to its unit cost of production when the technique represented by the vector \( a^*_j \) is chosen by the \( j \)th firm (cf. system (26) of Chapter 5).

Prices \( p_h \) are therefore adapted to the Leontief model constructed from the \( a^*_j \). Are they also appropriate to the true technical constraints expressed by (18)? The simplest way to check up on this is to ask each firm \( j \) which is its most economic vector \( a^*_j \) of technical coefficients for the prices \( p_h \). The closer these vectors stated by the firms approximate to the \( a^*_j \), the greater the likelihood that the solution obtained by the central agency is satisfactory.

We are now in a position to define the procedure in detail:

(i) The ‘prospective indices’ are prices and the firms’ ‘propositions’ are production techniques. At stage \( s \), the bureau states a vector \( p^s \) of the prices of the different products, the primary factor being taken as numéraire. The \( j \)th firm replies with a vector \( a^s_j \).

(ii) At stage \( s \), the \( j \)th firm determines \( a^s_j \) so as to minimise its unit cost of production calculated at the prices \( p^s_h \), that is, \( a^s_j \) minimises

\[
\sum_{h=1}^{l-1} p^s_h a_{hj} + f^*_j
\]

in \( A^s_j \).

(iii) The bureau determines the vector \( p^{s+1} \) by solving the linear system (22).

(iv) Finally the bureau determines the plan \((x^s, q^s)\) at stage \( S \) by calculating first of all the vector \( p^S \) as above from \( A^{S-1} \) and \( f^{S-1} \), then by calculating \( x^S \)
so as to maximise $S(x)$ subject to the constraint $p^S x = \omega_1$ and last of all by finding $q^S$ as the solution of the system

$$x^S = (I - A^{S-1})q.$$ 

We shall not linger over the properties of this procedure. It can be established that $x^S$ converges to the optimal consumption vector. It can also be shown that, if the plan $x^S$ is not yet optimal, the addition of a new stage necessarily leads to a plan $x^{S+1}$ which is preferable to $x^S$ provided that $S(x)$ is a strictly increasing function.\textsuperscript{†}

Note that this procedure involves a "decomposition" of the total problem of maximisation of $S(x)$ subject to the constraints expressed by (16), (17) and (18). At stage $s$ the 'partial programme' relating to the $j$th firm consists of minimising the linear form (23) in the set $A_j$. The central agency's problem consists of maximising $S(x)$ subject to the constraints (19) and (20). The data for each partial programme are the results of the immediately preceding central programme, just as the central programme uses the $a^j$ resulting from the preceding partial programmes.

6. Correct revelation of preferences

Until now we have assumed that the agents, consumers or producers, who collaborate in the preparation of the plan, scrupulously follow the rules of the chosen procedure. Since the plan involves them directly, there is a risk that they may cheat so as to influence it in their favour. There is therefore an obvious advantage in procedures which are obeyed spontaneously by the agents even in the absence of control or of a social morality.

The aim of every procedure is to gather information about the preferences or the constraints that govern the activity of consumers and producers. Will they not try deliberately to give biased answers?

The question is all the more important since it has been claimed that the market system ensures economically and correctly the collection of those bits of information which are the most relevant. When he presents his demands and supplies at the prices that tend to be realised, when he revises them as prices vary, each agent spontaneously reveals the comparative utilities of the different goods for him in the neighbourhood of the equilibrium which is in process of being established. Now, this is just the information that a planner needs to organise the production and distribution of goods.

In fact the market system has this advantage only in perfect competition and in an economy with no public goods and no external effects. As we have seen, a monopolist's supply takes account of the characteristics of the demand with which he is faced; it therefore does not reveal correctly, or at

\textsuperscript{†} See Part IV of the author's article 'Decentralized Procedures for Planning', op. cit.
least not directly, the cost conditions governing production. We shall also see in the next chapter why consumers often find it advantageous to behave in such a way as to hide the intensity of their need for collective goods.

Limiting attention to the situations considered in the preceding sections and to the planning procedures there discussed, we may still raise the following question: Will the agents find it to their interest to reveal their preferences and costs correctly?

We note first that the adopted rules are not of a kind to encourage obvious fraud. If he considers each stage separately, without examining its repercussions on the outcome of the procedure, the consumer disposing of income $R_t$ and confronted with prices $p_h$ has every reason to state the same demand as in perfect competition. Similarly the producer, knowing prices $p^*_h$, finds it to his interest to choose the technique whose cost is least at these prices. Again, the consumer to whom a complex $x^*_i$ is assigned will gain from marginal exchanges whose terms are favourable relative to his true rates of substitution. So in the second procedure, there is no obvious reason for the agent $i$ to distort his answers $n_i$. The three planning methods discussed in this chapter are not basically unrealistic.

However, if they consider the procedure as a whole, consumers and producers may find it to their advantage to distort their answers at stage $s$ so as to obtain at stage $s + 1$ prices $p_{s+1}^*$ or programmes $x_{s+1}^*$ which are particularly favourable to them. This possibility does not exist in an atomless economy where each individual answer has only negligible effect on prices or on average substitution rates. But clearly it may arise in economies where competition is naturally imperfect.

Consider, for example, the first procedure in the particular case of two goods and two consumers, and where the procedure is so devised as to ensure always that $p_{s0} = R$. We can follow the successive stages on an Edgeworth diagram (cf. Chapter 4, Section 3 and Chapter 5, Section 2). The fact that incomes $R_1$ and $R_2$ are exogenous implies that the budget line passes through the point $I$ on the diagonal $OO'$ such that

$$\frac{OI}{IO'} = \frac{R_1}{R_2}.$$  

The optimum is represented by the point $M^0$ such that the line $IM^0$ is tangential at $M^0$ to the two indifference curves passing through this point. Suppose now that the first consumer knows the preferences of the second consumer, and also knows that the latter obeys the procedural rules. The first consumer can then construct the second's demand curve $I_J$, which is defined by the condition that at each point $M$ the line $IM$ is tangential to the indifference curve $\mathcal{I}^2$ containing $M$. A particular point $M^1$ on this demand
curve is preferred by the first consumer, this being the point that the second would choose if the budget line were $IM^1$.

If he considers each stage as being not the last one but rather a phase in the total procedure, it is to the first consumer's advantage to reply giving the impression that his preferences imply at $M^1$ an indifference curve tangential to $IM^1$. This allows him to obtain a plan near $M^1$ rather than near $M^0$.

This example shows that the suggested procedure does not eliminate all possibility of fraud. It also shows, let us note in passing, that the fact that incomes are given exogenously does not necessarily define unambiguously the distribution of welfare among the consumers.

This difficulty is not particular to the proposed procedure. It arises much more generally in economies where the number of agents is sufficiently small that at least some of them are aware of effects like those we have just considered.

To deal with the problem in general terms we must represent the outcome of the procedure when agents do not feel obliged to give correct answers. So here we find a situation governed by certain rules in whose context agents behave in their own best interests; this is a typical game situation as described in Chapter 6 (also the line of reasoning for the example just considered, and Figure 1, are already familiar to us from the theory of imperfect competition).

Two assumptions appear natural for the present problem: first, that there is no cooperation among agents and second, that each agent can refuse to take part in operations that would lead to a less favourable final state for him than the initial state. In short, we can assume that the outcome of the procedure is an 'individually rational non-cooperative equilibrium' (see Chapter 6, Sections 1 and 5).
Now it has been shown that, in the most classical exchange economy with a finite number of consumers, there is no procedure leading to such an equilibrium that would moreover be a Pareto optimum and in which agents would give correct answers to the questions put to them. In short, where there is no cooperation among agents only those procedures so devised that they do not necessarily lead to an optimum can possibly be applied without any individual deliberately lying! However we note that there are procedures which lead to a Pareto optimum despite misleading answers.

The problem becomes even greater when we have to consider public services to be provided for the whole community, since then the fact that there may be many individually small agents does not, in general, eliminate motives for deliberate distortion of preferences, as we shall see in the following chapter.

However we must note that a purely economic approach to this problem may exaggerate the importance of the difficulty. The aim of economic theory is to study what happens if individuals are motivated only by self-interest. But where it is a question of participation in some collective decision process there may be other motivations such as public spirit or some feeling of responsibility towards the community to which one belongs. In fact, laboratory experiments appear to suggest that present economic theory exaggerates the problems that truthful revelation of preferences may raise in collective choice processes.

7. The theory of social choice

We must now broaden the question. Starting from the search for an optimum, that is, as it were, for computational rules, we have reached the point of considering the social decision process. Already we have anticipated questions of public consumption and external effects which will be discussed in the next chapter. But the problem of choice among different social states arises more generally in all social sciences. So it is under-
standable that it has been the object of much research at a high level of generality.

There are many reasons why the theory of the allocation of resources is concerned with such all-embracing research. We have just seen one reason. A second, related reason concerns the problem of 'incentives'; this bears on the problem of placing the different individuals in such situations that they will be induced to act naturally in such a way that wider aims can be achieved. Primarily the relevant literature deals with the management of centrally planned economies; it also relates to the principles of the organisation of large firms.

But the strongest motive lies in the necessary analysis of the very principles which should actuate the allocation of resources. In this respect economic theory has tried to make as much progress as possible without having to define these principles strictly. For this reason it has relied so much on the Pareto optimum, whose usefulness was discussed at the beginning of Chapter 4. But before the end of that chapter, we had to note the limitations imposed by exclusive use of this concept.

Since the theory of social choice extends far beyond the scope of this book and since most of it is laborious rather than significant, we shall only describe, without proofs, its two main results and state their consequences for the allocation of resources.

A society is assumed to contain \( m \) individuals \((i = 1, 2, \ldots, m)\). It may be in various states which a general theory need not specify, such as 'states of the economy' as defined, for example, at the beginning of Chapter 4 or as defined in the next chapter for an economy with public goods; or they may be political states defining government, or any other type of social state. Let \( Z \) be the set of possible states and let \( z \) denote a state of this set.

Each individual has certain preferences among these states expressed by a preordering \( P_i \) (see Chapter 2, Section 3; for clarity, we shall not specify a utility function \( S_i \) to represent this preordering). We know that it belongs to a certain class \( \mathcal{P} \) of preorderings defined on \( Z \) (\( \mathcal{P} \) may be simply the set \( \mathcal{P}^* \) of all preorderings on \( Z \); the same class is assumed to apply to all individuals).

Knowing \( m \), \( Z \) and \( \mathcal{P} \), we wish to see how social choices and decisions are determined. In other words, we want to know how these choices and decisions depend on individual preferences \( P_i \), that is, on the 'preference profile' which by definition specifies the \( m \) individual preorderings \( P = (P_1, P_2, \ldots, P_m) \).

We can see two problems immediately: the problem of determining which state the society will choose and the more precise problem of determining its preferences among the different states.

Both problems run up against logical difficulties in the sense that there
is some incompatibility among the various general properties which it seems natural to impose \textit{a priori} on the function that will determine social decision or social choice on the basis of the preference profile. Let us discuss these two problems in succession.

The function $z = f(P)$ is said to be a ‘social decision function’ if it determines which state $z$ is chosen when the preference profile is $P$. A social decision function is said to have a \textit{universal domain} if it is defined for all profiles which can be constructed from all the $P_i$ of $\mathcal{P}^*$ (and for $i = 1, 2, \ldots, m$). A social decision function is said to be \textit{dictatorial} if there exists an individual $j$ such that, for all admissible $P$, $f(P)$ is a maximal element of the preordering $P_j$; in other words, in all circumstances the social decision perfectly satisfies this particular individual who can then be called the dictator. Since the case of dictatorial social decision functions is obviously trivial, \textit{a priori} it seems we should consider non-dictatorial functions with universal domain.

Our discussion in the previous section draws attention naturally to another desirable property. The function $f$ should be such that it is to no individual’s advantage to conceal his true preferences. The social decision function can then be said to be ‘motivating’.

For a formal definition of this property, consider the opposite situation where, for a profile $P$, an individual $j$ who knows the true preferences of the other individuals or, more simply, who knows how the social decision depends on his own preferences, can gain by replacing his true $P_j$ by some other $P'_j$ chosen judiciously from $\mathcal{P}$; he prefers the decision $f(P_1, \ldots, P'_j, \ldots, P_m)$ to $f(P_1, \ldots, P_j, \ldots, P_m)$. The function $f$ is then said to be ‘manipulable’ in $P$. On the other hand it is said to be motivating if there is no profile $P$ in its domain of definition for which it is manipulable.

The \textit{Gibbard–Satterthwaite theorem} states that, if the social decision function $f$ with universal domain is motivating and if it can take more than two distinct values (its range contains more than two elements of $Z$) then it is dictatorial.\footnote{For the proof of this theorem see, for example, Green and Laffont, \textit{Incentives in Public Decision Making}, op cit.} In other words, it is impossible to conceive of a social decision function which is defined for all possible profiles, which avoids the risks of manipulation and which does not violently restrict the result of the social decision process (whether the latter conforms necessarily to a dictator’s preferences or whether it must lead to one or other of two states chosen \textit{a priori} without consideration of individual preferences).

We shall return later to the consequences of this theorem, which is related to another impossibility theorem concerning the second problem of the determination of social preferences.
Suppose now that we associate with each preference profile a preordering of social preferences rather than a decision, this preordering then allowing us to find the decision to be reached whatever restrictions may be imposed subsequently on the set Z of admissible states. Let \( R \) be such a social preordering which obviously belongs to \( \mathcal{P}^* \). The problem is to find how \( R \) is determined from \( P \).

The function \( R = F(P) \) which expresses this is said to be a 'social preference functional' or a 'constitution'. (Until recently, the term 'social choice function' was used to denote this; the terminology has not yet settled down, as is also the case for what we have called the 'social decision function'.) A constitution, or social preference functional, is said to have a universal domain if it is defined for all conceivable profiles for \( P_i \)'s belonging to \( \mathcal{P}^* \). Such a constitution is said to be dictatorial if there exists an individual \( j \) such that, for all admissible \( P \), \( F(P) \) coincides with \( P_j \).

There are two other properties usually considered desirable for constitutions. In the first place, they should obey the Pareto principle, that is, \( R = F(P) \) prefers \( z^1 \) to \( z^2 \) if the \( P_i \)'s of all the individuals \( i \) prefer \( z^1 \) to \( z^2 \). In most cases the property of independence of irrelevant alternatives is also imposed; social choice between two particular states \( z^1 \) and \( z^2 \) should, it is thought, remain unchanged if changing from a profile \( P \) to another profile \( P' \) does not affect the two states in question. Formally, if \( P \) and \( P' \) are such that the individuals \( i \) for whom \( P_i \) chooses \( z^1 \) rather than \( z^2 \) are exactly the same individuals for whom \( P'_i \) does so, then \( F(P) \) and \( F(P') \) must involve the same choice between \( z^1 \) and \( z^2 \).

Arrow's theorem states that, if \( Z \) has more than two elements and if the constitution \( F \), with universal domain, obeys the Pareto principle and the property of independence of irrelevant alternatives, then it is dictatorial. This result, which, like the previous one, is based on a purely logical analysis, clearly demonstrates the difficulty in aggregating individual preferences \( P_i \) in a social preference preordering \( R \).

If it is required that the social decision must not be manipulable, the difficulties are not eliminated by giving up the idea of finding a preordering at the social level, as the Gibbard-Satterthwaite theorem shows.†

On the other hand, the negative results of the two theorems can be avoided if we put a sufficiently strong restriction \( a \) priori on the domain \( \mathcal{P} \) of the preorderings which are considered possible, that is, if we do not require that the domain of the social decision function or of the

† The difficulties faced by the theory of social choice first appeared in the form of the 'Condorcet paradox' (1785): if social choice is decided by a simple majority, then the result is not a preordering because it does not obey the transitivity axiom. The majority may prefer \( z^1 \) to \( z^2 \) and \( z^2 \) to \( z^3 \) without preferring \( z^1 \) to \( z^3 \).
The theory of social choice constitution be universal.† Since the theory of social choice began to be developed, it has been recognised in particular that the majority decision rule was appropriate in the case where \( P \) is a set of 'single peak preferences' (the majority decision then leads to a preordering and to a motivating decision function). The condition on \( P \) is that there should exist a particular ordering on \( Z \), fixed for \( P \), and such that, if the elements of \( Z \) are taken in this order, each \( P_i \) finds them initially more and more preferable and then successively less and less preferable (for particular \( P_i \)'s, the peak may occur either at the first or at the last element).

The assumption of single peak preferences is obviously too restrictive to meet the difficulties facing the theory of social choice. In areas other than that of voting procedures there may be natural assumptions which restrict the class \( \mathcal{P} \) and allow the existence of non-dictatorial functions \( f \) or \( F \). But such possibilities must be examined for each particular case.

What conclusions can be drawn from these difficulties for the problem raised by the search for an optimal allocation of resources? The first is that the risk of manipulation, that is, of deliberate distortion of preferences, is not completely avoided by the skilful choice of decision rules. But conclusions about the choice among various possible Pareto optima, already discussed in Chapter 4, Section 8, must also attract attention.

We note first that it is fairly restrictive to require that a constitution should satisfy the property of independence with regard to irrelevant alternatives.‡ This amounts in particular to eliminating completely the idea that social choice may depend on the intensity of individual preferences among the different states. We see that aggregation of preferences is difficult if this intensity of preference is excluded.

But, to get round these difficulties completely, it is not sufficient to be able to compare the relative intensities of an individual's choices from the various available options, as we could do if a cardinal utility function \( S \) exists. We must go further and, in one way or another, arbitrate among the intensities of the different individuals. This can be done most explicitly by defining a 'social utility function'. All in all, the best approach is to be completely explicit in this matter.

So we are brought back to the discussion in Chapter 4, Section 8. But we have become aware that the economic problem of the allocation of

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†For the research in this area see Maskin, ‘Fonctions de préférence collective définies sur les domaines de préférence individuelles soumis à des contraintes’. Cahiers du séminaire d’économétrie, No. 20, CNRS, Paris 1979.

‡ For example, this property is not satisfied when each individual must assign a score to the various states (1, to the most preferable, 2 to the next and so on) and when the social decision is in favour of that state with the lowest total score (Borda's rule).
resources is but one aspect of the vast problem of collective decisions. The more general problem relates primarily to political science. Clearly there is nothing surprising in this close contact between economic theory and theories more generally related to the functioning of society.
External economies, public goods, fixed costs

1. General remarks

The model of production and consumption on which our discussion has so far been based has an important characteristic to which we must now turn our attention; it allows the strict minimum of interdependences among agents.

Consider the physical constraints. Those which are particular to one agent, the $ith$ consumer's set $X_i$ or the $jth$ producer's set $Y_j$, do not depend on the other agents' activities. The only common constraints result from the necessary equality of global supply and global demand for each good. Similarly each consumer's system of preferences is unaffected by other consumers' or producers' decisions.

There are situations to which this model is inappropriate, situations where the physical constraints restricting the consumer $\alpha$'s vector $x_\alpha$ or the firm $\beta$'s vector $y_\beta$ obviously depend on the other agents' vectors $x_i$ and $y_j$, situations where the consumer $\alpha$'s utility function $S_\alpha$ varies considerably with the values chosen for the $x_i$ and $y_j$ by other agents. The general terms 'external economies', 'external diseconomies' or simply 'external effects' are now used to characterise such situations. We shall see immediately how these terms arose.

The expression 'external economy' applies to the case where the production realised by one firm reduces costs for other firms. For example, a farmer's orchard increases his bee-keeping neighbour's output of honey. The installation or enlargement of an engineering factory in a town brings about the introduction of a female labour force (the workers' wives) which benefits a dress-manufacturer in the town. The professional training given to its employees by a very large firm often benefits other firms in the region when these employees leave the large firm.

Note also that these examples reveal a certain market imperfection: at no cost to himself, the beekeeper receives a service from his neighbour which improves his output; the dress-manufacturer, or the other firms in the region,
can employ a more carefully selected or a better trained labour force at the same wages as before.

In these cases of external economy, the firm whose activity benefits others has no way of excluding them from this benefit. It cannot sell the service, which appears as a by-product of its own production. So to identify this service as a new good would not allow us to revert to our previous general model. Note also that it is the imperfections in market organisation which oblige us to take explicit account of external effects.

We can easily think of situations where there are 'external diseconomies', when one firm's activity damages the activity of others or the wellbeing of consumers. Air-pollution and water-pollution are frequent examples. In most cases, those who suffer from such diseconomies have no way of making the responsible firm or firms bear the cost of them.

The existence of collective services creates another type of interdependence among agents. Our previous general model assumes that goods are used strictly in private, that is, that the use of a given quantity of a good by one agent implies its destruction, so that this quantity is no longer available for other agents. Such an assumption is inappropriate to certain collective services from which all the individual consumers benefit without making private use of them; defence, fine arts, justice, sanitation, television, etc.

Microeconomic models have been augmented by the introduction of 'public goods', which have the property that they are used simultaneously by all consumers without individual exclusion, in order to take account of such services (they might more properly be called 'collective goods', but the other term is too well established). In certain cases, each individual might consume the total supply of the service in question. In other cases, he may either consume or abstain at will without causing the slightest change in the other resources available to the different consumers, and, in particular, to himself.

The case of external effects proper, like that of public goods defined above, corresponds to extreme situations. In real life, intermediate situations are often encountered. For example, the quality of a service rendered to consumers for their private use may depend on the extent of the demand to be satisfied: speedy, comfortable transport, the quality of water supplies in large urban areas, etc. Similarly, the fact that some productive activity is carried out under increasing returns to scale creates a kind of interdependence among consumers, since it is to the benefit of each that the others' demand is particularly high; an increase in global demand induces a decrease in average cost and therefore probably also in price or taxation.

The effect of urbanisation and progress in such areas as telecommunication is to cause more and more complex interdependences among agents in modern societies. So we must try to discover the necessary amendments to the general
results of microeconomic theory when the model on which they have been based becomes insufficient.

The question arises for optimum as well as for equilibrium theory; but it is more serious in the latter case. The notion of Pareto optimum remains unchanged however complex the constraints or the definition of individual preferences. On the other hand, the very idea of equilibrium has to be reformulated in certain cases.

The main formulations of equilibrium involve direct confrontation of producers and consumers without the intervention of any control to ensure that their actions are consistent. In these models, competition eliminates the need for any concerted organisation of production and distribution. But how can they be made to cover public goods which, by their very nature, involve all the individuals collectively? The market seems inadequate both for determining the production programme of such goods and for financing its execution. A new decision process becomes necessary. The definition of equilibrium is obviously affected by this.

The consideration of public goods and, as we shall see, of external effects, requires the formal representation of decisions that are taken collectively rather than individually. When faced with these questions, the economist must willy-nilly take account of the political organisation in whose context these decisions are taken.

By adopting this approach he is also able to consider certain problems which could not otherwise be dealt with thoroughly. In particular, the redistribution of individual incomes effected by the fiscal system has not been really discussed in the previous chapters while it plays a major role in practice. The introduction of a representation of public decisions enables it to be discussed, as we shall see in this chapter.

Similarly, some public intervention in the productive sphere is intended to correct defects in actual economic organisation which obviously differs from that assumed by the perfect competition model. Without being able to plan productive operations completely, the State controls the activity of public enterprise, fixes regulations and adopts the fiscal system. It uses these methods to try to achieve an 'optimum' or, if this is impossible for various reasons, to approximate to it as closely as possible by a 'second best optimum'.

The economist does not need to build up a whole theory of political science in order to elucidate the major aspects of these problems. He can keep to a level of generality which is sufficient to allow him to distinguish the essential logic of collective decisions in the economic field.

One initial rule seems necessary: collective decisions are taken by the agents constituting the economy under investigation. Of course, it would be convenient to suppose that an omniscient State with sovereign powers
External economies, public goods, fixed costs
determines all choices beyond the level of the individual. But this would be
quite artificial, at least for the study of equilibrium. The aim of the theory
must be to explain, at least partially and in general terms, how producers and
consumers reach mutual agreement on the economic state to be realised.

A second rule has been adopted by the investigators of these problems. Just
as a state of the economy is assessed in optimum theory on the basis of what it
gives the individual consumers, so it is assumed that only these same indivi-
duals take part in collective decision-making. The citizen-consumer expresses
his choices both on the market and through political representations which
decide collective consumption and taxation, whose role we shall shortly
investigate. The producer or the firm then appears to have a less important-
function, only to organise certain productive operations so as to ensure
maximum profitability.

Economic science has not yet integrated into its general analytical frame-
work the various complications just mentioned, although their nature is
being better and better understood. So we shall confine ourselves to some
simple examples and show some of the problems which they involve. In
doing this, we shall touch on questions relating to the economic theory of
public finance, but obviously shall not attempt to discuss the whole of this
theory, even in summary.

In this chapter we shall be particularly concerned with the fairly detailed
discussion of external effects occurring in production on the one hand, and
on the other hand, with the case of completely public goods that are used by
all the consumers collectively without affecting production. We shall make
only brief mention of external effects in consumption, public goods used by
producers and the case where the private consumption of certain goods
directly concerns all the other individuals (services subject to congestion). We
shall end the chapter with the discussion of the problems raised by the presence
of fixed costs, which in some sense represent collective costs. The presence of
fixed costs is the cause of the greatest deviations from convexity and requires
that decisions are taken by procedures that are fairly comparable to those which
occur in the treatment of public goods. This explains their place in this chapter.

2. External effects

Let us see how optimum and equilibrium theories must be modified when
one firm’s activity has an external effect on the conditions of production for
other firms. It seems possible to lay bare the essentials of the problem by
considering a very simple model with only two firms \((j = 1, 2)\) and one
consumer. Let us assume that there are three commodities, the first two being
produced by each firm respectively, while the third one is the only input for
both firms. This commodity therefore occurs in production as ‘labour’, but it
can also be consumed by the individual consumer in the form of ‘leisure’.
We suppose finally that there is no primary resource other than the maximum quantity \( \omega_3 \) of labour that the consumer can provide.

Let \( x_1 \) and \( x_2 \) be the outputs of the first two commodities and \( x_3 \) the quantity consumed of the third by the individual consumer. His system of preferences is represented by a utility function \( S(x_1, x_2, x_3) \).

The external effects arising from a firm's activity depend in reality on a set of factors. But they tend to increase with the activity of the firm. So we can assume in our simple model that they are a function only of the volume of production. So the effect of the first firm's activity on the second firm depends on \( x_1 \), and the second firm's effect on the first depends on \( x_2 \).

The first firm produces \( x_1 \) from a labour-input \( a_{13} \). The technical conditions are represented by a production function involving \( x_2 \):

\[
x_1 = g_1(a_{13}; x_2).
\]

(1)

Similarly the second firm produces \( x_2 \) from the input \( a_{23} \) and is subject to the production function

\[
x_2 = g_2(a_{23}; x_1).
\]

(2)

Let \( g'_{13} \) and \( g'_{23} \) denote the derivatives of \( g_1 \) and \( g_2 \) with respect to the respective labour-inputs. We also let \( g'_{12} \) denote the derivative of \( g_1 \) with respect to \( x_2 \) and \( g'_{21} \) the derivative of \( g_2 \) with respect to \( x_1 \). The derivative \( g'_{12} \) is positive (or negative) according as firm 1 benefits from external economies (or suffers from external diseconomies) resulting from the activity of firm 2.

We must add to (1) and (2) the equilibrium condition of supply and demand for the third commodity:

\[
a_{13} + a_{23} + x_3 = \omega_3.
\]

(3)

In this very simple economy a programme, or state, is defined by five numbers, the values of \( x_1, x_2, x_3, a_{13} \) and \( a_{23} \). A programme is feasible if it satisfies (1), (2) and (3). In short, everything depends on the allocation of labour among its three uses, input for firm 1, input for firm 2 and leisure.

(i) Optimum

Let us first find the conditions under which a programme \( E^0 \) is an optimum. It must consist of five numbers which maximise \( S \) subject to the constraints (1), (2) and (3). So we can write the Lagrangian expression

\[
S(x_1, x_2, x_3) + \lambda_1[x_1 - g_1(a_{13}, x_2)] + \lambda_2[x_2 - g_2(a_{23}, x_1)] + \\
\lambda_3[a_{13} + a_{23} + x_3 - \omega_3].
\]

Equating the five first derivatives to zero, we have
After elimination of the Lagrange multipliers, these first-order conditions reduce to

\[
\begin{align*}
S'_1 + \lambda_1 - \lambda_2 g'_{21} &= 0 \\
S'_2 + \lambda_2 - \lambda_1 g'_{12} &= 0 \\
S'_3 + \lambda_3 &= 0 \\
- \lambda_1 g'_{13} + \lambda_3 &= 0 \\
- \lambda_2 g'_{23} + \lambda_3 &= 0.
\end{align*}
\]

Taking the third commodity as numéraire, we let \( p_1 \) denote the value for \( E^0 \) of the marginal rate of substitution \( S'_1/S'_3 \) between the first and third commodities. Similarly let \( p_2 \) denote the value of \( S'_2/S'_3 \). If the sufficient assumptions specified in Chapter 4 on optimum theory are satisfied, then \( E^0 \) is an equilibrium for the consumer who is confronted with prices \((p_1, p_2, 1)\) and has for his consumption of goods 1 and 2 an income from labour of \( \omega_3 - x_3 \) and an additional income of \( p_1 x^0 + p_2 x^0 + x_3^0 - \omega_3 \). But, for firms affected by external effects, the marginal conditions

\[
\begin{align*}
p_1 g'_{13} &= 1 - g'_{21} \frac{g'_{13}}{g'_{23}} \quad (5) \\
p_2 g'_{23} &= 1 - g'_{12} \frac{g'_{23}}{g'_{13}} \quad (6)
\end{align*}
\]

do not correspond to those for competitive equilibrium where firm 1 maximises its profit \( p_1 x_1 - a_{13} \) and firm 2 maximises its profit \( p_2 x_2 - a_{23} \):

\[
\begin{align*}
p_1 g'_{13} &= 1 \quad \text{and} \quad p_2 g'_{23} = 1. \quad (7)
\end{align*}
\]

The optimum no longer appears as a market equilibrium.

We must therefore find out in the first place how the equilibrium is likely to differ from the optimum, and in the second place, how institutions other than those of the market economy could bring about a good allocation of labour among its three uses. We shall make a preliminary examination of the additional terms in (5) and (6) with respect to (7). Let us, for example, fix attention on firm 1 and formula (5).

We note first that the new term \( g'_{21} g'_{13}/g'_{23} \) is zero if \( g'_{21} \) is zero, that is, if the extent of the first firm's activity does not affect production conditions for the other firm. This term is therefore explained by the external effects caused by the first firm and not by external effects from which it suffers or benefits. More precisely, \( g'_{21} g'_{13} \) measures the increase in production of good 2 caused

\[\dagger\] This clause will not be repeated subsequently.
by external effects for a unit of additional labour employed in firm 1. If production of good 2 is held at its previous level, the quantity of labour employed by firm 2 is reduced by $g'_{21}g'_{13}/g'_{23}$. In short, the additional term in (5) measures the quantity of labour which firm 2 can save without reducing output when an additional unit of labour is employed in firm 1.

Since $g'_{13}, g'_{23}, S'_1, S'_2$ and $S'_3$ can be considered positive, realisation of the optimum requires that $g'_{21}g'_{13}/g'_{23} < 1$ (see equation (5) above). The above interpretation suggests that this condition must be satisfied.

(ii) Relations between equilibrium and optimum

Before discussing in detail how the equilibrium allocation differs from an optimal allocation, let us consider the formulation of equilibrium. We assumed above for equations (7) that each firm maximises its profit, taking prices and the other firm's activity as given. We therefore adopted an assumption of behaviour comparable to that adopted in the theory of games for the definition of 'non-cooperative equilibria'. Is such behaviour plausible? Perhaps not in the context of our model, where there are only two firms. We shall therefore go on to consider alternatives. On the other hand, this assumption seems useful when the external effects are diffuse, that is, when they benefit or hinder a large number of agents who do not make up a coalition.

Suppose then for the moment that a competitive equilibrium $E^1$ is realised; equations (1), (2) and (3) are satisfied; prices $p_1, p_2$ and $l$ exist; at these prices each firm maximises its profit, knowing and taking as given the effect on its own technical possibilities of other firms' decisions; (7) is therefore satisfied. How might the allocation realised by $E^1$ be improved?

The answer obviously depends on the specifications of the different functions. We shall consider two typical cases, the first where only firm 1 causes external effects ($g'_{12} = 0$), the second where the external effects caused by the two firms are 'symmetric'.

(a) Suppose first therefore that $g'_{12} = 0$. Obviously if there are external economies (or external diseconomies) production and consumption in the equilibrium $E^1$ of the good whose manufacture gives rise to the external effect are too small (or too high). Let us make the following small modifications to $E^1$: let $a_{13}$ vary by $du$ and $a_{23}$ by $-du$, let $x_1$ vary by $g'_{13} du$ and $x_2$ by $-g'_{23} du + g'_{21}g'_{13} du$. Then the utility function $S$ varies by

$$[S'_1g'_{13} + S'_2(g'_{21}g'_{13} - g'_{23})] du.$$

Now, in competitive equilibrium, $S'_1g'_{13} = S'_3p_1g'_{13} = S'_3$ and $S'_2g'_{23} = S'_3$. The variation in $S$ is therefore

$$S'_3g'_{13}p_2 \cdot g'_{21} du.$$

The first three terms in the product are positive. If $g'_{21}$ is positive, that is, if
there is external economy, the utility function increases following a reallocation of labour in favour of the first firm and against the second.†

(b) If the two firms both give rise to external economies of comparable importance, the allocation of labour brought about by competitive equilibrium is not necessarily bad. This case has a certain practical significance.

Thus, it has been pointed out that economies of scale related to the existence of vast markets are often external to each firm taken in isolation. Specialisation of labour, diffusion of technical information, the presence of diversified distribution circuits, etc., become increasingly effective with the increasing volume of the market. Thus, the higher the level of production in an economy, the more favourable the context to the firms' productivity. Each firm benefits from external economies because of the activity of all the others. Conversely, certain of the nuisances and costs of overcrowding due to mass production may constitute external diseconomies which affect the firms symmetrically.

In order to introduce this aspect of reality to the model, we shall assume that the last terms of (5) and (6) are equal:

\[
g_{23} g_{13} = g_{21} g_{13} = e. \tag{8}
\]

(This is so in particular if the two firms are identical.) The equality is apparently not sufficient to ensure that the equilibrium equations and the optimality conditions are identical. However, let us consider a case where the equilibrium and the optimum coincide.

If \( x_3 \) does not come into the utility function, that is, if all the available labour is allocated to production, then the optimality conditions are no longer (4), but

\[
S_1 = g_{23} - g_{21} g_{13},
\]

\[
S_2 = g_{13} - g_{12} g_{23} \tag{9}
\]

The equilibrium equations are (7) and

\[
S_1 = \frac{p_1}{p_2}. \tag{10}
\]

When (8) is realised,

\[
g_{23} - g_{21} g_{13} = (1 - e) g_{23},
\]

so that (9) reduces to

\[
S_1 = \frac{g_{23}}{g_{13}} \tag{11}
\]

† This is purely local reasoning, and does not allow a true comparison of the equilibrium and the optimum. But it is sufficient to show where the economic losses lie in the equilibrium.
External effects

which is in fact realised in the equilibrium since it follows from (7) and (10).

But when the allocation must also specify the amount of leisure $x_3$ and when there are symmetric external economies, the equilibrium $E^1$ contains too large a quantity of leisure. To see this, we make the following small modifications in $E^1$: let $x_3$ vary by $du$ and $a_{13}$ by $-du$; let $x_1$ and $x_2$ vary correspondingly by $dx_1 = -\sigma g'_{13} du$ and $dx_2 = -\sigma g'_{13} g'_{21} du$ respectively, where $\sigma$ is the inverse of $1 - g'_{12} g'_{21}$, which also equals $1 - \epsilon^2$. (It can be verified that these modifications are compatible with (1) and (2), which express the technical constraints.) Now $g'_{21} g'_{13} = \epsilon g'_{23}$, so that $dx_2 = -\sigma \epsilon g'_{23} du$. The utility function therefore varies by

$$[S'_3 - \sigma(S'_1 g'_{13} + \epsilon S'_2 g'_{23})] du.$$ 

In competitive equilibrium, $S'_1 g'_{13} = S'_3$ and $S'_2 g'_{23} = S'_3$. The variation in $S$ is therefore

$$[1 - \sigma(1 + \epsilon)]S'_3 du = \frac{-\epsilon}{1 - \epsilon} S'_3 du,$$

the equality resulting from the fact that $\sigma$ is the inverse of $1 - \epsilon^2$. We saw that $\epsilon$ must be considered as less than 1 but positive in the case of external economy. The utility function will therefore increase if $du$ is negative, that is, if the importance of leisure is reduced. The converse obviously is true in the case of external diseconomy.

(iii) Payment for service or agreement

There are various possible ways of improving the allocation of resources relative to competitive equilibrium. As we shall see, most of them appear particularly difficult to realise when it is a case of external diseconomies. So we shall first adopt the situation of external economies, which allows us a clearer understanding of the nature of the proposed solutions. We shall assume that only the first firm gives rise to external effects, since this is sufficient for the clear statement of the problems that now concern us.

The ideal solution would obviously be to identify an exact payment for the service that the first firm provides for the other. We should then have a new commodity, with index 4, whose output, completely absorbed as input $a_{24}$ in the second firm, is equal to output $x_1$ of commodity 1. In the now amended competitive equilibrium, commodity 4 has a price $p_4$.

The first firm's profit is then $(p_1 + p_4)x_1 - a_{13}$, which gives the marginal equality

$$(p_1 + p_4)g'_{13} = 1. \quad (12)$$

The production function for firm 2 is $x_2 = g_2(a_{23}, a_{24})$ and its profit $p_2 x_2 - a_{23} - p_4 a_{24}$; hence the marginal conditions

$$p_2 g'_{23} = 1 \quad p_2 g'_{24} = p_2 g'_{21} = p_4. \quad (13)$$
If we take account of this value of \( p \) in (12), we find

\[
p_1 g'_{13} = 1 - g'_{21} \frac{g'_{13}}{g'_{23}}.
\]

This is just the optimality condition (5).

But this market equilibrium has no practical meaning, otherwise we should not talk of external effects. For one reason or another, the first firm cannot exclude the second from the service that it provides for it, and therefore cannot sell this service to it. In the case of diseconomies, the market does not allow compensation for the firm that suffers from external effects.

To resolve the difficulty, we might also think of a possible agreement between the firms. They then take a combined decision with a view to maximisation of the sum of their profits. If they operate in this way they will jointly determine the values \( a_{13} \) and \( a_{23} \) that maximise \( p_1 x_1 + p_2 x_2 - a_{13} - a_{23} \), that is:

\[
p_1 g_1(a_{13}) + p_2 g_2[a_{23}, g_1(a_{13})] - a_{13} - a_{23}.
\]

These values will satisfy the equalities

\[
\begin{align*}
p_1 g'_{13} + p_2 g'_{21} g_{13} - 1 &= 0 \\
p_2 g'_{23} - 1 &= 0
\end{align*}
\]

which imply conditions (5) and (6).

This result is not surprising. The presence of external effects in production is not an obstacle to the definition of prices which correctly evaluate marginal rates of substitution for the community; but it is an obstacle to the decentralisation of production decisions.

In the case of external economies, the conclusions of agreements like that just discussed may also take place without having to be imposed on the firms. If, for example, \( g'_{23} \) is positive, as we assume here, it is to the advantage of the second firm to propose a change in the competitive equilibrium to the first firm, since an increase in \( x_1 \) benefits the former more than it costs the latter. Suppose for instance that there is a small positive change \( du \) in \( x_1 \) and the corresponding change \( du/g_{13} \) in \( a_{13} \). Since \( p_1 g'_{13} = 1 \) in competitive equilibrium, the decrease in the first firm’s profit will be of second order with respect to \( du \). On the other hand, the increase in the second firm’s profit, \( p_2 g'_{21} du \), is of first order. There is therefore a possible refund by the second firm to the first which makes the increase in \( x_1 \) advantageous to both firms.

In practice, the conclusion of such agreements is certainly a frequent corrective to highly localised external economies. However, many external economies are so diffuse in character that the beneficiaries cannot easily be identified. Moreover, when the activity of one agent results in damage to another, as happens in the case of external diseconomy, public opinion
disapproves of the latter giving the former a reward for cutting down his activity.

These particular difficulties with regard to external diseconomies certainly explain why law and jurisprudence long ago introduced either restrictions on the exercise of property rights, or indemnities designed to correct those unfavourable external effects which can easily be localised.

(iv) Taxes and subsidies

An alternative solution lies in the institution of public aid for activities leading to external economies and taxation of activities responsible for external diseconomies. These subsidies or taxes could be so devised as to correct the reasons why competitive equilibrium does not bring about a good allocation of resources.

In the context of our model, and keeping to the situation where the second firm does not give rise to external effects \((g'_{12} = 0)\), suppose that the first receives a subsidy, or pays a tax, proportional to its output. Let \(\tau\) be the rate of subsidy \((\tau > 0)\) or \(-\tau\) the rate of tax \((\tau < 0)\). Profit \((p_1 + \tau)x_1 - a_{13}\) is maximised when

\[
p_1 g'_{13} = 1 - \tau g'_{13}.
\]

This equation coincides exactly with the optimality condition (5) if \(\tau\) is chosen correctly, that is, if

\[
\tau = \frac{g'_{21}}{g'_{23}},
\]

which is positive in the case of external economies. If (14) is realised, the equilibrium achieves a good allocation of resources.

More generally, the optimality conditions can in principle be realised by the introduction of subsidies or taxes that are correctly calculated and sufficiently diversified to expand activities generating external economies and reduce activities responsible for external diseconomies.

Note, however, that two questions arise. In the first place, how can the public authority determine the appropriate rate \(\tau\) of subsidy or tax? It must have some idea of the importance of external economies or diseconomies. The fact that they are diffuse greatly complicates the problem of determining the optimum and the corresponding rate \(\tau\).

In the second place, how will the subsidy be financed, or who will receive the yield from taxation? In our small model the only possible reply is that the corresponding sum must be subtracted from or added to the consumer's income. This could be done by a levy or a transfer involving the consumer. But it is important that this should be devised in such a way that the presence of either does not result in marginal rates of substitution \(S_1^i/S_3^i\) and \(S_2^j/S_3^j\)
differing from the prices $p_1$ and $p_2$. It is therefore necessary that the tax-regulations should make its amount independent of consumer decisions. Here again, the solution by subsidy or taxation is not easy.

(v) External effects in consumption

We have just made a fairly thorough investigation of a small model illustrating the problems raised by the presence of external effects in production. We can easily see that similar problems may appear if the needs or tastes of consumers are affected by the behaviour of other consumers. This is so when either altruism or the wish to emulate or impress their fellows causes some individuals to have preferences which no longer relate to the vector of their own consumption alone but to a vector involving also other individuals' consumption.

Without trying to go too deeply into this, we shall consider a very simple case of two consumers and two goods, where a state of the economy is represented by four numbers $x_{11}$, $x_{12}$, $x_{21}$ and $x_{22}$. We assume that the physical possibilities require that these numbers satisfy

$$x_{11} + x_{12} + x_{21} + x_{22} = \omega,$$

where $\omega$ is a given number: from the point of view of production, the marginal rate of substitution between the two goods is 1.

If $h = 1$ corresponds to a staple good and $h = 2$ to a luxury good and if each of the two individuals is egoistic but aware of others, we can assume that the first consumer's preferences are represented by a function $S_1(x_{11}, x_{12}; x_{22})$ decreasing in $x_{22}$ and the second consumer's preferences by a function $S_2(x_{21}, x_{22}; x_{12})$ decreasing in $x_{12}$. Let $S_{ih}$ be the derivative of $S_i$ with respect to $x_{ih}$. Let $Q'_1$ and $Q'_2$ be the negatives of the derivatives respectively of $S_1$ and $S_2$ with respect to $x_{22}$ and $x_{12}$ (where $Q'_1 > 0$, $Q'_2 > 0$).

Clearly a Pareto optimum state satisfies the following marginal equations:

$$\frac{S'_{12}}{S'_{11}} = 1 + \frac{Q'_2}{S'_{21}} \quad \frac{S'_{22}}{S'_{21}} = 1 + \frac{Q'_1}{S'_{11}}.$$

On the other hand, if an equilibrium is established in which the prices of the two goods are equal, because of production, and each individual takes as given the other's consumption, then the following equalities hold:

$$\frac{S'_{12}}{S'_{11}} = 1 \quad \frac{S'_{22}}{S'_{21}} = 1.$$

Obviously consumption of the luxury good is too high in such an equilibrium; the utility levels of individuals could be improved by the simultaneous
reduction, in some suitable way, of their consumption of 2 in favour of their consumption of 1.

Arguments similar to those dealing with external effects in production show that a Pareto optimum can be found by adequate taxation of the luxury good or by agreement between the two consumers to reduce their consumption of it.

3. Collective consumption†

We now go on to discuss an example of a public good involving all consumers collectively. Suppose that there are three goods of which the first is ‘public’ and that a single firm produces this good from the other two according to a production function \( y_1 = g(y_2, y_3) \). The \( i \)th consumer’s utility function is then \( S_i(x_1, x_{12}, x_{13}) \) where \( x_1 \) represents the total available quantity of the public good.

This quantity \( x_1 \) is thus collectively consumed by all individuals, each of them benefiting from the whole, his consumption implying no effect on consumption by others. One may indeed say that good 1 is public.

(i) Optimum

Let us first find necessary conditions for a state \( E^0 \) to be an optimum, by considering the maximisation of \( S_1 \) subject to the following constraints:

\[
\begin{align*}
S_i(x_1, x_{12}, x_{13}) &= S^0_i \quad i = 2, 3, \ldots, m, \\
y_1 &= g(y_2, y_3) \\
x_1 &= y_1 + \omega_1 \\
\sum_{i=1}^{m} x_{ih} &= y_h + \omega_h \quad h = 2, 3.
\end{align*}
\]

After elimination of the Lagrange multipliers, the first-order conditions reduce to

\[
\begin{align*}
\sum_{i=1}^{m} \frac{S'_{i1}}{S'_{i2}} &= -\frac{1}{g'_2} \quad (16) \\
\frac{S'_{12}}{S'_{13}} &= \frac{g'_2}{g'_3} \quad \text{for} \quad i = 1, 2, \ldots, m. \quad (17)
\end{align*}
\]

We are familiar with condition (17). It requires that the marginal rate of substitution between goods 2 and 3 is the same for all agents. But condition (16), which involves the public good, has a new form; it expresses the fact that the sum of the marginal rates of substitution of the public good 1 with respect

to the private good 2 must equal the marginal rate of substitution between these goods in production.

(ii) Market pseudo-equilibrium

Can the optimum $E^0$ be realised as a market equilibrium? Let us try to find a price-system compatible with the establishment of $E^0$. We can think of it as follows.

Ordinary prices $p_2$ and $p_3$ exist for the private goods 2 and 3, and these prices apply for all agents. On the other hand, there are as many prices for the public good as there are agents; $p_1$ for the producing firm, $p_{1i}$ for the $i$th consumer. So each unit of output of 1 brings $p_1$ to the firm while it costs the $i$th consumer $p_{1i}$. Under these conditions, $p_1$ must naturally be the sum of $p_{1i}$:

$$p_1 = \sum_{i=1}^{m} p_{1i},$$

(18)

that is, the organisation that manages the public good receives contributions from the consumers, pays the price of the good to the firm and has a balanced budget.

If in $E^0$ the firm maximises its profit subject to the constraint of its production function, then the following equalities are satisfied:

$$\frac{p_1}{p_2} = -\frac{1}{g'_2}, \quad \frac{p_2}{p_3} = g'_2.$$

(19)

If in $E^0$ the $i$th consumer maximises his utility function subject to the budget constraint

$$p_{1i}x_1 + p_2x_{2i} + p_3x_{3i} \leq p_1x_1^0 + p_2x_{2i}^0 + p_3x_{3i}^0,$$

then the following equalities are satisfied:

$$\frac{p_{1i}}{p_2} = \frac{S'_{1i}}{S'_{12}}, \quad \frac{p_2}{p_3} = \frac{S'_{12}}{S'_{13}}.$$

(20)

Thus in the optimum $E^0$, where (16) and (17) hold, appropriate prices exist and obey (18), (19) and (20). Conversely, in every feasible state $E^0$ where the firm maximises its profit and the consumers their respective utility functions, (19) and (20) are satisfied. By eliminating prices between (18), (19) and (20), we revert to (16) and (17).

It seems therefore that we can find a market equilibrium corresponding to the optimum $E^0$ by introducing individual prices $p_{1i}$ for the public good and that conversely such a market equilibrium constitutes an optimum.

However a little reflection shows that the expression 'market equilibrium' is misused here. It is at most a 'market pseudo-equilibrium' in Samuelson's phrase. We assumed above that the consumer fixes his demand for the public good 1 exactly as he would for a private good with price $p_{1i}$. But, since he knows that 1 is a public good, it is not in the consumer's interest to
reveal his demand, since if he does not claim it openly he can still benefit from it without having to bear its cost. So the quantity $p_1 x_1$ which represents the $i$th consumer's financial contribution to the production of $x_1$ will not be paid spontaneously. It can certainly take the form of a tax, but we are then no longer concerned with a pure market equilibrium and must find out how the amount of the tax can be decided.

(iii) Equilibrium with subscription

Before tackling this question, we shall try to find out which equilibrium is likely to be established in the absence of government authority or deliberate agreement among the agents. The only system that respects the complete autonomy of agents is of course the system whereby the public good is financed by subscription, with each consumer making a contribution to increase the production of the public good. However, when fixing the amount of his contribution, each individual is concerned only with the advantage that he personally will gain from the additional production, irrespective of the gain to others. It is therefore to be expected that he will fix his contribution at too low a level.

Let $s_i$ denote the $i$th consumer's subscription. The production of the public good is then determined by

$$p_1 x_1 = \sum_{Z=1}^{m} s_z.$$  \hfill (21)

If he takes as given the contributions $s_a$ of the other agents $a$, the $i$th consumer tries to fix his individual consumptions $x_{i2}$ and $x_{i3}$, his subscription $s_i$ and public consumption $x$ so as to maximise $S_i(x_1, x_{i2}, x_{i3})$ subject to the constraints (21) and

$$s_i + p_2 x_{i2} + p_3 x_{i3} = R_i.$$  

After elimination of Lagrange multipliers, the optimality conditions reduce to

$$\frac{p_1}{p_2} = \frac{S_{i1}}{S_{i2}} \quad \frac{p_2}{p_3} = \frac{S_{i2}}{S_{i3}}.$$  \hfill (22)

Comparison of (20) and (22) shows that, in an economy where the public good is financed by subscription the output of this good, as it results from the decisions of the individual consumers, is too small; each fixes his contribution so that the marginal rate of substitution of the public good for him is $p_1/p_2$. The sum of the individual rates is then $m$ times greater than the marginal rate of substitution of the first good with respect to the second in production.

Clearly the equilibrium with subscription is properly speaking a non-cooperative equilibrium for the game corresponding to the economy under discussion where each consumer has the 'pay-off function' $S_i$ and chooses
the action $s_i$. Now it is often to the mutual advantage of the players in a game to discard a non-cooperative equilibrium in favour of a state that is attainable only by concerted agreement. This is the case here, contrary to the situation in atomistic economies where there are neither external effects nor public goods.

(iv) The Lindahl equilibrium

Suppose now that by some method or other the individual prices $p_{1i}$ have been determined, or, what amounts to the same thing, the shares $p_{1i}/p_i$ which fall to the different individuals in financing the public good. Suppose also that, given these prices, each individual states the production $x_{1i}$ which he then desires. Suppose finally that these $x_{1i}$'s all happen to correspond to the same quantity $x_1$. If simultaneously prices $p_2$ and $p_3$ ensure that supply equals demand for goods 2 and 3, then the $p_{1i}$, $p_1$, $x_1$, $p_2$, $p_3$ and the corresponding final and intermediate consumption $y_2$, $y_3$, $x_{i2}$ and $x_{i3}$ define a 'Lindahl equilibrium' named after the Swedish economist who investigated this concept in the inter-war period.

More precisely, let us assume that $\omega_1$ is zero and that the $i$th individual has resources $\omega_{i2}$ and $\omega_{i3}$ of goods 2 and 3. His budget equation is

$$p_{1i}x_1 + p_{2i}x_{i2} + p_{3i}x_{i3} = p_2\omega_{i2} + p_3\omega_{i3}. \quad (23)$$

His utility is maximised under this constraint if equations (20) hold. Also equality of supply and demand require that

$$x_1 = g(y_2, y_3) \sum_{i=1}^{m} (x_{ih} - \omega_{ih}) = y_h \quad h = 2, 3. \quad (24)$$

So for a Lindahl equilibrium the $3m + 6$ equations (18), (19), (20), (23) and (24) must be satisfied.

There are as many equations as variables; one of the equations is redundant because of an identity similar to 'Walras' Law' but the system is homogeneous with respect to prices which are therefore determined apart from a multiplicative constant. The structure of the model for the Lindahl equilibrium is therefore very comparable to that of the model for competitive equilibrium in an economy without public goods. Clearly the analogy also holds in cases which involve any number of public goods.

The Lindahl equilibrium is obviously a market pseudo-equilibrium and therefore an optimum. But as in the case of competitive equilibrium it depends on initial resources and is very liable to favour those individuals who are best endowed with them. So from the standpoint of social justice, an optimum other than the Lindahl equilibrium may be preferable or, if this optimum cannot be achieved, a similar state which does not strictly obey (16) and (17) may be chosen.
Collective consumption

In addition, realisation of the Lindahl equilibrium is faced with the same difficulty as every market pseudo-equilibrium. Since he knows that his demand \( x_{1i} \) may react on his rate of contribution \( p_{1i} \), it is to the \( i \)th individual's advantage to lie about his demand and this is so even if there is an infinitely large number of agents. This is an essential difference from the case of competitive equilibrium in an atomistic economy with neither public goods nor external effects.

So the problem of 'finding an optimum' which was the topic of the previous chapter is posed even more forcibly in the present context. Apart even from any consideration of social justice, the attempt simply to achieve an efficient allocation of resources demands consideration of the methods by which the volume of public consumption is actually determined.

In fact, recent developments in the economic theory of public goods lay great stress on this problem. In the first place, they are concerned with determining methods of finding an optimum and in the second place, with studying the robustness of these methods vis-à-vis the strategies which individuals may adopt in order to bias results in their favour. It would be too much of a digression to discuss these here.\(^\dagger\) We shall instead describe an attempt to formalise the processes which govern decisions on public consumption in the real world.

(v) Politico-economic equilibrium\(^\ddagger\)

Suppose that a collective decision procedure is set up to determine collective consumption \( x_1 \) of the public good together with the contribution \( t_i \) of each individual. A public decision is now the choice of a 'budget' consisting of \( m + 1 \) quantities \( (x_1; t_1, t_2, \ldots, t_m) \). Note that this decision, although motivated by the existence of the public good, may also aim at modifying the distribution of income or wealth by means of taxes \( t_i \). What will the equilibrium be for a community like this where the individual consumers have set up a public authority to supervise and finance their collective needs?

To answer this, we return to the model used in our discussion of the optimum and of market pseudo-equilibrium. Private individual decisions determine consumptions \( x_{12} \) and \( x_{13} \); the private decision of the firm determines \( (y_1, y_2, y_3) \). Public decision determines the budget

\[
(x_1; t_1, t_2, \ldots, t_m).
\]

\(^\dagger\) See Green and Laffont, op cit.; see also their article in Cahier du séminaire d’économie, No. 19, CNRS, Paris, 1977; also Champsaur, ‘Comment répartir le coût d’un bien public?’, Cahier du séminaire d’économie, No. 17, CNRS, Paris, 1976.

\(^\ddagger\) This section is based on Foley, Resource Allocation and the Public Sector, Yale Economic Essays, 7, Spring 1967.
Let us assume that the markets for the three goods are competitive and that prices $p_1, p_2, p_3$ are established in them. This may seem a strong assumption for the market for the public good; we could make it more plausible by supposing that several firms, rather than only one firm, produce this good, but this further complication adds nothing in clarity to our analysis. At all events, we assume that the firm maximises its profit, taking prices as given.

Obviously the $i$th consumer makes his decision with the aim of maximising $S_i$; it is subject to the budget constraint

$$p_2 x_{i2} + p_3 x_{i3} = R_i - t_i,$$

where $R_i$ is the $i$th consumer's disposable income before he makes his contribution $t_i$ (if the initial resources are privately owned, $R_i$ is the value $p_0i$ of the vector $w_i$ of $i$'s resources). The firm makes its decision with the aim of maximising its profit; it must obey the production function. What of the public decision?

For a complete theory of equilibrium, we ought to represent in detail the process of collective decision-making. The attempt to do this is liable to distract us too far into the field of political science, since we should have to establish distinctions between different institutional systems. So, as we did previously in the discussion of the optimum, we shall be content with a partial theory, and make an assumption about the way in which the decision process works. This assumption will not be sufficient to characterise it, but will allow us a better grasp of our present problem.

Since the public decision results from organised consultation among the representatives of the individual consumers, it is natural to assume that the chosen budget will have the following property: there is no further possible change in the budget that will improve the situation of one individual without causing a deterioration in the situation of any other individual. In fact, it would be to no one's interest to reject an improvement of this kind, so that it would necessarily be adopted in every decision-making process where each individual is represented. In other words, the budget must not be rejected unanimously by the citizens.

A *politico-economic equilibrium* is therefore a feasible state with accompanying price-system and tax-system, where resources are compatible with uses for each good, the firm maximises its profit subject to the constraint of its production function, consumers maximise their utility functions subject to their budget constraints (25) and the public budget satisfies the above condition.

The assumption on the public budget is clearly analogous to the assumption that the outcome of a game necessarily belongs to its 'core'. In the language of games theory, we could say that the chosen budget must not be blocked by
the coalition consisting of all the individuals. Now, as we saw previously in
Chapter 5, information and communication costs, or a refusal to participate
on the part of agents seeking special advantages, may prevent the assumption
from being realised. It is therefore more restrictive than it appears at first
sight. However, we shall show that, when it is satisfied, every equilibrium is
necessarily an optimum.

Given our definition of optimality, this would obviously be a trivial result
if the collective decision related directly to the state of the economy. It is
interesting because this decision relates only to the budget and takes the
prices of the different goods as given. Thus the economy preserves some
degree of decentralisation with the consumers, the firm and the 'public
authority' acting in a relatively autonomous way.

Let us examine more closely the conditions to be satisfied by the chosen
budget. This budget is obviously balanced, which requires

\[ p_1 x_1 = \sum_{i=1}^{m} t_i. \]  

(26)

Our assumption also requires that \( x_1 \) and the \( t_i \) are chosen so as to maximise
\( S_1 \) subject to the constraint that the values of \( S_2, S_3, \ldots, S_m \) are fixed. This
condition assumes implicitly that the private consumptions \( x_{i2} \) and \( x_{i3} \) of
the \( i \)th individual are settled permanently so that \( S_i \) is maximised subject to
the budget constraint expressed by (25).

In other words, the joint effect of the consumers' behaviour and the public
authority's decision-making process is to determine \( x_{i2} \)'s and \( x_{i3} \)'s, \( x_1 \) and
the \( t_i \)'s which, given values of \( p_1, p_2, p_3 \) and the \( R_i \), maximise \( S_i(x_1, \ldots, x_{12}, x_{13}) \)
subject to the constraints

\[
\begin{align*}
S_i(x_1, x_{i2}, x_{i3}) &= \bar{S}_i^p \\
p_2 x_{i2} + p_3 x_{i3} &= R_i - t_i \\
p_1 x_1 &= \sum_{i=1}^{m} t_i.
\end{align*}
\]

(27)

After elimination of the Lagrange multipliers, the first-order conditions
reduce to

\[
\sum_{i=1}^{m} \frac{S_{i1}}{S_{i2}} = \frac{p_1}{p_2}, \quad \frac{S_{i2}'}{S_{i3}'} = \frac{p_2}{p_3}.
\]

(28)

Suppose now that an equilibrium has been established. The decisions of the
consumers and the public authority ensure that (28) holds, while the decision
of the firm ensures that (19) holds. This equilibrium appears as a 'market
pseudo-equilibrium' in which price \( p_{1i} \) equals \( p_2 S_i'/S_{i2}' \). The equalities (18),
(19) and (20) are then satisfied. As we have seen, this state is Pareto optimal.

The proof suggests that the result does not depend on the form in which
the individuals' contributions are expressed. Their basis and their method of
calculation are irrelevant to optimality, since \( x_1 \), the \( t_i \), the \( x_{i2} \) and the \( x_{i3} \) are decided simultaneously by the parallel behaviour of consumers and public authority. Of course, the fiscal system may be more or less favourable to such and such an individual; but, to the extent that our assumption is satisfied, the system finally adopted necessarily ensures that a Pareto optimum is established.

Conversely, suppose we have an optimum \( E^0 \); it satisfies (16) and (17). Let prices, taxes and incomes be defined so that (18), (26) and (25) are satisfied successively, as is always possible. This gives us a politico-economic equilibrium, which ensures that the optimum is maintained, provided that any change in the budget requires unanimous agreement among the individuals, and that the functions \( g \) and \( S_i \) satisfy the usual convexity assumptions. Equations (19) are then sufficient for maximisation of the firm's profit, and (27) and (28) are sufficient for a joint equilibrium of the consumers and the public decision.

The statement that every optimum corresponds to a politico-economic equilibrium can easily be misinterpreted. The only restriction on the public budget appearing in this equilibrium is that it should not be rejected unanimously by the citizens. Now, is it possible, by appropriate political organisation, to realise any budget that is not rejected unanimously? In fact, the adoption of some budgets among those of this kind may well require that certain individuals are given a dictatorial influence in the decision-making process.

To return to our particular example, we note also that the public good affects only the consumers and not production conditions for firms. This fact was used in the proof that every politico-economic equilibrium is an optimum. So what we said does not apply to the case where public goods affect firms.

Of course we could consider this case and see how taxes and subsidies, or participation by firms in collective decision-making processes allow the realisation of a Pareto optimum. But we should learn little new from this.

In real life there are many situations where external effects and collective consumptions are combined in varying ways. The formal analysis of such situations obviously becomes complex, but the principles established above remain valid.

4. Public service subject to congestion

We shall briefly discuss the example of a public service involving a good that can be used privately but whose quality depends on the global demand to be satisfied, which is typical of situations of congestion such as arise more and more frequently in urbanised communities.

Suppose then that there are only two goods and that the \( i \)th consumer's utility function is \( S_i(x_{i1}, x_{i2}, x_2) \) where \( x_2 \) is total consumption of the second
good. Suppose also that there is only one firm (the public service) producing the good 2 from the good 1 according to the production function \( f(y_1, y_2) = 0 \).

This case is intermediary to the two examples of pure external effect and pure public good discussed in Sections 2 and 3. As in Section 2, where an external effect appeared in the area of production, so here an external effect appears in the area of consumption, since \( i \)'s preferences depend through \( x_2 \) on the other individuals' consumptions \( x_{a2} \). Also, the good 2 can be considered in two ways: first as a private good, since it is privately used, and then as a public good since each particular individual is affected by its total production.† In the case of congestion, the total consumption of \( x_2 \) in fact has disutility for the individuals, that is, the derivative of \( S_i \) with respect to \( x_2 \) is negative; for simplicity, we shall denote this derivative by \( S'_{i2} \).

Let us first examine the conditions for an optimum. The following constraints are involved for maximisation of \( S_i \):

\[
\begin{align*}
S_i(x_{i1}, x_{i2}, x_2) &= S_i^0 & i &= 2, 3, \ldots, m \\
f(y_1, y_2) &= 0 \\
\sum_{i=1}^{m} x_{i1} &= y_1 + \omega_1 \\
x_2 &= \sum_{i=1}^{m} x_{i2} = y_2 + \omega_2.
\end{align*}
\]

(29)

After elimination of the Lagrange multipliers, the first-order conditions reduce to

\[
\frac{f_2'}{f_1'} = \frac{S'_{i2}}{S'_{i1}} + \sum_{a=1}^{m} \frac{S'_{a3}}{S'_{a1}} & \quad i = 1, 2, \ldots, m.
\]

(30)

If the common value in an optimum \( E^0 \) of the ratios \( S'_{i2}/S'_{i1} \) is taken as defining relative price \( p_2/p_1 \), the pair \( (x_{i1}^0, x_{i2}^0) \) is an equilibrium for the \( i \)th consumer.

In order that the pair \( (y_1^0, y_2^0) \) should be an equilibrium for the firm, its relative price must be, not \( p_2/p_1 \), but

\[
\frac{p_2}{p_1}(1 - \tau),
\]

where, by definition, \( \tau \) is the number:

\[
\tau = -\frac{p_1}{p_2} \sum_{a=1}^{m} \frac{S'_{a3}}{S'_{a1}}.
\]

(31)

† Kolm proposes that the good 2 be said to cause 'collective concern'. See Kolm, 'Concernements et décisions collectifs; contribution à l’analyse de quelques phénomènes fondamentaux de l’organisation des sociétés'. Analyse et Prévision, July-August 1967.
Since the derivative $S_{13}$ is negative, $\tau$ is generally positive. The public service must decide on its output taking account of the fact that the social value of an additional unit is not equal to the price $p_2$ paid by consumers but to a lower price $p_2(1 - \tau)$. It must fix output at the level where $p_2(1 - \tau)$ equals marginal cost. Conversely, we can say that the price $p_2$ paid by the consumer has two constituents: $p_2(1 - \tau)$, the marginal cost of production, and $\tau p_2$, the marginal social cost due to congestion. The absence of such a difference between marginal cost of production and price would lead the individuals to consume beyond the social optimum.

Here as before, the essential difficulty lies in the measurement of external effects, that is, in the determination of the marginal rates of substitution $S_{13}/S_{21}$ involved in the calculation of $\tau$. The market tells us nothing about them. This gap could conceivably be filled by a suitable system of inquiries, or a collective decision-making process. To the extent that the same tax $\tau p_2$ must be paid by all the consumers, the difficulties relating to the revelation of preferences are less serious than in the case of pure public goods.

5. Public service with fixed cost

As we saw in Chapter 4, the existence of activities carried on under increasing returns to scale complicates the questions relating to the optimal organisation of production and distribution. We are now in a position to return to this problem and to see its nature more clearly.

We shall consider a simple model where a public service produces a private good but is subject to a high fixed cost and therefore to decreasing average costs. For reasons that will appear later, it often happens that activities carried on under increasing returns to scale are publicly managed, although this is not absolutely necessary. (We saw that a private monopoly may also find itself in equilibrium in spite of the presence of increasing returns.)

We note in passing that this model and the model discussed in Section 3 show that the distinctions of public and private goods on the one hand, and public and private firms on the other, must not be confused. A public good may be produced by private enterprise; a private good may be produced by public enterprise.

(i) Optimum

Suppose then we have an economy with $m$ consumers, 2 firms and 3 goods. Suppose that there are no initial resources of the first two goods, which are consumable ($w_1 = w_2 = 0$), and positive initial resources $w_3$ of the third good, which occurs only as input in the production of the first two goods. Let $x_{13}$ and $x_{23}$ be the inputs in question. The $i$th consumer's utility function is the quasi-concave function $S_i(x_{i1}, x_{i2})$. Production of the first good is
Public service with fixed cost

governed by the production function $x_1 = g_1(a_{13})$, which obeys the usual assumptions and therefore involves non-increasing marginal returns. Production of the second good is governed by

$$a_{23} = \begin{cases} \beta + \gamma x_2 & \text{if } x_2 > 0, \\ 0 & \text{if } x_2 = 0; \end{cases} \quad (32)$$

where $\beta$ and $\gamma$ are two positive numbers representing a fixed cost, involved whenever production is non-zero, and a proportional cost respectively. This is obviously a particular form for increasing returns to scale. However, it has some relevance since it is based on the indivisibility of a fixed cost and indivisibilities are the real cause of increasing returns.

In the space $(x_1, x_2)$ of total consumptions the set of attainable vectors is represented partly by the points within or on the curve $BC$ defined by eliminating $a_{13}$ and $a_{23}$ in

$$\begin{cases} x_1 = g_1(a_{13}) \\ a_{23} = \beta + \gamma x_2 \\ a_{13} + a_{23} = \omega_3, \end{cases} \quad (33)$$

and partly by the points on the segment $AB$, where $A$ has coordinates $(g_1(\omega_3), 0)$. The curve $BC$ is concave downwards, since marginal returns for $g_1$ are non-increasing.

A priori, the optimal states can be represented in this space by the point $A$ if there is zero production of the second good (cf. Figure 2, for the case of a single consumer), or by the points other than $B$ on $BC$ if there is positive production of the second good (cf. Figure 1).

An optimum represented by $A$ is obviously a market equilibrium provided that the second good does not exist in the market. So we shall concentrate initially on an optimum represented by a point lying above the $x_1$-axis (the point $M$ in Figure 1).
In such an optimal state $E^0$, $S_1(x_{11}, x_{12})$ is maximised subject to the constraints:

$$
\begin{align*}
S_i(x_{11}, x_{12}) &= S_i^0, \quad i = 2, 3, \ldots, m \\
x_1 &= g_1(a_{13}) \\
a_{23} &= \beta + \gamma x_2 \\
x_1 &= \sum_{i=1}^{m} x_{i1} \\
x_2 &= \sum_{i=1}^{m} x_{i2} \\
\omega_3 &= a_{13} + a_{23}.
\end{align*}
$$

Let $p_1, p_2, p_3$ denote the Lagrange multipliers relating to the last three constraints. After elimination of the multipliers relating to the other constraints, the necessary first-order conditions for an optimum are:

$$
\begin{align*}
\frac{S_i'}{S_{i1}'} &= \frac{p_2}{p_1}, \quad i = 1, 2, \ldots, m; \\
g_i' &= \frac{p_3}{p_1}; \\
p_2 &= \gamma p_3.
\end{align*}
$$

If $p_1, p_2$ and $p_3$ are interpreted as the prices of the three goods, we revert to the more general results of Chapter 4. The complex $(x_1^0, x_2^0)$ appears as an equilibrium for the $i$th consumer and the complex $(a_{13}^0, a_{23}^0)$ as an equilibrium for the first firm. Moreover, the price of the second good must equal its marginal cost $\gamma p_3$. But $(x_2^0, a_{23}^0)$ is not an equilibrium for the second firm since the corresponding profit $p_2 x_2^0 - \beta p_3 - \gamma x_2^0 p_3 = - \beta p_3$ is less than the zero profit from zero production.

If the optimum in question is to be realised in a market economy, the second firm must be required to produce the good 2 and to sell it at marginal cost. But it then incurs a deficit, which must be covered.

The covering of the deficit will naturally be ensured by taxes $t_i$ imposed on the individuals and such that

$$
\sum_{i=1}^{m} t_i = \beta p_3.
$$

The definition of such taxes raises no particular difficulty since household incomes $R_i$ can always be chosen so that

$$
R_i = p_1 x_{i1}^0 + p_2 x_{i2}^0 + t_i.
$$

Note however that $t_i$ must be fixed independently of the consumption complex $(x_{11}, x_{12})$ chosen by the $i$th consumer, since it might otherwise be to his
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advantage to choose a complex other than \((x_{i1}^0, x_{i2}^0)\) with a view to reducing his contribution \(t_i\).

The conditions under which firm 2 must be managed therefore differ widely from the purely competitive system. They assume fairly strict public intervention. This explains why firms placed in similar situations often have the status of public services.

(ii) Politico-economic equilibrium

The above discussion deals with the characterisation of an optimum as a judiciously amended market equilibrium. The converse property is certainly of more interest: how can we define a decentralised economy that will achieve an optimum? At our present stage, the answer is fairly immediate.

We assume that the markets for the goods are competitive, and that firm 2 is required to sell its product at marginal cost in spite of its resulting deficit. A collective decision-making process is established which decides whether or not the good 2 is to be produced and in the former case, how the coverage of the deficit \(\beta p_3\) is to be shared among the individuals.

We shall see that, if this process satisfies the assumption of section 3(iv), then an equilibrium is also an optimum.

Consider, for example, an equilibrium \(E^0\) involving positive output of the good 2. In particular, let \((x_{i1}^0, x_{i2}^0, t_i^0)\) be the characteristics of the equilibrium for the ith consumer. We assume that, contrary to our required result, there exists a state \(E^1\) that is preferable to \(E^0\) for all the consumers. The case where \(E^1\) involves positive output of the second good is eliminated by the theory in Chapter 4 (cf. proposition 6), since, assuming that the fixed cost of production of the second good is covered, the politico-economic equilibrium \(E^0\) is a market equilibrium in the sense of Chapter 4; in particular, if no account is taken of the fixed cost, firm 2 maximises its profit. The state \(E^1\) is therefore such that

\[ S_i(x_{i1}^1, 0) > S_i(x_{i1}^0, x_{i2}^0) \quad \text{for} \quad i = 1, 2, \ldots, m \]  

(40)

where the inequality holds strictly at least once. Moreover, \(x_1^1 = g_1(\omega_3)\), since we can always assume that resources are totally employed in the state \(E^1\).

The concavity of \(g_1\) implies

\[ x_1^1 = g_1(\omega_3) \leq g_1(a_{i3}^0) + g_1'(a_{i3}^0) \cdot a^0_{i3} \]  

(41)

since \(a_{i3}^0 + a_{i3}^0 = \omega_3\) (cf. theorem 1 of the appendix). In view of (33) and (36), which are satisfied in \(E^0\), (41) becomes

\[ x_1^1 \leq x_1^0 + \frac{p_2^0}{p_1^0}(\beta + \gamma x_2^0) \]
or, in view of (37),
\[ p_1^0x_1^1 \leq p_1^0x_1^0 + p_2^0x_2^0 + p_3^0\beta. \]  
(42)

We set
\[ t_i^* = p_1^0x_{1i}^0 + p_2^0x_{12}^0 + t_i^0 - p_1^0x_{1i}^1 = R_i - p_1^0x_{1i}^1, \]  
(43)
where \( R_i \) is the income associated with \( E^0 \).

The relation (38) satisfied in \( E^0 \) and (42) then imply
\[ \sum_{i=1}^m t_i^* \geq 0. \]  
(44)

A fortiori, there exist taxes \( t_i^* \) at most equal to the \( t_i^* \) and whose sum is zero.
The initial budget is therefore rejected unanimously in favour of the budget involving taxes \( t_i^* \) and zero production of the good 2. The inequality \( t_i^* \leq R_i - p_1^0x_{1i}^1 \) shows that this new budget allows each consumer to obtain \((x_{1i}^1, 0)\), which by hypothesis is preferred to the best complex \((x_{1i}^0, x_{12}^0)\) compatible with the budget contained in \( E^0 \).

The existence of \( E^1 \) therefore contradicts the fact that \( E^0 \) is an equilibrium, which is what we had to prove. Completely similar reasoning applies to the case where \( E^0 \) involves zero production of the good 2.

Thus every politico-economic equilibrium is a Pareto optimum. This is not a surprising result by analogy with the result in Chapter 4 stating that every market equilibrium is an optimum. However, it is significant in so far as a politico-economic equilibrium involving positive production of the good 2 may exist even though there is no market equilibrium that has this characteristic.

However, we have not completely solved the problem raised by the decentralisation of decisions in our model, and a fortiori in more general economies where some firms operate under conditions of increasing returns to scale. For we have not really shown that every optimum can be realised as a politico-economic equilibrium, even with our very unrestrictive definition of the latter.

Consider what we did. We associated with the optimum a system of taxes \( t_i \) ensuring coverage of the deficit incurred by the public service. But we did not show that, if prices \( p_1, p_2, p_3 \) are taken as given, the budget defined by the production decision for the good 2 and by taxes \( t_i \) will in no circumstances be rejected unanimously. This can only be proved if \( g_1 \) is linear, when relative prices \( p_1/p_3 \) and \( p_2/p_3 \) are independent of the chosen state. If this particular condition is not satisfied, we can conceive of an optimum incompatible with the restricted decentralisation involved in our politico-economic equilibria.

Consider the situation illustrated by Figure 3, where there is a single consumer while the optimum is a point \( M \) involving positive consumption of the good 2. The prices \( p_1, p_2, p_3 \) corresponding to this optimum are well defined, up to a multiplicative constant, by (36) and (37). Also the tax \( t \) equals \( \beta p_3 \).
When he examines the budget on the basis of the prices $p_1, p_2, p_3$ and the tax $t$, the consumer thinks that by not paying the tax he could achieve a point $U$ involving zero consumption of the good 2 and consumption $x^U$ of the good 1 defined by

$$p_1 x^U = p_1 x^0_1 + p_2 x^0_2 + t. \quad (45)$$

The consumer therefore rejects the budget if the point $U$ lies to the right of the indifference curve $\mathcal{S}$ passing through $M$. Now, $U$ is always on the right of $A$ when the first good is produced under decreasing marginal returns ($g_1$ is strictly concave) so that $U$ may well be on the right of $\mathcal{S}$ even though by hypothesis $A$ is on the left. The optimum cannot then be realised as a politico-economic equilibrium.

Let us verify that $U$ is on the right of $A$ when $g_1$ is concave. Let $T$ be the point where the tangent at $M$ to $BC$ meets the horizontal axis. We can write (45) in the form:

$$x^U = x^T + \beta \frac{p_3}{p_1}, \quad (46)$$

or

$$x^U = x^T + \beta g_1(a^0_{13}). \quad (47)$$

Also,

$$x^A = x^B + g_1(\omega_3) - g_1(\omega_3 - \beta). \quad (48)$$

Now, since $g_1$ is strictly increasing and concave, $x^B < x^T$ and

$$g_1(\omega_3) - g_1(\omega_3 - \beta) < \beta g'_1(\omega_3 - \beta) < \beta g'_1(a^0_{13}).$$

These two inequalities imply that $x^A < x^U$.\(^\dagger\)

\(^\dagger\) This proof also establishes that $x^A = x^U$ when $g_1$ is linear, in which case the optimum can always be realised as an equilibrium, as was stated earlier.
(iii) An economic calculus

The difficulty which has just been raised stems from the fact that the prices corresponding to the optimum \(M\) evaluate the marginal equivalences correctly only in the neighbourhood of \(M\). To get round this difficulty, a rule of economic calculus has been suggested which takes account of the fact that prices must be revised progressively as we move along the boundary of the domain of attainable states. Let us examine this rule in the context of our model.†

It is now convenient to choose the good 3 as numéraire and to let \(r_1\) and \(r_2\) denote the supposed prices of the first two goods, these prices being functions of the characteristics of the state to which they refer. More precisely, given a programme for the public service (a value of \(x_2\)), these prices must correspond to the marginal rates of substitution and transformation in the remaining sectors of the economy, these sectors being assumed to be optimally run. In other words, \(r_1\) and \(r_2\) permanently satisfy

\[
\frac{1}{g'(a_{13})}, \quad (49)
\]

\[
\frac{r_2}{r_1} = \frac{S_{i2}}{S_{i1}}. \quad (50)
\]

Suppose we have a situation where the production of the second good is zero, where the resource \(o>3\) is completely used in the production of the first good and where the output of this good is distributed among the consumers in a certain way. We now assume that production of the good 2 is increased progressively from zero and that each individual's utility remains constant at its level when production was zero; for the moment we are not concerned whether this transformation is technically feasible. The variations in output of goods 1 and 2 must be distributed among the consumers so that

\[
\frac{dx_{i1}}{S_{i1}} = \frac{dx_{i2}}{S_{i2}} = -\frac{r_2}{r_1} dx_{i2}; \quad (51)
\]

it follows that, for total outputs \(x_1\) and \(x_2\),

\[
\frac{dx_1}{r_1} = -\frac{r_2}{r_1} dx_2. \quad (52)
\]

Let us now examine the implications for inputs of the variations \(dx_1\) and \(dx_2\); but we still ignore the fixed cost, which must be incurred when we go from zero production to positive production of the second good. The

† A general theory of this economic calculus is given by Lesourne, in ‘A la recherche d'un critère de rentabilité pour les investissements importants,’ Cahiers du Séminaire d'Econométrie, No. 5, 1959.
negative variation \( dx_1 \) liberates a certain quantity \( -da_{13} \) of good 3 while the positive variation \( dx_2 \) absorbs a quantity \( da_{23} \). The net available surplus will be

\[
- da_{13} - da_{23} = \frac{1}{g_1} dx_1 - \gamma dx_2,
\]
or, in view of (49) and (52),

\[
(r_2 - \gamma) dx_2.
\]

Clearly there is never any advantage in increasing \( x_2 \) beyond the quantity \( x^*_2 \), for which \( r_2 = \gamma \), that is, for which (37) holds, since, with the usual convexity assumptions, \( r_2 \) decreases as \( x_2 \) increases (the marginal rate of substitution \( S'_{12}/S'_{11} \) decreases and \( g'_1 \) increases, therefore \( r_2/r_1 \) and \( r_1 \) both decrease). Beyond \( x^*_2 \) a change keeping utilities constant no longer makes more of the good 3 available, but on the contrary absorbs a positive increasing quantity of it, because of variable costs; such a change is therefore disadvantageous.

But is it advantageous to go from \( x_2 = 0 \) to \( x_2 = x^*_2 \)? It will be, if this releases a greater quantity of good 3 than that required to cover the fixed cost \( \beta \).

To calculate the quantity of good 3 that is released, we need only consider the expression \( \sigma \), called the 'surplus'† and defined by:

\[
\sigma = \int_0^{x^*_2} (r_2 - \gamma) dx_2,
\]

where the integral is taken for \( r_2 \) varying with \( x_2 \) along the transformations described above.

If \( \sigma > \beta \), it will be possible to cover both the fixed cost and the variable cost of production of \( x^*_2 \), to maintain each consumer’s utility at its level when \( x_2 \) is zero and to release an additional quantity of good 3, which can be used to produce either good 1 or good 2 and thus increase the utility of one or more consumers. Conversely, if \( \sigma < \beta \), it is not possible to produce the second good and at the same time maintain the utility of all the consumers; consequently the optimum implies \( x_2 = 0 \).

This rule can be illustrated by a diagram with \( x_2 \) as abscissa, and, as ordinate, the value of \( r_2 \) corresponding to the marginal rate of substitution between goods 2 and 3 in the rest of the economy when it is optimally managed and the individuals’ utilities remain constant. The surplus is equal to the area between the curve \( \% \) representing \( r_2 \) and the horizontal with ordinate \( \gamma \). It is advantageous to produce \( x^*_2 \) if this area exceeds \( \beta \).

Has this rule any practical relevance? Is it possible for the managers of the

† There are many variants of the notion of surplus throughout economic theory. The reader must always check rigorously which particular version is used if he wishes to ensure that an argument is valid. In fact it is only rarely that the introduction of a 'surplus' helps toward the solution of the stated problem.
External economies, public goods, fixed costs

Fig. 4

public service producing the good 2, or the citizens required to make a
decision about it, to construct C? It seems difficult to give a positive answer
_a priori_. The variations in \( r_2 \) depend as a rule on all the elements of our
model, namely the functions \( S_i \), the function \( g_1 \), the initial state on which our
reasoning is based. It seems as easy to determine the optimum directly as to
construct the curve; in fact, both demand very full information. In short, the
rule we have just established does not seem to allow real decentralisation of
decisions.

Its supporters hold that a first approximation to the curve \( C \) can often be
determined from very partial information and that such an approximation
is sufficient. This is a question of fact which the reader can try to decide for
himself.

The particular case where \( g_1 \) is linear has been given special consideration.
It is not surprising that it is favourable, since, as we have seen, it lends itself
better to decentralisation than the general case. Let us consider it again.

Equation (49) shows that the price \( r_1 \) of the first good is then constant.
Let us call it \( p_1 \) to remind us of this property. Price \( r_2 \) now depends only on
individual utility functions since (50) becomes

\[
 r_2 = \frac{S_{12}'}{S_{i1}'} .
\]  

(54)

Under these conditions, we can imagine a process for constructing a curve
near \( C \). Let us fix the income of each individual at the value \( R_i = p_1 x_{i1} \) of
the quantity of the good 1 that he receives if the second good is not produced.
We state successively decreasing prices \( r_2 \), starting with a value sufficiently
high to correspond to zero demand for \( x_2 \). At each stated price \( r_2 \) we observe
the demands \( x_{i2} \) of the different individuals and the corresponding sum \( x_2 \).
Since 2 is a private good, we can assume that individual preferences will be
revealed correctly and that individual demands will continually satisfy (54).
Public service with fixed cost

The total demand \( x_2 \) will then define the abscissa of the point on a curve \( C' \) corresponding to the stated price. We can conceive that in practice determination of the demands at each price will be carried out by survey of a representative sample of individuals.

The difference between \( C \) and \( C' \) stems from the fact that the former is defined with reference to the indifference curves passing through the initial complexes \( x_1 \), while for the second incomes were fixed. The criterion discussed above for deciding whether to produce \( x_2 \) does not apply to the 'surplus' defined on \( C' \). But this surplus can be considered as an approximation to that defined on \( C \).

There is a tariff principle connected with this rule, as opposed to the sale at marginal cost justified in Chapter 4 and discussed above in Sections (i) and (ii). Let us discuss this briefly.†

Instead of assuming that all units of the second good are sold at the same price, let us assume that the public service sells each additional quantity at its marginal value to the individual buyer,‡ that is, at the value \( p_l S_{i2} \frac{dx_{i2}}{S_{i1}} \) of the quantity \( dx_{i1} = S_{i2} \frac{dx_{i2}}{S_{i1}} \) that is equivalent to \( dx_{i2} \). The abscissa of the point on \( C' \) with ordinate \( r_2 \) then represents the total number of units that will be sold at a price greater than or equal to \( r_2 \). If total output \( x^*_2 \) is determined so that the last unit just covers the variable cost, the public service's net profit \( \sigma - \beta \) will be positive or zero exactly when the optimum involves production of the good 2. The tariff principle in question is therefore advocated together with the rule that the public service must not suffer a loss.

Of course in practice it is impossible to apply a tariff schedule modelled exactly on demand. But the above principle may justify some discrimination among the units sold. The aim of such discrimination may be to balance the budget of the public service; the amount that each consumer pays in excess of the variable cost of the quantity he demands is then his contribution to the fixed cost \( \beta \). According to some writers, this 'user-finance' often conforms to social justice.

The theory obviously gives us no cause to reject such a tariff principle, so long as an optimal quantity \( x^*_2 \) is produced, that is, so long as each consumer’s demand is the same as if he could acquire an additional unit at marginal cost \( \gamma \). However, this last condition cannot easily be satisfied by a discriminatory tariff. In practice it assumes that individual demands are completely inelastic, and that the \( i \)th consumer does not reduce his demand when the price of the service to him is increased from \( \gamma \) to \( \gamma + t_i \).

† This principle is due in particular to Dupuit and Colson. See the 'théorie du péage, in Colson, Textes choisis, edited by G.-H. Bousquet, Dalloz, Paris 1960, pp. 152-178.
‡ We could then speak of an 'ad valorem' tariff provided that we interpret this as a charge assessed in accordance with the value of the service rendered. But the expression is in fact used in a different sense to define transport tariffs that are proportional to the value of the freight.
6. Redistribution and second best optimum

On several previous occasions we have touched on questions of equity in the distribution of goods among individuals. In Chapter 4 we encountered the ‘Pareto optimum’ and saw that it was so defined that such questions were not prejudged. The choice of optimum assumed that some previous decision had been made on equity. In Chapter 8 this principle was expressed very simply since, for example, the methods of Sections 8.3 and 8.4 are based on income-distributions assumed to be given a priori. Such an approach suffices when the question at issue is that of the efficiency of economic organisation. But it is obviously too crude to reveal the redistributive effects of public action.

In the real world, in the absence of deliberate intervention, distribution depends on individuals’ abilities, on their property rights and on the institutions which govern their contractual relations. The positive theories so far discussed do not disguise this. When dealing with competitive equilibrium we saw that prices and consumption depended on the initial resources held by each individual and in particular, on the relative scarcity of these resources. Going on to situations of imperfect competition we discussed the possible effects of monopoly positions on redistribution.

On a closer examination we saw also that the distribution of the variables $R_j$ intended to represent incomes or wealth is not sufficient for a true description of the distribution of welfare among individuals. Since needs vary from one to another, one income-distribution may be more or less favourable to such and such an individual according to what prices are. This remark is reinforced if we consider public consumption which, varying in extent and available to all, benefits in particular those who have most need of it.

Given all this it appears pointless to think of being able to establish a distribution which will be optimal from the standpoint of equity. In fact, the public authority restricts its intervention to actions aimed at a partial redistribution of income and wealth. So the system of individual taxes $t_1, t_2, \ldots, t_m$ introduced in Sections 3 and 5 gives a better description of reality than the previous assumption of a distribution $R_1, R_2, \ldots, R_m$ given a priori.

However, to represent redistribution by a set of individual taxes is too summary a basis for a serious discussion of this question. Fiscal and parafiscal contributions must be established in an objective and easily applicable way on certain characteristics of the situation or of the activity of those liable to contribute. Looking at things more closely, we soon see that almost all taxes imposed in practice affect the agents’ economic decisions, and this in a way that is often prejudicial to efficiency.

Thus, the effect of specific taxes is to discourage consumption of the
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goods to which they apply; if they are not aimed at correcting clearly identified external effects they generally lead to distortions in the use of resources and hence to some loss of efficiency. General taxes such as value added or income tax are sometimes said to have neutral intent vis-à-vis allocation but do in fact hit either consumption or income without affecting the loss of earnings resulting from the reduction in work done; it is often thought that they cause the ablest individuals to reduce their efforts to the detriment of society as a whole. As a rule taxes on wealth, that is, on property rights \((\omega_{ik}, \theta_{ij})\) do not have this drawback; but first, modern governments have never succeeded in covering much of their expenditure by this means, and second, such a tax, if regularly extracted, discourages saving relative to consumption and thus adversely affects intertemporal efficiency (see Chapter 10).

In short, the choice of a fiscal system to achieve redistribution comes down to finding a principle of ‘least harm’ or of a ‘fair balance’ between on the one hand a policy of abstention which means abandoning the concern for equity and on the other hand, a policy of establishing huge and continually repeated transfers which would be highly detrimental to efficiency. There can be no hope of achieving ‘the optimum’ but, in view of the set of constraints on public action, only of finding a ‘second best optimum’, the best among the set of states which can actually be achieved.

This necessary consideration of constraints other than those arising from purely physical requirements is not unique to the field of redistribution. It is a characteristic of most economic decisions by public agencies who are placed in a context which makes a ‘first best optimum’ impossible to achieve.

It is beyond our present purpose to discuss this problem fully since this would take us into the special field of the theory of public finance. As in earlier sections of this chapter, we shall discuss only a limited example which has no pretensions to realism but is intended only to set a problem of a second best optimum and to reveal the nature of the solution.

The example concerns fiscal intervention aimed at partial correction of imperfect competition in the private sector of production which is not directly controlled by the State.

Consider an economy with three goods, the first two of which are produced and consumed in quantities \(x_1\) and \(x_2\), the third being a factor (labour, say) of which a fixed quantity \(\omega\) is available. There are three firms engaged in production, of which the first two are private and produce the good 1 \((j = 1, 2)\) while the third is public and produces the good 2 \((j = 3)\). If \(z_1\), \(z_2\) and \(z_3\) are the quantities of labour employed in the three firms, their production functions are respectively

\[
y_1 = g_1(z_1), \quad y_2 = g_2(z_2), \quad y_3 = g_3(z_3)
\]  

(55)
and the equalities between resources and uses:

\[ x_1 = y_1 + y_2, \quad x_2 = y_3 \]  
\[ z_1 + z_2 + z_3 = \omega. \]  
(56)  
(57)

Suppose there is a single consumer whose utility function is \( S(x_1, x_2) \). Clearly the first best optimum is defined by solving the system (55), (56), (57) and

\[ S_1'g_1' = S_1'g_2' = S_2'g_3' \]  
(58)

where \( S_1' \) and \( S_2' \) are obviously the two partial derivatives of \( S \) while \( g_1', g_2', g_3' \) are the derivatives of \( g_1, g_2, g_3 \).

But we are assuming that the State does not have direct control of the distribution of labour among the three firms. There are three tools at its disposal: \( z_3 \), the quantity of labour employed in the public firm, \( p_2 \), the price of the good which it produces (the numéraire being labour) and \( t_1 \), a specific tax (or subsidy) applied to production of the good 1. For this good, the price paid by the consumer is \( p^1 \) while the price received by firms 1 and 2 is \( r_1 = p_1 - t_1 \).

In the private sector the consumer takes prices as given and behaves as in perfect competition so that

\[ \frac{S_1'}{S_2'} = \frac{p_1}{p_2}. \]  
(59)

Similarly the first firm takes \( r_1 \) as given and maximises its profit so that the value of the marginal productivity of labour becomes 1:

\[ r_1 g_1 = 1. \]  
(60)

But, for a reason which we shall not specify, the second firm fixes this marginal value at a given value \( u \), which differs from 1:

\[ r_1 g_2' = u. \]  
(61)

The behaviour of this firm can be said to be ‘deviant’; it would be too much of a digression to discuss plausible explanations for such behaviour—competitive imperfections, financial constraints, etc. may induce it in the real world.

So, for the State, the problem is to determine the values for these tools which, subject to constraints (55), (56), (57), (59), (60) and (61) lead to the highest possible value of \( S(x_1, x_2) \). This value cannot coincide with the first best optimum since (60) and (61) are incompatible with the first equation of (58) where \( u \neq 1 \) (one of the assumptions of this exercise is that a discriminatory tax against the second firm only is excluded).
Obviously it is equivalent to fix \( z_3, p_2 \) and \( r_1 \) rather than \( z_3, p_2 \) and \( t_1 \). But given \( r_1 \), then (60) and (61) determine \( z_1 \) and \( z_2 \). The values of the other variables result from the other constraints. Since \( p_1 \) and \( p_2 \) occur only as a ratio, \( p_2 \) can be chosen arbitrarily (subject to the consumer's budget equation). In short, the problem for the State reduces to choosing \( z_1, z_2, z_3 \) and \( r_1 \) so as to maximise
\[
S[g_1(z_1) + g_2(z_2), g_3(z_3)]
\] (62)
subject to the constraints (57), (60) and (61).

After elimination of Lagrange multipliers the first order conditions reduce to
\[
S_2 g'_3 = (1 - \tau) S_1 g'_1
\]
(63)
where
\[
\tau = \frac{u(1 - u)g''_1}{ug''_1 + g''_2}.
\]
(64)
If \( u = 1 \) this is obviously condition (58) for the first best optimum. If \( u \neq 1 \), condition (63) can be simply interpreted if we assume that \( p_2 \) is taken as the marginal cost of good 2, or \( 1/g'_2 \), and take account of (59). Equation (63) becomes
\[
(1 - \tau)p_1 g'_1 = 1.
\]
(65)

Compared with (60) this equation shows that the rate of tax on good 1 must be \( \tau \). Since the second derivatives \( g''_1 \) and \( g''_2 \) are negative, \( \tau \) is positive when \( u < 1 \) and negative when \( u > 1 \).

However (64) shows that the tax rate corresponding to the second best optimum is fairly difficult to find in practice since it depends on the second derivatives of the production functions. So, unfortunately, the search for a second best optimum often leads to formulae which are difficult to apply in practice.

This concludes our discussion of some examples showing the directions in which economic science has sought the solution to the new problems arising from the complex interdependences among agents. As was pointed out at the beginning of the chapter, we have not given a full treatment of the questions raised. However, the reader can assess their importance and diversity.
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In principle, the theories examined up till now apply to models involving a time scale as well as to those which do not. However the problems raised by the choice between present and future consumption, or by capital accumulation, are sufficiently important in themselves to be considered explicitly, even if this only brings us back to the analyses already discussed. Also, interest and the discounting of values have a fairly subtle role. Their implications are important for the distribution of incomes, and we must therefore consider them in particular even if we have only to establish some direct consequences of what we already know about the general characteristics of the price system.

In addition, the development through time of production and consumption suggests the need to investigate new properties which have not been touched on up till now since they are meaningless in a static context. So this chapter will contain essentially new analyses in addition to the application of theories with which we are already familiar.

The questions now to be tackled have been discussed in the past under various headings without their essential unity being always understood: the theory of interest, the theory of capital, the theory of growth are so many extensions of optimum and equilibrium theories, which must obviously first be firmly established before the former can be developed.

Here we shall not attempt the complete treatment of interest, capital and growth, since too many difficult problems are involved. We shall introduce only those questions that follow most directly from our previous analyses. Thus we shall hope to make clear the common logic in microeconomic theories and lay the proper groundwork for further study.

In particular, we shall ignore that body of research concerned with the characterisation of possible growth paths in a competitive economy, or of interesting growth programmes resulting from planning.† In the author's

opinion, the results obtained thus far in the context of microeconomic formulations are too specialised for inclusion here.

(A) A DATE FOR EACH COMMODITY

As we saw initially, the theories discussed up till now apply to a time economy provided that two quantities available at two different dates are always considered to relate to different commodities even if their physical nature is the same.

There are some consequences of this remark which, although fairly straightforward, have not always been clearly understood. This first part of the chapter will be devoted to them, but will end with the discussion of a new concept, namely optimality in M. Allais' sense. In the second part we shall introduce a more specific formulation, which will be particularly useful for the investigation of stationary states and proportional growth programmes.

Suppose then that commodities are distinguished both by nature \((q = 1, 2, \ldots, Q)\) and by date \((t = 1, 2, \ldots, T)\). The former index \(h\) for a commodity is now replaced by the double index \((q, t)\). To avoid confusion, we shall now use the term *good* for commodities of the same nature \(q\) considered at different dates \((t = 1, 2, \ldots, T)\). The index \(q\) will then refer to goods.

We shall be concerned with the organisation of production, distribution and consumption over all dates. We wish to study individual or collective decisions in the period from \(t = 1\) to \(t = T\). We therefore place ourselves at the moment when these decisions are made, that is, *at the beginning of the period*. The date \(t = 1\) can be considered as 'today', \(t = 2, \ldots, T\) being future dates, which we assume to be ordered in time at regular intervals.

A complete specification of the activity of the various agents at the various dates constitutes a 'programme', which seems a preferable term here to the term 'state' used up till now. We are concerned with a programme adopted for the immediate and more distant future.

1. Market prices and interest rates

First of all we shall discuss the price system resulting from the theory developed particularly in Chapters 4 and 5. For the moment we do not have to state explicitly whether this system is introduced in order to allow the decentralised realisation of an optimum or if it arises from the existence of competitive markets for the different commodities.

In the first chapter, prices \(p_{qt}\) of the various commodities were defined in such a way that the ratio \(p_{qt}/p_{rt}\) measures the quantity of the commodity \((r, \tau)\) that must be given in exchange for one unit of the commodity \((q, t)\), that is, the quantity of the good \(r\) that, at date 1, must be guaranteed for delivery
at date \( t \) in return for the promised delivery at date \( t \) of one unit of the good \( q \). Thus, by applying our general principles, the price-system defined by the \( p_{qt} \) is found applicable to forward contracts, the case of a spot contract corresponding to the particular situation where the two commodities exchanged are both available at the initial date \( (t = \tau = 1) \). These forward contracts are lending or borrowing operations when they involve the same good at two distinct dates.

Let us assume that the commodity \((Q, 1)\) is the numéraire, that is, that \( p_{qt} \) is the quantity of \( Q \) which must be given at date 1 to buy the right to one unit of the good \( q \) deliverable at date \( t \). This is said to be the 'discounted price' of the commodity \((q, t)\). The origin of this expression will very shortly become clear.

We can define 'own interest rates' for a good on the basis of prices \( p_{qt} \) relating to it when it is available at different dates. To do this, we call the ratio

\[
\beta_{qt} = \frac{p_{qt}}{p_{q1}} \tag{1}
\]

the 'own discount factor' \( \beta_{qt} \). It is therefore the quantity of \( q \) which must be given today to obtain the promised delivery of one unit of the same good at date \( t \) (this discount factor is defined only if \( p_{q1} \neq 0 \)). The own interest rate for period \( t \), going from date \( t \) to date \( t + 1 \), is the number \( \rho_{qt} \) such that

\[
\beta_{q,t+1} = \frac{1}{1 + \rho_{qt}} \beta_{qt} \tag{2}
\]

(\( \rho_{qt} \) is defined only if \( \beta_{q,t+1} \) is defined and differs from zero, that is, if \( \rho_{q,t+1} \) and \( p_{q1} \) both differ from zero).

With this definition of the own interest rate, we can immediately verify, taking account of (1), that

\[
p_{q,t+1} = \frac{1}{1 + \rho_{qt}} p_{qt}. \tag{3}
\]

This equality shows that a loan contract involving the provision of one unit of \( q \) at date \( t \) and the return of \( 1 + \rho_{qt} \) units of the same good at date \( t + 1 \) conforms to the price-system, since the two values \( p_{qt} \) and \( p_{q,t+1}(1 + \rho_{qt}) \) exchanged are equal. We can also say that \( \rho_{qt} \) is the interest rate appropriate to a contract that stipulates the loan of one unit of the good \( q \) between the dates \( t \) and \( t + 1 \).

It may happen that the \( \rho_{qt} \) take values \( \rho_q \) that are independent of \( t \). Then repeated application of (2) gives

\[
\beta_{q,t+1} = (1 + \rho_q)^{-t}
\]

(formula (1) shows that \( \beta_{q1} = 1 \)). It then follows that

\[
p_{qt} = (1 + \rho_q)^{-t+1} p_{q1}.
\]
These two formulae, similar to those used in actuarial calculations, justify the terms 'discount factor' and 'discounted price' used for \( \beta_{qt} \) and \( p_{qt} \) respectively.

In general, own interest rates relating to different goods and the same period do not coincide. In order that they should, discounted prices must be such that the ratios \( p_{a,t+1}/p_{a,t} \) have the same value for all goods. But a priori, there is no reason for this to happen (however, see Section B.2 below).

When we talk of the discount factor or of the rate of interest, or equivalently the discount rate, without specifying the good to which it refers, this good is understood to be that occurring in the definition of the numéraire; here it is identified by the index \( Q \). In what follows, we shall use the term numéraire to denote the good \( Q \) without the risk of confusion. We shall simply write \( \beta_t \) and \( \rho_t \) instead of \( \beta_{Qt} \) and \( p_{Qt} \).

To say that prices are non-negative is equivalent to saying that discount factors are non-negative and that all the defined interest rates are greater than or equal to \(-1\). However, we note that some interest rates may very well be negative.

Although the whole theory can be presented directly in terms of discounted prices, it is sometimes convenient also to define undiscounted prices, which are proportional, for a given date, to discounted prices but are such that the price of the particular good serving as numéraire is 1 on all dates. Undiscounted prices are determined uniquely from discounted prices, given the numéraire. Suppose again that the latter is the last good. The undiscounted prices \( \bar{p}_{1t}, \ldots, \bar{p}_{qt}, \ldots, \bar{p}_{Qt} \) at date \( t \) must be proportional to the corresponding discounted prices \( p_{1t}, \ldots, p_{qt}, \ldots, p_{Qt} \) and, in addition, \( \bar{p}_{Qt} \) must equal 1. It is therefore necessary that

\[
\bar{p}_{qt} = \frac{p_{qt}}{p_{Qt}} = \frac{\rho_{qt}}{\rho_{Qt}} \tag{4}
\]

or,

\[
\bar{p}_{qt} = \frac{1}{\beta_t} p_{qt} \tag{5}
\]

since \( \rho_{Qt} = 1 \) implies that, for the good \( Q \), (1) can be written in the form

\[
\beta_t = p_{Qt}. \tag{6}
\]

Consider a complex of commodities defined by the quantities \( z_{q\theta} \) of the different goods available at the dates \( \theta = t, t + 1, \ldots, t^* \). Let \( z_\theta, p_\theta \) and \( \bar{p}_\theta \) denote the vectors with the \( Q \) components \( z_{q\theta} \), \( p_{q\theta} \) and \( \bar{p}_{q\theta} \) respectively. For this complex, the discounted value at date \( t \), or the present value at date \( t \), is, by definition,

\[
\frac{1}{\beta_t} \sum_{\theta = t}^{t^*} p_{\theta} z_{\theta}, \quad \text{which equals} \quad \sum_{\theta = t}^{t^*} \frac{\beta_{\theta}}{\beta_t} \bar{p}_{\theta} z_{\theta}.
\]
In order to calculate the discounted value from the undiscouted prices \( \bar{p}_{q0} \) and the coefficients \( \beta_{q} \), we can first determine the \( \bar{p}_{0z0} \), the undiscouted values of the bundles of goods available at the different dates, then associate with each of these terms the 'discount factor' \( \beta_{0}/\beta_{t} \), which discounts at date \( t \) the values concerning the later date \( \theta \). If the interest rate is the same for all periods (\( \rho_{0} = \rho \)), this discount factor is

\[
\frac{1}{(1 + \rho)^{\theta - t}}.
\]

It is less than 1 when the interest rate is positive.

For the same complex, we can also define the capitalised value at date \( t^{*} \) as the quantity

\[
\frac{1}{\beta_{t^{*}}} \sum_{\theta = t}^{t^{*}} p_{0z\theta}, \quad \text{which equals} \quad \sum_{\theta = t}^{t^{*}} \frac{\beta_{\theta}}{\beta_{t^{*}}} \bar{p}_{0z\theta}.
\]

To find this value, we can start with the \( \bar{p}_{0z\theta} \) and multiply them respectively by the 'capitalisation factors' \( \beta_{\theta}/\beta_{t^{*}} \), which capitalise to date \( t^{*} \) the values concerning the previous dates \( \theta \). If the interest rate is constant, the factor \( \beta_{\theta}/\beta_{t^{*}} \) equals \((1 + \rho)^{t^{*} - \theta} \); it is greater than 1 whenever \( \rho \) is positive.

2. The consumer

For the discussion of the consumer we can omit the index \( i \). The consumption vector then has \( QT \) components, \( x_{qt} \) representing the quantity of the good \( q \) used by the consumer at date \( t \); \( x \) is therefore in fact the 'consumption plan' covering the \( T \) dates from \( t = 1 \) to \( t = T \).

No particular problem arises in the definition of the set \( X \) in \( R^{QT} \) which contains all physically possible consumption plans. So we turn to the utility function \( S(x) \) representing the consumer's preferences among these different plans.

The marginal rate of substitution of the good \( q \) at date \( t \) with respect to the same good at date \( 1 \) can be considered as an own 'subjective discount factor' for this good; it is, in fact, the quantity by which consumption of \( q \) at date \( 1 \) must be increased to compensate for a decrease of one unit in consumption of \( q \) at date \( t \):

\[
- \frac{dx_{q1}}{dx_{qt}} = \frac{S'_{q}(x)}{S'_{q1}(x)}.
\]

(7)

In particular, if \( q = Q \) is the numéraire, we can talk of the subjective discount factor without specifying the good \( Q \) to which it relates. Subjective interest rates defined by formulae similar to (2) correspond to the subjective discount factors. The values of the discount factors and the subjective interest rates
clearly depend on the consumption plan \( x \) with respect to which they are defined.

Consider in particular the case of a single good and two dates. The consumer's indifference curves can be represented on a graph with \( x_{11} \) as abscissa and \( x_{12} \) as ordinate. With respect to a particular vector \( x \), the subjective discount factor \( \beta \) (for the second period) is determined by the tangent to the indifference curve passing through \( x \), as shown in Figure 1. It follows from (7) that it is in fact the gradient of the normal to this tangent. The definition of the subjective interest rate implies that the vector \((1 + \rho, 1)\) is collinear with the vector \((1, \beta)\) and is therefore parallel to the normal at \( x \).

![Figure 1](image)

It is usually assumed in actual observed situations that the subjective discount factors are in most cases less than 1 and that most subjective interest rates are positive. In the present example with only one good, this may result from the joint realisation of two assumptions and one particular circumstance.

According to the first assumption, individuals show a systematic psychological preference for the present over the future; this can be called 'impatience'. By this we mean that, if the consumption plan involves the same quantities at all dates for each good, then the increase in \( x_{q} \) to compensate for a decrease of one unit in \( x_{q1} \) must be greater than 1. On Figure 1, at any point on the line \( x_{11} = x_{12} \), the tangent to the indifference curve would have a gradient whose absolute value is greater than 1.

The second assumption is that the utility functions are quasi-concave (assumption 4 of Chapter 3). The effect of this on our graph would be to make the indifference curves concave upwards.

Finally, the consumption plans usually considered involve greater future than present consumption. In the particular case of Figure 1, \( x \) would lie...
above the line $x_{11} = x_{12}$. The gradient of the tangent to $S$ at $x$ would then be greater than the gradient of the tangent at the point of intersection with the bisector. The subjective interest rate would be higher at $x$ than at this point of intersection, and therefore \textit{a fortiori} would be greater than 1.

In order to make clear how the theory discussed in Chapter 2 for consumer equilibrium generalises to a situation involving time, we now examine the budget constraint

$$
\sum_{t=1}^{T} \sum_{q=1}^{Q} p_{qt} x_{qt} = \sum_{t=1}^{T} \beta_t \sum_{q=1}^{Q} \tilde{p}_{qt} x_{qt} \leq R. \tag{8}
$$

The discounted value of the consumption plan must not exceed the value $R$ of the resources that are available to the consumer \textit{a priori}. In the static theory we have previously let $R$ denote alternatively income or wealth. Only wealth is appropriate here since $R$ relates to a budget covering not one particular date but the set of $T$ dates under consideration.

The theory of consumer behaviour, as so far examined, assumes that the consumer considers discounted prices as given and chooses his whole consumption plan for the dates from $t = 1$ to $t = T$ so as to maximise his utility function subject to his budget constraint.

As thus interpreted therefore, the theory assumes that the consumer:

(i) has knowledge of all discounted prices (for all dates and all goods) as well as knowledge of all his future needs;

(ii) has the possibility of making forward contracts, that is, of buying or selling forward, for any date, quantities of products or services which he may wish to acquire or dispose of.

It is not indispensable that all forward contracts be concluded. It is sufficient that future prices are known and that the consumer may lend or borrow any quantity of numéraire at the interest rates $\rho_t$ subject only to the constraint that he must balance his operations over all the $T$ dates.

$R$ can be considered as the consumer's initial wealth and $-\sum q \tilde{p}_{qt} x_{qt}$ as his 'savings' at date $t$. If $e_t$ denotes this saving and $A_t$ his net assets after taking account of $e_t$, then $A_1 = R + e_1$ and $A_t = (1 + \rho_{t-1})A_{t-1} + e_t$. We can easily verify that (8) is equivalent to $A_T \geq 0$ (we need only note that $\beta_t e_t = \beta_t (A_t - \beta_{t-1} A_{t-1})$. The consumer must only end up with non-negative net assets at the terminal date $T$.

This theory therefore ignores uncertainty on future needs and prices, as well as possible stricter limitations on individuals' borrowing facilities than is required by their solvency over all the $T$ periods considered (on the latter point, see the previous remarks in Chapter 2, Section 5).
3. The firm

Similarly, if we apply the general theory of Chapter 3 to an intertemporal economy, each firm must maximise its total profit, which can be written here:

$$\sum_{t=1}^{T} \sum_{q=1}^{Q} p_{qt} y_{qt} = \sum_{t=1}^{T} \beta_t \sum_{q=1}^{Q} \bar{p}_{qt} y_{qt}. \quad (9)$$

This is the discounted value of the net outputs of all periods. Like the consumer, the firm must know all discounted prices and have the possibility of concluding forward contracts for all goods, or at least of lending and borrowing amounts of numéraire which it either needs or has to dispose of.

The vector \( y \) of the \( QT \) net productions \( y_{qt} \) must be technically feasible. We have represented this constraint in two ways, either

$$y \in Y \quad (10)$$

where \( Y \) is a set of \( QT \)-dimensional space, or

$$f(y_{11}, \ldots, y_{qt}, \ldots, y_{QT}) \leq 0, \quad (11)$$

where \( f \) denotes a real function defined on this space and assumed to be differentiable.

In neither of these two representations are operations internal to the firm described; all that matters is what the technical constraints imply for the set of inputs acquired by the firm and for the outputs that it produces for disposal to others. There is nothing new in this: we noted it when defining production functions. Here it implies in particular that there is no call for detailed representation of the use of capital installations. Acquisitions of such equipment are dealt with in the same way as any other input; they are deducted as a whole in the calculation of the \( y_{qt} \) corresponding to the date of acquisition.

However, in this respect the initial and terminal dates are particular cases. The physical capital existing in the economy at date 1 is often treated as a primary resource available at that date. The part of this capital that is used by the \( j \)th firm must therefore appear among its inputs at date 1. Conversely, the capital equipment of the \( j \)th firm at the terminal date \( T \) is often considered as output at this date.

It may also happen that the initial capital of the firm does not appear explicitly in the model but is taken account of in the definition of the production set \( Y \) or the production function \( f \). A vector \( y \) then belongs to \( Y \) if it represents the net productions of a programme that is technically feasible for the firm on the basis of its available capital.

A priori, (10) can accommodate itself to very diverse formulations of the technical constraints. So the following remark concerning the production function (11) does not apply to the general results established directly on the
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basis of (10). We have had occasion to point out that most of the properties discussed previously were generalised on the basis of models involving production sets $Y$ instead of production functions $f$. So the following remark should not be taken as critical of the theories discussed here, but rather of the presentation we are giving of them in these lectures.

The existence of a differentiable production function of the type (11) implies that, without changing any other net productions, the firm can substitute an infinitely small quantity $dy_{qt}$ of the net production of good $q$ at date $t$ for another quantity $dy_{r\theta}$ of the net production of any good $r$ at any date $\theta$, subject only to the condition that

$$- \frac{dy_{qt}}{dy_{r\theta}} = \frac{f'_{r\theta}(y)}{f'_{qt}(y)}.$$  \hspace{1cm} (12)

The marginal rates of substitution of type (12) are supposed to be defined for all pairs with double indices $(qt, r\theta)$ and with respect to all the vectors $y$ satisfying $f(y) = 0$ (except obviously in the cases where $f\theta_q(y) = 0$). A priori, it may seem highly unlikely that such vast possibilities of substitution should exist. However, let us accept this assumption for the moment. We shall return to it at the start of part B.

Just as we can define ‘subjective interest rates’ from the consumer’s marginal rates of substitution, so we can define technical interest rates from the producer’s marginal rates of substitution defined by (12). The own technical discount factor of good $r$ for date $\theta$ is the value of (12) when $q = r$ and $t = 1$. Technical interest rates can be deduced from technical discount factors by formulae similar to (2). Own technical interest rates can, a priori, be either positive or negative, as we shall see if we consider a simple particular case.

Suppose that there are two periods and a single good of which the firm possesses a certain quantity $A$ a priori. At the first date, the firm may release of this good a quantity $y_{11}$ that is subject only to the restriction that it must not be greater than $A$. At the second date it will possess and make available the quantity

$$y_{12} = (A - y_{11})(1 + \alpha),$$

where $\alpha$ is a fixed number. This representation is appropriate, for instance, if the firm stocks good 1, but the latter suffers some deterioration between dates 1 and 2, in which case $\alpha$ is negative and equal, apart from sign, to the proportion of deteriorated units. It is also appropriate if the firm is working a forest, when $\alpha$ is positive and equals the rate of growth of the standing timber (good 1) between the two dates.

In such a case, where the quantity $A$ is not introduced explicitly in net productions, the function $f$ is

$$f(y_{11}, y_{12}) = y_{12} - (1 + \alpha)(A - y_{11}).$$
consequently,
\[ f'_{11} = 1 + \alpha, \quad f'_{12} = 1, \]
these derivatives being well-defined to the extent that \( y_{11} \) and \( y_{12} \) are both positive.

The technical discount factor for good 1 is therefore
\[ \frac{f'_{12}}{f'_{11}} = \frac{1}{1 + \alpha}. \]

The technical interest rate, \( \alpha \), is negative in the first case where the firm stocks good 1, and positive in the second example of forestry.

4. A positive theory of interest

Economic science must investigate how the interest rates that actually apply in borrowing and lending operations between agents are determined and how the rates of return in productive operations that employ capital are established. The theory of general equilibrium in perfect competition provides an answer to these questions, an answer that may be deceptive because of its lack of realism, but that must be thoroughly understood before its relevance can be discussed.

According to the generalisation with which we are now concerned, a competitive economy functions through markets which exist for all pairs \((q, t)\). Thus for each good there are as many forward markets as there are dates. On the \((q, t)\) market are confronted all the supplies and demands implied for good \(q\) and date \(t\) by the present plans of the agents. This confrontation leads to the determination of a discounted price \(p_{qt}\) which, together with the other discounted prices determined simultaneously on the other markets, ensures the equality of total supply and total demand. In addition, it is assumed that, in such an institutional context, agents fix their plans taking discounted prices as given, that is, that they behave as briefly described in the two previous sections.

We can state directly a certain number of results applying to such an economy and following from the theory in Chapters 2, 3 and 5. We shall do so without on each occasion stating the conditions required for the validity of each property. This would be tedious, and reference can easily be made back to previous chapters for the relevant material.

(i) The consumer's equilibrium, that is, the consumption plan maximising his utility subject only to his budget constraint, is such that the marginal rates of substitution are equal to the ratios of the corresponding discounted prices. In particular, the subjective interest rates are equal to the corresponding market interest rates, which are defined on the basis of discounted prices, as we saw
earlier (Section 1). It is to the consumer's advantage to contract debts or make loans in such a way that this equality finally holds.

(ii) The equilibrium for the firm, that is, the net production plan maximising its total discounted profit (9) subject to its technical constraint, is such that the marginal rates of substitution (12) are equal respectively to the ratios of discounted prices $p_{qt}/p_{r}$. In particular, the technical interest rates are equal to market interest rates.

It follows that the 'marginal rate of profit' for the firm between dates $t$ and $t+1$ is equal to the market rate $\rho_{t}$. To define this 'rate of profit', let us consider a marginal investment implying inputs $\delta a_{qt}$ at date $t$ and giving outputs $\delta b_{q,t+1}$, which are all available at date $t+1$. Introducing the $Q$-vectors $\bar{p}_{t}, \bar{p}_{t+1}, \delta a_{t}$ and $\delta b_{t+1}$, we can define the marginal rate of profit as the net undiscounted revenue to the investment divided by the cost involved, namely

$$r_{t} = \frac{\bar{p}_{t+1}\delta b_{t+1} - \bar{p}_{t}\delta a_{t}}{\bar{p}_{t}\delta a_{t}}. \quad (13)$$

(We shall see later that such a definition may be open to criticism.) Given that we are concerned with an investment appearing as marginal vis-à-vis a criterion represented by discounted profit (9), we can write

$$-\beta_{t}\bar{p}_{t}\delta a_{t} + \beta_{t+1}\bar{p}_{t+1}\delta b_{t+1} = 0 \quad (14)$$

It then follows from (13), (14) and (2) that

$$r_{t} = \rho_{t}. \quad (15)$$

This expresses the fact that the firm will carry out a productive operation involving only the dates $t$ and $t+1$ precisely if the rate of profit from it is at least equal to $\rho_{t}$, otherwise it gains by lending the sum $\bar{p}_{t}\delta a_{t}$ that it is considering tying up in the investment.

(iii) A competitive equilibrium is defined by a set of discounted prices for all goods and all dates, by consumption plans and production plans that are equilibria for consumers and firms respectively and are also compatible with the equality of total demand and total supply for each good and each date. In a competitive equilibrium, the ratios between discounted prices are equal to the corresponding marginal rates of substitution both for each consumer and for each firm. In particular, for each good and each period, the own market interest rate is equal to the own subjective interest rate of all consumers and the own technical interest rate of all firms.

Let us examine briefly how a theory of interest can be derived from what has just been said. Even for an elementary period lasting between two successive instants $t$ and $t+1$, there are generally multiple interest rates $\rho_{qt}$. We must therefore state the choice of numéraire and assume $Q$ to be determined so that the rates $\rho_{t}$ can be considered truly representative of
interest rates: $\rho_t$ must have a central position in the set of $\rho_{qt}$ relating to the same date. It is equivalent to say that the evolutions of the undiscounted prices $\bar{p}_{qt}$ of goods other than $Q$ do not show a systematic trend, which would reveal the particular nature of $Q$. In fact, (5), (2) and (3) imply

$$\frac{\bar{p}_{q,t+1} - \bar{p}_{qt}}{\bar{p}_{qt}} = \frac{\rho_t - \rho_{qt}}{1 + \rho_{qt}}.$$  \hspace{1cm} (16)

If $\rho_{qt}$ is greater than $\rho_t$, this is because the undiscounted price of $q$ decreases between $t$ and $t + 1$. The choice of the numeraire would be inappropriate for $\rho_t$ to define the real interest rate if either most $\bar{p}_{qt}$ would be decreasing or most $\bar{p}_{qt}$ increasing.

What factors account for the more or less high levels of market interest rates? How does it come about that these rates are positive? Since interest rates are elements of a complete price-system, since the theory presently under discussion follows from a generalisation of the theory of value examined in Chapter 5, we know that the explanation lies in various factors simultaneously: consumers' needs and preferences, the composition of the vectors of primary resources (and therefore also the way in which each $\omega_{qt}$ develops), the characteristics of production techniques. In Section 2 we saw why an assumption of 'impatience' is often adopted for individual preferences, which implies positive interest rates. We saw that the nature of certain technical processes such as in the forestry example of Section 3, has the same effect. But, at our present level of generality it is difficult to go further than this. We shall return to the question in the second part of this chapter, when we shall find that it is very complex.

For the moment we shall note only that stockpiling of a seasonal perishable foodstuff is covered by the model (the example of Section 3 with $x < 0$). The own interest rate for the corresponding good $q$ is negative during every period $(t, t + 1)$ in which it is stocked, because of the nature of the technical process. If the interest rate $\rho_t$ is positive, as is usually the case, the undiscounted price of the foodstuff $q$ increases between $t$ and $t + 1$, in view of (16). However an equilibrium is realised when the good $q$ fulfils needs existing at the date $t + 1$ since, apart from stocks, the available quantities are assumed to decrease between $t$ and $t + 1$.

Can this theory, whose main elements have just been stated, help us to understand certain aspects of reality? Before answering this question, we must admit the very abstract character of the central part of the analytic apparatus: in no actual economy do there exist institutions which can be considered as making up a complete system of forward markets for all goods and all future dates, nor a fortiori for the relatively long periods involved in the installation and use of equipment.

To investigate the relevance of the theory, we must inquire into the actual
role of prices and interest rates in economic decisions. The explicit or implicit calculations by which the various agents reach their decisions do in fact involve prices and interest rates. Present prices, of date $t = 1$, can be observed more or less precisely; similarly, there exist interest rates relating to the borrowing and lending of money for varying periods. But future undiscounted prices must be predicted by each individual. In fact consumers and producers have available information other than that assumed by the theory; they have less direct information on prices, but on the other hand, they often have some knowledge of the conditions of later economic development, which allows them to assess the advisability and profitability of the operations on which they are engaged. Of course, the consistency of individual plans is not completely assured since there is no systematic confrontation of the demands and supplies which result, for the different goods and the various future dates, from decisions taken today. Nevertheless the system of present prices and interest rates contributes to the partial consistency realised by existing institutions.

Whatever the usefulness of the positive theory discussed in this chapter, we see also that the conceptual framework on which it is based is very well adapted to the examination of the normative problems raised by the organisation of economic activity over time. Before leaving the positive standpoint we have still to consider an approach and a formalisation which assume a system much less well-endowed with markets.

5. Temporary equilibrium

For the study of growth and general fluctuations of the economy, it is natural to think of economic development as proceeding step by step. Each period inherits human and material resources from the past; it is subject to particular constraints; the various agents’ activities depend on these and influence each other. Thus the various periods must be analysed in succession with reference to the past and to the future. So the study of economic development reduces to a series of such analyses which are carried out period by period.

This type of conceptual approach is aimed especially at phenomena other than the allocation of resources and the determination of relative prices. It is applied systematically in much of macroeconomic theory. However, it has naturally also been considered in microeconomic theory, the subject of this book. So it has served both to provide a basis for macroeconomic theory and to round off the theory of prices and the allocation of resources.

We shall make the same assumption as before, namely that prices adjust
so as to ensure that demand always equals supply.† But now they reach equality step by step, period by period in a rather 'short-sighted' way and no longer as in the previous section at one fell swoop for all future periods as well as for the present.

Here we shall consider formally the case of only two successive periods ($T = 2$). This is sufficient for clear definition and avoids the complicated notation required for the general case.

At date 1, that is, 'today', products are exchanged at prices $p_{q1}$. But at this date, there are no markets for the exchange of products which will be available only later at date 2 nor for the exchange of an immediate delivery against a guaranteed future delivery. So there are no forward markets. However an exception is made for one particular product, the numéraire $Q$, which can be borrowed and lent; the loan of one unit consists of the immediate delivery by the lender of the quantity 1 of $Q$ against the borrower's promise to repay the quantity $1 + \rho$ of $Q$ at date 2. Present prices $p_{q1}$ and the interest rate $\rho$ adjust so that the immediate supply of $q$ equals its immediate demand (for $q = 1, 2, \ldots, Q$) and so that the supply of and demand for loans are also equal. It is clearly much less unrealistic to assume the existence of such a market system than to assume the existence of a complete system of forward markets.

The agents' supplies and demands on markets at date 1 clearly depend on their plans for date 2. For example, the $i$th consumer's demand for product $q$ is the result of his intended immediate consumption (stockpiling is regarded as a production activity) but this intended consumption is in the context of a consumption plan covering both periods. To decide on their plans, agents must obviously forecast not only their needs and their particular working conditions, as we assumed previously, but also the market conditions on date 2. So these forecasts or expectations must be expressed explicitly in the theory.

So, let $p_{q2}^i$ be the (undiscounted) price which the $i$th consumer expects to hold at date 2 for the product $q$ and let $R_{i2}^1$ be his anticipated net income at date 2. He knows that, as a function of his consumption $x_{i,q1}$ and his income $R_{i1}$ at date 1, he will lend the following quantity of numéraire:

$$m_i = R_{i1} - \sum_{q=1}^{Q} p_{q1} x_{i,q1}.$$  \hspace{1cm} (17)

† Recent developments in microeconomic theory consider situations where prices are not flexible enough to ensure complete equalisation of demand and supply. But it would be too much of a digression to discuss this here and in particular to consider 'fixed price equilibria'. See, for example, Grandmont, 'Temporary General Equilibrium Theory', *Econometrica*, April 1977, or Chapter 1 of Malinvaud, *The Theory of Unemployment Reconsidered*, Basil Blackwell, Oxford, 1977.
So he anticipates that his consumption $x_{iq2}$ at date 2 must obey the constraint

$$\sum_{q=1}^{Q} p_{q}^{j} x_{iq2} = R_{2}^{j} + (1 + \rho)m_{i}. \quad (18)$$

The $i$th consumer fixes his behaviour in view of (17) and (18).

So the following operations can be considered to be involved in his decisions:

—observe current income $R_{1}$, current prices $p_{q1}$ and the interest rate $\rho$:
—forecast future income $R_{2}^{j}$ and future prices $p_{q2}^{j}$:
—then, taking the above elements as exogenous and in view of (17) and (18), choose present consumption $x_{iq1}$ and future consumption $x_{iq2}$ so as best to satisfy needs and preferences, together with the consequent amount $m_{i}$ of net lending:
—on current markets, express the demand and supply resulting from the $x_{iq1}$'s and from $m_{i}$.

The other consumers act in a similar way. Also, producers determine their production plans on the basis of current prices, the interest rate and anticipated future prices; from these they calculate their immediate supply and demand for the different products and their borrowing of numéraire.

A ‘temporary general equilibrium’ is therefore defined when values of current prices $p_{q1}$ and the interest rate $\rho$ are determined such that net total demand by all agents' is zero on all markets. There is no new problem in establishing the existence and possible uniqueness of such an equilibrium in view of the theory of Chapter 5 if all the agents' forecasts are taken as exogenous. We shall consider other possibilities later.

Obviously a temporary general equilibrium for period 1 does not ensure that the agent’s plans for period 2 are mutually consistent. The net total demand obtained by aggregating individual intentions for the second period will generally differ from zero although equilibrium in lending and borrowing operations in period 1 may have established an initial consistency.

So temporary equilibrium in period 2 generally requires some revision of previous intentions. A factual investigation appears more appropriate than a theoretical one to find out if major or minor revisions are required.

We can, of course, envisage the case where all the forecasts take the values which would be given by the intertemporal general equilibrium of the previous section; for example, all consumers may forecast the same price $p_{q2}^{j}$ for the product $q$ and this may coincide with the undiscounted price $p_{q2}$ in the intertemporal equilibrium. In such a case, the temporary equilibrium for period 1 conforms to the intertemporal equilibrium;
intentions and forecasts are confirmed in period 2. But this is obviously a very special case.

The formal model whose broad outlines have just been indicated can be made more realistic in terms of assumptions about forecasts.

In the first place, it must be recognised that in most cases, forecasts are uncertain. So $R_i^2$ and $p_{ql2}$ are no longer taken as given but as subject to probability distributions representing the $i$th agent's state of uncertainty. It follows that his intentions $x_{iq2}$ are also subject to error. Hence obviously behaviour in the face of uncertainty must be represented; but this raises no real problem for the theory of temporary equilibrium since we need only apply the type of representation to be discussed in the next chapter.

We must also take account of the fact that forecasts are not independent of economic development. In most cases, they follow from whatever observations the agents can make. In order to construct a theory of growth and business fluctuations through the determination of a sequence of temporary equilibria, forecasts must be taken as endogenous and it must be recognised that they depend at any particular moment on previous development.

It is also conceivable that this process of endogenisation must take place within each temporary equilibrium. For example, $p_{ql2}$ may depend on the price $p_{q1}$ which the $i$th individual observes for the product $q$ in period 1, for which he decides on his supply and demand; in temporary equilibrium theory $p_{ql2}$ must then no longer be treated as exogenous, but an (exogenous) function must be introduced which expresses the dependence of this anticipated price on the observed price $p_{q1}$. The introduction of such functions to represent the way in which forecasts are made raises no problem of principle but complicates the formal specification of temporary equilibrium. Moreover it is clear that the existence and properties of such an equilibrium may be affected by the kind of functions chosen, which introduce an additional interdependence among the quantities to be determined. This is also why general theories of temporary equilibrium make assumptions about such functions. This does not concern us here, since we shall not study this theory more closely.

6. Optimum programmes and the discounting of values

For the choice of public investments it has been suggested that the economist's aim should be to determine the discounted net value returned by each project and each of its variants (or, the 'discounted net revenue'). Such a rule receives some justification from optimum theory applied to an intertemporal economy.

As we saw earlier, a programme is a set of consumption plans and produc-
tion plans, one for each agent. A programme is 'feasible' if each agent's plan is physically possible for him and if, in addition, for each good and each date, global supply is equal to global demand.

A programme is called a 'production optimum' if it is feasible and if there exists no other feasible programme giving at least as large a global net production $\sum_j y_{jqt}$ for all the pairs $(q, t)$ and larger for at least one of them. Similarly, a programme is a 'Pareto optimum' if it is feasible, and if there exists no feasible programme which is considered at least equivalent by all consumers and preferable by one.

We saw in Chapter 4 that, with respect to an optimal programme, the marginal rate of substitution between two commodities $(q, i)$ and $(r, \tau)$ is the same for all interested agents: all producers in the case of a production optimum, all producers and all consumers in the case of a Pareto optimum. It follows that, for a given good and period, the producers all have the same technical interest rate $\rho_{qt}$ and, where a Pareto optimum is concerned, $\rho_{qt}$ is also the subjective interest rate for all consumers.

Under the usual convexity assumptions, we can associate with an optimal programme a price-system with precisely the characteristics discussed in Section 1 of this chapter. If a numéraire is chosen, this system can be expressed by undiscounted prices $\bar{p}_{qt}$ for each good and each date, together with interest rates $p_t$. The latter are often rather called 'discount rates' in the present context, so as not to prejudice the possible equality of the numbers $\rho_t$ thus defined with the interest rates actually applying in borrowing and lending operations.

An optimal programme is 'sustained' by the corresponding price-system when the agents involved use this system and make their economic calculations according to the rules discussed in Sections 2 and 3. In particular, each producer $j$ must maximise the discounted value of his net productions, which can be calculated according to formula (9), namely

$$\sum_{t=1}^{T} \beta_t \sum_{q=1}^{Q} \bar{p}_{qt} y_{jqt}$$

(19)

where the $\beta_t$ are 'discount factors'.

Suppose then that, relative to a programme $P^0$ containing for him the net productions $y^0_{jqt}$, the public producer $j$ is considering an investment project which is not included in $P^0$, or a variant of an included project. Let $\partial y_{jqt}$ be the net productions attributable to the project, or the changes in net productions if the variant is adopted instead of the project occurring in $P^0$. (We recall that the acquisition of capital equipment is accounted for among inputs and therefore appears as negative net production.) The producer $j$ must verify that he has no grounds for carrying out the project in the first case, or for choosing the variant in the second. Maximisation of (19) implies the
inequality
\[ \sum_{t=1}^{T} \beta_t \sum_{q=1}^{Q} \bar{p}_{qt} \bar{y}_{jqt} \leq 0 \] (20)

This is the discounted return from the project, or the difference between the discounted returns from the two variants, which must provide the criterion of choice.

Without going into more detail, we can also think of public decisions as resulting from a planning procedure similar to those discussed in Chapter 8. The prospective indices are undiscounted prices and discount rates; at each stage, the public firms fix their plans, choosing a set of projects that maximises the present value (19) calculated on the basis of previously announced discount rates. This ideal context in fact offers some justification for the rule usually put forward.

However, we must add two remarks here to those that are generally provoked in another way by the theories of Chapters 4 and 8. In the first place, this justification is valid only if all producers, private as well as public, reach their decisions after similar calculations and on the basis of the same prices and discount rates. It no longer applies rigorously if, for example, the private sector of the economy adopts different rules of choice. (Also, it is very difficult to determine exactly the best rules to be adopted then in the public sector for decentralised economic decisions.)

In the second place, knowledge of undiscounted prices \( \bar{p}_{qt} \) for future dates is as important \textit{a priori} as knowledge of discount rates. However the situation could conceivably arise where future prices \( \bar{p}_{qt} \) are, for most goods \( q \), equal to the corresponding present prices \( \bar{p}_{q1} \). Given present prices and discount rates, fairly little additional information would then need to be obtained.

7. Optimality in Allais' sense†

In actual societies it seems to be common that social choices deviate from consumer preferences in the assessment of the relative importance of future needs with respect to present needs. It is frequently held that individual choices contain too marked a preference for present consumption, and that it is necessary to bring about a larger volume of savings than appears spontaneously. Public saving and legal arrangements such as compulsory pension schemes allow this objective to be realised.

The situation is represented in Figure 2, which applies to the case of only one good, two periods, one consumer and one firm. (The construction is similar to that in Figure 9 of Chapter 9). While production possibilities are not

† See Allais, \textit{Economie et Intérêt}, Paris, Imprimerie Nationale, 1947, particularly Chapter VI and Appendix III.
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systematically more favourable for the first period than for the second, the consumer, who, by hypothesis, has a strong preference for the present, chooses a plan $M$ that sacrifices his future consumption. If this is the situation, then it is often held that, in the choice between the present and the future, the consumer must have imposed on him a plan other than that which he chooses spontaneously.

It was in order to generalise optimum theory to such a collective attitude that M. Allais put forward the concept of 'rendement social généralisé'. His idea is to define and investigate a notion of optimum in which individual preferences are retained for the choice between consumptions relating to the same date, but not necessarily between those relating to different dates. For simplicity, the theory will be given here for only two dates ($T = 2$); it can easily be generalised to any number of dates.

Let $x_{it}$ be the consumption of the good $q$ by the consumer $i$ at date $t$ (where $t = 1, 2$). Let $x_{i1}$ and $x_{i2}$ be the vectors with $Q$ components representing the consumptions of the different goods by the consumer $i$ at dates 1 and 2 respectively. At date 1, his utility function $S_t$ depends on the values of the two vectors $x_{i1}$ and $x_{i2}$ (this function represents a preorder on complete consumption plans); we can write it $S_t(x_{i1}; x_{i2})$.

Now we must also introduce a utility function at date 2, that is, a function $S_{i2}(x_{i2})$ representing the $i$th consumer's preferences at date 2 between the different vectors $x_{i2}$. Obviously this function is not independent of $S_t$; if it were, there would be little reason to refer to individual preferences for choices internal to future periods. Moreover, for Allais' theory, the definition of $S_{i2}$ must be independent of the vector $x_{i1}$. We therefore adopt the
following assumption†:

ASSUMPTION 1. There exists a function $S_{i2}$ of the vector $x_{i2}$ such that the function $S_i$ can be written in the form $S_i^*(x_{i1}; S_{i2})$, where $S_i^*$ increases with $S_{i2}$. The function $S_{i2}(x_{i2})$ represents the $i$th consumer's choices at date 2.

On reflection, we see that this assumption implies a certain independence of choices at different dates. If a change in prices at date 1 brings about a change in $x_{i1}$, this should not change $i$'s preferences among the different vectors $x_{i2}$.

We can now define optimal programmes in Allais' sense. To do this, we must refer to a partial preordering of programmes, a preordering that respects individual preferences at each of the two dates, but is not necessarily conclusive for choices between these dates. Hence the following definition:

DEFINITION 1. A programme $P^0$ is said to be an 'Allais optimum' if it is feasible and if there exists no feasible programme $P$ such that

$$S_i(x_{i1}; x_{i2}) \geq S_i(x_{i1}^0; x_{i2}^0) \quad \text{for} \quad i = 1, 2, \ldots, m \quad (21)$$

$$S_{i2}(x_{i2}) \geq S_{i2}(x_{i2}^0) \quad \text{for} \quad i = 1, 2, \ldots, m, \quad (22)$$

where at least one of all these $2m$ inequalities holds strictly.

In short, $P^0$ cannot be changed so as to increase one consumer's utility at date 1 without decreasing another consumer's utility at date 1 or at date 2, or the first consumer's utility at date 2.

Consider a programme $P$ which is optimal in the Pareto sense. There exists no feasible programme $P$ satisfying (21) and consequently no such programme satisfying both (21) and (22). A Pareto optimum is therefore an Allais optimum. But clearly, the converse is not true. Thus, in the example of Figure 2, $M$ is the only point representing a Pareto optimum while all the programmes on the boundary $\Gamma + \omega$ to the left of $M$ are also Allais optima since movement along the boundary from the vertical axis up to $M$ implies an increase in $S(x_{i1}; x_{i2})$ but a decrease in $S_2(x_{i2})$.

What are the properties of an Allais optimum?

To answer this question, we can use the constrained maximisation techniques widely used in Chapter 4. But we can also adopt direct reasoning.

Let $S_{i2}(x_{i2}^0) = S_{i2}^0$. If $P^0$ is an Allais optimum, then there exists no feasible programme $P$ such that

$$S_i^*(x_{i1}; S_{i2}^0) \geq S_i^*(x_{i1}; S_{i2}^0) \quad \text{for} \quad i = 1, 2, \ldots, m \quad (23)$$

$$S_{i2}(x_{i2}) \geq S_{i2}(x_{i2}^0) \quad \text{for} \quad i = 1, 2, \ldots, m \quad (22)$$

where at least one inequality holds strictly. For, if such a programme exists,
we can write, in view of (23) and the fact that $S_1^*$ increases with $S_{i2}$:

$$S_i(x_{i1}, x_{i2}) = S_i^*(x_{i1}; S_{i2}) \geq S_i^*(x_{i1}; S_{0i2}) \geq S_i^*(x_{0i1}; S_{0i2}) = S_i(x_{0i1}; x_{0i2}) \quad (24)$$

Since (22) and (24) are identical to (21) and (22), the existence of a feasible programme satisfying (22) and (23) contradicts the assumption that $P^0$ is an Allais optimum.

We see now that $P^0$ can be formally considered as a Pareto optimum in the following fictitious economy: it is identical to the economy under consideration in respect of firms and primary resources, but contains $2m$ consumers; the first $m$ consumers have consumption vectors $x_{i1}$ and utility functions $S_i^*(x_{i1}; S_{0i2})$ considered as functions only of the vector $x_{i1}$; the last $m$ consumers have consumption vectors $x_{i2}$ and utility functions $S_i^*(x_{i2})$. Therefore each consumer of this imaginary economy lives in one and only one period. The fact that no feasible programme $P$ satisfies (22) and (23) shows that $P^0$ is a Pareto optimum for the fictitious economy.

We can therefore apply the usual optimum theory and state the marginal equalities to be satisfied.† Thus we have directly, both for time $t = 1$, where $S'_{i1}$ is equal to $\frac{\partial S_i}{\partial x_{i1}}$, and for time $t = 2$,

$$\frac{S'_i}{S'_{i1}} = \frac{S'_{i2}}{f'_{i2}} = \frac{f'_{i1}}{f'_{i2}} \quad (25)$$

for all $i, \alpha = 1, 2, \ldots, m; j = 1, 2, \ldots, n; q, r = 1, 2, \ldots, Q$.

We can also write

$$\frac{f'_{i1}}{f'_{i2}} = \frac{f'_{q1}}{f'_{q2}} \quad (26)$$

for all $j, \beta = 1, 2, \ldots, n; q = 1, 2, \ldots, Q$; technical interest rates must be the same for all firms.

On the other hand, for the real economy we can no longer equate subjective and technical interest rates, nor can we equate the subjective interest rates of the different consumers. For, in the above fictitious economy, each consumer acts in one period only; his marginal rates of substitution are defined only for pairs of commodities relating to a single period.

Under the usual convexity assumptions, every Allais optimum appears as a market equilibrium for this fictitious economy. With respect to the initial economy, this state is also a market equilibrium for firms since all the necessary marginal equalities are satisfied. In this equilibrium, firms are in particular assumed free to conclude forward contracts at fixed interest rates.

† The part played by assumption 1 becomes clear here. If it is not satisfied, the consumer's choices at time 1 depend not only on the level of utility at time 2 but also on the chosen vector $x_{i2}$. In the fictitious economy, an 'external effect' then appears between the two imaginary consumers corresponding to $i$. 

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Each consumer can freely acquire his consumptions at market prices, but his
net expenditures in each period are not necessarily equal to what he would
choose if free to borrow and lend as he pleases on the markets.

To establish this, we need only apply proposition 5 of Chapter 4 to the
fictitious economy. Associated with $P^0$, there exist discounted prices $p_{qt}$ (for
all goods and both dates) and incomes $R_{it} = \sum_q p_{qt}x^0_{qt}$ such that, in
particular,†

(i) the vector $x^0_t$ maximises $S^*_t(x^0_t; S^0_{t2})$, and therefore also $S_t(x^0_t; x^0_{t2})$
subject to the constraint $\sum_q p_{qt}x_{iq1} \leq R_{i1}$, for $i = 1, 2, \ldots, m$;

(i') the vector $x^0_{t2}$ maximises $S_{t2}(x^0_{t2})$ subject to the constraint
$$\sum_q p_{qt}x_{iq2} \leq R_{i2} \quad \text{for} \quad i = 1, 2, \ldots, m.$$  

This theory can clearly be generalised to any number $T$ of dates. A slightly
more complex assumption than assumption 1 must imply some independence
of the preference systems relating to each period. A fictitious economy can be
defined where $i$ is split up into $T$ distinct consumers. With an Allais optimum
we can associate a system of discounted prices and a market equilibrium
whose only special feature is that consumers have given `incomes' for each
period and can neither lend nor borrow.

The fact that they disregard the possibility of consumer saving makes the
new equilibria introduced by M. Allais' theory appear somewhat unrealistic.
However, their discussion can usefully round off the knowledge acquired
from the study of classical market equilibria.

(B) PRODUCTION SPECIFIC TO EACH PERIOD

Until relatively recently, the theory of capital and interest has been based
on the study of stationary régimes in which each period repeats the previous
one. Still today, the real nature of some problems can be more easily under-
stood if they are examined in a stationary context.

To investigate such régimes, we must introduce a new representation of
technical constraints, which will also be useful for less simple models of
development and which does not contradict the representation used so far.
Its particular feature is that it applies directly to the production operations
relating to an elementary period and is thus more analytic than the production
function (11).

† $(i)$ can be interpreted in two ways. On the one hand we can assume that, given prices
$p_{q2}$ and his income $R_{i2}$ at date 2, the $i$th consumer chooses first $x^0_{i2}$, then the complex $x^0_t$,
that is best for him at date 1. On the other hand, we can consider that, at date 1, the con-
sumer does not know income $R_{i2}$ and prices $p_{q2}$, but that his choices at date 1 are not
affected by $S^0_{t2}$. This second interpretation therefore assumes that assumption 1 is
strengthened.
The questions to be tackled in this second part of the chapter are almost uniquely concerned with the organisation of production in its relationships with prices, interest rates and incomes. Consumers will only occasionally be considered explicitly.

1. The analysis of production by periods

Let us consider one particular firm, omitting the index \( j \) for the moment. Up till now, we have discussed its operations over all \( T \) dates \( t = 1, 2, \ldots, T \), using only the net productions \( y_{qt} \) made available for use by other agents. Let us now try to represent its operations between two successive dates \( t \) and \( t + 1 \), this time-interval being called the ‘period \( t \)’.

At date \( t \), the firm puts into operation inputs \( a_{qt} \) of the various products or services; as a result of its activity, it obtains outputs \( b_{q,t+1} \), which are available at date \( t + 1 \). Since as economists we need not know the mechanism by which inputs are transformed into outputs, we can describe production during period \( t \) by the pair of vectors \( (a_t; b_{t+1}) \).

For this representation to be meaningful, the \( a_{qt} \) must describe all the inputs including inputs of new and old capital equipment available to the firm in period \( t \) and possibly also including articles in course of manufacture at date \( t \). Of course, a new piece of equipment and an existing piece of the same kind must be considered as two different goods; the same is true of an article in course of manufacture and the corresponding finished article. This is not a very serious constraint, since there is no restriction on the number \( Q \) of goods. However, for equilibrium it implies that there are well-defined prices for existing equipment and for products in course of manufacture.

In short, the vector \( a_t \) represents the set of products and services immobilised for production in period \( t \). We shall call it the firm’s capital at date \( t \), without disguising the fact that such a definition, like that used in the nineteenth century, in particular by Karl Marx, is wider than that commonly accepted. As thus conceived, capital is a stock of goods. Its value, which will be discussed in Section 3, is also called ‘capital’. The particular interpretation will be clear from the context. Capital thus includes quantities of labour, (Marx’s ‘variable capital’), current inputs of raw materials, power, etc. as well as durable equipment. It is therefore both ‘circulating capital’ and ‘fixed capital’.

The vector \( b_{t+1} \) likewise represents not only the firm’s outputs properly so called, but also all its equipment in whatever state it may be at the end of period \( t \), and also articles in course of manufacture at date \( t + 1 \).

How does this new representation of the firm’s operations relate to that given in part A of this chapter? This can be simply illustrated (see Figure 3). Net production \( y_{qt} \) of good \( q \) at date \( t \) is obviously the quantity of \( q \) made
available by the firm, that is, the excess of output in period \( t - 1 \) over input in period \( t \):

\[ y_{qt} = b_{qt} - a_{qt}. \]  

(27)

We again let \( y_t \) denote the vector of the \( y_{qt} \) at date \( t \).

The equipment remaining in use in the firm during periods \( t - 1 \) and \( t \) appears both in \( b_{qt} \) and \( a_{qt} \); therefore it is not included in \( y_{qt} \). However, for (27) to apply to the initial and terminal dates, we set

\[ b_{q1} = 0; \quad a_{qT} = 0. \]  

(28)

This convention also agrees with our discussion at the beginning of this chapter since equipment existing at date 1 is in most cases counted negatively in the \( y_{q1} \) and equipment surviving at date \( T \) is counted positively in the \( y_{qT} \).

With this new formulation, it is natural to represent the technical constraints which limit production during period \( t \) by

\[ g_t(a_t; b_{t+1}) \leq 0, \]  

(29)

where \( g_t \) is a real-valued function with \( 2Q \) arguments, called the ‘production function for period \( t \).

At the beginning of Chapter 3 we made a careful examination of the meaning of production functions and the exact bearing of assumptions made about them. What was said then applies rigidly to the \( g_t \), and there is no point in repeating that discussion.

2. Intertemporal efficiency

From the production functions (29) relating to each of the \( T - 1 \) elementary periods we can obviously deduce a production function of the type (11) referring directly to the \( y_{qt} \) and relating to all \( T - 1 \) periods. We need only take account of the fact that the firm will naturally choose for each period input and output combinations in such a way that they lead to ‘technically efficient’ net productions in the sense of Chapter 3. Without reference to the
price-system or to the market structure, the firm must already impose certain conditions of \textit{intertemporal efficiency} on the sequence of pairs \((a_t; b_{t+1})\).

To make these conditions clear in general, we can assume that all the \(y_{qt}\) except one are given, say \(y_{QT}\) is not given, and assume that production in the period from 1 to \(T\) is organised so that \(y_{QT}\) is maximised. The constraints are then equations (27), (28) and (29) written for all suitable periods and dates. The maximisation conditions express the requirements of intertemporal efficiency. Moreover, the problem as thus stated has generally a solution, which varies with the \(y_{qt}\) that are assumed as given. The equation \(f(y) = 0\), satisfied by the vector of the \(y_{qt}\) when \(y_{QT}\) is determined in this way, is, by definition, the production function for the whole period from 1 to \(T\).

It will certainly be instructive to examine this question in detail in a simple case. Consider the case where \(Q = 2\) and \(T = 3\). Let quantities of each of the two goods be represented on a Cartesian graph. Let a point \(A_1\) represent a vector \(a_1^0\) of inputs at date 1, these inputs being considered as fixed. Then let \(\Gamma_2\) be the locus of the extremities of the vectors \(a_2\) that are feasible on the basis of \(a_1^0\) when net production at date 2 is restricted to a fixed vector \(y_2^0\). The vectors \(a_2\) of \(\Gamma_2\) are restricted to satisfy
\[
g_1(a_1^0; y_2^0 + a_2) = 0.
\] (30)

Similarly, from a point \(A_2\) on \(\Gamma_2\) we can draw the curve \(C_3\) of the extremities of the vectors \(b_3\) which can be established from \(a_2\), that is, which satisfy
\[
g_2(a_2; b_3) = 0.
\]

When \(A_2\) moves along \(\Gamma_2\), the curve \(C_3\) is also displaced. Let \(\Gamma_3\) be the envelope of \(C_3\) in this displacement. Starting from \(a_1^0 = - y_1^0\) and having to provide \(y_2^0\), the firm may realise any vector \(y_3 = b_3\) whose extremity belongs...
to $\Gamma_3$, but no vector whose extremity lies beyond it. Therefore $\Gamma_3$ is the locus of the $y_3^0$ of the technically efficient vectors. Its equation can be written in the form:

$$f(y_1^0, y_1^1, y_2^0, y_2^1, y_3^0, y_3^1, y_3^2) = 0,$$

in which there appear explicitly the quantities $y_1^0, y_1^1, y_2^1, y_2^2$ on which the position of $\Gamma_3$ depends. Considered as a function of its six arguments, $f$ is therefore the production function for the whole period from 1 to 3.

From a point $B_3$ on $\Gamma_3$ corresponding to a vector $b_3^0$ satisfying (31), we can also construct the curve $C_2'$, the locus of the extremities of the vectors $a_2$ which allow $B_3$ to be achieved, that is, of the vectors $a_2$ such that

$$g_2(a_2; b_3^0) = 0.$$ (32)

Clearly $C_2'$ and $\Gamma_2$, which both contain $a_2^0$, are tangents, otherwise $B_3$ could be reached from a point on the left of $\Gamma_2$, and could be exceeded from a properly chosen point on $\Gamma_2$, at least if $g_2$ is increasing in $b_3$ and decreasing in $a_2$, a property that can be assumed.

It is convenient to introduce the following notation for the partial derivatives of $g_t$, which is assumed differentiable:

$$g_{rt} = \frac{\partial g_t}{\partial a_r} \quad g_{rt+1} = \frac{\partial g_t}{\partial b_{r,t+1}}.$$ (33)

The fact that $C_2'$ and $\Gamma_2$ are tangents can then be expressed as:

$$\frac{g_{12}}{g_{22}} = \frac{g_{12}}{g_{22}},$$ (34)

the derivatives being evaluated for the values $a_1^0, b_2^0, a_2^0$ and $b_3$ of the vectors that are their arguments. Thus, the marginal rate of substitution between the two goods at date 2 is the same whether it is calculated from the production function relating to period 1, the goods appearing as outputs, or from the production function relating to period 2, the goods appearing as inputs.

This last result characterises an organisation of production that is efficient relative to the whole period from 1 to 3. It can obviously be generalised to any number of periods and products.

In fact, the conditions of intertemporal efficiency are

$$\frac{g_{rt}}{g_{rt}} = \frac{g_{rt}}{g_{rt}}, \quad q, r = 1, 2, \ldots, Q$$ (35)

as can be seen from the general solution to the maximisation problem defined at the start of this section.

It is obviously not necessary to assume the existence of differentiable functions $g_t$ in order to establish a correspondence between the technical constraints expressed for the pairs $(a_t; b_{t+1})$ and a similar constraint ex-
pressed for the vector $y$ with the $QT$ components $y_{qt}$. For, let $P_t$ be in $2Q$-dimensional space the set containing the pairs $(a_t; b_{t+1})$ that are technically feasible during period $t$. The vector $y$ is technically feasible if and only if there exist $T - 1$ vectors $a_t$ (for $t = 1, 2, ..., T - 1$) and $T - 1$ vectors $b_t$ (for $t = 2, 3, ..., T$) such that:

$$
\begin{align*}
(a_t; b_{t+1}) & \in P_t, \quad t = 1, 2, ..., T - 1; \\
-a_{q1} & = y_{q1} \\
b_{qT} & = y_{qT} \\
b_{qt} - a_{qt} & = y_{qt} 
\end{align*}
$$

for $q = 1, 2, ..., Q$; for $t = 2, 3, ..., T - 1$.

This condition then defines the set $Y$ of feasible vectors $y$. It is easily verified that, in particular, the convexity of $Y$ follows from the convexity of the $P_t$.

Using the general properties of maximisation, for example the Kuhn-Tucker theorem, we can establish the conditions of intertemporal efficiency by demanding that the sequence of the $(a_t; b_{t+1})$ leads to a technically efficient vector $y$. This generalises relations (35).

3. Interest and profit

We now return to the price-system, with which the first section of this chapter was concerned, and examine its implications for the operations in one period in more detail. This leads us to the investigation of the distribution of the incomes created in each period.

Incomes originate in production, and we must therefore first consider how the calculation of values is affected when productive operations are analysed for a single period. Only thereafter can we establish consistent definitions for the different types of income.

In Section A.3, equilibrium for the firm was described as resulting from the maximisation of discounted total profit (9). The expression for the latter is now:

$$
\sum_{t=1}^{T} p_t y_t = \sum_{t=1}^{T} (p_t b_t - p_t a_t).
$$

In view of (28), it can also be written:

$$
\sum_{t=1}^{T-1} (p_{t+1} b_{t+1} - p_t a_t) = \sum_{t=1}^{T-1} \pi_t
$$

with, by definition,

$$
\pi_t = p_{t+1} b_{t+1} - p_t a_t.
$$

The quantity $\pi_t$ is basically the profit, discounted at date 1, from the
production realised during period $t$. We can also define the undiscounted profit available at the end of the period, that is, at date $t + 1$:

$$\pi_t = \frac{\pi_t}{\beta_{t+1}} = \bar{p}_{t+1}b_{t+1} - (1 + \rho_t)\bar{p}_t a_t,$$

(38)

the last equality following from (5) and the definition of the interest rate $\rho_t$.

Thus we see that, by applying the general rules for finding discounted values, the profit $\pi_t$ resulting from production during period $t$ must be computed as the difference between the undiscounted value of outputs and a cost comprising both the value of inputs and an interest charge applied to all inputs. This definition applies at the level of the firm in isolation as well as at the level of the whole community.

If we wish to define a 'value added' equal to the sum of incomes created by production, we must distinguish two categories of inputs: inputs of labour and 'material inputs'. The vector $a_t$ is then written as the sum of two vectors, $l_t$ which has zero components for all goods other than the various services provided by labour, and $m_t$ which on the other hand has zero components for these services. The value $R_t$ added by production in period $t$ is defined as the difference between the value $\bar{p}_{t+1}b_{t+1}$ of outputs and the values $\bar{p}_t m_t$ of 'material inputs';

$$R_t = \bar{p}_{t+1}b_{t+1} - \bar{p}_t m_t.$$  

(39)

In view of (38), and since $a_t = l_t + m_t$, we can also write

$$R_t = \bar{p}_t l_t + \rho_t \bar{p}_t a_t + \pi_t.$$  

(40)

According to (40), the 'value added' or 'global income' is equal to the sum of three terms:

- the return to labour $\bar{p}_t l_t$,
- interest on capital $\rho_t \bar{p}_t a_t$,
- profits $\pi_t$.

There are certain remarks to be made about this decomposition of global income.†

In the first place, it applies not only to the economic calculus concerning the programmes of a society where markets for future commodities exist but obviously also to operations taking place currently. It does not assume a competitive system underlying the determination of prices and interest.

† We must also note that, for a given programme and a given system of discounted prices, the definition of value added varies with the choice of numéraire for each date. If $\bar{p}_t$ remains fixed, and $\bar{p}_{t+1}$ is multiplied by a number $\phi$, the 'income' $R_t$ increases by $(\phi - 1)\bar{p}_{t+1}b_{t+1}$, profit $\pi_t$ is multiplied by $\phi$ and interest increases by $(\phi - 1)(1 + \rho_t)\bar{p}_t a_t$, the rate of interest varying by $(\phi - 1)(1 + \rho_t)$. The numéraire should therefore be chosen so that the income has satisfactory practical significance.
It allows in fact a particular *theory of distribution* to be derived from each price theory.

In the second place, the term 'profit' is the source of some ambiguity in economic literature as in everyday language. Here we obtained the definition of profit $\bar{\pi}_t$ for period $t$ by the natural generalisation of a concept first defined for an economy that did not explicitly involve time. It is therefore 'pure profit', which appears as residual when the whole interest charge on the capital engaged has been deducted. The term 'profits' is often given to all incomes other than incomes from labour, or 'unearned incomes' as they are sometimes called, that is, the sum $\rho_t \bar{p}_i a_i + \bar{\pi}_t$. It is therefore necessary to check the definition used by the author of any theoretical or applied work using the term profit.

In scientific literature the most common reference is to pure profit $\bar{\pi}_t$; but a *rate of profit* is sometimes also discussed, this being defined as the ratio between the sum of unearned incomes and the value of the capital employed, i.e. in the present case:

$$\frac{\rho_t \bar{p}_i a_i + \bar{\pi}_t}{\bar{p}_i a_i}.$$  \(41\)

We shall not attempt to avoid this ambiguity and shall occasionally talk of (41) as the average rate of profit and call

$$r_t = \frac{\rho_t \bar{p}_i da_i + d\bar{\pi}_t}{\bar{p}_i da_i}$$  \(42\)

the *marginal rate of profit*, where $da_i$ is a small variation in the input vector and $d\bar{\pi}_t$ the resulting variation in pure profit. This expression has already been used in Section A.4 in the discussion of competitive equilibrium when we stated that the marginal rate of profit was equal to the rate of interest (see (13) and (15)). In the following section we shall see that, in competitive equilibrium, the pure profit $\bar{\pi}_t$ for each period is maximised, so that $d\bar{\pi}_t = 0$ and we again have $r_t = \rho_t$.

In the third place, the decomposition of $R_t$ according to (40) corresponds to an analysis of the source of incomes; it does not generally correspond to the distribution of income among different agents or *a fortiori* among different social categories. Not only does it ignore all transfers, particularly those due to the fiscal system, which is quite natural since collective services are not taken into account here, but it can be accommodated to very varied distribution systems according to the assumptions made about property rights and the conventions governing payments.

For their distribution theories the major economists often started from different assumptions about the social structure. Thus, at the beginning
of the nineteenth century,† Ricardo distinguishes three classes: workers, who sell their labour, landlords who rent their land, and finally farmers and capitalist entrepreneurs who organise production and put up capital other than land. So to proceed from (40) to the distribution of income, the input vector $a_t$ must be split into two: a vector $f_t$ corresponding to land and a vector $g_t$ corresponding to other inputs. The return to labour, assumed to be received at date $t$, is then $p_t l_t$, the return to landlords, received at $t + 1$ and called ‘rent’, is $p_t p_t l_t g_t$ and the return to capitalists is $p_t p_t a_t + n_t$. Marx‡ distinguishes only two classes: workers, who receive $p_t l_t$ and capitalists, who organise production and put up the total capital required, and receive $p_t p_t a_t + n_t$. The classical writers at the beginning of the century§ follow (40) more strictly by identifying not only workers and capitalists, who lend capital, but also ‘entrepreneurs’ whose only function is to organise production without contributing either labour or capital. These three categories then receive the incomes $p_t l_t$, $p_t p_t a_t$ and $n_t$ respectively.

We should also pay attention to dates. For example, in the last case it is assumed that, at date $t$, capitalists make the value of inputs $p_t a_t$ available to entrepreneurs. The latter immediately acquire and pay for these inputs, in particular for inputs of labour $l_t$. At date $t + 1$, entrepreneurs sell all their outputs $p_t f_{t+1} l_{t+1}$ and repay capital $p_t a_t$ and interest $p_t p_t a_t$ to capitalists; so they have left a profit $n_t$. (This description assumes that operations in period $t$ are considered independently of those in other periods, a point which will not be emphasised here since we return to it in the next section.) But other assumptions can be made as to dates. For example, if the elementary period is considered to be of short duration, we can assume that the workers receive only at date $t + 1$ the return for their efforts during period $t$. Then the entrepreneur borrows no more than $p_t m_t$, the capitalists’ income becomes $p_t p_t m_t$ and the workers’ income $(1 + p_t) p_t l_t$.

In the next section we shall see that, if the production function for period $t$ has constant returns to scale, pure profit $n_t$ is zero in competitive equilibrium. Decreasing returns to scale leads to a positive profit $n_t$; but it could only be due to the existence of scarce resources available in limited quantities in the productive sphere and not taken explicitly into account in the definition of inputs (site, particular skills of the managing director, etc.). The return $n_t$ is then in reality the result not of an organising activity but of the employment of the resources in question.

§ See, for example, Knight, *Risk, Uncertainty and Profit*, Boston 1921.
In such cases, the classical writers of the beginning of the century held rightly that clarity was gained by treating this revenue as due to the owners of resources rather than to ‘entrepreneurs’. It was not really a case of profit, but of ‘rent’, comparable to that which Ricardo identified as due to landlords. In competitive equilibrium, every scarce resource of this type must have a value, which conforms to the rent that it brings in. If \( v_t \) is its value at date \( t \), then to let it must bring in a return \( p_t v_t \), which must be equal to the rent. The latter can therefore be considered as interest.†

Therefore if all scarce resources are clearly identified among inputs, interest includes all rent, returns to scale are constant and pure profit becomes zero in competitive equilibrium.

Is this not paradoxical? Why should an entrepreneur bother organising production if his income must be zero? This question obviously preoccupied economic theorists. Schumpeter gave a persuasive answer.‡ If the entrepreneur obtains a profit, this is because the economy is never perfectly competitive nor in perfect equilibrium.§ Positive pure profit exists either because of monopoly positions, or of temporary deviations of actual prices from equilibrium prices. More precisely, the entrepreneur keeps looking for ‘innovations’, that is, for profit possibilities not yet exploited. By discovering such possibilities and putting them into operation, he makes a temporary monopoly for himself and realises a disequilibrium profit (an ‘extra surplus-value’ according to Marx) so long as competition from other entrepreneurs does not appear; the size and duration of these profits varies according to the difficulty of the productive and commercial processes which the innovation involves and according to the degree of rigidity in the economy’s institutional structure.

Competitive equilibrium analysis is therefore inadequate to explain the importance of pure profit. On the other hand, it should be informative about the factors that may take part in the division of value between return to labour and interest on capital. We shall discuss this question in Section B.8.

4. Short-sighted decisions and transferability of capital

Let us now return to the decisions of firms in a competitive market. The firm tries to maximise its discounted total profit subject to the technical

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† Failure to account for such scarce resources brings in a bias in the evaluation of global income whenever their value varies with time. The increase (or decrease) \( v_{t+1} - v_t \) in the value of a resource should in principle be accounted for in the value added \( \hat{p}_{t+1} b_{t+1} - \hat{p}_t a_t \).

‡ Schumpeter, The Theory of Economic Development, Cambridge 1934, Chapter IV.

§ We must also mention the presence of uncertainty, to be discussed in the next chapter.
constraints which govern it. For the representation of production in periods, the constraints are expressed by the sequence of production functions \( g_t \), that is, the inequalities (29). Each pair of vectors \((a_t, b_{t+1})\) appears as argument in only one of these inequalities, that for period \( t \). Now, (36) shows that the discounted total profit \( \Sigma p_{q,t} \), can be expressed as a sum of discounted profits \( \pi_t \) relating to the different periods and that the choice of the pair \((a_t, b_{t+1})\) affects only one of these profits. Consequently, to maximise \( \Sigma p_{q,t} \) subject to the set of inequalities (29) written for \( t = 1, 2, \ldots, T - 1 \), it is sufficient for the firm to maximise the profits \( \pi_t \) successively and independently, taking account in each period only of the production constraint relating to it.

We shall presently see why this apparently rather surprising result follows from the model under consideration. For the moment, let us look at its consequences.

Maximisation of

\[ \pi_t = p_{t+1}b_{t+1} - p_t a_t \]

subject to the constraint

\[ g_t(a_t, b_{t+1}) = 0 \]

imposes the following first-order conditions:

\[
\begin{cases}
  p_q = -\lambda q g_q' & q = 1, 2, \ldots, Q \\
  p_{q,t+1} = \lambda t q_{q,t+1}
\end{cases}
\]  

(43)

where \( \lambda_t \) is a Lagrange multiplier and the notation (33) is used for the partial derivatives.

From these equations, and taking account of formula (8) defining \( \rho_{q,t} \), we obtain directly

\[
\rho_{q,t} = \frac{p_q - p_{q,t+1}}{p_{q,t+1}} = -\frac{g_{q,t}'}{\gamma_{q,t+1}} - 1
\]

(44)

showing that the own rate of interest of good \( q \) during period \( t \) is equal to the ratio between the net increase in supply of this good,

\[ d(b_{q,t+1} - a_q) \]

and the increase in the input of the same good, \( da_q \), when only \( a_q \) and \( b_{q,t+1} \) vary from the equilibrium state for the firm. (Indeed, the equality \( g_{q,t}' da_q + \gamma_{q,t+1}' db_{q,t+1} = 0 \) implies that the ratio in (44) equals the ratio of \( d(b_{q,t+1} - a_q) \) to \( da_q \).

We note also that conditions (43) imply conditions (35), which we obtained when investigating intertemporal efficiency. This result is not surprising, since a Pareto optimum is obviously 'intertemporally efficient'. Now, in Chapter 4 we discussed a property that applies perfectly in a time context and states that every competitive equilibrium is a Pareto optimum.
The necessary first-order conditions for maximisation of $\pi_t$ subject to the constraint $g_t = 0$ are also sufficient when a suitable convexity assumption is satisfied. More precisely, let $P_t$ be the set of $2Q$-dimensional space which contains the pairs $(a_t; b_{t+1})$ satisfying the technical constraints

$$g_t(a_t; b_{t+1}) \leq 0.$$

We shall then state the following assumption:

**Assumption 2.** The sets $P_t$ are convex; the functions $g_t$ are differentiable, non-decreasing with respect to the $b_{q,t+1}$, and non-increasing with respect to the $a_{qt}$.

Discussion of the validity conditions for this assumption takes us straight back to the remarks in Chapter 3. In particular, the assumptions about the direction of increase of $g_t$ express the fact that a technically feasible pair cannot be reached from an unfeasible pair simply by reducing inputs or increasing outputs.

We saw in Chapter 3 that the convexity property found practical justification in two other properties, which can often be considered to be approximately satisfied, namely additivity and divisibility. But we saw also that then production must be carried out under constant returns to scale; if the pair $(a_t; b_{t+1})$ is technically feasible, then so also is the pair $(\mu a_t; \mu b_{t+1})$, for any positive number $\mu$. Now, if the first pair returns a profit $\pi_t$, the second returns the profit $\mu \pi_t$. The maximum value of $\pi_t$ is therefore necessarily zero, and the consequences of this property have been discussed in the previous section.

Let us now examine the origin of the property established at the beginning of this section: for a firm in a 'competitive market', the optimal policy is separate maximisation of the profits relating to each period.

This property assumes the existence of perfect markets for all commodities including equipment in use and products in course of manufacture. In particular, it implies that no transaction cost hinders the sale or purchase of second-hand material.

Without this assumption, the choice of the optimal policy must involve simultaneously the operations over all periods.

To see this clearly, we shall consider a very simple example, of a machine that can be used in the two successive periods 1 and 2. Let $p_1$ be its price new at date 1 and $p_2$ its discounted second-hand purchase price at date 2. The firm can also resell the machine at date 2 after having used it during period 1, but at a discounted price $p^*_2$ which is less than $p_2$. The discounted gross receipts for the firm are $u^*_1$ and $u^*_2$ in the two periods when the machine is not used, $u^*_1$ and $u^*_2$ when it is.

The firm must make a decision for each period: to use (1) or not to use (0) the machine. There are therefore four ‘programmes’ leading to the following
discounted total profit:

\[ \pi(0, 0) = u_1^0 + u_2^0 \]
\[ \pi(0, 1) = u_1^0 + u_2^1 - p_2 \]
\[ \pi(1, 0) = u_1^1 + u_2^0 - p_1 + p_2^* \]
\[ \pi(1, 1) = u_1^1 + u_2^1 - p_1. \]

This total profit cannot be expressed as the sum of a first term depending on the decision taken for period 1 and of a second term depending on the decision taken for period 2. For then we should have

\[ \pi(1, 1) - \pi(0, 1) = \pi(1, 0) - \pi(0, 0), \]

that is, \( p_2 = p_2^* \). In such an example we can no longer define the profit relating to each period as a function only of the decisions involving this period.

In short, the property under consideration assumes that capital is freely transferable at each date, at well-defined prices. In the real situation, a large part of capital is 'fixed'. The cost of transferring it from one use to another is often prohibitive. Thus the general theory with which this chapter is concerned ignores one aspect of reality which is important in certain cases.

Unfortunately it seems impossible to achieve general theoretical results when we consider the practical irreversibility of investment operations, i.e. when it is no longer feasible for existing installations to change their use. So in what follows, we shall ignore the possible effects of non-transferability. This will not be a serious drawback since we shall mainly be discussing stationary programmes or proportional growth programmes where no transfer of existing equipment is required.

5. Efficient stationary states and proportional growth programmes

A stationary regime or state is a programme in which the quantities representing the activity of the different agents have the same values in all periods so that production and consumption in one period are the same as in the previous period.

Stationary states are unlikely to be realised if the conditions governing the activity of consumers and producers vary over time, and in these circumstances there is nothing special to be gained from their investigation. For this reason the theory of stationary states assumes the environment invariant over time.

Confining ourselves for the time being to production operations, we can define precisely what is meant by a stationary environment. In each firm \( j \), the production functions \( g_{jt}(a_{jt}; b_{j,t+1}) \) are the same for all periods, which excludes all technical progress. Moreover, in a stationary state inputs \( a_{jt} \) and outputs \( b_{j,t} \) are also the same in all periods. So we shall use simply \( g_j \) to
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denote the production function, \( a_j \) for the input vector and \( b_j \) for the output vector. We shall let \( y_j = b_j - a_j \) be the vector of the net productions available at all intermediary dates, where obviously \( y_j \) is \(-a_j\) at the initial date and \( y_jT = b_j\) at the terminal date.

A production programme is in general a set of vectors \( a_{jt} \), \( b_{jt} \) for all firms and all dates. Such a programme is feasible if it obeys the inequalities

\[
g_j(a_j; b_{jt+1}) \leq 0
\]

for all \( j \) and all \( t \), as well as the conditions at the extreme dates. It is a production optimum if it is feasible and if there is no other feasible programme giving a higher level for at least one global net production:

\[
y_{qt} = \sum_{j=1}^{n} (b_{jq} - a_{jq}) \quad \begin{cases} q = 1, 2, \ldots, Q \\ t = 1, 2, \ldots, T, \end{cases}
\]

and giving a lower level for none.

More precisely, the stationary programme \( E^0 \) is a production optimum if it is feasible and if there exists no feasible programme \( E \) such that, for all \( q \),

\[
- \sum_{j=1}^{n} a_{jq} \geq - \sum_{j=1}^{n} a_{jq}^0
\]

\[
\sum_{j=1}^{n} (b_{jq} - a_{jq}) \geq \sum_{j=1}^{n} (b_{jq}^0 - a_{jq}^0) \quad t = 2, \ldots, T - 1
\]

\[
\sum_{j=1}^{n} b_{jqT} \geq \sum_{j=1}^{n} b_{jq}^0
\]

where at least one inequality holds strictly.

We are now in a position to establish the following result.

**PROPOSITION 1.** Let \( E^0 \) be a stationary state which is a production optimum. If the functions \( g_j \) satisfy assumption 2, then there exists a non-zero vector \( p \) with \( Q \) components and a number \( p \) (where \( p_q \geq 0 \) and \( p > -1 \)) such that \((a_j^0; b_j^0)\) maximises \( pb_j - (1 + p)pa_j \) over the set of pairs of vectors \((a_j; b_j)\) satisfying \( g_j(a_j; b_j) \leq 0 \).

For, consider the vectors \( y_j \) whose components are the \( QT \) numbers \( y_{jqt} \); consider also the inequalities \( f_j(y_j) \leq 0 \) representing the technical constraints on the \( y_j \) which can be deduced from (45). It is easy to verify that assumption 2 on the \( g_j \) implies that the sets \( Y_j \) are convex and the functions \( f_j \) are differentiable and non-decreasing with respect to each of the \( y_{jqt} \).

Since, by hypothesis, \( E^0 \) is a production optimum, proposition 3 of Chapter 4 implies that there exist \( QT \) numbers \( p_{qt} \), not all zero, such that \( y_j^0 \) maximises \( py_j \) over the set of \( y_j \) satisfying \( f_j(y_j) \leq 0 \). As we saw earlier in Section B.4, this implies that for each \( t \) from 1 to \( T - 1 \), \((a_j^0; b_j^0)\) maximises
Let us consider the marginal equalities resulting from this last property. They are expressed by:

\[
\begin{align*}
    p_{q,t} &= -\lambda_{jt} g'_{jq} & q &= 1, 2, \ldots, Q \\
    p_{q,t+1} &= \lambda_{jt} \gamma'_{jq} & t &= 1, 2, \ldots, T - 1,
\end{align*}
\] (46)

where \(g'_{jq}\) and \(\gamma'_{jq}\) denote the values of the derivatives of type (33) for the pair of vectors \((a^0_j, b^0_j)\). (The stationarity of \(E^0\) means that these derivatives do not depend on \(t\).) System (46) implies conditions on the \(g'_{jq}\) and \(\gamma'_{jq}\). We shall not emphasise them here, since they have already been discussed on other occasions in similar contexts. But this system also implies conditions on the \(p_{qt}\). In fact, the ratio \(p_{qt}/p_{rt}\) must equal \(g'_{jq}/g'_{jr}\); it is independent of \(t\), which means that the vectors \(p_t\) relating to different dates differ by at most a multiplicative constant. So we shall write

\[p_t = \beta_t p,\] (47)

where \(p\) denotes a suitable vector with \(Q\) components.

System (46) also implies that the ratio \(p_{q,t+1}/p_{qt}\), which equals \(\beta_{t+1}/\beta_t\), has the value \(-\gamma_{jq}/g'_{jq}\), which is independent of \(t\) and can be denoted by \(\beta\). Adopting the convention \(\beta_1 = 1\), which is always possible, we can deduce \(\beta_t = \beta^{t-1}\) and

\[p_t = \beta^{t-1} p.\] (48)

The form at which we have just arrived shows that discounted prices \(p_{qt}\) are such that the interest rates relating to the different goods are all equal and the interest rates relating to the different periods are also equal. We can therefore let \(\rho\) denote this common rate for all goods and all periods. The maximised expression \(p_{t+1} b_{jt+1} - p_t a_{jt}\) is then proportional to \(pb_{jt+1} - \rho p a_{jt}\), which completes the proof of proposition 1.

This proposition shows the sense in which relative prices \(p_q\) and the interest rate \(\rho\) are defined uniquely with respect to every programme corresponding to a stationary regime which is a production optimum. It can easily be generalised to the case of proportional growth.

A state of proportional growth is a programme in which the quantities representing the activity of the different agents all increase at the same rate \(\alpha - 1\) from period to period. If the \(a_{jq}\) represent inputs at date 1, then

\[a_{jt} = \alpha^{t-1} a_{jq} \quad t = 1, 2, \ldots, T - 1\]

Similarly, if the \(b_{jq}\) represent outputs at date 2, then

\[b_{jt} = \alpha^{t-2} b_{jq} \quad t = 2, 3, \ldots, T.\]

States of proportional growth are almost as special cases as stationary regimes (the case \(\alpha = 1\)). In fact, they assume that the environment is stationary.
and that production is carried on under constant returns to scale. So that the condition that the growth is technically feasible can be expressed simply as
\[ g_j(a_j; b_j) \leq 0. \]

In order to sustain a state of proportional growth which is a production optimum, the price system must also satisfy (46). It must therefore have the form (48).

6. Capitalistic optimum

In the previous section we applied optimum theory purely and simply, and confined ourselves to production. In particular, in order to establish a programme of proportional growth as an optimum, we compared it with all other feasible programmes, whether or not they were of proportional growth.

We might also think of comparing proportional growth programmes with each other directly, concentrating on the net productions which they yield. For this, we consider the following definition.

**Definition 2.** A proportional growth programme \( E^0 \) is said to be a 'capitalistic optimum' if it satisfies the technical constraints
\[ g_j(a_j; b_j) \leq 0 \quad j = 1, 2, \ldots, n \] (49)
and if there is no other programme \( E \) of proportional growth which satisfies the same constraints, grows at the same rate \( \alpha^0 \), gives a higher net production of at least one good and does not give a lower net production of any other:
\[ \sum_{j=1}^{n} (b_{jq} - \alpha^0 a_{jq}) \geq \sum_{j=1}^{n} (b^0_{jq} - \alpha^0 a^0_{jq}) \quad q = 1, 2, \ldots, Q \] (50)
where the inequality holds strictly at least once.

This definition reveals a certain relationship between production optimum and capitalistic optimum. However, there is a fairly clear-cut difference between the two notions. For the second, no explicit account is taken of the initial and terminal situations of the programme, which on the other hand are involved in the production optimum. In the comparisons to which the latter concept gives rise, the inequalities (50) must be supplemented by the following, which result directly from the constraints relating to the initial and terminal dates respectively:
\[ -\sum_{j=1}^{n} a_{jq} \geq -\sum_{j=1}^{n} a^0_{jq}, \] (51)
\[ \sum_{j=1}^{n} b_{jq} \geq \sum_{j=1}^{n} b^0_{jq}. \]

In other words, we can say that, when determining a capitalistic optimum, we can leave the \( a_{jq} \), the quantities relating to capital, completely unrestricted since, in comparisons between programmes of proportional growth, we do
not consider the \(a_{jq}\) directly, but only the \(b_{jq} - \alpha^0 a_{jq}\). In a capitalistic optimum, the equipment, stocks and current inputs represented by the \(a_{jq}\) are, in a certain sense, optimal from the standpoint of the net productions which they yield under proportional growth. But, in the initial concrete situation in an economy, there is no reason a priori for existing equipment and stocks to be extensive enough to allow the immediate realisation of such an optimum. This is the reason why capitalistic optima are also often called in the literature 'golden age' programmes.

We can now establish

**PROPOSITION 2.** Let \(E^0\) be a proportional growth programme, which is a capitalistic optimum. If the functions \(g_j\) satisfy assumption 2 and, when \(\alpha^0 \neq 1\), have constant returns to scale, there exists a non-zero vector \(p\) such that \((a^0; b^0)\) maximises \(pb_j - \alpha^0 pa_j\) over the set of pairs of vectors \((a_j; b_j)\) satisfying the technical constraints (49).

The proof is similar to the proof of proposition 3 in Chapter 4, so only the main elements will be given here.

If \(E^0\) is a capitalistic optimum, it maximises

\[
\sum_j (b_{j1} - \alpha^0 a_{j1})
\]

subject to the constraints

\[
\begin{align*}
\left\{ \sum_j (b_{jq} - \alpha^0 a_{jq}) = \sum_j (b_{jq}^0 - \alpha^0 a_{jq}^0) \right. & \quad q = 2, 3, \ldots, Q; \\
g_j(a_j; b_j) = 0 & \quad j = 1, 2, \ldots, n.
\end{align*}
\]

Therefore there exist Lagrange multipliers \(\sigma_1 = 1, \sigma_q\) and \(\mu_j (q = 2, 3, \ldots, Q; j = 1, 2, \ldots, n)\) such that \(E^0\) equates to zero the derivatives with respect to the \(a_{jq}\) and \(b_{jq}\) of the function that consists of (52) added to the constraints (53), each multiplied by its Lagrange multiplier. Equation to zero of the derivatives in question is expressed by

\[
\begin{align*}
\sigma_q + \mu_j &= 0, \\
- \alpha^0 \sigma_q + \mu_j &= 0.
\end{align*}
\]

On the other hand, the first-order conditions for maximisation of \(pb_j - \alpha^0 pa_j\), subject to the constraint (49), are

\[
\begin{align*}
p_q &= \lambda_j \gamma_{jq} \\
\alpha^0 p_q &= - \lambda_j \beta_{jq}.
\end{align*}
\]

These conditions are satisfied by \(E^0\) if \(p_q = \sigma_q\) and \(\lambda_j = - \mu_j\). Finally, they are sufficient for maximisation of \(pb_j - \alpha^0 pa_j\) when the function \(g_j\) obeys assumption 2. This completes the proof of proposition 2.

The price-system introduced by proposition 3 has the special feature that it involves an interest rate equal to the growth rate \(\alpha^0 - 1\), and, in particular,
a zero interest rate in the case of a stationary regime. In fact, the value of inputs is accounted for in the profit \( pb_j - a^0 pa_j \) with the addition of an interest charge equal to \( (a^0 - 1) pa_j \).

This result may seem more natural, and the relation between production optimum and capitalistic optimum may become clearer if we consider the simple case of stationary programmes in an economy with a single good and a single firm.

The curve in Figure 5 represents the variations in \( b - a \) as a function of \( a \) when \( g(a; b) = 0 \). Any point \( M^1 \) situated on the increasing part of this curve defines a stationary state \( E^1 \), which immediately appears as a production optimum. (To increase \( b - a \) beyond \( b^1 - a^1 \) implies an increase of capital beyond \( a^1 \), that is, a decrease in 'initial net production' \( y_1 = -a \).) The gradient of the tangent to the curve at \( M^1 \) defines the interest rate \( \rho \) corresponding to \( E^1 \), since \( M^1 \) must maximise profit, which here becomes \( (b - a) - \rho a \) when the good serves as numéraire. The point \( M^0 \), the maximum of the curve, defines a stationary state \( E^0 \), which is obviously a capitalistic optimum. The tangent at \( M^0 \) is horizontal, consequently the rate of interest is zero.

Thus, in a stationary economy the return to capital disappears if capital is sufficiently plentiful, if production is organised efficiently, and if the price-system correctly reflects marginal equivalences. It is remarkable that this statement is no longer exact for a programme of proportional growth corresponding to true expansion \( (a^0 > 1) \). If capital is optimal in such a state of growth, then, the rate of interest remains positive. This must be so a fortiori if capital is too scarce to allow immediate realisation of a capitalistic optimum.

Fig. 5
7. The theory of interest once again

This naturally leads us to conceive of a relation between the rate of interest and the 'scarcity' of capital, or between interest and 'capital-intensity'. In a given state of technique, that is, for given production functions or sets, the price-system varies \textit{a priori} as a function of (i) the resources available to the economy, (ii) consumer preferences and (iii) the distribution of property rights. The description of such variations may be very complex. However, are they not compatible with the existence of a simple relation between the rate of interest and certain physical characteristics of the programmes under consideration?

Most economists who have approached this question have believed it possible to give a positive answer, at least so long as the investigation is confined only to stationary regimes. However, we must now recognise that there is no simple universal relation between the rate of interest and capital intensity. Certainly a tendency exists, but it is often contradicted by examples which are not particularly abnormal.

For a clear grasp of the subject we shall first establish an inequality resulting from profit maximisation. This inequality leads to clear-cut conclusions for the most aggregative model; but it has no simple implication when even a small number of goods is being considered. We shall then discuss a small example that should help to reveal where the difficulties lie. We shall conclude the chapter with another example that gives rise to reflection on the special features of 'stationary equilibria'.

Let us try to apply the idea that the study of production conditions alone allows us to establish a relation between the rate of interest and capital intensity.

Let us assume that there are two categories of goods: primary resources, which can neither be produced nor consumed, and products. Let \( z \) denote the input vector of primary resources and \( w \) their price vector. We let \( a, b, y \) and \( p \) denote the vectors relating to the products. With this new notation, the profit \( \bar{\pi} \) realised in an elementary period is

\[
\bar{\pi} = py - \rho pa - w'z
\]  

where, by convention, \( w' \) denotes \((1 + \rho)w\).

We now refer to two stationary equilibria: \( E^0 \) (with quantities defined by \( y^0, a^0, z^0 \) and prices by \( p^0, w^0, \rho^0 \)) and \( E^1 \) (with similarly \( y^1, \ldots, p^1 \)). We set, for example

\[
\Delta y = y^1 - y^0.
\]

Maximisation of profit with respect to the price-system of \( E^0 \) implies

\[
p^0 \Delta y - \rho^0 p^0 \Delta a - w^0' \Delta z \leq 0.  
\]  

(57)
Similarly, profit maximisation with respect to the price-system of $E^1$ implies

$$p^1 \Delta y - p^1 p^1 \Delta a - w^1 \Delta z \geq 0. \quad (58)$$

It follows from the last two inequalities that

$$\Delta p \Delta y - \Delta (pp) \Delta a - \Delta w^1 \Delta z \geq 0. \quad (59)$$

Inequality (59), which can be called the 'relation of comparative dynamics', sets a condition on the variations which, affecting quantities ($\Delta y, \Delta a, \Delta z$) and prices ($\Delta p, \Delta (pp), \Delta w^1$) simultaneously, are compatible with the given production possibilities. To make use of this inequality, we assume further that $E^0$ and $E^1$ use the same primary inputs $\Delta z = 0$. We then say that the capital-intensity of $E^1$ is greater than that of $E^0$ if all the components of $\Delta a$ are positive; using the same inputs of labour, $E^1$ uses more products—equipment, power, raw materials, etc. When $\Delta z = 0$, inequality (59) becomes

$$\Delta p \cdot \Delta y - \Delta (pp) \cdot \Delta a \geq 0. \quad (60)$$

It has a simple implication in an aggregate model where $y, a$ and $p$ have each a single component: the same product represents both 'production goods' and 'consumption goods'. This product can be taken as numéraire so that $\Delta p = 0$ and $\Delta (pp) = \Delta p$. It then follows from (60) that

$$\Delta p \cdot \Delta a \leq 0. \quad (61)$$

The greatest capital-intensity corresponds to the lowest interest rate.

But, apart from this model to which economists have tended to attribute too much general significance, (60) does not necessarily lead to such a clear-cut result. As we shall see, we can construct examples in which a family of stationary equilibria is not ranked in inverse order according as capital intensity or the rate of interest is being used as the ranking criterion.

Suppose then that there is a single primary resource ($z$ and $w$ are scalars), a 'subsistence good' taken as numéraire and not used as input, and finally a 'durable good' with price $p$. The input of the latter is denoted by $a$, its net production by $y_2$, and that of the subsistence good by $y_1$. The technical constraints are represented by the production function

$$y_1^\alpha + y_2^\beta = A^\beta a^\alpha z^\beta - a \quad (62)$$

where $\alpha$ and $\beta$ are two parameters.† Assumption 2 is satisfied when $\beta \geq 1$ and $0 < \alpha < \beta$.

We shall assume that $z = 1$, so that $a$ will be taken as a measure of capital

† The reader can verify that we revert to this function with $\alpha = 1$ and $z = 1$ if we consider an economy with two primary resources, one of which can only be used for product 1 and the other for product 2, and in which the net outputs of the two products are $y_1 = Aa_1^\alpha$ and $y_2 = Aa_2^\beta$ when the primary resources are all used, the numbers $a_1$ and $a_2$ denoting capital inputs of the 'durable good' in each production.
intensity. A stationary equilibrium then depends on two numbers, \( a \) and, for example

\[
s = \frac{y_2}{y_1},
\]

the third number being determined by (62). The number \( s \) increases as consumption is directed more to the durable good, to the detriment of the subsistence good \((y_1 \text{ and } y_2 \text{ are naturally used for consumption})\).

Profit is

\[
\bar{\pi} = y_1 + py_2 - \rho p a - w'z,
\]

its maximisation subject to (62) implies

\[
\begin{align*}
\beta y_1^{\theta-1} &= \lambda \\
\beta y_2^{\theta-1} &= \lambda p \\
\frac{u}{a} &= \lambda \rho p \\
(\beta - \alpha)\frac{u}{z} &= \lambda w'
\end{align*}
\]

where \( \lambda \) is a Lagrange multiplier and \( u \) is the expression \( A^\theta a^z z^{-\alpha} \).

From this system we can deduce directly

\[
\frac{w'}{\rho p} = \left( \frac{\beta}{\alpha} - 1 \right) a
\]

when \( z = 1 \). *Capital intensity is related directly to the ratio between the current cost of labour (\( w' \)) and the current cost of capital (\( \rho p \)).* But \( w' \) and \( p \) depend on the characteristics of equilibrium so that the relation between \( a \) and \( \rho \) is not simple.

We can also deduce from (64):

\[
p = s^{\theta-1}
\]

which, combined with (65), gives

\[
\frac{w'}{\rho} = \left( \frac{\beta}{\alpha} - 1 \right) a \cdot s^{\theta-1}.
\]

The ratio between the 'rate of wages' and the 'rate of profit' increases as capital-intensity increases and as consumption tends to be more directed towards the durable good.

But the expression for \( w' \) as a function of \( a \) and \( s \) is complex. We can deduce from (64):

\[
w' = \left( 1 - \frac{\alpha}{\beta} \right) u y_1^{1-\beta}.
\]

Now,

\[
u = y_1^\theta + y_2^\theta = A^\theta a^z,
\]
Intertemporal economies

Finally, which, combined with (67), gives

\begin{equation}
\rho = \frac{\alpha A}{\beta} a^{\alpha/\beta - 1}(1 + s^{-\beta})^{1 - 1/\beta}.
\end{equation}

The rate of interest certainly decreases as \( a \) increases, since \( \alpha < \beta \); but it also depends on \( s \). Two stationary equilibria \( E^0 \) and \( E^1 \) can be such that \( \rho^1 > \rho^0 \) and \( a^1 > a^0 \) on condition that \( s^1 - s^0 \) is negative and large enough in absolute value.

To make things more precise, we can imagine that, for each level \( a \) of capital intensity, there exists a single combination \((y_1, y_2)\) of net outputs, that is, a single value of \( s \) compatible with the consumers’ preferences between the ‘subsistence good’ and the ‘durable good’. Figure 6 illustrates such a situation for the case of a single consumer. In the plane \((y_1, y_2)\), the curve
UV represents the set of combinations that are feasible in a stationary equilibrium for a given level of \( a \), and the curve \( U'V' \) corresponds to a higher value of \( a \). Indifference curves are drawn in dotted lines. To each level of \( a \) there corresponds an equilibrium represented by the point on the curve of production possibilities which is highest in the consumer’s preferences: \( P \) on \( UV \), or \( P' \) on \( U'V' \).

The indifference curves have been drawn so that, for increasing levels of \( a \), the equilibrium point moves first along the horizontal segment \( AB \) and then on an increasing curve \( BC \). We can verify that, if \( a > 1 \), the rate of interest increases along \( AB \) while capital intensity also increases.

In fact, (69) implies

\[ y_2 = s y_1 = A a^{\alpha / \beta} (1 + s^{-\beta})^{-1 / \beta} \]

When \( y_2 \) remains constant, \((1 + s^{-\beta})\) varies proportionally with \( a^\alpha \). In view of (71), the rate \( \rho \) varies proportionally with

\[ a^{\alpha / \beta - 1} \cdot a^{(1 - 1 / \beta)} = a^{\alpha - 1} \]

Figure 7 illustrates how \( \rho \) then varies with the increase in capital intensity: the rate of interest increases initially and only decreases after \( y_2 \) increases.†

![Diagram](image.png)

Fig. 7

8. Overlapping generations and stationary equilibria

In the previous sections we have seen how theories of interest, capital and growth may prove interesting properties resulting only from the fact that most productive operations can be described as taking place within

---

one period or several successive periods. For, apart from a reference to consumer preference in the last example, we have so far considered only production.

Obviously the allocation of resources in intertemporal economics also raises problems which directly concern consumers. If consumption is badly geared over a lifetime so that, for example, old age is too much favoured over youth, or the opposite, this could be called a bad allocation; an allocation where the needs of future generations are sacrificed to those of the present generation could also be rated as bad.

We see immediately that analysis by periods is appropriate for such problems. We must certainly take account of the fact that an individual lives through several successive periods; but we must also note that no individual lives indefinitely. We should also recognise that generations are renewed from one period to another.

This is why the present practice is to consider a model in which successive overlapping generations are represented. We shall discuss this model briefly and, within this context, define a stationary equilibrium.†

For a fuller understanding of the theory of interest it is also important to represent individual choices. It is often held that the interest rate (or the discount rate) expresses the intensity of preference for the present. The greater the degree of impatience in individual utility functions, then the higher the rate of interest, so it is thought. Confining ourselves to stationary equilibria, we shall see that, all things considered, this is not a simple relationship.

We must first reconsider and define more precisely the representation of the consumer given in Section A.2. In general terms, we should identify dates of birth and death for each consumer. For example, if the ith consumer lives from $u_i$ to $v_i$, then he is active only in the period $[u_i, v_i]$; in other words his consumption plan $x_i$ must satisfy the condition that $x_{i,t}$ is zero for all dates $t < u_i$ and $t > v_i$.

There is little point in going on to further description of a general formulation whose structure is easily grasped since the representation of generations is important only for fairly specific problems. In most cases the study of the economic aspect of these problems is simplified if regular demographic development is assumed. This assumption is in fact presently made in those areas of microeconomic theory which deal with this subject.

In the most extreme schema, the same number of consumers is born in each period and each consumer lives for only two successive periods; so at any moment there are as many young as there are old consumers (this

abstract model can be given some practical reference if a 'young consumer' is defined as an adult working household while an 'old consumer' is a retirement household).

The ith consumer's consumption plan can then be represented by a pair of vectors with \( Q \) components, \((x_{iu}, x_{iv})\) given that \( x_{iu} \) is realised in the period \( u \) and \( x_{iv} \) in the period \( u_i + 1 \). Consumer preferences are easily represented by a function \( S_i(x_{iu}, x_{iv}) \). If a complete intertemporal price system exists, then consumer decisions are determined exactly as before.

It remains to be seen whether this particular structure of the consumption sector affects the properties of intertemporal competitive equilibria and in particular, if interest rates are higher when the functions \( S_i \) express a greater degree of impatience.

As a first approach, we restrict ourselves to a very simple case and consider only a possible stationary equilibrium for it. Since this is only an example we can allow ourselves a high degree of simplicity.

Suppose there is a single good (as we shall see later, the model also applies if it also contains labour, considered as a primary resource available in a fixed quantity). We can set the undiscounted price of this product as 1, that is, we adopt it as numéraire.

Let us assume that there is a single firm whose technology is invariant over time, the lag of output behind input being exactly equal to one period. Its production function is

\[
b = f(a)
\]

and its capitalised profit at the end of the production period:

\[
\bar{\pi} = b - a/\beta
\]

where \( \beta \) is the discount factor \((1 + \rho)^{-1}\).

Let us assume that exactly one consumer is born at each date and that his discounted income at the beginning of his life is \( R \). His consumption plan \((x_u, x_v)\) must satisfy the budget constraint

\[
R = x_u + \beta x_v.
\]

His preferences are represented by the function \( S(x_u, x_v) \).

At each date, the equilibrium condition in the market for the good is

\[
x_u + x_v = b - a.
\]

What shall we say is a stationary competitive equilibrium in such an economy? Obviously, values of the different variables \((a, b, x_u, x_v, \beta, \bar{\pi}, R)\) such that

(i) The firm maximises \( \bar{\pi} \) subject to the constraint of its production function (that is, it determines \( \bar{\pi}, a \) and \( b \) as a function of \( \beta \), considered as
given for the firm; hence three equations); (ii) Each consumer maximises $S$ subject to the constraint of his budget equation (74) (that is, he determines $x_u$ and $x_v$ as a function of $R$ and $\beta$; hence two equations); (iii) Equilibrium is realised in the market for the good (equation (75)).

These three conditions (i), (ii), (iii) imply six equations among the seven variables. If there are no other conditions for equilibrium, then it has one degree of freedom a priori.

Looking at the situation more closely, it appears that equilibrium can be meaningful in such a model only if we define how profit is distributed to the consumers and if they have no other source of income. Let us assume that a fraction $\alpha$ of profit is distributed to the consumer who has just been born and a fraction $1 - \alpha$ to the consumer who is in the second half of his life. In these conditions, the discounted income of a consumer at the beginning of his life is

$$R = \bar{\pi}[\alpha + \beta(1 - \alpha)]$$

(76)

which completes the six previous equations for the determination of equilibrium.

To study the properties of a stationary equilibrium we can first easily eliminate $R$ and $\bar{\pi}$ by reducing (73), (74) and (76) to

$$[\alpha + \beta(1 - \alpha)](\beta b - a) = \beta x_u + \beta^2 x_v.$$  

(77)

Replacing $x_v$ by the value implied by (75) we obtain the condition

$$(1 - \beta)[\beta x_u + (\alpha + \beta)a - \alpha \beta b] = 0.$$  

(78)

We see that there may be stationary equilibria of two different types.

First, a capitalistic optimum may be an equilibrium with zero interest rate ($\beta = 1$). The value $a^0$ such that $f'(a^0) = 1$ then conforms to the behaviour of the firm. Profit $\bar{\pi}$, net output $b - a$ and income $R$ are all equal to $f(a^0) - a^0$, which is distributed between $x_u$ and $x_v$ so that the preferences of the consumer whose life is beginning are satisfied as well as possible. When a capitalistic optimum exists and there is a possible distribution which ensures the consumer at least his minimum living standard, then this type of stationary equilibrium exists.

We note that the interest rate, zero, in equilibria of this type is completely independent of the consumers' preferences for the present. If we compare two such stationary situations corresponding to the same production function $f(a)$ but with two different specifications of the utility function we see that the distribution of $f(a^0) - a^0$ is most favourable to $x_u$ in the situation where impatience is strongest; but this does not affect
the interest rate. So the suggestion that this rate is a simple expression of
the degree of preference for the present cannot be generally valid.

Second, (78) suggests a possible second type of stationary equilibrium in
which the expression in square brackets is zero. We see that this is not a
purely hypothetical case if we consider an example such as

\[ f(a) = a^\gamma \quad S(x_u, x_v) = x_u x_v^\delta \quad \alpha = 1 \tag{79} \]

where \( \gamma \) and \( \delta \) are two given coefficients (\( \gamma < 1 \)). In particular, this leads to

\[ \beta = \frac{\delta(1 - \gamma)}{\gamma(1 + \delta)}, \quad \frac{x_v}{x_u} = \frac{\gamma(1 + \delta)}{1 - \gamma}. \tag{80} \]

Since \( \delta \) is an indicator of the degree of preference for the future, this
example shows that there exists a stationary equilibrium in which the
interest rate increases as impatience increases; \( \beta \) and \( x_v/x_u \) are increasing
functions of \( \delta \).

We must, however, note that this second type of stationary equilibrium
does not exist in all possible specifications of the model; for example, if
\( \alpha = 0 \), the expression in square brackets in (78) cannot be zero since we
must have \( a > 0, x_u > 0 \) and \( \beta > 0 \).

But the main observation is to note that, in the overlapping generation
model, stationary competitive equilibria may exist that are not Pareto
efficient. Exhibiting an example will prove the point.

Let us specify (79) further and assume \( \gamma = \frac{1}{3} \) and \( \delta = 2 \), this last value
signalling a preference for future consumption. The equilibrium corre-
sponding to (80) has \( \beta = \frac{2}{3} \) hence \( \rho = -\frac{1}{3} \). Computation of the quantities
in this equilibrium \( \hat{E} \) leads to:

\[ \hat{a} = \frac{8}{27}, \quad \hat{b} = \frac{2}{3}, \quad \hat{x}_u = \frac{4}{27}, \quad \hat{x}_v = \frac{2}{9}. \tag{81} \]

On the other hand, the equilibrium \( E^* \) characterized by \( \beta = 1 \) (hence \( \rho = 0 \)) in the same economy is found to require:

\[ a^* = \frac{1}{3\sqrt{3}}, \quad b^* = \frac{1}{\sqrt{3}}, \quad x_u^* = \frac{2}{9\sqrt{3}}, \quad x_v^* = \frac{4}{9\sqrt{3}}. \tag{82} \]

Assuming that the stationary equilibrium \( \hat{E} \) has been established, one
may see that shifting away from this equilibrium may be advantageous.
Indeed, at any time one would increase the utility of future generations by
shifting to the stationary equilibrium \( E^* \), while also giving some utility
gain to the present generation.

First, one easily computes the utility levels in the two stationary
equilibria: \( \hat{S} = 2^4 \cdot 3^{-7} \) and \( S^* = 2^5 \cdot 3^{-7.5} \), hence \( S^* > \hat{S} \). Second, one sees
what happens when a direct shift occurs at any time $t$ from $\hat{E}$ to $E^*$. The output $\hat{b} = \frac{2}{3}$ is available. The old consumer is entitled to $\hat{x}_v = \frac{2}{3}$. The input must be $a^* = 3^{-1.5}$. What remains available for the young consumer is equal to:

$$b - \hat{x}_v - a^* = \frac{4 - \sqrt{3}}{9}$$

which is even larger than $x_v^*$. The inefficiency of the stationary competitive equilibrium $\hat{E}$ can be understood by reference to the discussion in Section B.6. In this equilibrium, input into production $\hat{a}$ exceeds what is required by the capitalistic optimum $E^*$. As a consequence too much resource is invested into the production process and the real interest rate $\rho$ is negative (see Figure 8 and compare it with Figure 5). Notice, that in $\hat{E}$ each agent behaving as a price taker maximises his objective function and does not realise the overall inefficiency.

Fig. 8

One may wonder how this example of a Pareto inefficient competitive equilibrium may agree with the general results of optimum theory, which states under weak conditions that a market equilibrium is efficient (see
propositions 2, 4 and 6 of Chapter 4). The only formal difference between the present model and the one used in standard optimum theory is that now the number of periods, hence the number of commodities, is infinite since we are dealing with stationary equilibria without any terminal date. But this difference matters. It has been shown that, in infinite horizon models, competitive equilibria are not all efficient.

A sufficient condition for efficiency of an infinite horizon equilibrium is that, in this equilibrium, the present value \( p_t a_t \) of the input vector tends to zero as \( t \) increases indefinitely, i.e. as one considers inputs that are farther and farther removed in the future.† For stationary equilibria this amounts to saying that efficiency holds when the discount rate is positive and it may be shown in general that it fails to hold when this rate is negative, the case of \( E \). This remark completes the theory of capitalistic optimum: a rate of interest that is smaller than the one of such an optimum signals a lack of efficiency; one may then speak of overcapitalisation, a situation occurring for instance in Figure 5 when \( a > a^0 \).

When there are two or several stationary equilibria, and particularly when one of them is Pareto inefficient, the question arises of which one is most likely to be realised. Clearly, this question cannot be easily answered. We shall leave it open here.

The overlapping generation model exhibits another interesting feature related to the existence of financial assets or money in actual economies. It is typically found that the value of the consumption vector \( x_{tv} \) of an old consumer exceeds the sum of the value of his endowment when old and of what he can get from those with which he traded when young (indeed some of them were already old and disappeared). For instance in the particular specification discussed above, when \( x = 1 \), the old consumer has nothing but the saving he made when he was young; this saving would be worthless if the young consumer of the following generation was not ready to accept it. More generally, the savings on which old consumers live must exist in such a form that they will be traded against goods that young consumers have or produce, these consumers striving in their turn to provide for their old age by some saving. In modern societies money and financial assets are precisely the instruments of such trades. Although they have no direct utility, they are valuable indirectly because they are commonly accepted for trade against useful goods. This is what P. Samuelson called 'the social contrivance of money'.‡


This model with a single product, a single firm and a single consumer in each generation is obviously too simple in many respects. However it is sufficient to demonstrate (i) the complexity of the relationship between the rate of interest and the characteristics of individual needs and frames of mind, (ii) difficulties concerning Pareto efficiency in overlapping generation models with unlimited horizon.
In the models discussed so far, we have assumed that agents have perfect knowledge of the consequences of their decisions and that these decisions determine the equilibrium completely, provided that they are mutually consistent. There was no element of risk or uncertainty in the situation.

Around 1950, equilibrium and optimum theories could be accused of thus neglecting a basic aspect of the real world. It was difficult at that time to decide how far the simplifying assumption of the absence of uncertainty affected the relevance of the results. Thanks to recent progress in the theory of decision-making under uncertainty, this very considerable gap has largely been filled in. Generalisation of the abstract properties discussed up till now may still appear insufficient for the theoretical description of the real situation, which can be very complex. But the logical extension of microeconomic theories to situations involving uncertainty has been well elucidated. We must devote some time to it.

1. States and events

How does uncertainty affect our general formulation? Here are some examples: such and such agricultural production may be feasible on the basis of such and such inputs only if the composition of the soil has some particular characteristic and if weather conditions are favourable; a consumer may tomorrow prefer one entertainment to another according as his mood will be happy or sad; some proposed factory will be profitable only if a newly discovered geological deposit has sufficient reserves beyond those already known. Thus, the sets of feasible activities \((X_i \text{ and } Y_j)\), the preferences \((S_i)\) and the resources \((\omega_k)\) in the economy may depend on elements as yet unknown.

To represent this situation, we must identify all the elements affecting the equilibrium or optimum: soil composition, weather conditions, the consumer's
future mood, the extent of undiscovered reserves, etc. *A priori*, each element can have two or more values. Uncertainty disappears if we know the value of each of them.

So the following theoretical formulation is required: let e be a particular set of values given to each of the uncertain elements in the situation under consideration and let \(\Omega\) be the set of e's that are possible *a priori*. Uncertainty is represented by \(\Omega\); it disappears if we know which e of \(\Omega\) is realised. It is customary nowadays to call e the 'state of nature', or more simply, the *state*.† In short, the agents of the economy must make their decisions in the knowledge of the set \(\Omega\) of possible states, but not knowing which of the e's is 'true'.

An uncertain event is then a subset \(H\) of \(\Omega\); for example, the fact that the consumer will be happy tomorrow is the event defined by the set of all states for which this takes place. In most cases, the consequences of a particular decision depend on events comprising a certain number of states. But we shall scarcely be concerned with this in what follows.

At this point there are three remarks which must be made about this formulation:

(i) *Uncertainty and time*. Uncertainty is mostly concerned with the future. But this is not always so; for example, the extent of geological deposits is as much a characteristic of the present as of the future. The theories which we shall be discussing assume nothing about the temporal nature of the set of states. So there is no point in going into more detail here.‡

However, when the model involves uncertainty and time simultaneously, we must remember that a 'state' specifies all uncertain elements which may be important, that is, the whole 'story of nature', whether it involves unknown past, present or future facts.

(ii) *Uncertainty and probability*. When we say that the state e belongs to \(\Omega\), is this sufficient to represent the available information completely? Certainly not, since some states of \(\Omega\) may be more probable than others.

Clearly there is nothing to prevent us from assuming a distribution on \(\Omega\) defining the probabilities that the agents attribute to the different states and the different events.§ We shall do so in Sections 5 and 6 below. But the most direct generalisation of microeconomic theories need not concern itself in principle with such a distribution, even when it exists. So we can ignore it at least for the next two sections.

† Of course, this notion of state must not be confused with the notion of 'state of the economy' used previously. To avoid confusion, the latter expression will not be used in this chapter.

‡ For the study of some consequences of the interplay between time and uncertainty, the reader may refer to D. C. Nachman, 'Risk Aversion, Impatience and Optimal Timing Decisions', *Journal of Economic Theory*, October 1975.

§ If \(\Omega\) is not a finite set, the definition of the distribution assumes previous definition of probabilisable events. There is no point in dwelling on this here.
Thus, our theory will cover the case where different agents have different
distributions on $\Omega$. Each of these individual distributions can properly be
called ‘subjective’ since it depends on the subject to which it applies. The fact
that different agents attribute different probabilities to the same state is no
more inconvenient for our theory than the fact that different consumers
have different tastes.

(iii) Uncertainty and information. To define $\Omega$ is to define the information
common to all agents in the community; all know that the true state belongs
to $\Omega$. However, we have just seen that they do not necessarily agree on the
probabilities to be attributed to the different states, which we can now
interpret to mean that they have differing information.

There are, of course, many other problems raised by consideration of
information within microeconomic theory. We saw in Chapters 8 and 9
how decentralisation of information interferes with resources allocation.
We shall consider other problems in the next chapter. In this one we shall
pay no attention to the fact that individuals may have different
information.

2. Contingent commodities and plans

We shall adopt a similar approach to that used in the treatment of inter-
temporal economies, and first try to apply to an uncertain economy the con-
cepts and theories examined in earlier lectures. This will be an aid to clearer
discussion of the general problems raised by the organisation of economic
activities affected by random influences. It must therefore provide a basis for
the more specific studies which may be required because of the presence of
uncertainty.

How does the elementary concept of a commodity apply to an economy
whose state of nature is uncertain? Two equal quantities of the same good are
not equivalent if they must be available for different sets of states, the first
when the true state belongs to the event $H^1$, and the second when it belongs
to $H^2$ (where $H^1 \neq H^2$). So the complete characterisation of a commodity
must specify the states in which it is available. In other words, the com-
modities which we shall now be discussing must be ‘contingent’, that is,
their existence must be related to the realisation of certain events.

Consider also a contract stipulating that a certain quantity of a good
must be delivered if a particular event $H$ comprising three states $e^1$, $e^2$ and $e^3$
is realised. It will be convenient subsequently to say that this contract
implies a complex of three elementary commodities, the first being the good
in question subject to the condition that $e^1$ is realised, the second the good
if $e^2$ is realised, and the third the good if $e^3$ is realised. This procedure allows
us to describe any contract stipulating conditional delivery; we need only introduce a complex of elementary commodities, each consisting of a specified good which is due if and only if a particular state is realised. This concept of elementary commodity is sufficient for theoretical purposes.

In short, a commodity is now defined not only by its physical characteristics, its location, the date at which it is available, but also by a particular state of nature, that which must be realised in order that a stipulated delivery of this commodity should take effect.

We have no reason here to take location or date in isolation. So we shall say that such and such a ‘commodity’ consists of such and such a ‘good’ available if such and such a ‘state’ is realised. We shall talk of ‘commodities’ without mentioning each time that we are concerned with elementary contingent commodities. The index $h$ previously used to characterise commodities will now correspond to the pair $(q, e)$ where $q$ refers to the good and $e$ to the state.

In our theoretical investigation we assumed that the number of commodities was finite. So for the moment we shall assume that the number $N$ of states is finite: $e = 1, 2, \ldots, N$. If there are $Q$ goods, then there exist $l = NQ$ commodities.

The activity vectors of the agents, $x_i$ for the $i$th consumer, $y_j$ for the $j$th firm, then define quantities for each good and each state. These vectors represent ‘uncertain prospects’, ‘plans of action’, or what are sometimes called ‘strategies’. To choose the vector $x$ is to choose to consume $x_{11}$, $x_{21}$, $\ldots$, $x_{Q1}$ if the first state is realised, $x_{12}$, $x_{22}$, $\ldots$, $x_{Q2}$ if the second is realised, etc. In fact, a consumption strategy is chosen. In the generalisation of equilibrium and optimum theories, each agent no longer has to fix his activity, but rather to decide on his strategy.

This change of outlook does not basically affect the definition of sets of feasible vectors, $X_i$ for the $i$th consumer, $Y_j$ for the $j$th firm. It remains true to say that certain plans of action are physically or technically possible for the individual while others are not. The general assumptions introduced for the $X_i$ and $Y_j$ seem to raise no particular difficulty in the actual context.†

Similarly, the $i$th consumer’s choices here must relate to plans of action rather than to activity vectors. This fact does not seem likely to affect either the general assumptions on individual preferences nor the definition of

† Once again we may, however, feel somewhat uneasy when representing each set $Y_j$ by a single production function $f_j(y_j) = 0$. For instance consider a firm that has an uncertain output of good 1 and just decide on its inputs before knowing which state will occur. The vector $y$ of this firm must be such that $y_{qe} = -a_q$ for $q = 2, \ldots, Q; e = 1, 2, \ldots, N$. Moreover the output $y_{1e}$ that will be obtained if state $e$ occurs may be written as a function of the inputs $a_q$ and of the state $e$, thus $y_{1e} = g(a_2, \ldots, a_Q, e)$. So the fact that $y$ belongs to $Y$ implies no longer a single equation on $y$, but $QN - Q + 1$ independent equations (after elimination of the $a_q$). We shall no longer insist on this point, since we discussed in Chapter 3 the case of several constraints on production.
utility functions. We shall have occasion to look at this more closely very shortly. We must first consider the prices of contingent commodities and the nature of the markets for such commodities.

3. The system of contingent prices

The generalisation of the basic concepts being now clear, we can examine, in the context of an uncertain economy, the nature of the price-system and the market equilibria with which our theories have dealt so far. We shall then consider the possible role of such prices or equilibria in positive and normative theories.

The price \( p_{qe} \) of the commodity \((q, e)\) is the price to the purchaser in a contract stipulating that a unit quantity of the good \(q\) must be delivered if the state \(e\) is realised, but that otherwise, nothing is due from the seller. Note that the price \( p_{qe} \) applies firmly to the contract; it represents the value of the contract involving conditional delivery, and does so independently of the realisation of the event. In other words, the price \( p_{qe} \) must be firmly tendered by a purchaser wishing to obtain the promise of a conditional delivery.

Of course, it is also possible to define the price of a ‘conditional contract’ which will come into force, both as regards payment by the purchaser and delivery by the seller, only if the state \(e\) is realised.

Let us now express prices as quantities of the good \(Q\). We shall call this good the ‘numéraire’, although this is an abuse of language relative to our general concepts, where the numéraire is a particular commodity.

The price \( \hat{p}_{qe} \) in the conditional contract proposed above is

\[
\hat{p}_{qe} = \frac{p_{qe}}{p_{Qe}}.
\]  

(1)

In fact, this contract is equivalent to the simultaneous conclusion of two firm contracts between the agents \(A\) and \(B\). According to the first contract, \(A\) is bound to pay the price \(p_{qe}\) while \(B\) must deliver one unit of \(q\) if \(e\) is realised. According to the second, \(B\) must pay the price \(p_{qe}\) while \(A\) is bound to deliver \(\hat{p}_{qe}\) units of \(Q\) if \(e\) is realised. The conditional price \(\hat{p}_{qe}\) must be such that the second contract is fair relative to the price-system which has been introduced, that is, that the firm value \(p_{Qe}\hat{p}_{qe}\) of the conditional delivery given by \(A\) is equal to the firm value \(p_{qe}\) given by \(B\). This justifies formula (1).

It is also possible to define firm prices for conditional deliveries depending on the realisation of events \(H\) compatible with several states. Thus, the delivery of one unit of good \(q\) subject to the condition that \(H\) is realised, consists of the delivery of a ‘complex’ of elementary commodities: one unit
of each of the commodities \((q, e)\) for which \(e\) belongs to \(H\). The price of this delivery is

\[ p_{qH} = \sum_{e \in H} p_{qe}. \]  

(2)

In particular, we can let \(p_q\) denote the price of a firm delivery of one unit of \(q\). Formula (2) applies here with \(H = \Omega\), that is:

\[ p_q = \sum_{e = 1}^{N} p_{qe}. \]

(3)

Since we are considering the good \(Q\) as numéraire, we shall normalise prices so that \(p_Q = 1\). (Note that then \(p_{Qe}\) is generally less than 1, and so \(p_{Qe} < \hat{p}_{qe}\), as is required.)

This price system defines a value for each consumption plan or production plan. For example,

\[ px = \sum_{q = 1}^{Q} \sum_{e = 1}^{N} p_{qe}x_{qe} \]

(4)

is the value of the consumption plan \(x\). Here we are concerned with a firm value determined before the true state of nature is known. We can also write

\[ px = \sum_{e = 1}^{N} p_{Qe} \cdot \hat{p}_e x_e \]

(5)

where \(\hat{p}_e\) and \(x_e\) denote the vectors with the \(Q\) components \(\hat{p}_{qe}\) and \(x_{qe}\) respectively. The scalar product \(\hat{p}_e x_e\) is the ‘conditional value’ of the plan \(x\) if the state \(e\) is realised. The firm value \(px\) is then the average of the conditional values weighted by the \(p_{Qe}\), whose sum is equal to 1.

In a ‘market equilibrium’ defined as in Chapter 4, each consumer \(i\) chooses that plan which he prefers among all plans belonging to \(X_i\) and whose value does not exceed a numerical income \(R_i\). Each firm \(j\) chooses a plan whose value is maximum among all plans belonging to \(Y_j\). Moreover, the usual conditions of equality of global demand and global supply are satisfied for each commodity, that is, for each good and each state.

How relevant is this concept of equilibrium to the description of actual economies in so far as they are affected by the presence of uncertainty?

The critical assumption lies in the existence of prices for all pairs \((q, e)\), prices known to all agents and at which any contracts containing conditional clauses can be concluded, prices ensuring equilibrium in the markets for all goods and doing so in each conceivable state of nature. Because of the existence of markets for contingent goods, each consumer \(i\) can choose any consumption strategy \(x_i\) subject only to the constraints that the value of \(x_i\) does not exceed income \(R_i\) and that \(x_i\) belongs to \(X_i\).
There is another noteworthy consequence of this assumption: the firm's decisions entail no risk as to the profit to be realised, since the firm can conclude contracts thanks to which it can immediately realise the sure and firm value of its production plan. Consequently it is not concerned with risk; it need only compare its returns from certain different strategies whose physical consequences are partly uncertain but whose values are determined here and now by the market.

Note that the consumer has to consider risk. He certainly has sure knowledge of the cost of each consumption plan; but he must choose from among more or less uncertain plans. His attitude towards risk is reflected in the fact that his chosen plan contains consumptions which vary to a more or less marked degree with the states of nature. We shall return to this point later.

In a market equilibrium as thus conceived, the structure of contingent prices expresses the joint result of consumer preferences and of the influence that the state of nature has both on the conditions of production and on the availability of primary resources.

In practice, contracts involving contingent commodities are relatively rare. A fortiori, there are few 'markets' involving such commodities, that is, few institutional systems determining the prices to apply in such contracts through the confrontation of supply and demand. The best three examples are in insurance, lottery tickets and the Stock Exchange.

The buyer of an insurance policy agrees to pay the firm value of the benefit that will be due to him from the insurer if a particular event occurs. The buyer of a lottery ticket is in a similar position. The buyer of a share in an industrial company pays the discounted firm value of future profits which will depend on events involving the particular company.

An insurance market can validly be held to exist. Stock Exchanges are often put forward as prototypes of well-organised markets. So some actual prices are very similar to our theoretical contingent prices. But they are obviously too few to define the multitude of \( p_{qe} \)'s relating to a fairly complete sample of goods and states of nature. Thus the market equilibrium discussed above is a quite abstract idealisation of the way in which real markets function.

As in certain other of its aspects, microeconomic theory may be of more normative than descriptive interest. It suggests that an efficient allocation of resources requires the exchange of risks and the organisation of an insurance market (see Sections 8 and 9 below). Moreover, duality properties state that, subject to conditions which we shall not restate, there exist contingent prices corresponding to every optimal programme, and that with these prices, the programme appears as a 'market equilibrium'. Determination of these prices may improve the conditions in which
decentralised economic decisions are taken, and thus ensure that risk is more adequately taken into account.

Finally, the theory offers a precise conceptual framework, which is both rigorous and has wide generality. So it is very likely to prove fruitful in the investigation of more specific questions involving the influence of uncertainty on the conditions of economic management.

4. Individual behaviour in the face of uncertainty

We shall now look more closely at the behaviour of the individual consumer confronted with risk; there are some useful results bearing on this subject. Let us fix attention on the simple case of a single good and two states \((Q = 1; N = 2)\) and, for simplicity, omit the index \(q\) relating to goods.

Figure 1 represents an indifference curve in the plane whose coordinates are the consumptions obtained if the first state is realised (abscissa) and if the second state is realised (ordinate). To fix ideas, we shall assume that the first state is ‘it will rain tomorrow’, and the second ‘it will be sunny tomorrow’. To choose a vector \(x\) is to fix the consumptions that will take place in each of these eventualities.

For the indifference curve to be meaningful, it is obviously necessary that \textit{a priori}, the individual should be able to consider any complex on this curve, that is, that he can acquire a title giving him the right to receive \(x_1\) if it rains and \(x_2\) if it is sunny. Suppose that this condition is satisfied, as is required by the general formulation given in the previous sections. Two distinct points on the same indifference curve represent two titles (‘plans of action’ or ‘uncertain prospects’) considered as equally advantageous by the individual.

The points lying on the first bisector are of particular interest since they correspond to sure consumptions, that is, to complexes ensuring the same
consumption in both states. What is the significance of the marginal rate of substitution defined by the tangent to the indifference curve at the point $M$ where it cuts the bisector? This rate, $-\frac{dx_2}{dx_1}$, indicates the amount by which the individual agrees to diminish his consumption in sunny weather in order to obtain the guarantee that he will increase his consumption by one unit in rainy weather. Why is it not necessarily 1?

There may be two reasons for this. In the first place, the individual may have differing needs in the two states. He may think it necessary to increase his consumption in rainy weather over his consumption in sunny weather, for example by buying an umbrella. In order to increase his consumption by one unit in rainy weather, he is willing to make a bigger reduction in his consumption in sunny weather. In the second place, he may think that it is more likely to rain than to be sunny. If his needs are the same in both states, it is to his advantage to obtain an additional unit of consumption in the more probable state if to do so, he need only agree to a unit decrease in consumption in the less probable state.

Thus the fact that marginal rates of substitution differ from 1 in the neighbourhood of certainty is explained both by changes in needs and tastes as a function of states of nature and by differences in the likelihood attributed by the individual to the different states.

If it can be assumed that needs and tastes do not depend on the state, then the marginal rates in question reveal the likelihood or the 'subjective probability' of each of the different states for the individual. In the particular example, if we know that $-\frac{dx_2}{dx_1} = 2$ in the neighbourhood of certainty and that needs are unchanged whether it is rainy or sunny, then it seems in fact that the individual thinks there are 2 chances out of 3 that it will rain.

Subject to certain axioms about choices between uncertain prospects, it has in fact been shown that the individual behaves as if he had constructed a (subjective) distribution on the set $\Omega$ of states of nature. This theory will be mentioned again in more detail at the end of Section 6.

Let us assume that, for one reason or another, the marginal rate in the neighbourhood of certainty is 2. Suppose that there exist markets for contingent commodities and that prices are such that $p_1/p_2$ also equals 2. (So now to obtain an additional unit of consumption in rainy weather, the assurance of 2 units in sunny weather must be given up.) Will the individual then decide on a certain consumption plan? Not necessarily; everything depends on his 'attitude to risk'. He will certainly be indifferent to any infinitely small displacement in the neighbourhood of certainty along his budget line. But a finite displacement may seem advantageous to him.

Figures 2 and 3 illustrate two different types of behaviour. The budget line $PR$ is the same in each case. It is tangential to an indifference curve at the point $M$ where it intersects the bisector. In Figure 2, where the indifference
curve is concave upwards, the individual chooses $M$, that is, certainty. In Figure 3 he chooses another point $N$ which lies on a higher indifference curve. It is very natural to say that Figure 2 shows an individual with an aversion to risk, while Figure 3 shows an individual who enjoys risk.

More generally, we can say that, in the application of our model to situations involving uncertainty, quasi-concavity of the utility function $S(x)$ implies aversion to risk in the sense that certainty appears optimal whenever contingent prices correspond to the marginal rates of substitution calculated in this state of certainty.† We have had sufficient discussion of the role of quasi-concavity of $S$ to understand directly which properties depend on this aversion to risk.

5. Linear utility for the choice between random prospects

What we have just said is sufficient for generalisation of microeconomic theory to the case of uncertainty. However, individual preferences have often been given a more restrictive form, which allows more specific results to be proved.

In the situation most frequently considered, there exists, given a priori, a distribution on $\Omega$. In other words, with each state $e$ there is associated a known, well-defined probability $\pi_e$. We also talk of objective probabilities, meaning by that the given $\pi_e$. The economist F. Knight introduced the distinction between risk and uncertainty, suggesting that the former word be

† Note that, with this definition, aversion to risk has a fairly wide meaning since it covers the case where the individual considers the certain prospect as equivalent but not preferable to uncertain prospects.
kept for situations in which objective probabilities exist. So we shall now deal with risk.

In such a situation, the utility function is often given the particular form

\[ S(x) = \sum_{e=1}^{N} \pi_e u(x_e), \]  

(6)

where \( x_e \) denotes the vector with the \( Q \) components \( x_{qe} (q = 1, 2, \ldots, Q) \) and \( u \) denotes a function, which we shall call the elementary utility function. Thus, the global utility function \( S \), with \( NQ \) arguments, is written as the expected value of the elementary utility function. The global utility function is therefore linear with respect to the probabilities.

Such a form was first postulated directly as a good representation of behaviour in the face of risk. Nowadays its existence is established from a system of axioms on individual preferences, a system to be discussed in Section 6.

Note that expression (6) is still very general. If the function \( u \) is suitably chosen, we can represent, at least approximately, very varied systems of preferences. To see this, we shall consider the particular case of a single good \((Q = 1)\).

Figure 4 represents the variations of \( u(x_e) \) as a function of \( x_e \). It allows us to construct point by point an indifference curve similar to that in Figure 1. Consider, for example, the curve corresponding to \( S(x_1, x_2) = 0 \), a value which has no particular virtue since the addition of the same constant to \( S(x) \) and to \( u(x_e) \) affects neither equation (6) nor the system of preferences. Let us also assume that the two states have the respective probabilities \( \pi_1 = 2/3 \) and \( \pi_2 = 1/3 \).
The abscissa of the point $M$ where the curve in Figure 4 cuts the $x$-axis corresponds to the abscissa of the point where the indifference curve cuts the bisector in Figure 1 (certain prospect corresponding to $S(x) = 0$). To construct another point on the indifference curve, consider some abscissa $x_1$ and the point $A$ with coordinates $x_1$ and $u(x_1)$ on Figure 4. The abscissa of the point $B$ with ordinate $-2u(x_1)$ defines the quantity $x_2$ such that the point $(x_1, x_2)$ lies on the indifference curve in question in Figure 1. (For, $u(x_2) = -2u(x_1)$, and so $\pi_1 u(x_1) + \pi_2 u(x_2) = 0$.)

By applying this construction it can be verified that the functions $u(x_e)$ represented in Figures 4 and 5 lead to indifference curves of the same appearance as those drawn in Figures 2 and 3 respectively.

The global utility function is partly arbitrary since an increasing transformation applied to $S$ does not change the system of preferences. Clearly nothing is changed in this general property, which still holds. But all the equivalent functions $S$ cannot simultaneously have the form (6). If we wish to keep this form, we must allow only increasing linear transformations on $S$ (or equivalently on $u$).

A priori, the elementary utility function $u$ has no other significance than to serve, through (6), in the representation of the system of preferences. It has sometimes been interpreted as an 'absolute utility function' between certain prospects, that is, as allowing comparisons between differences in utility (cf. Chapter 2, Section 10). Because he has absolute utility $u$, so the argument goes, the individual tries to maximise the expected value of $u$. For example, when he compares the certain prospect containing $x_0$ and an uncertain prospect containing $x_1$ with probability $2/3$ and $x_2$ with probability $1/3$, the individual tries to find out if the gain in utility when $x_2$ is substituted for $x_0$ is twice as great as the loss in utility when $x_1$ is substituted for $x_0$. Conversely, observation of choices among uncertain prospects would reveal the underlying absolute utility function, which can thus be estimated indirectly. Obviously there is no need to take sides on this question. Elementary utility $u$ and absolute utility between certain prospects (function $\bar{S}$ in Chapter 2), can very well be considered as essentially different, even when both are considered to exist.

We can immediately verify that the quasi-concavity of $S(x)$ implies that $u(x_e)$ is also quasi-concave. For, let $\xi^1$ and $\xi^2$ be two vectors with $Q$ components such that

$$u(\xi^1) = u(\xi^2).$$

Consider two uncertain prospects $x^1$ and $x^2$, which are identical except for a state $e$ with non-zero probability, for example, the state $e = 1$, and such that $x_1^e = \xi^1$ and $x_2^e = \xi^2$. Then $S(x^1) = S(x^2)$ and the quasi-concavity of $S(x)$ implies $S[\alpha x^1 + (1 - \alpha)x^2] \geq S(x^1)$ for any number $\alpha$ such that $0 < \alpha < 1$. 
The existence of a linear utility function

Given the form (6) for $S$ and the definitions of $x^1$ and $x^2$, the inequality in question can also be written

$$\pi_1 u[\alpha x^1 + (1 - \alpha) x^2] \geq \pi_1 u(\xi^1),$$

which proves that $u(x_e)$ is quasi-concave.

Conversely, the concavity of $u(x_e)$ implies the concavity of $S(x)$ as defined by (6), and consequently also the quasi-concavity of any other function representing the same system of preferences. (Note here that the quasi-concavity of $u(x_e)$ is not sufficient.) For, let $x^1$ and $x^2$ be any two vectors with $NQ$ components:

$$u[\alpha x^1_e + (1 - \alpha) x^2_e] \geq \alpha u(x^1_e) + (1 - \alpha) u(x^2_e)$$

for all $e$ and for any number $\alpha$ such that $0 < \alpha < 1$; consequently

$$S[\alpha x^1 + (1 - \alpha)x^2] \geq \alpha S(x^1) + (1 - \alpha)S(x^2).$$

Thus a concave elementary utility function represents the choices of an individual with an aversion to risk.

In fact, when choices are represented by a linear utility function, concavity of $u(x_e)$ can be taken directly as defining aversion to risk. Given some prospect $x^0$, we associate with it the sure prospect $\bar{x}$ defined by

$$\bar{x}_{qe} = \sum_{e=1}^{N} \pi_e x^0_{qe} \quad \text{for all } q \text{ and all } e.$$

($\bar{x}_{qe}$ is therefore independent of $e$; it is the expected value of $x^0_{qe}$). Aversion to risk can be defined naturally as the property that the individual always finds the sure prospect $\bar{x}$ at least equivalent to the corresponding uncertain prospect $x^0$.† This is expressed by:

$$u \left[ \sum_{e=1}^{N} \pi_e x^0_e \right] \geq \sum_{e=1}^{N} \pi_e u(x^0_e),$$

an inequality that must be satisfied for every set of non-negative numbers $\pi_e$ whose sum is 1. This inequality then defines precisely the concavity of $u$.

6. The existence of a linear utility function‡

We must now show that the existence of a utility function of the form (6) can be deduced from some axioms relating to individual behaviour in the face of risk. To deduce this, we must modify the model so far used, since the property to be proved does not apply without additional restriction when

† As before, aversion to risk then covers the case of indifference between $x^0$ and its expected value $\bar{x}$.
‡ On the mathematical theory of this section, see P. C. Fishburn, ‘Separation Theorems and Expected Utilities’, *Journal of Economic Theory*, August 1975.
states of nature are only finite in number. However, the first axiom will allow us to define a relatively simple formulation.

**Axiom 1.** Preferences do not involve the states of nature, in the sense that they concern only the probability distribution of the vector $x_e$.

In other words, to classify a prospect $x$ in the scale of preferences, we need only give the values of the vectors $x_e$ and the probability with which each value is realised; there is no point in identifying the states for which the values in question appear. If there are only two states with the same probability (rainy and sunny weather, for example, or heads and tails in the toss of a coin), the uncertain outlook defined by $x_1 = \xi_1$ and $x_2 = \xi_2$ should, according to axiom 1, be equivalent to that defined by $x_1 = \xi_2$ and $x_2 = \xi_1$, this being true for any $\xi_1$ and $\xi_2$.

This axiom may obviously appear debatable in certain concrete situations. It seems particularly valid in lotteries and games of chance since the preferences of the individual player do not depend on the random events determining that some particular ticket, number or card will be drawn. On the other hand, in the example discussed at the beginning of this section, we assumed that needs might differ in the case of rain or of sunshine.

In fact, the axiom assumes that three concepts have been carefully distinguished: states, actions and consequences, all of which are precisely defined in decision theory. Individual choices relate solely to consequences, which are functions of states and actions. But the list of consequences must be complete. For example, if the individual has chosen (action) a complex of contingent commodities containing no umbrella in the case of rain, then the consequence in the case of rain (state) must specify that the individual will be wet. His preferences therefore relate to consequences whose description is supposed to be sufficiently precise to ensure that the states causing them do not directly affect choice. Thus, in principle there always exists a formulation of the problem which makes the axiom valid; but this formulation is sometimes too complex to be useful.

Be that as it may, axiom 1 allows a new representation of uncertain prospects. In fact, a prospect can be characterised sufficiently well by finding the probabilities with which there appear in it the different values $\xi$ which the vector $x_e$ can take a priori. For example, if $x_e$ must belong to a subset $X$ of $R^Q$, a prospect defines a distribution on $X$; two prospects defining the same distribution are equivalent (axiom 1) and will therefore be taken as identical in what follows.

We shall now assume that $x_e$ can take only a finite number of values $\xi_1, \xi_2, ..., \xi_R$. This will greatly facilitate our following discussion, and is justified by the needs of exposition, while it does not play an essential part in the theory. There is no reason why we should not think of $R$ as very large. We shall subsequently call the $\xi$, 'sure prospects'.
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To find a prospect (uncertain or sure) is to find the \( R \) probabilities \( \mu_r \) relating to each of the values \( \xi_r \) (for \( r = 1, 2, \ldots, R \)), given that

\[
\mu_r \geq 0 \quad \text{for } r = 1, 2, \ldots, R
\]

\[
\sum_{r=1}^{R} \mu_r = 1.
\]

By definition, \( \mu_r \) equals the sum of the probabilities \( \pi_e \) of all the states \( e \) for which the vector \( x_e \) equals \( \xi_r \) in the prospect under consideration. We shall also let \( \mu \) denote the vector of the \( R \) numbers \( \mu_r \) and talk of 'the prospect \( \mu \)' instead of the prospect \( x \). Similarly, the consumer's choices may be defined by a function \( S^*(\mu) \) as well as by a function \( S(x) \) satisfying axiom 1. Thus, to prove the existence of a utility function of the form (6), we must find \( R \) numbers \( u_r \) and establish that

\[
S^*(\mu) = \sum_{r=1}^{R} \mu_r u_r
\]

provides an indicator of the individual's system of preferences among the different possible prospects \( \mu \).

We shall do this, assuming that the vector \( \mu \) can be chosen arbitrarily provided that it satisfies conditions (11) and (12). The individual can obtain the prospect defined by any \( \mu \) if he wishes to and has sufficient resources to cover its value. It is here that we assume the existence of an infinite number of states, since, if there is a finite number of states with specified probabilities \( \pi_e \), each component \( \mu_r \) of \( \mu \) must be either zero or equal to one of the \( \pi_e \)'s, or to the sum of several \( \pi_e \)'s (those of the states in which the vector resulting from the prospect coincides with \( \xi_r \)).

Given any two particular prospects, \( \mu^1 \) and \( \mu^2 \), the vector \( \mu = \alpha \mu^1 + (1 - \alpha)\mu^2 \), where \( 0 < \alpha < 1 \), defines a precise prospect which attributes the probability \( \alpha \mu^1_r + (1 - \alpha)\mu^2_r \) to \( \xi_r \). In fact, this vector satisfies conditions (11) and (12). The prospect \( \mu \) thus defined constitutes a sort of 'lottery ticket', which gives the prospect \( \mu^1 \) with probability \( \alpha \) and the prospect \( \mu^2 \) with probability \( 1 - \alpha \). The prospects \( \mu^1 \) and \( \mu^2 \) can themselves be lottery tickets, in which case \( \mu \) corresponds to a lottery whose lots are the tickets for other lotteries.

Consider now the individual's system of preferences. It implies a pre-ordering on the vectors \( \mu \), that is, a relation which is complete, transitive and reflexive. Let \( \mu^1 \succeq \mu^2 \) indicate that the prospect \( \mu^1 \) is judged preferable or equivalent to the prospect \( \mu^2 \). Similarly, let \( \mu^1 \sim \mu^2 \) indicate that \( \mu^1 \) and \( \mu^2 \) are considered equivalent (\( \mu^1 \succeq \mu^2 \) and \( \mu^2 \succeq \mu^1 \)), and finally let \( \mu^1 > \mu^2 \) mean that \( \mu^1 \) is preferred to \( \mu^2 \) (\( \mu^1 \succeq \mu^2 \) but not \( \mu^2 \succeq \mu^1 \)). We need the second axiom:

**Axiom 2.** If \( \mu^1 > \mu^2 \), if \( \mu \) is some prospect and if \( 0 < \alpha < 1 \), then

\[
\alpha \mu^1 + (1 - \alpha)\mu > \alpha \mu^2 + (1 - \alpha)\mu.
\]
Similarly, if \( \mu^1 \sim \mu^2 \), then
\[
\alpha \mu^1 + (1 - \alpha)\mu \sim \alpha \mu^2 + (1 - \alpha)\mu.
\]

This axiom appears fairly natural if we consider the choice between two lottery tickets both giving \( \mu \) with probability \( 1 - \alpha \), the first also giving \( \mu^1 \) with probability \( \alpha \) and the second \( \mu^2 \) with probability \( \alpha \). If \( \mu^1 \) is preferred to \( \mu^2 \), it seems that the first lottery ticket should be preferred to the second. If \( \mu^1 \) is equivalent to \( \mu^2 \), it seems that the two tickets must also be equivalent.

However, this axiom has been criticised by those who do not admit certain of its implications.† Suppose, for example, that there is a single good, money, and three sure prospects \( \xi_1 \) giving the right to 10,000 francs, \( \xi_2 \) giving the right to 1,000 francs, and \( \xi_3 \) the right to 0 francs. Consider the three prospects:
\[
\mu^1 = [0.10 \ 0.90 \ 0]
\]
\[
\mu^2 = [0.20 \ 0.60 \ 0.20]
\]
\[
\mu = [0 \ 0 \ 1],
\]
and \( \alpha = 0.1 \). Then
\[
\mu^3 = \alpha \mu^1 + (1 - \alpha)\mu = [0.01 \ 0.09 \ 0.90]
\]
\[
\mu^4 = \alpha \mu^2 + (1 - \alpha)\mu = [0.02 \ 0.06 \ 0.92]
\]

Suppose that some prudent individual prefers \( \mu^1 \) to \( \mu^2 \) because \( \mu^1 \) gives him at least 1,000 francs, which is quite a valuable sum of money, and because the risk of getting nothing with \( \mu^2 \) (1 in 5) is not compensated for him by the increased probability of winning 10,000 francs (this probability increases from 1/10 to 2/10). If he obeys axiom 2, he must also prefer \( \mu^3 \) to \( \mu^4 \). Some economists have disputed that the second choice follows from the first. They say that the individual in question may quite logically prefer \( \mu^4 \) to \( \mu^3 \) since the two prospects have similar probabilities of gaining nothing while \( \mu^4 \) gives a probability of gaining 10,000 which is twice that in \( \mu^3 \).

The reader must judge for himself whether axiom 2 is compatible with real behaviour, as a first approximation, and whether it constitutes a norm that he would think reasonable to impose on his own choices, or on collective choices for which he might be responsible.

We still need an axiom of continuity for the system of preferences:

**Axiom 3.** Given any three prospects \( \mu^1, \mu^2 \) and \( \mu^3 \), if \( \mu^1 \succeq \mu^2 \succeq \mu^3 \), then there exists a number \( \alpha \), where \( 0 < \alpha < 1 \), such that
\[
\alpha \mu^1 + (1 - \alpha)\mu^3 \sim \mu^2.
\]

† See the discussions at the colloquium organised by the C.N.R.S., the reports of which are published in the volume *Économétrie*, Paris, C.N.R.S., 1953.
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In other words, there exists a lottery ticket that combines the two extreme prospects with appropriate probabilities and is equivalent to the intermediary prospect.

To construct a preference indicator of the form (13), let us first consider the sure prospects $\xi_r$. Since their number is finite, there exists one to which no other is preferred and one that is not preferable to any other. We can assume without loss of generality that the former is $\xi_1$ and the latter $\xi_R$. We can also assume that $\xi_1 > \xi_R$, without which all prospects are equivalent. We then set

$$u_1 = 1, \quad u_R = 0.$$  

(14)

Let us apply axiom 3 to the sure prospects $\xi_1$, $\xi_r$, and $\xi_R$, where $1 < r < R$. There exists a number $\alpha$ such that $\alpha \xi_1 + (1 - \alpha) \xi_R$ is equivalent to $\xi_r$; let this number equal $u_r$. The utilities $u_r$ of the sure prospects are then fixed. We must show that the function $S^*(\mu)$ defined by (13) is an indicator of the individual’s preferences. We shall do this for the case where $R = 3$, generalisation to any value of $R$ raising no difficulty of principle.†

![Fig. 6](image)

The vectors $\mu$ restricted by (11) and (12) are easily represented on a classical triangular diagram in which $\mu_1$, $\mu_2$ and $\mu_3$ measure distances to the three sides (cf. Figure 6). At each vertex of the triangle we represent the corresponding sure prospect $\xi_1$, $\xi_2$ or $\xi_3$. The first $\xi_1$ is, for example, the vector $(1, 0, 0)$. In this triangle, the prospect $\mu = \alpha \mu_1 + (1 - \alpha) \mu_2$ is represented by the centre of gravity $M$ of the points $M_1$ and $M_2$ representing $\mu_1$ and $\mu_2$ with which the masses $\alpha$ and $1 - \alpha$ are associated respectively. On the side $\xi_1 \xi_3$ we can let $N$ denote the prospect $\mu^N = (u_2, 0, 1 - u_2)$ which is equivalent to $\xi_2$. In order to prove that

$$S^*(\mu) = \mu_1 + \mu_2 u_2$$  

(15)

Uncertainty is an indicator of individual preferences, it is necessary and sufficient to establish that the indifference curves are straight segments parallel to $\xi_2N$. It is necessary because (15) implies this property of indifference curves. It is also sufficient since the contours of the function (15) coincide with the indifference lines and are classed in the same order.

Let $M$ be a point in the triangle corresponding to some prospect $\mu$. To fix ideas, let us assume that $M$ lies on the same side as $\xi_1$ of the line $\xi_2N$. Draw the parallel through $M$ to $\xi_2N$; it cuts $\xi_1\xi_3$ and $\xi_1\xi_2$ at $A$ and $B$ respectively. Moreover,

$$\frac{A\xi_1}{N\xi_1} = \frac{B\xi_1}{\xi_2\xi_1}.$$  \hspace{1cm} (16)

The prospects $\mu^A$ and $\mu^B$ represented by $A$ and $B$ are equivalent. Indeed let $\lambda$ denote the common value of the ratios (16). We can write

$$\mu^A = \lambda \mu^N + (1 - \lambda)\xi_1 \quad \text{and} \quad \mu^B = \lambda \xi_2 + (1 - \lambda)\xi_1.$$

But $\mu^N$ and $\xi_2$ are equivalent; axiom 2 then implies that $\mu^A$ and $\mu^B$ are also equivalent. The same axiom implies that any prospect represented by a point on $AB$ is also equivalent to $\mu^A$ or $\mu^B$ (in the statement of the axiom, take $\mu^1 = \mu^A$, $\mu^2 = \mu = \mu^B$, with $\alpha$ denoting the probability of $\mu^A$ in the intermediate prospect under consideration).

To establish the required result completely, we need only show that the indifference class contains no points other than those on $AB$. If it contains another such point, then we can show by the above reasoning that it contains the whole segment parallel to $AB$ and passing through this point. It therefore contains a point $A'$ of $\xi_1\xi_3$, distinct from $A$. But it is impossible for two distinct points of this segment to be mutually equivalent. To show this, we shall assume, for example, that $A'$ lies between $A$ and $\xi_1$. In view of axiom 2, the relation $\xi_1 > \mu^A$ implies $\mu^{A'} > \mu^A$, which contradicts the equivalence of $A'$ and $A$. But, if $A$, $A'$ and $\xi_1$ are all equivalent, then $\mu^{A'} > \xi_3$ and axiom 2 implies $\mu^{A'} > \mu^A$, which is also a contradiction. This completes our proof.

The theory whose main argument has just been given was introduced first in 1944 by von Neumann and Morgenstern as one of the foundations of their theory of games. It can usefully be generalised to the case where the probability of events is not given a priori. Subject to a certain number of axioms on individual behaviour in the choice among uncertain prospects, we can prove the existence of an elementary utility function and a (subjective) probability on the space of states, this function and this probability being representative of individual choices in the sense that, when calculated with the probabilities in question, the expected value of the elementary utility function is an indicator of preferences.† We have tried to show in Section 4 how an agent’s

choices reveal the probabilities that he attributes to the different states. The property just stated makes use of this.

7. Risk premiums and the degree of aversion to risk

The economic literature dealing with situations involving uncertainty attributes an important role to 'risk premiums'. We must see how they can be defined within our formulation.

Let $x$ be a consumption prospect containing elements of risk in the sense that the vectors $x_e$ corresponding to the different states are not all equal in this prospect. The sure prospect $\bar{x}$, the expected value of $x$, is defined by

$$\bar{x}_q = \bar{x}_{q,e} = \sum_{e=1}^{N} \pi_e x_{q,e} \quad \text{for all } q \text{ and all } e,$$

this formula having already been given at the end of Section 5. The concept of risk premium is related to the fact that $\bar{x}$ is usually preferred to $x$ so that we can deduce from $\bar{x}$ a 'premium' for obtaining another sure prospect that is equivalent to $x$. More precisely, let $\rho$ be the number such that

$$u[(1 - \rho)\bar{x}] = \sum_{e=1}^{N} \pi_e u(x_{e}),$$

where $\bar{x}$ is considered as a vector with $Q$ components. The sure prospect $(1 - \rho)\bar{x}$ is equivalent to the risky prospect $x$. The number $\rho$ can be called the 'risk premium rate'.† With the definitions given at the end of Section 5, this premium is positive if the individual has a genuine aversion to risk, and zero if he is indifferent to risk.

A parallel is often drawn between the risk premium and the subjective rate of interest defined in Chapter 10. The former results from a systematic preference for certainty and the latter from a systematic preference for the present. We saw that the rate of interest may be positive for reasons other than 'impatience'. But there is a more important reason why this parallel is dangerous.

We saw that, for optimal organisation of production and distribution or for competitive equilibrium, subjective interest rates must be the same for all individuals and must equal technical interest rates. These rates are a characteristic of the price system. Nothing similar exists for risk premiums; they cannot play a role similar to that of interest rates in economic calculus. Only the system of contingent prices has solid justification here.

However, consideration of risk premiums leads naturally to a measure of the degree of aversion to risk. Let $x$ be a prospect which is fairly near

† It might be thought preferable to establish a marginal definition of risk premium by comparing the risky prospect $x$ with infinitely close prospects with diminishing risk. But such a marginal definition does not seem to lead to any significant new result.
Uncertainty:

\[ x_e = \bar{x} + \xi_e \]  

where \( \xi_e \) is a vector with \( Q \) components considered as small, and zero expectation:

\[ \sum_e \pi_e \xi_e = 0 \]  

We can approach \( u(x_e) \) by a limited expansion:

\[ u(x_e) \sim u(\bar{x}) + \xi'_e \text{grad } u + \frac{1}{2} \xi'_e U \xi_e \]

where \( \xi'_e \) denotes the transpose of \( \xi_e \), \( \text{grad } u \) is the vector of the derivatives of \( u(\bar{x}) \) with respect to its \( Q \) arguments \( \bar{x}_e \) and \( U \) is the matrix of the second derivatives of the same function. It follows from (20) that

\[ \sum_e \pi_e u(x_e) \sim u(\bar{x}) + \frac{1}{2} \sum_e \pi_e \xi'_e U \xi_e. \]  

Let \( V \) be the covariance matrix of \( x_e \):

\[ V = \sum_e \pi_e \xi_e \xi'_e \]  

(this is a square matrix of order \( Q \)). We can write:

\[ \sum_e \pi_e \xi'_e U \xi_e = \text{tr } UV \]  

(if \( A \) is a square matrix, \( \text{tr } A \) denotes the sum of its diagonal elements). Formula (21) can then be written:

\[ \sum_e \pi_e u(x_e) \sim u(\bar{x}) + \frac{1}{2} \text{tr } UV. \]  

Since the risk premium rate \( \rho \) is necessarily small whenever the \( \xi_e \) are small, we can similarly approach \( u[(1 - \rho)\bar{x}] \) by

\[ u[(1 - \rho)\bar{x}] \sim u(\bar{x}) - \rho \bar{x}' \text{grad } u. \]  

In view of (18), comparison of (24) and (25) implies

\[ \rho \sim -\frac{\text{tr } UV}{2\bar{x}' \text{grad } u}. \]  

Therefore the risk premium rate \( \rho \) depends on the covariance matrix of \( x_e \) and on the matrix \( -U/\bar{x}' \text{grad } u \). The latter can be taken as a measure of the aversion to risk.

In the particular case where there is a single good (\( Q = 1 \)), the matrix \( V \) reduces to \( \sigma^2 \), the variance of \( x_e \), and (26) becomes

\[ \rho \sim -\frac{u''(\bar{x}) \sigma^2}{2u' \cdot \bar{x}'}. \]  

This is why \( -\bar{x}u''/u' \) is called the 'relative degree of risk aversion' while \( -u''/u' \) is called the 'absolute degree of risk aversion'. If the function
The exchange of risks

8. The exchange of risks

We can see intuitively that, in an exchange economy, individuals with the least aversion to risk accept the most uncertain prospects and so in a sense act as insurers for the other individuals. We can illustrate this graphically for the simple case of a single good, two equally probable states, and two exchanging agents.

In an Edgeworth diagram, let $P$ be the point representing initial resources, which we assume to be equally distributed between the two parties to exchange; resources are much greater in state 1 than in state 2. If we adopt assumption 1 and recall that $\pi_1 = \pi_2$, we know that the first consumer's indifference curves have a slope of $45^\circ$ where they cut the bisector of the angle $O$, and so also have the second consumer's indifference curves where they cut the bisector of the angle $O'$. If the first consumer has a greater aversion to risk than the second, the concavity of his indifference curves is more marked. The equilibrium point is therefore to the left of $P$. It obviously involves a higher contingent price for state 2 than for state 1. At these prices, the first exchanger ensures for himself a consumption that does not greatly depend on the state of nature; the second exchanger is willing to give up part of his resources if state 2 is realised, in exchange for a larger quantity that he will receive if state 1 is realised.†

Let us look at this question in more general terms.

† If there are no objective probabilities for the states, the exchange can be explained both by differences in needs or attitudes to risk and by differences in the subjective probabilities that the exchangers attribute to the states.
Suppose that, in a competitive equilibrium where markets exist for contingent commodities, the risky prospect $x$ has been chosen by a consumer who has an aversion to risk. Then the sure prospect $\bar{x}$, the expected value of $x$, must be greater than $x$ in value, otherwise it would have been chosen in preference to $x$. Consequently

$$\bar{p}\bar{x} > \sum_{e=1}^{N} p_e x_e$$

(28)

where $\bar{p}$ is the vector with $Q$ components defined by

$$\bar{p}_q = \sum_{e=1}^{N} p_{qe} \quad q = 1, 2, \ldots, Q.$$

(29)

This is the price vector for unconditional delivery already discussed in Section 3.

With the definition of $\bar{x}$ given by (17), the inequality (28) can be written:

$$\sum_{e=1}^{N} (\pi_e \bar{p} - p_e) x_e > 0.$$  

(30)

But (29) and the fact that the sum of the $\pi_e$ is 1 imply

$$\sum_{e=1}^{N} (\pi_e \bar{p} - p_e) = 0.$$  

(31)

Comparison of (30) and (31) shows that, for a given good, $x_{qe}$ must in most cases be large when $p_{qe} < \pi_e \bar{p}_q$.

Inequality (30) applies to a specified consumer. If all consumers have an aversion to risk, the corresponding inequalities can be summed so that (30) applies to the aggregate consumption prospect. In particular, in an exchange economy the latter must equal the prospect $\omega$ of initial resources, and therefore

$$\sum_{e=1}^{N} (\pi_e \bar{p} - p_e) \omega_e > 0.$$  

If there are two states and if $\omega_{qe}$ varies from one state to the other only for a single good $q = g$, then in view of (31) the inequality becomes

$$(\pi_1 \bar{p}_g - p_{g1})(\omega_{g1} - \omega_{g2}) > 0.$$  

If, for example, $\omega_{g1} > \omega_{g2}$, then contingent prices must be such that

$$\frac{p_{g1}}{\pi_1} < \bar{p}_g < \frac{p_{g2}}{\pi_2}.$$  

(33)

The ratio between the contingent price and the probability of the corresponding state is smaller for the state in which the resource is less scarce.

The preceding discussion of general equilibrium assumes the existence of markets for all contingent commodities. New features appear when the
market system is incomplete, that is, when one can make conditional sales or purchase of some goods but not of others.

The study of such cases shows that agents may then find it advantageous to follow sequential strategies: they may use initially available exchange opportunities while keeping the option of making new exchanges when the state of nature will be known. If subjective probabilities given to various events differ among agents, some of them often find it interesting to initially buy more than they need for consumption, so as to resell later on. This explains the occurrence of speculation, which would have no role to play in the ideal case when markets would exist for all contingent commodities.† We shall come back on speculation in the next chapter, Section 6.

9. Individual risks and large numbers of agents

Up till now we have assumed that uncertain events involve all agents directly. There are some events of this type, but many risks are in fact very localised; the risks against which one insures in most cases concern a single person or a small number of persons. Similarly, the physical or technical risks affecting many productive activities are fairly largely independent of each other.

We can easily imagine that the social consequences of individual risks are quite different from those of collective risks affecting all agents or a large proportion of them. In particular, it seems that, for efficient allocation of individual risks, the price of an insurance contract should be equal to the value of the risk covered multiplied by its probability. More precisely, if there is a large number of agents and if only individual risks exist, conditional prices should be independent of the states to which they refer, and contingent prices should be proportional to probabilities. We shall see this illustrated by a simple case, without trying to give a rigorous proof.‡

Let us consider an exchange economy for which the vector of resources is sure. Let us assume that the risks affect only the needs of individual 1, to whom assumption 1 does not therefore apply. The utility function of the other consumers is

$$\sum_{e} \pi_e u_t(x_{ie}), \quad i = 2, 3, \ldots, m$$  \hspace{1cm} (34)

† On these questions see J. Hirshleifer, 'Speculation and Equilibrium: Information, Risk and Markets', Quarterly Journal of Economics, November 1975.

With an optimum we can associate a system of contingent prices \( p_{qe} \) such that each consumer maximises his utility function (34) subject to a budget constraint

\[
\sum_{\varepsilon} \sum_{q} p_{qe} x_{i,q,\varepsilon} \leq R_i. \tag{35}
\]

The equality between marginal rates of substitution and price-ratios implies here, for a given good \( q \) and two distinct states \( e \) and \( \varepsilon \):

\[
\frac{u'_{i,q}(x_{i,e})}{u'_{i,q}(x_{i,\varepsilon})} = \frac{p_{qe}}{p_{q\varepsilon}} \quad \frac{\pi_{e}}{\pi_{\varepsilon}}. \tag{36}
\]

If there is a large number of individuals, then in all circumstances the first consumer takes up only a small part of the resources. The quantities \( \omega_q - x_{1,\varepsilon} \) distributed among the others do not depend to any great extent on the state \( e \).

We can therefore assume that the allocation received by a consumer \( i \neq 1 \) does not depend much on \( e \). The ratio on the left of (36) is therefore near 1 and the \( p_{qe} \) are nearly proportional to the \( \pi_{e} \).

In short, we can write

\[
p_{qe} \sim \pi_{e} \bar{p}_q. \tag{37}
\]

In view of (1) and since \( \bar{p}_q = 1 \), it follows that

\[
\bar{p}_{qe} \sim \bar{p}_q. \tag{38}
\]

This conclusion is unrelated to the fact that a single individual is affected by uncertainty. If all were subject to distinct personal risks, a 'state of nature' \( e \) would be a complete specification of the situations of the different individuals. By comparison with a given state \( e \), there would exist states \( \varepsilon \) which differ from \( e \) only in the situation of one single individual. Equation (36), written for such pairs of states \( e \) and \( \varepsilon \) then implies that \( p_{qe}/\pi_{e} \) approximately equals \( p_{q\varepsilon}/\pi_{\varepsilon} \), which can be generalised to all states step by step.

The approximate formulae (37) and (38) lead us back to a remark at the end of Section 3. We then saw that there were too few existing markets to determine the very numerous \( p_{qe} \) relating to a fairly exhaustive sample of goods and states. But if we know that \( p_{qe} \) is equal to \( \pi_{e} \bar{p}_q \), then we need only know the \( \bar{p}_q \) applying to sure deliveries. The markets necessary for the formation of an appropriate price system are therefore much less numerous than it appeared at first sight. Those relating to contingent commodities are required only to the extent that collective risks are involved.

Note also that a full study of individual risk insurance should take into consideration 'moral hazard', which raises subtle theoretical problems: some actions taken by exposed individuals may increase or decrease the probability of the insured risk. An efficient allocation of risk would often require not only that individuals take insurance contracts, but also that
they somewhat protect themselves; but once insured they may have insufficient incentives for so doing.†

10. Profit and allocation of risks

In Section 3 we saw that, in a market equilibrium generalising those investigated in Chapters 4 and 5, producers were not subject to any risk; they could immediately realise the sure value of their chosen production plans. In other words, they would insure against the risk of loss.

When (37) applies, the value of a production plan \( y_j \) of the \( j \)th producer is

\[
P_j = \sum_e \pi_e \bar{p}_j e
\]

(39)

where \( y_{je} \) is the vector with the \( Q \) components \( y_{jec} \). Now, \( \bar{p}_j e \) is the profit \( P_{je} \) realised by \( j \) in the eventuality \( e \). The value \( P_j \) of the production plan is therefore the expected value of the profit. The reason why the producer can restrict his attention to this expected value \( P_j \) is that he is able to contract by giving up the difference \( P_{je} - P_j \) when it is positive but covering himself against it when it is negative.

Such contracts are extremely rare in reality. It is nevertheless true that, for an efficient allocation of resources, producers ought to maximise the expected value of their profits, at least to the extent that they are subject only to individual risks.

It is often assumed that, in real life, firms behave in the face of risk as consumers do. Unable to insure, they give greater weight to losses than to gains of equal probability. Instead of maximising \( P_j \), the expectation of the \( P_{je} \), the \( j \)th producer maximises

\[
\sum_e \pi_e u_j(P_{je})
\]

(40)

where the function \( u_j \) represents the ‘utility’ attributed to the profit \( P_{je} \) and is strictly concave because of aversion to risk. Such an attitude would give rise to some inefficiency in the organisation of production.

It would also have repercussions on the distribution of income. If competition is free, if in fact firms maximise their expected profit, pure profit, excluding rent and interest on capital, is on average zero in the equilibrium. Indeed we know that constant returns to scale imply that the equilibrium values of the \( P_j \) are zero; therefore on average, the \( P_{je} \) are zero. (We shall not repeat the reasons justifying constant returns to scale.)

But, if firms maximise a function such as (40) and if the \( u_j \) are strictly concave, profits are positive on average. Indeed, consider small variations \( dP_{je} = P_{je} d\lambda \) relative to equilibrium profits \( P_{je} \); such variations are possible

since there are constant returns to scale. The variation in (40) must be zero (dλ ≥ 0):

$$\sum_e \pi_e P_{je} u'_j(P_{je}) = 0.$$  \hspace{1cm} (41)

Also, the strict concavity of $u_j$ implies

$$(P_{je} - P_j)[u'_j(P_{je}) - u'_j(P_j)] \leq 0$$

where the inequality holds strictly if $P_{je} ≠ P_j$ (see theorem 1 of the Appendix). Consequently

$$\sum_e \pi_e (P_{je} - P_j)[u'_j(P_{je}) - u'_j(P_j)] < 0$$  \hspace{1cm} (42)

except in the trivial case where all the $P_{je}$ are equal. Since $P_j$ is the expectation of the $P_{je}$, we can write

$$\sum_e \pi_e (P_{je} - P_j)u'_j(P_j) = 0.$$  \hspace{1cm} (43)

Now, (41), (42) and (43) imply directly

$$- P_j \sum_e \pi_e u'_j(P_{je}) < 0$$

and, since the multiplier of $- P_j$ is obviously positive,

$$P_j > 0.$$  \hspace{1cm} (44)

Aversion to risk, which, according to prevailing opinion characterises the behaviour of firms, is thus a new cause for the existence of positive profits. Apart from competitive imperfections, apart from disequilibria related to innovations, the caution of firms in the face of the risk of loss explains why pure profits are on average positive.

11. Firms' decisions and financial equilibria

To assume as we have just done that each firm $j$'s risk taking behaviour is autonomous and that its decisions can be expressed by an exogenous utility function such as (40) is to ignore an important aspect of the real world. The behaviour of firms is clearly the result of the behaviour of certain people. For an individual firm it is the owner-manager who determines behaviour. The situation is less clear-cut for large joint stock companies since management attitudes matter; however it is still possible to assume that major decisions result from the behaviour of the shareholders.

The relationship between firms' decisions in the face of risk and the behaviour of individuals is all the more complex because it very often results from the choice of those who decide to become the head of a firm or a major shareholder in a company; these people do not fear risks too
much. In other words, we should not only relate each firm's behaviour to that of its owner or owners, but we should also explain why this firm belongs to him or them.

In an economy with private property and stock markets firms are bought and sold and shares in large companies are exchanged. These operations can be considered as determining an equilibrium in the distribution of inherited wealth and in risk-bearing. What is the efficiency of this equilibrium? The attempt to define and analyse it has led to a fuller understanding of the phenomena. Here we can briefly discuss some of the main steps in the reasoning.†

(i) A model

We shall adopt the following very simple model with a single product and two dates, where only operations at the second date are affected by uncertainty. The jth firm’s activity vector \( y_j \) has \( N + 1 \) components: \( y_{j0} \) represents net output at date 0 while \( y_{je} \) is net output at date 1 given that the state \( e \) is realised, \( (e = 1, 2, \ldots, N) \). We can also say that \( -y_{j0} \) is input at date 0 and \( y_{je} \) is output at date 1. The ith consumer, who initially owns the quantity \( \omega_i \) of the product and shares \( \theta_{ij} \) of the different firms \( (j = 1, 2, \ldots, n) \) consumes \( x_{i0} \) at date 0 and \( x_{ie} \) at date 1, given \( e \) is established. Clearly equilibrium in operation on goods implies:

\[
\sum_i x_{i0} = \sum_i \omega_i + \sum_j y_{j0} \tag{45}
\]

\[
\sum_i x_{ie} = \sum_j y_{je} \quad e = 1, 2, \ldots, N \tag{46}
\]

The existence of stock markets means that individuals can exchange their shares in firms at prices which express the values of the firms. Let \( q_j \) denote the value of the jth firm. So the ith consumer can sell his holding \( \theta_{ij} \) in \( j \) at the price \( \theta_{ij} q_j \). After such operations considered to be carried out at date 0 he has holdings \( t_{ik} \) in the different firms \( k = 1, 2, \ldots, n \). The product can also be borrowed and lent at the rate of interest \( \rho \). Let \( u_i \) be the net lending agreed by the ith individual at date 0. At that date his budget equation is

\[
x_{i0} + u_i + \sum_j t_{ij} q_j = \omega_i + \sum_j \theta_{ij} q_j. \tag{47}
\]

Since everything stops at date 1 the firms’ profits will then be distributed among their owners. Now if the state \( e \) is realised, the profit of

the jth firm will be
\[ P_{je} = y_{je} + (1 + \rho)y_{j0}. \]  
(48)
So the ith consumer's budget equation at date 1, given \( e \), will determine his consumption
\[ x_{ie} = \sum_j t_{ij}P_{je} + (1 + \rho)u_i \quad e = 1, 2, \ldots, N. \]  
(49)

In such an economy we shall be interested in a certain type of non-cooperative equilibrium. This concept will have a close similarity with a competitive equilibrium but will assume that consumers have fuller information and that a particular decision rule is followed by firms.

Clearly the ith individual is assumed to know stock-market prices, that is, the \( q_i \) and \( \rho \), and to take them as given. But he is also assumed to know and take as given the firms' decisions, or, more precisely, their results, the \( P_{je} \) (for \( j = 1, 2, \ldots, n \) and \( e = 1, 2, \ldots, N \)). So his behaviour can be expressed by determination of the quantities \( x_{i0}, x_{ie}, t_{ij} \) and \( u_i \) which maximise a utility function \( S_i(x_i) \) subject to \( N + 1 \) constraints (47) and (49).

After elimination of Lagrange multipliers, the first order conditions for maximisation reduce to
\[ \sum_e \sigma_{ie} = \beta \]  
(50)
\[ \sum_e P_{je}\sigma_{ie} = q_j \quad j = 1, 2, \ldots, n \]  
(51)
where by definition \( \beta \) is the discount factor and \( \sigma_{ie} \) the marginal rate of substitution
\[ \beta = \frac{1}{1 + \rho} \quad \sigma_{ie} = \frac{\delta S_i}{\delta x_{ie}} \bigg/ \frac{\delta S_i}{\delta x_{i0}}. \]  
(52)
(Obviously this marginal rate of substitution is a function of \( x_i \) and the \( N + n + 2 \) equations (47), (49), (50) and (51) are assumed to determine uniquely the equilibrium for the ith consumer.)

(ii) Decisions of firms

How must the jth firm behave, that is, how is the vector \( y_j \) determined? To answer this question let us first consider the case of a single proprietor, the ith individual \( (t_{ij} = 1) \). Naturally he tries to maximise the value \( q_j \) of the firm; as its head, he no longer takes this value as given, but as the result of choosing \( y_{j0} \) and \( y_{je} \); so he tries to maximise the left hand side of (51) where the \( P_{je} \) are replaced by the expression given for them by (48). Basically the head of the firm acts as if his own marginal rates of
substitution would fix the (discounted) prices of contingent commodities, the numéraire being the product at date 0 and as if he had no influence on these prices.

Considering the general case we shall make here the assumption that the \(j\)th firm tries to maximise

\[
\sum_e p_{je} y_{je} = \sum_e p_{je} y_{je} + y_{j0}
\]

(53)

taking the \(N\) numbers

\[
p_{je} = \sum_i t_{ij} \sigma_{ie}
\]

(54)
as given.

((53) takes account of the fact that the sum of \(p_{je}\) for all \(e\) is equal to the discount factor in view of (50) and because the sum of holdings \(t_{ij}\) for all the individuals is 1.) In short, the \(j\)th firm behaves as in perfect competition and as if the prices of contingent commodities were the \(p_{je}\). Intuitively it may appear normal to determine these prices by (54); there are other possible justifications which we shall not discuss here.†

If the technical constraints on the \(j\)th firm are represented by the production function

\[
f_j(y_j) = 0
\]

(55)

then equilibrium for the firm is determined by (55) and the following \(N\) equations resulting from the first order conditions after elimination of Lagrange multipliers:

\[
\varphi_{je} = p_{je} \quad e = 1, 2, \ldots, N
\]

(56)

where \(\varphi_{je}\) is the marginal rate of substitution

\[
\varphi_{je} = \frac{\partial f_j}{\partial y_{je}} / \frac{\partial f_j}{\partial y_{j0}}.
\]

(57)

In this general equilibrium model the endogenous variables are the physical quantities \(x_{i0}, x_{ie}, y_{j0}, y_{je}\), financial assets \(u_i, t_{ij}\) and prices \(q_j, p\) (leaving aside intermediate variables such as \(P_{je}\) or \(p_{je}\)). The number of these endogenous variables is \(m(N + n + 2) + n(N + 2) + 1\). They are related by (45), (46), (47), (49), (50), (51), (55) and (56) to which we must add the financial equilibria

\[
\sum_i u_i + \sum_j y_{j0} = 0
\]

(58)

\[
\sum_j t_{ij} = 1 \quad j = 1, 2, \ldots, n.
\]

(59)

† See Dréze, op. cit.
So there are in all $m(N + n + 2) + n(N + 2) + N + 2$ equations but they are not independent since there exist $N + 1$ 'Walras identities'; first, the sum of (46) and (58) is identically equal to the sum of the $m$ equations (47) in view of (59) and of the fact that the sum of the $\theta_{ij}$ is 1 for all $j$; second, for all $e$, when we sum equations (49) for $i = 1, 2, \ldots, m$ and take account of (58), (59) and the definition of $P_{je}$ by (48), then equation (46) results identically. In short, a count of independent equations leads us to find precisely the number of endogenous variables.

Is risk efficiently distributed in such a general equilibrium? In other words, is a general equilibrium a Pareto optimum? It is interesting to note that the answer may be positive if the number of firms is sufficiently large relative to the number of events.

(iii) *A favourable case*

Consider equations (50) and (51) applying to a particular consumer $i$. The number of equations is $n + 1$; but there are only $N$ variables which depend on this consumer's identity, namely the $\sigma_{ie}$. If $n + 1 \geq N$ we can expect that the $\sigma_{ie}$ are in fact independent of $i$; for, the system of $n + 1$ equations (50) and (51) can be considered as relating the $N$ variables $\sigma_{ie}$ as functions of $\beta$, the $P_{je}$ and the $q_j$; now this must mean that these variables are determined uniquely if $n + 1 \geq N$, since it would be very unlikely that the $nN$ numbers $P_{je}$ take values such that the system (50)–(51) has rank less than $N$. Since $\beta$, $P_{je}$ and $q_j$ are the same for all $i$, the $\sigma_{ie}$ so determined must be independent of $i$.

If $n + 1 \geq N$ and if the marginal rates of substitution $\sigma_{ie}$ are therefore independent of $i$, we can denote them by $p_e$. We see then that (54) and (59) imply $p_{je} = p_e$ while (56) implies $q_{je} = p_e$. Thus the same marginal rate of substitution between the contingent commodity $e$ and the good 0 applies to all agents, consumers and producers; under the usual convexity assumptions this guarantees that the equilibrium is a Pareto optimum.

We can also see that in this case the assumed stock markets function so as to lead to an equilibrium which is just that generalising the familiar concept discussed in Chapter 5 and applying it to the case of uncertainty. It is a competitive equilibrium with markets for all contingent commodities. The number of firms is assumed to be large enough so that the stock market precisely determines the prices of all contingent commodities.

To verify this, let us consider the equations of this equilibrium with contingent commodities. To the $N + n + 1$ equations (45), (46) and (55) we must add the consumers' $m$ budget equations

$$x_{i0} + \sum_e p_{e} x_{ie} = \omega_i + \sum_{j} \theta_{ij} \left[ y_{j0} + \sum_{p} p_{p} y_{je} \right]$$

(60)
and the \((n + m)N\) price equilibrium equations

\[
p_e = \sigma_{ie} = \varphi_{je} \quad \text{for all } i, j, e.
\]

(61)

These equations determine the \((n + m)(N + 1) + N\) endogenous quantities \(x_{i0}, x_{ie}, y_{j0}, y_{je}, p_e\) (in fact there is one redundant equation because of the Walras identity).

Now, all the above equations are satisfied by competitive equilibrium with stock markets in the case where system (50)–(51) implies that the \(\sigma_{ie}\) are independent of \(i\) so that we can set \(\sigma_{ie} = p_e\). To find the \(i\)th consumer’s budget equation (60) we need only take account of the resulting values of \(\rho, \beta\) and the \(q_j\) and enter them in (47), (48) and (49).

Conversely, if competitive equilibrium with markets for all contingent commodities has been determined, we can deduce the values \(q_j\) of firms, the discount factor \(\beta\) and the \(P_{je}\) from (48), (50) and (51). Except in special circumstances we can then solve the system of \(N\) equations (49) to find the \(n + 1\) variables \(u_i\) and \(t_{ij}\) since \(n + 1 \geq N\). The budget equation (60) then shows that (47) is satisfied. So we come back to competitive equilibrium with stock markets.

To check on this equivalence, we can see how the \(i\)th consumer can acquire a unit of a particular contingent commodity \(e\) on the stock markets. He need only solve the \(N\) equations (49) after setting \(x_{ie} = 1\) and \(x_{te} = 0\), for \(e \neq e\), in their left hand sides. Now we can see that the value of the resulting ‘portfolios’ will be exactly \(p_e\). If, for example, we take the case where \(N = n + 1\) we see that the row-vector \(z_e\) whose elements are \((1 + \rho)u_i\) and the \(n\) appropriate values of the \(t_{ij}\) is \(1_eB^{-1}\) where \(1_e\) is the row-vector whose component in the \(e\)th position is 1 and whose other components are zero while \(B\) is the matrix whose first row is 1 and whose \((j + 1)\)th row has as elements the \(P_{je}\) \((e = 1, 2, \ldots, N)\). With this notation the system (50)–(51) can be written \(Bp = \hat{q}\) where the \(p_e\) are the elements of the vector \(p\) while the first element of the vector \(\hat{q}\) is \(\beta\) and its \((j + 1)\)th element is \(q_j\). The value of the portfolio is \(z_e\hat{q}\), that is \(1_e\rho\) or \(p_e\).

The case where market equilibrium involves implicit determination of the prices of contingent commodities is of particular interest \(\text{vis-à-vis}\) the principle chosen for firms’ decisions. For in this case we can say that the shareholders of the \(j\)th firm are unanimous as to the best choice of vector \(y_j\). The \(i\)th individual wishes the firm to maximise

\[
\sum_e \sigma_{ie}P_{je} = \sum_e \sigma_{ie}y_{je} + y_{j0}
\]

(62)

where the \(\sigma_{ie}\) are taken as fixed at their equilibrium values. Where all the individuals have the same marginal rates of substitution \(\sigma_{ie}\), maximisation is the same for all. In short, the principle adopted in (54) of taking the \(t_{ij}\) as weights for finding the \(p_{je}\) is no longer important.
(iv) Multiplicative uncertainty

The case where the system (50)-(51) implies that the $\sigma_{ie}$ are determined (uniquely) and therefore independently of $i$ is, however, a very special case. It must be expected that the number of firms, that is, the number of securities, is much less than the number of states of nature. This was stated at the end of Section 3. So the existence of stock markets is not sufficient to ensure efficiency in the distribution of risk. In equilibrium, the various consumers will in most cases have different marginal rates of substitution between two given contingent commodities.

However a production optimum may conceivably be achieved, failing a Pareto optimum; it is even conceivable that firms’ decisions are in accord with the wishes of all their shareholders even if the distribution of risk is not optimal. We shall end our discussion with a case where this is so, whatever the number $n$ of firms and the number $N$ of events.

In this case the technical constraints on production are not expressed by the $n$ equations (55) but by the following $nN$ equations:

$$y_{je} = b_{je}g_j(y_{j0}) \quad \text{for all } e \text{ and } j,$$

where the coefficients $b_{je}$ and the functions $g_j$ are given. Random variations in output are independent of the chosen input and occur multiplicatively. In some respects this description of technical constraints may appear preferable to that given by the production functions $f_j$ whose differentiability may be suspect. However it must be remembered that in the real world there is a multiplicity of products and that the choice of the factor mix is often motivated by the concern to reduce the harmful effects of such and such random events.

Be that as it may, if the technical constraints are expressed by (63) then the criterion (62) which the $i$th individual should come to select spontaneously for the $j$th firm is

$$r_{ij}g_i(y_{j0}) + y_{j0}$$

where the number

$$r_{ij} = \sum_e \sigma_{ie}b_{je}$$

does not depend on $y_j$. But (51) can be written

$$r_{ij}g_j(y_{j0}) + y_{j0} = g_j$$

which shows that in the equilibrium $r_{ij}$ is independent of $i$. Thus, given equilibrium on the stock market, all the individuals will be induced to choose the same maximisation criterion when they are considering the $j$th firm’s production plan. In this case they will again be unanimous.
The problems raised by the allocation of resources are often related to the distribution of relevant information among the different agents of the society in question. This has become more and more apparent in the course of the preceding chapters where we concentrated mainly on a particular information structure as defined precisely in Chapter 8: each agent has knowledge of his own wants, resources and opportunities but has no knowledge of those of the other agents.† There are two important theoretical questions here; one is to find out if the price system functions adequately in such a context, the other is to determine possible methods of exchanging information which could finally lead to an efficient allocation of resources.

The treatment of uncertainty leads naturally to the discussion of other problems and other information structures. Sometimes we must take account of the fact that many decisions are sequential; they are made progressively as information is obtained. Sometimes we must consider certain transactions which have not the same significance to the two parties involved because they are unequally informed about the object of the transaction. Sometimes we have to consider cases where only some of the agents possess information which bears directly on the opportunities of other agents. Sometimes we must ask when it is worth while to bear the cost of acquiring additional information.

There are so many different issues and the treatment of most of them is so relatively recent that we cannot even hope to introduce them all in this chapter. Instead we shall draw attention to the existence of certain difficulties in the allocation of resources, to their effects on the organisation of economic operations and to recent developments in theory which are often difficult but still very interesting.

† In Chapter 6, on the other hand, in the discussion of imperfect competition a different information structure was adopted in most cases, that is, the structure where each agent has knowledge of the other agents’ needs, resources and opportunities as well as his own.
1. The state of information

The formal description of an agent's state of information may be conceived in various ways. Here we shall choose the simplest one, which proceeds from the first representation of uncertainty where probability needs not enter.

If \( e \) denotes a state of nature and \( \Omega \) the set of all possible states, then to have complete information is to know which \( e \) of \( \Omega \) applies; but in more general terms to be informed is to know that \( e \) belongs to a subset \( H \) that is more restricted than \( \Omega \). This subset can be said to be the information possessed by the agent in question. We can also say that the information \( H^1 \) is at least as precise as the information \( H^2 \) if \( H^1 \) is contained in \( H^2 \).

As we have seen systematically in this book, problems of the allocation of resources concern the organisation of decisions and hence assume a certain perspective. Where these problems are concerned, to say that an agent \( z \) is better informed than another agent \( j \) usually refers to their respective situations vis-à-vis information rather than to the sets \( H_i \) and \( H_j \) representing their information in some particular case. This is why an agent's 'state of information' must be defined with some reservation.

More precisely, this state of information is a partition \( \mathcal{J} \) of the set \( \Omega \) of states of nature, that is, a list of a certain number of disjoint sets \( H^k \) whose union coincides with \( \Omega \). To say that an agent's state of information is \( \mathcal{J} \) is to say that, in each particular case, he will know to which set \( H^k \) of \( \mathcal{J} \) the true state of nature \( e^0 \) belongs. We can also say that he receives a 'signal' \( s(e) \) telling him which of the sets \( H^k \) applies; by definition, \( s(e) \) is such that \( e \in s(e) \) for all \( e \).

The \( j \)th agent will then be 'at least as well informed' as the \( j \)th agent if the partition \( \mathcal{J}_i \) is 'at least as fine' as the partition \( \mathcal{J}_j \), that is, if \( H^1 \in \mathcal{J}_i \) implies that there exists \( H^2 \in \mathcal{J}_j \) such that \( H^1 \subset H^2 \). We can also say that \( s_i(e) \) denotes a set contained in \( s_j(e) \), for all \( e \).

An agent's state of information can obviously evolve through time. If we are referring to states of nature which are permanent vis-à-vis the problem under consideration, then we generally assume that the agent does not forget previous signals, so that he becomes better and better informed (or rather, he is at least as well informed at time \( t^2 \) as at the previous time \( t^1 \)).

To define an 'information structure' is to define the different agents' states of information, or their states of information at different dates if time is involved.

Clearly the above definitions do not exclude the introduction of probabilities for the states of nature. Rather, such probabilities should be taken into account for certain problems. This can easily be done on the basis of the \( \pi_e \)'s attributed to the different states \( e \) of \( \Omega \). Clearly we are dealing here with 'prior probabilities', that is, they are attributed prior to
When to decide?

any information that is studied within the model (previous information is generally accounted for in the definition of Ω and the π_e). Whenever we shall introduce different agents, 'objective probabilities', that is, probabilities common to all agents, will be involved.

Anyone who has information that the true state of nature belongs to H and has no other information, assigns a zero probability to states outside H and a 'posterior probability' π(e/H) to the states e of H; this probability is calculated by the usual formula

$$\pi(e/H) = \frac{\pi_e}{\sum_{e \in H} \pi_e} \quad \text{for } e \in H$$

$$\pi(e/H) = 0 \quad \text{for } e \notin H.$$  

If an agent i is at least as well informed as another agent j, then for any e^0 his posterior probability distribution will be at least as concentrated as j's. This is such a natural property that it could be considered as a starting-point for the definition of the state of information of the different agents.

The receipt of information can clearly modify choice. This is particularly easy to understand in the case where objective probabilities exist and where choices can be represented by a linear utility function of the type introduced in the previous chapter (see, for example, Chapter 11, Section 5).

If a decision d must be chosen within a set D and if the utility of the result of this decision is u(d, e) in the case where the state e is realised, then the utility of d in the absence of information is

$$S(d) = \sum_{e=1}^{N} \pi_e u(d, e).$$  

But, if we know that e belongs to H, then it becomes

$$S(d/H) = \sum_{e=1}^{N} \pi(e/H) u(d, e).$$

We note that, naturally, the posterior utility is now unaffected by values of u(d, e) corresponding to states e which do not belong to H. Depending on whether the decision is made before or after the receipt of information H, either S(d) or S(d/H) must be maximised. Clearly the best decision is not generally the same in both cases.

2. When to decide?

Proper account must be taken of information structures when discussing problems of the allocation of resources. This appears obvious;
however it is not always customary nor easy to do this in practice. We
can illustrate this by considering the relationship between irreversibility
and the probable future receipt of new information.

Most decisions involve the future; in many cases, the different feasible
decisions do not do so to the same degree. So we go on to distinguish
between irreversible and less irreversible decisions. If the options open to
the agents include waiting, then this is the classic type of reversible
decision; on the other hand, the decision to construct a certain kind of
factory in a certain place does in most cases exclude building it elsewhere
to some other design. Decisions about the environment and the use of
land often involve irreversibility; before deciding to push a road through a
forest, it may be advisable to seek further information about traffic
developments and the ecological balance of the region.

The problem here is not really the problem of choosing the best
moment to carry out an investment since this arises anyway in the
absence of uncertainty. The present problem is to know whether or not to
defer a decision until new information has been obtained, given that
otherwise the operations involved by the decision should have been
started immediately.

For the simplest possible context, let us assume that there are only
three possible decisions: \( d^0 \), which must be made before any information is
obtained, \( d^1 \) and \( d^2 \); the choice between \( d^1 \) and \( d^2 \) can be made after the
receipt of information. For example, \( d^0 \) might be “build such and such a
road during this decade”, while \( d^1 \) might be “build the road during the
next decade” and \( d^2 \) “abandon the project completely”. We also assume
that if no information was expected, \( d^0 \) would be chosen and we must
study how we should proceed in order to take account of the expected
future information. We shall then go on to verify the commonsense view
that the more precise the future state of information, the stronger are the
motives for postponing the decision.

Let us adopt the context where choices are governed by a linear utility
function as defined by (2). By hypothesis

\[
S(d^0) > \text{Max} \{S(d^1), S(d^2)\}. \tag{4}
\]

But, if the state of information is \( \mathcal{I} \) before the choice is made between \( d^1 \)
and \( d^2 \), this is not the important inequality. \( S(d^0) \) must rather be
compared with \( S \) (not \( d^0 \)), that is, with a quantity which we can write
\( S(d^0; \mathcal{I}) \): the expected value of the level of utility obtained when \( d \) is
chosen from \( d^1 \) and \( d^2 \) knowing information whose state is \( \mathcal{I} \).

Now, if the information is \( H \), this latter choice will maximise \( S(d/H) \)
given by (3). Thus

\[
S(d^0; \mathcal{I}) = \sum_{H \in \mathcal{I}} \pi(H) \text{Max} \{S(d^1/H), S(d^2/H)\} \tag{5}
\]
where \( \pi(H) \) is the probability of the information \( H \), that is,
\[
\pi(H) = \sum_{e \in H} \pi_e. \tag{6}
\]

Now, equation (1) shows that we can write
\[
S(d) = \sum_{H \in \mathcal{I}} \pi(H) S(d/H). \tag{7}
\]

Comparison of (5) and (7) gives the following inequality:
\[
S(d^0, \mathcal{I}) \geq \text{Max} \{S(d^1), S(d^2)\}. \tag{8}
\]

In spite of (4) it is quite possible that the best initial decision is to discard \( d^0 \).

The same reasoning shows that as information improves (that is, as \( \mathcal{I} \) becomes finer) so \( S(d^0, \mathcal{I}) \) increases and therefore the utility associated with postponement of the decision increases. For example, if \( \hat{\mathcal{I}} \) coincides with \( \mathcal{I} \) except in that the last set \( H_k \) of the partition \( \mathcal{I} \) is the union of the last two sets \( H_k \) and \( H_{k+1} \) of \( \hat{\mathcal{I}} \) then \( S(d^0, \mathcal{I}) \geq S(d^0, \hat{\mathcal{I}}) \) follows from the fact that the weighted mean of the maximum of \( S(d^1/H_k) \) and \( S(d^2/H_k) \) and the maximum of \( S(d^1/H_{k+1}) \) and \( S(d^2/H_{k+1}) \) is greater than or equal to the maximum of \( S(d^1/H_k) \) and \( S(d^2/H_k) \) where the weighting coefficients are \( \pi(H_k)/\pi(H_k) \) and \( \pi(H_{k+1})/\pi(H_k) \).

3. The diversity of individual states of information

The consideration of information structures greatly complicates the theory of the allocation of resources. It certainly obliges us to discuss many very important questions relating to the efficient functioning of developed economies; but it leads to a badly synthesized set of models and results. So there is a loss of elegance and the theory becomes difficult to build up and to grasp.

Matters would remain simple if all the agents were in the same situation vis-à-vis information. Of course, a faithful theoretical model should make it clear how this common state of information evolves and it should exhibit the consequent effects on the set of feasible operations, individual preferences and the price system. But this could be achieved without fundamental revision relative to the previous chapter. For example, the \( i \)th individual's consumption vector \( x_{it}(e) \) at date \( t \) should be a function of the state of nature \( e \) only through the information \( H_t \) available at that date. Similarly the vector of discounted contingent prices at date \( t \) should no longer be \( p_t(e) \) but \( p_t(H_t) \).

But in fact, the different agents do not have access to the same information. Without even considering the passage of time, we must
recognise that the informations $H_i$ and $H_j$ held by $i$ and $j$ respectively are not the same for both and that the $i$th agent's activity must be compatible with $H_i$ and the $j$th agent's with $H_j$. This not only complicates the theory; in particular, it gives rise to many new problems which we shall discuss in the rest of this chapter.†

For a brief discussion let us assume, for example, that there are $m$ agents who together have complete information in the sense that the family of intersection sets

$$\bigcap_{i=1}^{m} H_i \quad \text{for } H_i \in \mathcal{I}_i$$

(9)

coincides with $\Omega$; each set of this type contains a single element $e$ of $\Omega$ and each element $e$ of $\Omega$ corresponds to one of these sets. However let us also assume that no agent has complete information; in each $\mathcal{I}_i$ there is at least one $H_i$ containing two or more elements. To represent the set of contingent commodities we must obviously choose the same $N\Omega$-dimensional Euclidean space as in the previous chapter ($Q$ products and $N$ states of nature). But in this space the $i$th agent's activity vector $x_i$ must belong to the subspace satisfying

$$x_i(e) = x_i(e)$$

(10)

for every pair of states $(e, \varepsilon)$ belonging to the same set $H_i$ of $\mathcal{I}_i$. Clearly such equalities can complicate the theory; for example, they contradict assumption 1 of Chapter 2, which we have used on various occasions.

But this is not the essential difficulty, which stems rather from the fact that it becomes unrealistic to go on accepting as relevant the concept of market equilibrium which has been the pivot of the discussion of the allocation of resources. This will be made clear in the following sections.

4. Self-selection

Much theory has been directed to the case of ‘asymmetric information structures’, particularly where two exchanging agents are unequally informed about the good involved in the transaction. Thus, the seller may have perfect knowledge of its quality while the purchaser does not; an applicant for a job may not know the exact nature of the work involved, while the employer does; conversely, the applicant may know his own capacity to carry out the work while the employer does not.

† For an introduction to the appropriate formalisations and to the difficulties involved in generalising theories relating to the optimum and to competitive equilibrium, see Radner, ‘Équilibre des marchés à terme et au comptant en cas d'incertitude’, *Cahiers du séminaire d'économétrie*, No. 9, CNRS, Paris, 1966.
If the transaction between the two agents does not come within the context of long lasting and renewed contractual relationships and if there is no particular protection for the less well-informed agent, then it is to be feared that the behaviour of the other will tend to be selective; the seller of two products of unequal quality will offer the worse product, the applicant choosing between two jobs will not choose the job best suited to his abilities but will accept the more attractive offer even if he knows he does not have the necessary qualifications.

Such effects may be important enough in practice to prevent the exchanges which would take place if all agents had the same information. Similar considerations explain why all types of risk cannot be insured against, in particular, most of the risks borne by heads of firms who launch out into new production; it is possible to insure against the objective risk of fire in factories, but impossible to insure against the risk that the new product does not please their customers. The reason for this is that the second risk depends too much on the actions of the entrepreneur; if the product does not sell well, this may be due not to bad luck but to the producer’s negligence in bad design, bad workmanship or a bad sales campaign. Since his responsibility cannot be evaluated objectively, there is no way of drawing up an insurance contract which could benefit both the entrepreneur who, in good faith, wishes only to cover himself against misfortune, and the insurer who must also take account of the risk of bad management.

We sometimes speak of ‘moral hazard’ to describe those risks which imply this responsibility on the part of the agent who is subject to them. We see that there can be no insurance against possibilities involving mainly moral hazard: since neither the insurer nor an arbitrator would have the necessary information to distinguish how much was due to this factor.

Let us look more closely at the effect of self-selection in the field of insurance. Suppose that consumers are offered a contract covering them against an individual risk which can be objectively estimated; if it occurs, the ith consumer receives a sum $z_i$ which he has chosen himself; on the other hand, he has to pay the premium $p z_i$ in advance. He knows the probability $\pi_i$ of the risk for him; on the other hand, the insurers do not know this, but only the average frequency of claims over all clients. Clearly in this situation those individuals most subject to risk take out the best cover, provided also that their situations are similar and they have the same aversion to risk.

Suppose, for example, that the risk is the loss of income which would otherwise be $R$, the same for all. Suppose that the same utility function $u$ applies to all. The ith consumer chooses the non-negative value of $z_i$ which maximises
\[ \pi_i u[(1 - p)z_i] + (1 - \pi_i)u[R - pz_i]. \] (11)

This is either zero or is found by solving

\[ (1 - p)\pi_i u'[\pi_i (1 - p)z_i] = p(1 - \pi_i)u'[R - pz_i] \] (12)

the second order condition being satisfied automatically in the case of aversion to risk \( u'' < 0 \) since it is

\[ v_i = (1 - p)^2\pi_i u''[(1 - p)z_i] + p^2(1 - \pi_i)u''[R - pz_i] < 0. \] (13)

Now, the solution \( z_i \) of (12) is an increasing function of \( \pi_i \) since differentiation gives\(^\dagger\)

\[ v_i \, dz_i + \{(1 - p)u'[\pi_i (1 - p)z_i] + pu'[R - pz_i]\} \, d\pi_i = 0. \] (14)

We can extend the study of equilibrium by assuming that insurance premiums must cover claims exactly and, taking account of the large number \( m \) of consumers, making the approximation which consists of equating the average value of claims with its expected value. This leads to the equation

\[ \frac{p}{m} \sum_{i=1}^{m} z_i = \frac{1}{m} \sum_{i=1}^{m} \pi_i z_i. \] (15)

The \( m + 1 \) equations (12) and (15) determine the \( m + 1 \) variables \( z_i \) and \( p \) as a function of the \( \pi_i \)'s and of \( R \).

For example, consider the case where \( u(x) \) is the function \( \log x \) and where \( \pi_i \) is \( \pi_a \) for half the consumers and \( \pi_b \) for the other half. The amounts of insurance \( z_a \) and \( z_b \) which each takes out, together with the level of premium, are given by

\[ p = \frac{\pi_a^2 + \pi_b^2}{\pi_a + \pi_b}, \quad pz_i = \pi_i R \quad i = a, b. \] (16)

We see that, if the probabilities \( \pi_a \) and \( \pi_b \) are equal, the rate of premium \( p \) is equal to their common value; otherwise it is greater than the average probability of risk \( (\pi_a + \pi_b)/2 \). If, for example, \( \pi_a > \pi_b \) then \( \pi_a > p > \pi_b \) and those individuals with the highest probability of risk are overinsured: \( z_a > R > z_b \); they can be said to take advantage of the situation at the expense of the others since, if they were alone in the market, the premium rate would be higher. Thus there is a kind of external effect between the two types of consumer.

\(^\dagger\) We note that, if \( p = \pi_i \) equation (12) implies \( z_i = R \) so that disposable income is independent of whether the risk is realised. This is not surprising, as we saw earlier when discussing the definition of aversion to risk.
Qualitatively similar results can be established more generally for the equilibrium solution of equations (12)-(15). For, equation (15) together with the fact that the $z_i$ cannot be negative imply that $p$ lies between the extreme values of the $\pi_i$. Also, the solution of (12) can be written $z_i(\pi_i, p)$ and this function is increasing in $p$ and such that $z_i(p, p) = R$ and so $z_i > R$ precisely when $\pi_i > p$.

Our study of this insurance market with asymmetric information and self-selection should not stop at this point. In fact, it is fairly unrealistic to assume that each individual has the choice of fixing his amount $z_i$ of insurance without affecting the rate of premium. Since it is understood that, the higher the individual probability of risk, the greater will be the amount subscribed if $p$ is independent of $z_i$, insurers organise themselves so as to offer a range of policies each specifying the amount $z_i$ concerned and involving a rate of premium $p(z_i)$ which increases with $z_i$. (Arrangements are made so that each individual can enter into only one contract.)

Equilibrium in such a market is defined by $p(z_i)$ and by the $m$ quantities $z_i$. It is clearly much more difficult to determine equilibrium than for the case discussed here.† One also finds that cases with no equilibrium exist and that, if there is one, it is not generally a Pareto optimum.

Thus in the case of this type of insurance and in many others where information is asymmetric, we are led on to consider increasingly complex contractual models, which are however increasingly realistic. These are recent developments in the theory, which becomes more and more difficult to synthesize.

5. Transmission of information through prices

An individual who is not completely informed may know that others, consumers or firms, whose identity he may not even know, have information which would be relevant to his situation. Without acquiring such information directly, he may sometimes be able to find out some of it indirectly by observing the result of the behaviour of these informed agents. In the previous example, insurers do not know the probability $\pi_i$ of the risk concerning the $i$th individual, but they could discover it through the amount $z_i$ which he chooses (of course, in the real world, insurers have no exact knowledge of either the resources or the aversion to risk of each of their clients). This indirect transmission of information is one of the essential aspects of the subject of this chapter.

† See Rothschild and Stiglitz, 'Equilibrium in Competitive Insurance Markets: An Essay on the Economics of Imperfect Information', Quarterly Journal of Economics, November 1976; see also, in the same issue, various other articles grouped under the rubric 'Symposium: The Economics of Information'. Also the Review of Economic Studies, October 1977 is entirely devoted to the economic theory of information.
In particular, the price system may be the vehicle by which some information is transmitted. An individual who is managing a portfolio of investments may be badly informed about the earning prospects of the different shares; but, by simply observing prices, he can gain information indirectly since he knows that price movements reflect trends in such prospects. Similarly, a farmer who has to decide on his planting programme may not know the prices at which his crops will be sold; but he knows that dealers on forward markets for cereals are well informed on trends in supply and demand. So he looks to forward prices for indirect information.

The part played by prices as a vehicle of information creates an additional interdependence between price and behaviour. Clearly the theory must be developed to incorporate this interdependence in the study of equilibria. Let us consider briefly how the problem arises in the context of general equilibrium in perfect competition.

In general terms, the price vector can be said to depend on the information received by the different agents, this information affecting their behaviour and consequently prices. In Section 1 we chose in particular a function $s(e)$ defining the received signal as a function of the state of nature $e$, to represent information. We must now recognise that the information received by the $i$th agent about the state $e$ contains not only the signal $s_i(e)$ but also what can be inferred about $e$ from observation of prices. Let $H = S(p)$ be this additional information, that is, the set of all states which are considered to lead to the situation that the price vector is $p$.

So the argument of the $i$th agent’s net demand function $\xi_i$ is not only $p$ but also the intersection of $s_i(e)$ and $S(p)$. The fact that total net demand of the $m$ agents is zero implies

$$\sum_{i=1}^{m} \xi_i[p, s_i(e) \cap S(p)] = 0.$$  

(17)

Let us assume that this equality determines $p$ as a function of $e$, which we can write

$$p = \Phi(e).$$  

(18)

It is natural to consider that the functions $\Phi$ and $S$ must be mutually reciprocal in the sense that $p = \Phi(e)$ implies $e \in S(p)$. To observe $p$ is to know that the state $e$ belongs to the set of states which can lead to this price vector.

So, given the functions $s_i$ and $\xi_i$, an equilibrium is a pair of functions $\Phi$ and $S$, mutually reciprocal and such that (17) and (18) are satisfied. Let us discuss the nature of this equilibrium before considering its usefulness for theoretical research.
The main hypothesis behind the above definition of equilibrium is the assumption that the function $S$ is the same for all agents and is the reciprocal function of $\Phi$. This is equivalent to assuming that each agent knows the function $\Phi$; but it does not make clear how he arrives at this knowledge. Clearly it can be considered as the result of learning by experience but then, in principle, this process should be analysed and this is rarely attempted because of the probable complexity involved. Also, as in some theories of imperfect competition, we might take the view that each agent has exact knowledge of the situation of each of the other agents, that is, that he knows all the functions $s_i$ and $\xi_i$; knowing that $S$ must be the reciprocal of $\Phi$, he can then calculate both these functions. But getting and processing all this knowledge is a tremendous task. So in both of these cases certain difficulties are disregarded and the agents are assumed to be highly rational.

Thus we see why this is called the 'rational expectations equilibrium'; expectations about the state of nature which are represented by the intersection of $s_i$ and $S$ involve a high degree of rationality.†

As often happens in theoretical research the best justification for such strong assumptions as that of rational expectations must be the fact that they can yield significant answers to questions which would otherwise remain completely obscure. That is why one may want to consider its consequences in particular cases and later wonder whether a more realistic model could not be constructed; this would entail a different specification of the function $S_i(p)$ which represents the $i$th agent's inference from his knowledge of the vector $p$.

The theory of general equilibrium with rational expectations is obviously difficult. Even the existence of equilibrium may raise problems because of the discontinuities which arise naturally in some of the functions of the model. We shall not broach this topic here.‡

6. Speculation

One of the most difficult subjects in the theory of the allocation of resources is the analysis of the role of speculation. Some economists have long held that speculation plays a useful part in the allocation of resources by carrying out some of the arbitrage which allows the price system to adapt continuously to the changing conditions in which resources must be allocated. Other economists, taking account of erratic price movements on

† The concept of rational expectations is also used in macroeconomic theory. We shall not attempt here to show how the theories of this section are linked with macroeconomic theory. The two types of theory are developed almost independently.

some markets and the large profits which then accrue to a few speculators are of the opinion that speculation is responsible for these disturbances which have a bad effect on actual production operations.

At present economic theory does not distinguish precisely how much truth lies in each of these two contrasting attitudes. However, the problem has been tackled in recent research. We shall refer to it briefly.

First, what is speculation? Its definition is not self-evident. However, we can say that intervention in a market is speculative if it is motivated by the prospect of gains from future price trends and if it is subject to some risk; it involves the purchase of a good not for present consumption or use in production but for future sale in conditions which are expected to be more favourable. It involves changing the composition of a portfolio, not in order to adapt its structure to a change in real needs which it must satisfy in the more or less long term, but in order to make a relatively short-term profit from a price trend which could be very advantageous and from which profits can be realised by the resale of newly acquired assets.†

It is the risk involved in it which distinguishes speculation from arbitrage, which also consists of taking advantage of price differences or of temporary disequilibria in the price structure. This distinction is not always clear-cut.

Before we can understand the possible usefulness of speculation, we must first describe clearly how it functions. But as yet there is no generally accepted model. Sometimes speculation is treated as equivalent to an exchange of information and the question is whether the better informed agents render a service to the less well informed. Sometimes it is treated as an exchange of risks and the question is whether it is a useful supplement to the insurance system and whether it reduces the degree of risk borne by those most directly exposed to it, or who have the greatest aversion to risk.

Here we cannot follow up either of these two lines of research. But the discussion of an abstract case may help us to understand the difficulties involved.

Suppose that $x_i$ is the net demand for an asset whose yield $r(e)$ is uncertain, which has no direct utility and which no-one issues nor holds at the outset. The market determines the price $p$ of this asset. The various individuals $i = 1, 2, \ldots, m$ also have incomes $R_i$ and all have an aversion to risk; but they do not all have the same degree of aversion nor do they

† See the following definition: ‘An investor behaves speculatively if the prospect of being able to resell a particular asset makes him prepared to accept a higher price than if he had to hold it for its normal term” (Harrison and Kreps, ‘Speculative Investor Behaviour in a Stock Market with Heterogeneous Expectations’, Quarterly Journal of Economics, 1978).
have the same information. Clearly, in this abstract case, the rational expectations equilibrium entails that the asset is not used and there is no exchange of information or risk. Nor can the asset, which has no direct utility, give rise to speculation in the equilibrium.

This is a trivial result. But it does show that apparently speculation cannot arise in the simplest conceivable situation. There is neither exchange of information nor of risk if no-one likes risk and no-one is obliged to assume the burden of it. The result still holds if income \( R_i \) is variable but if \( r(e) \) and \( R_i(e) \) appear as independent random variables in all possible information situations for the group of \( m \) individuals.

Any relevant study of speculation must probably combine the exchange of risk and the exchange of information. Since time also appears to be an essential factor, this kind of study is obviously complex.

Despite its triviality this example of a rational expectations equilibrium is useful if only for the fact that it makes us reflect on the usefulness of the concept of equilibrium; the reader may imagine how much help this concept would be in less simple cases. Already, in this example, it points up a difficulty.

Let \( G_i(e) \) be the \( i \)th individual's gain from his holding of \( x_i \):

\[
G_i(e) = [r(e) - p]x_i. \tag{19}
\]

Because of aversion to risk either \( x_i = 0 \) or the expected value of \( G_i(e) \) is positive (see Chapter 11, Section 7). Given the \( i \)th individual's information we can write

\[
E[\frac{G_i(e)}{s_i(e) \cap S(p)}] > 0 \quad \text{if } x_i \neq 0. \tag{20}
\]

and, a fortiori

\[
E[\frac{G_i(e)}{S(p)}] > 0 \quad \text{if } x_i \neq 0. \tag{21}
\]

To obtain this inequality we need only take the expected value of (20) with respect to the distribution of \( s_i(e) \) when \( e \) is already known to belong to \( S(p) \). But market equilibrium requires that the sum of the \( x_i \)'s is zero and so that the sum of the \( G_i(e) \) is zero for all \( e \) and so also

\[
E \left[ \sum_{i=1}^{m} \frac{G_i(e)}{S(p)} \right] = 0. \tag{22}
\]

Taken with (21) this equality implies that all the \( x_i \)'s are zero.

From the above proof our attention is directed towards a possibility which might not otherwise have occurred to us.† The transition from (20) to (21) and the comparison of (21) and (22) assume in fact that the three

† The proof is due to Jean Tirole.
expected values come from the same system of distributions, the only difference being that information is more precise in the first than in the second and third. But (20) refers to the behaviour of the ith individual; there is nothing to stop us from considering that it involves a subjective probability which is particular to this individual and different from that of another individual. On the other hand, (22) involves an expected value calculated from a distribution common to all individuals (and, in this sense, 'objective'). If there is a variety of subjective distributions the proof no longer applies; we must then write $E_i$ instead of $E$ in (20) and (21); no conclusion can be drawn from comparison with (22). In short, the proof assumes that, underlying the behaviour of all the individuals and before any information is received, the same distribution applies a priori.

On the other hand, it is conceivable that the asset is exchanged and so provides a kind of 'pure speculation' if a priori the individuals make different assessments of the probabilities of the different states $e$, if they know that they assess them differently, but if each thinks that the others are mistaken in their assessment of these probabilities.† In the absence of any information, the individual who assigns the smallest value to $E_i[r(e)]$ will sell his asset and the one who assigns the highest value to this expectation will buy it, price $p$ taking an intermediate value. This is a case where we can talk of exchanging risks but we can also say that the two individuals act as speculators since, while they do not have to bear risk, they do accept it given the prospect of an apparently advantageous random profit.

7. The search for information

Until now we have assumed that the states of information of the various agents are given. The functions $s_i(e)$ defining the signals to be received are exogenous. There are many situations unsuited to this assumption since some information is accessible but at a more or less high cost. So for each agent, the question is to decide whether he will bear this cost in order to obtain better direct information.

This brings in the notion of behaviour vis-à-vis the search for information. Clearly new problems are raised if we try to incorporate this in equilibrium theory.

Here we shall only use an example to give us an initial idea of the kind of question which must be dealt with by a complete economic theory of information.

† The assumption that the other agents are mistaken is somewhat alien to the behaviour assumed for rational expectations equilibrium.
Suppose there are two assets, one with fixed and the other with variable purchasing power. The different individuals exchange them on a competitive market and, at a certain cost, can obtain partial information about the return on the asset which is subject to risk. How are exchanges, prices and the list of informed individuals (that is, those who have accepted the cost of obtaining information) determined?

Let us suppose that initially, the $i$th individual has a quantity $m_{i0}$ of the fixed asset and a quantity $\omega_i$ of the variable asset. After a possible search for information and after exchanging, he has quantities $m_i$ and $z_i$ of the two assets. If $p$ is the price of the variable asset and $c$ is the cost of information, with the fixed asset as numéraire, the budget equation is

$$m_i + pz_i = m_{i0} + p\omega_i$$

for an uninformed individual and

$$m_i + pz_i + c = m_{i0} + p\omega_i$$

for an informed individual. Also, if $r(e)$ is the purchasing power of a unit of the variable asset, the $i$th individual's consumption is

$$x_i = m_i + r(e)z_i.$$  

We must also note what information each individual can receive. In this example we assume that all individuals willing to bear the cost $c$ receive the same signal $s(e)$ before exchanging assets. So they know that $e$ belongs to the subset $H(s)$ of $\Omega$ which gives for $s(e)$ precisely the observed value $s$. For this information to be useful, of course, the probability distribution of $r(e)$ must be less dispersed on $H(s)$ than on $\Omega$, as we assume.

From this example we can conceive of three types of equilibrium depending on the intensity of the search for information; either all individuals become informed, or none, or some but not all of them. According to the specification of the model and in particular, the cost of information, the chosen equilibrium will be of one or other type (we ignore cases where no equilibrium exists or where there are multiple equilibria).

Clearly the third type is the most difficult to study. It is, in fact, natural to take account of the fact that those individuals who have not sought information know that the others have done so; the former know that price $p$ reflects to some extent the signal received by the latter; if the signal indicates that there will be a high return to the variable asset then demand for it is high from the informed individuals, which means that its price is high; the price will be low in the opposite case. So individuals must take account of indirect but free information $S(p)$ which they can obtain by observing prices. Here again the concept of rational expect-
Information

ations equilibrium may be applicable if the axioms on which it depends are acceptable.

We shall not attempt the analytic discussion of this example, which is obviously difficult. However there are two immediate significant remarks.

First, we can see that the study of this type of example contributes to the analysis of stock markets where individuals are not equally well informed and where some operators can pursue the search for information to a greater or lesser extent. For a complete description of the determination of prices on these markets, the above analysis should be combined with the analysis of speculation in the previous section.

Second, to set the problem in this way clarifies from the start the amount of truth contained in a proposition which is sometimes advanced about the price system. It has been suggested that “at any moment prices reflect all available information” and this has been taken to mean that “every economic agent has access to all the available information, thanks to prices”. In fact the price system contributes largely to the dissemination of information; for example, a rise in the price of a raw material indicates an immediate deficiency in supply relative to demand and often draws attention to those continuing factors which can lead to a long-term scarcity. But it is inconsistent to assume that there is a cost involved in obtaining information and at the same time that markets transmit information completely.

In fact, no equilibrium is possible where there is some search for information if those who bear its cost are not compensated by some additional profit. Arbitrage stops at the point where the compensation is just sufficient to cover the cost of research. So those individuals who have not sought information directly must remain less well-informed than the others.

8. Multiplicity of prices

The fact that there are costs involved in acquiring information has many other consequences. It explains differences between the way the price system actually works and the picture of it given by the very stylised models on which the theory has most often concentrated. At present very active research is being carried on into these differences, their underlying causes and effects.

† This has been carried out for a particular model in Grossman and Stiglitz, ‘On the Impossibility of Informationally Efficient Markets’, American Economic Review, June 1980.
The most notable difference certainly relates to what has been called 'the law of one price' (the word 'assumption' would be more appropriate than 'law'); for a given good, the same price holds in all exchanges. So the prices of the different goods are defined unambiguously. In economies with many individually small agents, each agent must accept these prices and cannot affect them in any way.

In fact observation shows that there is some spread of prices for a given good even if it is of a well-defined quality, at a certain date and within a small geographical area. Such price variation is rarely great, but its very existence demands explanation if the approximations derived from theories based on the law of one price are to be properly assessed.

If two firms can sell the same product at different prices, giving identical sales service, this must be because all purchasers are not well informed; those paying the higher price are unaware that they could buy the product at a lower price, or, if they know this, do not know where they could do so. If some purchasers are not well-informed, this is because there are costs involved in acquiring information; it would take too much time to go round all sales outlets systematically and this is not worth while if the variation in prices is likely to be small.

But firms are obviously influenced by the possibility of selling their products at other than the minimum feasible price. Competition becomes less effective in preventing sellers from making abnormal profits. At a given moment, each firm has the choice between satisfying its usual customers while charging relatively high prices and increasing its clientèle by charging low prices and mounting an advertising campaign to inform potential buyers. But each firm must also be aware that in the long run its clientèle forms a certain picture of its price policy and so it can expand or contract progressively even without advertising initiatives.

These few remarks are enough to make us aware of the very many considerations behind a complete theory aiming at simultaneous explanation of the actual range of prices for the same good and of the behaviour of agents either as sellers or buyers. To build up such a theory it is legitimate and also necessary to start with partial models representing only some aspects of the real world; but we must not have too many illusions about the relevance of the initial conclusions thus obtained, since they are liable to be challenged by the analysis of other partial models.

So at the present moment a whole field of research lies open. But as yet we cannot hope to give a brief summary of established results.
The theories which we have investigated are built round a central model whose exact significance we have attempted to make quite clear. The student may go on to round off his knowledge of each of the questions discussed either by referring to deeper and more general proofs of the essential properties or by extending the analysis to situations so far unconsidered.

He may also think of the most serious limitations of microeconomic theory as a model for private or collective decisions relating to the organisation of production and exchange. In particular, it will be remembered that on several occasions we had to ignore transaction costs and information costs. These have been discussed by various authors in particular contexts. But they have not been incorporated in general economic theory because they complicate matters considerably.

In particular, this explains why we have not discussed monetary phenomena. The holding of money is due essentially to the transaction and information costs which agents must bear if they wish to dispense with cash. Monetary theory must therefore deal preponderantly with factors that do not figure largely in microeconomic theory. To go on now to monetary questions would divert us from the main line of development of these lectures. It seems preferable to end at the point we have now reached.
Appendix

The extrema of functions of several variables with or without constraint on the variables

by J.-C. MILLERON

The object of this appendix is to give succinct justification for a certain number of simple mathematical methods concerning maxima and minima of functions of several variables. In various chapters of this book we have to find the maximum of a function $f(x)$ of the variables $x_1, x_2, \ldots, x_n$ either when they can be chosen arbitrarily or when they are subject to constraints of the form $g_j(x) = 0$ or $g_j(x) \geq 0$, for $j = 1, 2, \ldots, m$. In classical mathematics textbooks this problem generally is not considered with sufficient precision for our needs.

We shall see that the methods discussed here are not completely general, but a certain number of particularly interesting cases can be dealt with in full.†

1. Useful definitions

(a) The notion of maximum

Let $f(x)$ be a real function defined on $\mathbb{R}^n$ and $X$ a set of $\mathbb{R}^n$. In this appendix we shall use the expression 'maximum of $f(x)$' to designate not only the largest value taken by $f$ but also any maximising vector $\hat{x}$ for which this value is achieved. More precisely:

(i) $\hat{x}$ is said to be a maximum of $f(x)$ in $X$, or $\hat{x}$ is said to be a constrained maximum of $f(x)$ subject to the condition that $x$ belongs to $X$, if $\hat{x}$ is in $X$ and $f(\hat{x}) \geq f(x)$ for all $x$ of $X$.

This is said to be an unconstrained maximum if $X$ is the whole space $\mathbb{R}^n$.

(ii) $\hat{x}$ is said to be a local maximum of $f(x)$ if there exists a neighbourhood $U(\hat{x})$ of $\hat{x}$ in which $f(x)$ is never greater than $f(\hat{x})$.

† See also Frisch, Maxima et Minima (Dunod, Paris, 1960) who gives a very detailed introduction to the methods presented here.
This is said to be an **absolute maximum** if \( \hat{x} \) maximises \( f(x) \) in the whole set \( X \), that is, if \( \hat{x} \) is a local maximum for which the neighbourhood \( U(\hat{x}) \) can be identified with \( X \).

The above concepts can easily be superimposed.

We then obtain the following definitions of a maximum.

<table>
<thead>
<tr>
<th></th>
<th>Unconstrained</th>
<th>Constrained</th>
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<tbody>
<tr>
<td><strong>Local</strong></td>
<td>There exists ( U(\hat{x}) ) such that ( f(\hat{x}) \geq f(x) ) for all ( x \in U(\hat{x}) )</td>
<td>( \hat{x} \in X ) and there exists ( U(\hat{x}) ) such that ( f(\hat{x}) \geq f(x) ) for all ( x \in U(\hat{x}) \cap X )</td>
</tr>
<tr>
<td><strong>Absolute</strong></td>
<td>( f(\hat{x}) \geq f(x) ) for all ( x )</td>
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<td>( \hat{x} \in X ) and ( f(\hat{x}) \geq f(x) ) for all ( x \in X )</td>
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We sometimes introduce the concept of **strict maximum**, keeping the same definitions as in the above table, but replacing the sign \( \geq \) by the sign \( > \) (strict inequality) and requiring that \( x \neq \hat{x} \). For example, \( \hat{x} \) is, in the strict sense, a constrained absolute maximum of \( f(x) \) in \( X \) if \( \hat{x} \) belongs to \( X \) and if \( f(\hat{x}) > f(x) \) for all \( x \in X \) such that \( x \neq \hat{x} \).

**(b) Concave functions**

A set \( X \) of \( \mathbb{R}^n \) is said to be **convex** if the vector \( x = \alpha x^1 + (1 - \alpha)x^2 \) belongs to \( X \) whenever \( x^1 \) and \( x^2 \) belong to \( X \) and \( 0 < \alpha < 1 \).

A function \( f(x) \) defined on a convex set \( X \) of \( \mathbb{R}^n \) is said to be **concave** if, for all \( x^1 \) and all \( x^2 \) of \( X \) and for every scalar \( \alpha \) lying between 0 and 1, the following inequality holds:

\[
\alpha f(x^1) + (1 - \alpha)f(x^2) \leq f[\alpha x^1 + (1 - \alpha)x^2].
\]

When the inverse inequality is realised under the same conditions, the function \( f \) is said to be **convex**.

It is equivalent to say that, if \( f(x) \) is concave, the set of vectors \( (x, y) \) of \( \mathbb{R}^{n+1} \) such that \( y \leq f(x) \) is convex and that, if \( f(x) \) is convex, the set \( \{(x, y) \in \mathbb{R}^{n+1} \mid y \geq f(x) \} \) is convex.

Figures 1 and 2 illustrate these definitions for the case of a function \( f(x) \) of a single variable.

We now prove the following important property:

**Theorem I.** If \( f(x) \) is differentiable and concave,† then

\[
f(x) \leq f(x^0) + (x - x^0)' \text{grad}f(x^0)
\]

for all \( x \) and all \( x^0 \) of \( X \).

† 'Prime' notation will be used for the transposes of vectors and matrices; \( \text{grad}f(x^0) \) represents the vector of the first derivatives of \( f \) at the point \( x^0 \).
Using the definition of concavity with $x^1 = x$, $x^2 = x^0$ and an infinitely small positive number $\alpha$ which we can denote by $dt$, we get:

$$dt f(x) + (1 - dt) f(x^0) \leq f[dx + (1 - dt)x^0],$$

which can also be written,

$$dt [f(x) - f(x^0)] \leq f[x^0 + (x - x^0) dt] - f(x^0).$$

Since $dt$ is positive, this inequality implies

$$f(x) \leq f(x^0) + \frac{f[x^0 + (x - x^0) dt] - f(x^0)}{dt},$$

which must hold for all $dt$ and therefore also in the limit when $dt$ tends to zero through positive values. The limiting inequality is precisely that stated in theorem 1, which is therefore proved.

(c) **Quadratic forms**

A quadratic form of the variables $x_1, ..., x_n$ is any homogeneous polynomial of second degree in $x_1, ..., x_n$;

$$Q = \sum_{i=1}^{n} \sum_{j=1}^{n} b_{ij} x_i x_j.$$  

If $x$ denotes the vector with components $x_1, ..., x_n$ and $A$ the symmetric square matrix whose elements $a_{ij}$ are defined by

$$a_{ii} = b_{ii}; \quad a_{ij} = \frac{b_{ij} + b_{ji}}{2} \quad \text{for} \quad i \neq j,$$

then the quadratic form $Q$ can also be written

$$Q = x' Ax.$$

$Q$ is said to be

- positive definite if $x' Ax > 0$ for all $x$ other than the null-vector
- negative definite if $x' Ax < 0$ for all $x$ other than the null-vector
- positive semi-definite if $x' Ax \geq 0$ for all $x$
- negative semi-definite if $x' Ax \leq 0$ for all $x$. 
2. Unconstrained maximum of a function of several variables

Confining our analysis to functions with continuous first and second derivatives, we shall try to characterise a local unconstrained maximum $x^0$ of the function $f(x)$ defined on $\mathbb{R}^n$.

(a) Necessary first-order conditions

We shall prove the following property:

**Theorem II.** In order that the differentiable function $f(x)$ should have a local unconstrained maximum at $x^0$, it is necessary that $\nabla f(x^0) = 0$.

Since $f(x)$ is differentiable, we can write

$$f(x) = f(x^0) + \sum_{i=1}^{n} (x_i - x^0_j)[f'_i(x^0) + \epsilon_i(x)], \quad (1)$$

where $f'_i(x^0)$ denotes the value at $x^0$ of the derivative of $f$ with respect to $x_i$ and $\epsilon_i(x)$ tends to zero as $x$ tends to $x^0$.

Let us assume that one of the derivatives $f'_i(x^0)$ is not zero, for example that $f'_j(x^0)$ is positive. Let us then choose the vector $x$ so that all its components are equal to those of $x^0$ except for $x_j$, which we take as equal to $x^0_j + a_j$, where $a_j$ is positive (if $f'_j(x^0)$ is negative, we take $a_j$ as negative). Equation (1) can then be written:

$$f(x) = f(x^0) + a_j[f'_j(x^0) + \epsilon_j(x)]. \quad (2)$$

If now $a_j$ tends to zero through positive values, then $x$ tends to $x^0$ and $\epsilon_j(x)$ to zero; therefore $f'_j(x^0) + \epsilon_j(x)$ necessarily becomes positive for sufficiently small values of $a_j$. Equation (2) then shows that $f(x) > f(x^0)$. But, for sufficiently small values of $a_j$, $x$, which tends to $x^0$, belongs to the neighbourhood $U(x^0)$ within which, by hypothesis, $x^0$ maximises $f$. It is therefore a contradiction for $f(x)$ to exceed $f(x^0)$, and this proves the theorem.

This theorem provides a necessary condition for a maximum. The same condition applies for a local unconstrained minimum $x^0$ of $f(x)$ since this is a maximum of $-f(x)$ and since $\nabla [-f(x^0)] = -\nabla f(x^0)$ is zero when $\nabla f(x^0)$ is zero.

(b) A case where the first-order conditions are sufficient; $f$ is concave.

**Theorem III.** A differentiable concave function has an unconstrained absolute maximum at $x = x^0$ if and only if $\nabla f(x^0) = 0$.

Every absolute maximum is a local maximum. In view of theorem II, the condition that $\nabla f(x^0) = 0$ is necessary. Conversely, if this condition is satisfied, it follows immediately from theorem I that we can write $f(x) \leq f(x^0)$ for all $x$, which proves that $x^0$ maximises $f(x)$. 

(c) **Necessary second-order conditions**

Let us assume that $x^0$ is a local maximum of a twice differentiable function $f(x)$. In view of theorem II we can write

$$f(x) = f(x^0) + \frac{1}{2}(x - x^0)' \begin{bmatrix} f''(x^0) + [e(x)] \end{bmatrix} (x - x^0),$$

where $[f''(x^0)]$ is the matrix of the second derivatives of $f$ for $x = x^0$ and $[e(x)]$ is a square matrix of order $n$ whose elements tend to zero as $x$ tends to $x^0$.

We wish to establish

**THEOREM IV.** If $x^0$ is a local maximum of a twice differentiable function $f(x)$, then $[f''(x^0)]$ is negative semi-definite.

We must prove that, for all $x$,

$$(x - x^0)' [f''(x^0)] (x - x^0) \leq 0.$$  

Suppose that there exists $x^*$ such that

$$(x^* - x^0)' [f''(x^0)] (x^* - x^0) > 0.$$  \hspace{1cm} (4)

We can then find a sufficiently small positive number $\lambda$ so that simultaneously:

(a) $x^1 = x^0 + \lambda (x^* - x^0)$ belongs to the neighbourhood $U(x^0)$ in which $x^0$ maximises $f(x)$;

(b) $|(x^* - x^0)' [e(x^1)] (x^* - x^0)| < (x^* - x^0)' [f''(x^0)] (x^* - x^0)$.

But $x^1 - x^0 = \lambda (x^* - x^0)$ so that, since $\lambda$ is positive, (4) and (b) imply

$$(x^1 - x^0)' [f''(x^0)] (x^1 - x^0) > 0.$$  

It then follows from (3) that

$$f(x^1) > f(x^0) \quad \text{where} \quad x^1 \in U(x^0),$$

which contradicts the assumption that $x^0$ maximises $f(x)$ in $U(x^0)$. The theorem is therefore proved.

![Fig. 3](image)

(d) **A case where the second-order conditions are sufficient; the matrix of the second derivatives is negative definite.**

**THEOREM V.** Let $f(x)$ be a twice differentiable function. If grad $f(x^0) = 0$ and if $[f''(x^0)]$ is negative definite, then $x^0$ is a strict local maximum of $f(x)$. 

Appendix

We can define a neighbourhood $U(x^0)$ such that, for all $x$ in $U(x^0)$ and not equal to $x^0$, we have

$$|(x - x^0)'[\epsilon(x)][x - x^0]| < - (x - x^0)[f''(x^0)](x - x^0).$$

In fact, the left hand side is bounded above by $\|x - x^0\|^2$ multiplied by the largest latent root $\tilde{\mu}(x)$ of $[\epsilon(x)]$ while the right hand side is bounded below by $\|x - x^0\|^2$ multiplied by the smallest latent root $\nu$ of $[f''(x^0)]$. The root $\nu$ is positive and $\tilde{\mu}(x)$ tends to zero† as $x$ tends to $x^0$.

Equation (3) then implies:

$$f(x) < f(x^0) \text{ for all } x \text{ other than } x^0 \text{ and belonging to } U(x^0).$$

Note. The above theorems can be transposed immediately to the case of a minimum. In theorem III, $f(x)$ must be a convex function since $- f(x)$ must be concave. In theorems IV and V $[f''(x^0)]$ must be positive semi-definite and positive definite respectively.

3. Extremum subject to constraints of the form $g_j(x) = 0; \ j = 1, 2, \ldots, m$

From now on, we shall assume that not only $f$, but each of the functions $g_j$ is twice differentiable.

(a) Necessary first-order conditions; Lagrange multipliers.

THEOREM VI. Let $X$ be the set of $x$'s satisfying the constraints $g_j(x) = 0$, for $j = 1, \ldots, m$. If $x^0$ is a local maximum of $f(x)$ in $X$ and if the matrix $G^0 = [\partial g_j(x^0)/\partial x_i]$ has rank $m$, then there exists a vector $\lambda^0$ of $R^m$ such that

$$\text{grad } f(x^0) + \sum_{j=1}^m \lambda^0_j \text{ grad } g_j(x^0) = 0. \quad (5)$$

The numbers $\lambda^0_j$ are called 'Lagrange multipliers'.

Consider the system of $m$ equations

$$g_j(x) = z_j \quad j = 1, 2, \ldots, m \quad (6)$$

† In fact the latent roots of a matrix tend to zero as it tends to the zero matrix. Let $\lambda$ be a root of $A$ and let $x$ be a corresponding latent vector: $Ax = \lambda x$. Let us define the norms $\|A\|$ and $\|x\|$ as equal respectively to the maxima of the absolute values of the elements of $A$ and $x$. If $n$ is the order of $A$ and $i,j$ the indices of its elements, we can establish directly:

$$|\lambda x_i| \leq \sum_{j=1}^n |a_{ij}| \cdot |x_j| \leq n\|A\| \cdot \|x\|$$

and therefore

$$|\lambda| \cdot \|x\| \leq n\|A\| \cdot \|x\| \quad \text{and} \quad |\lambda| \leq n\|A\|,$$

which implies the stated result.
Extremum subject to constraints of the form $g_j(x) = 0; j = 1, 2, \ldots, m$ in which the $z_j$ are real variables. Since $G^0$ has rank $m$, we must have $n \geq m$. Moreover, the theorem of implicit functions\(^\dagger\) ensures that, in a neighbourhood of $x^0$, we can express $m$ of the variables $x_i$ as differentiable functions of the other $n-m$ variables and the $z_j$. Suppose, for example, that the first $m$ variables $x_i$ are expressed in this way:

$$x_k = \xi_k(z_1, z_2, \ldots, z_m; x_{m+1}, \ldots, x_n) \quad k = 1, 2, \ldots, m.$$ 

Substituting these expressions in $f$, we define a new differentiable function:

$$f(x) = F(z_1, z_2, \ldots, z_m; x_{m+1}, \ldots, x_n).$$

To say that $x^0$ is a local maximum of $f(x)$ in $X$ is to say that $x^0$ locally maximise the function $F(0, 0, \ldots, 0; x_{m+1}, \ldots, x_n)$.

It follows from theorem II that the derivatives of $F$ with respect to the $x_{m+1}, \ldots, x_n$ are zero. Thus, the differential of $f$, identically equal to the differential of $F$, can be written:

$$df = dF = \mu_1 dz_1 + \ldots + \mu_m dz_m$$

where the $\mu_1, \mu_2, \ldots, \mu_m$ are the partial derivatives of $F$ with respect to $z_1, z_2, \ldots, z_m$. Setting $\lambda_j = -\mu_j$ and taking account of (6), we can transcribe the last equation as follows:

$$df + \sum_{j=1}^{m} \lambda_j^0 dg_j = 0,$$

which expresses precisely the equality to be proved.

Remarks

(1) To determine the coordinates of the constrained maxima (or minima) $x^0$, of a function $f(x)$, we may write that the necessary conditions (5) are satisfied and that also

$$g_j(x^0) = 0 \quad \text{for} \quad j = 1, 2, \ldots, m. \quad (7)$$

Equations (5) and (7) are equal in number to the components of the vectors $x^0$ and $\lambda^0$. The solutions for $x^0$ and $\lambda^0$ of the system that they constitute include the maxima and minima of $f$, but possibly also certain other vectors (saddle-points of the function, etc.). Stronger conditions are necessary for the precise determination of maxima and minima.

(2) With each $x^0$ that satisfies (5) there is associated one or more $\lambda^0$, which we shall call vectors of the dual variables at $x^0$, in accordance with recent usage.

(3) The following two propositions are naturally equivalent:

(i) $x^0$ is a maximum of $f(x)$ in the set $X$ defined by $g_j(x) = 0$ for $j = 1, \ldots, m$.

(ii) $x^0$ is a maximum of $f(x) + \sum_{j=1}^{m} \lambda^0_j g_j(x)$ in the same set $X$.

For, for every $x$ in $X$,

$$f(x) = f(x) + \sum_{j=1}^{m} \lambda^0_j g_j(x).$$

(b) **Necessary second-order conditions for a local maximum of $f(x)$**

We saw that, if $\|\partial g_j(x_0)/\partial x_i\|$ has rank $m$, the existence of a local maximum of $f(x)$ in $X = \{x|g_j(x) = 0; j = 1, 2, \ldots, m\}$ is equivalent to the existence of an unconstrained local maximum of $F(0, \ldots, 0; x_{m+1}, \ldots, x_n)$. We could therefore proceed directly to find the matrix of the second derivatives of this function and to write that this matrix is negative semi-definite (theorem IV).

It is simpler to investigate the function

$$l(x) = f(x) + \sum_{j=1}^{m} \lambda^0_j g_j(x),$$

also written for simplicity $f(x) + \lambda^0 g(x)$, which we shall call the 'Lagrangian', and take account of the fact that $l(x)$ has a maximum at $x^0$ in $X$ (remark (3) above).

Considering $x_1, \ldots, x_m$ as implicit functions of $x_{m+1}, \ldots, x_n$, we can write, as on page 305:

$$L(x_{m+1}, \ldots, x_n) = l[\xi_1(x_{m+1}, \ldots, x_n), \ldots, \xi_m(x_{m+1}, \ldots, x_n), x_{m+1}, \ldots, x_n].$$

The arguments $z_j = 0$ of the $\xi_j$ are omitted for simplicity. Our problem therefore reduces to finding the matrix of second derivatives of $L$.

Now, we have

$$d^2 L = d\xi^T \left[ \frac{\partial^2 l}{\partial x_i \partial x_h} \right] d\xi + \sum_{i=1}^{n} \frac{dl}{\partial x_i} d^2 x_i. \tag{8}$$

If no simplification were possible, we should have to eliminate the terms in $dx_i$ and $d^2 x_i$ between (8) and the equations $dg_j = 0$, $d^2 g_j = 0$; we should then have to identify the coefficients of the terms in $dx_i$ $dx_h$ ($i, h = m + 1, \ldots, n$) as second derivatives of $L$.

It is possible to use more simple reasoning. We see that, in the expression for $d^2 L$, the terms in $d^2 x_i$, $i = 1, \ldots, m$ disappear, since the first-order conditions imply

$$\frac{dl(x^0)}{\partial x_i} = 0.$$
Therefore we need only require that the quadratic form
\[ d^2L = dx' \left| \frac{\partial^2 f}{\partial x_i \partial x_i} \right| dx \]
is negative semi-definite in a subspace defined by the equations \( dg_j = 0 \) for \( j = 1, \ldots, m \).

Hence the theorem:

**Theorem VII.** Let \( X \) be the set of \( x \)'s such that \( g_j(x) = 0 \), for \( j = 1, \ldots, m \). Suppose that \( f(x) \) and \( g_j(x) \) are twice differentiable. If \( x^0 \) is a local maximum of \( f(x) \) in \( X \), and if \( \lambda^0 \) is a dual vector associated with \( x^0 \), the quadratic form
\[ d^2L(x^0) = dx' \left| \frac{\partial^2 f(x^0)}{\partial x_i \partial x_i} + \lambda^0 \frac{\partial^2 g(x^0)}{\partial x_i \partial x_i} \right| dx \]
is negative semi-definite subject to the constraints
\[ \sum_{i=1}^n \frac{\partial g_j(x^0)}{\partial x_i} dx_i = 0 \quad j = 1, \ldots, m. \]

(c) A case where the second-order conditions are sufficient

We can also apply theorem V to the case of a constrained maximum:

**Theorem VIII.** Let \( f(x) \) and \( g_j(x), (j = 1, \ldots, m) \), be twice differentiable functions. If there exists a vector \( \lambda^0 \) of \( \mathbb{R}^m \) such that
\[ \text{grad } f(x^0) + \sum_{j=1}^m \lambda^0_j \text{grad } g_j(x^0) = 0 \]
at a point \( x^0 \) such that \( g_j(x^0) = 0 \), for \( j = 1, \ldots, m \), and if, in addition, the quadratic form
\[ d^2L = dx' \left| \frac{\partial^2 f(x^0)}{\partial x_i \partial x_i} + \lambda^0 \frac{\partial^2 g(x^0)}{\partial x_i \partial x_i} \right| dx \]
is negative definite subject to the constraints
\[ \sum_{i=1}^n \frac{\partial g_j(x^0)}{\partial x_i} dx_i = 0 \quad j = 1, \ldots, m, \]
then \( x^0 \) is a local maximum of \( f(x) \) in \( X = \{ x | g_j(x) = 0, j = 1, \ldots, m \} \).

Suppose that this is not the case. There exists a sequence \( x^s \) of vectors of \( X \) tending to \( x^0 \) and such that \( f(x^s) \geq f(x^0) \). If \( \eta^s \) is the length of \( x^s - x^0 \), the vectors \( u^s = (x^s - x^0)/\eta^s \) belong to the unit sphere, which is a compact set. We can therefore extract from the sequence of the \( u^s \) a sub-sequence tending to a vector \( u \), which is obviously non-zero. Let us confine attention to this sub-sequence. In view of the fact that \( g_j(x^0) = 0 \) and grad \( l(x^0) = 0 \), we can write
\[ 0 = g_j(x^s) = \eta^s u^s [\text{grad } g_j(x^0) + \delta^s] \]
and
\[ l(x^s) = l(x^0) + \frac{1}{2}(\eta^s)^2 u''[l''(x^0)] + \varepsilon^s u^s \]
where \([l''(x^0)]\) is the matrix that occurs in the expression for \(d^2L\). Reasoning similar to that in the proof of theorem V shows that the vector \(\delta^s\) and the matrix \(e^s\) are negligible for sufficiently large \(s\).

Thus, in the limit,
\[ u \cdot \text{grad} \, g_j(x^0) = 0 \]
and therefore
\[ u'[l''(x^0)]u < 0 \]
and consequently also
\[ u''[l''(x^0)]u^s < 0 \]
for sufficiently large \(s\). It then follows from the limited expansion of \(l(x^s)\) that, for sufficiently large \(s\),
\[ f(x^s) = l(x^s) < l(x^0) = f(x^0). \]
This is the required contradiction, which establishes the theorem.

(d) A case where the first-order conditions are sufficient: the Lagrangian is a concave function

THEOREM IX. If \(f(x)\) and \(g_j(x)\) are differentiate and if there exists \(\lambda^0\) of \(\mathbb{R}^m\) such that, at a point \(x^0\) of \(X\),
\[ \text{grad} \, f(x^0) + \sum_{j=1}^{m} \lambda_j^0 \text{grad} \, g_j(x^0) = 0 \]
and such that the associated Lagrange function
\[ l(x) = f(x) + \sum_{j=1}^{m} \lambda_j^0 g_j(x) \]
is concave, then \(x^0\) is an absolute maximum of \(f(x)\) in
\[ X = \{x|g_j(x) = 0, \quad j = 1, 2, \ldots, m\}. \]
Since \(l(x)\) is concave, theorem 1 implies
\[ l(x) \leq l(x^0) + (x - x^0)' \text{grad} \, l(x^0) \]
or
\[ f(x) + \sum_{j=1}^{m} \lambda_j^0 g_j(x) \leq f(x^0) + \sum_{j=1}^{m} \lambda_j^0 g_j(x^0) + (x - x^0)' \text{grad} \, l(x^0). \]
Since \(\text{grad} \, l(x^0) = 0\) and \(g_j(x^0) = 0\),
\[ f(x) \leq f(x^0) \]
for all \(x\) such that \(g_j(x) = 0; \quad j = 1, 2, \ldots, m\).
Particular case. If \( f(x) \) is concave and if the \( g_j(x) \) are linear, the Lagrangian is concave; the first-order conditions are sufficient to establish that \( x^0 \) is a maximum.

4. Extremum subject to constraints of the form \( g_j(x) \geq 0, j = 1, \ldots, m \)

In what follows we shall have to use a theorem known as Farkas' theorem. Its proof is fairly laborious so we shall assume

**Theorem X.** Given a matrix \( Q \), a row vector \( r \) and a variable vector \( x \), then in order that \( Qx \geq 0 \) should imply \( rx \geq 0 \) it is necessary and sufficient that there exist a row vector \( p \) with non-negative elements such that \( r = pQ \).

From now on we shall let \( Y \) denote the set of \( x \)'s such that

\[ g_j(x) \geq 0, \quad \text{for} \quad j = 1, \ldots, m. \]

Let \( x^0 \) be a maximum of \( f(x) \) in \( Y \).

By convention, \( E \) is the set of indices \( j \) such that \( g_j(x^0) = 0 \) and \( E \) is the set of the other indices \( (g_j(x^0) > 0) \). Finally, \( K \) is the cone of the vectors \( x \) for which

\[ (x - x^0)^\top \text{grad} \ g_j(x^0) \geq 0, \quad \text{for all} \ j \in E. \]

We make the following assumptions:

**Assumption 1.** \( f(x) \) and the \( g_j(x) \) have first derivatives.

**Assumption 2.** For every \( x \) of \( K \), there exists in \( Y \) an arc which is a tangent at \( x^0 \) to the line \( x - x^0 \).

More precisely, given \( x \) in \( K \), there exists a line segment with equation \( \xi = e(\theta), 0 \leq \theta \leq 1 \), such that

\[
\begin{align*}
  e(0) &= x^0 \\
  \frac{de(\theta)}{d\theta} &= \rho(x - x^0) \\
  \end{align*}
\]

where \( \rho \) is a positive number.

Note that the condition is not generally satisfied if the matrix \( G^0 \) of theorem VI has rank smaller than \( m. \)

Figure 4 illustrates assumption 2 in the case of two variables and two constraints. The following constraints provide an example where the assumption is not satisfied:

\[
\begin{align*}
  \begin{cases} 
  g_1(x) = -x_1^3 + x_2 \geq 0 \\
  g_2(x) = x_1^4 - x_2 \geq 0 
  \end{cases}
\end{align*}
\]

† Here we follow the approach given in Huard, *Mathématiques des programmes économiques*, Dunod, 1965.

‡ Assumption 2 is often called the 'constraint qualification' as a reminder that the assumption relates to the set of functions defining the constraints and not to the function \( f \) to be maximised.
If $x^0$ is the origin, the cone $K$ is identified with the $x_1$-axis. The condition in the assumption is not satisfied for any $x$ belonging to the positive part of this axis (cf. Figure 5).

We wish to establish the following theorem:

**Theorem XI (Kuhn-Tucker theorem).** If $x^0$ is a maximum of $f(x)$ in $Y$ and if assumptions 1 and 2 are satisfied, there exists a vector $\lambda$ none of whose components is negative, and which is such that simultaneously

$$\nabla f(x^0) + \sum_{j=1}^m \lambda_j \nabla g_j(x^0) = 0$$

Fig. 4

Fig. 5
Extremum subject to constraints of the form $g_j(x) \geq 0$, $j = 1, \ldots, m$

and

$$\sum_{j=1}^{m} \lambda_j g_j(x^0) = 0.$$ 

For applying Farkas’ theorem, we shall first prove that

$$\begin{cases}
\text{if } (x - x^0)' \text{ grad } g_j(x^0) \geq 0 \text{ for all } j \text{ of } E \text{ (therefore if } x \in K), \\
\text{then } (x - x^0)' \text{ grad } f(x^0) \leq 0.
\end{cases} \quad (10)$$

Let $\xi = e(\theta)$ be the arc whose existence is guaranteed by assumption 2. Consider the function $\Phi(\theta) = f[e(\theta)]$ for $0 \leq \theta \leq 1$. Since the points $e(\theta)$ are in $Y$, we have

$$\Phi(0) = f(x^0) \geq f(\xi) = \Phi(\theta);$$

hence,

$$\frac{d\Phi(0)}{d\theta} \leq 0$$

or

$$[\text{grad } f(x^0)]' \frac{de(0)}{d\theta} \leq 0.$$ 

In view of (9), the last inequality can be written:

$$[\text{grad } f(x^0)]' \rho(x - x^0) \leq 0$$

and, since $\rho$ is positive,

$$(x - x^0)' \text{ grad } f(x^0) \leq 0.$$ 

Let us now apply Farkas’ theorem to preposition (10). There exists a vector with components $\lambda_j \geq 0$, for all the $j$’s of $E$, such that

$$- \text{ grad } f(x^0) = \sum_{j \in E} \lambda_j \text{ grad } g_j(x^0). \quad (11)$$

We also set $\lambda_j = 0$ for all the $j$’s of $E$. Then (11) becomes

$$\text{grad } f(x^0) + \sum_{j=1}^{m} \lambda_j \text{ grad } g_j(x^0) = 0. \quad (12)$$

But $g_j(x^0) > 0$ implies $\lambda_j = 0$, according to the definitions of the $\lambda_j$ and of $E$. On the other hand, $\lambda_j > 0$ implies $g_j(x^0) = 0$, so that $\lambda_j g_j(x^0)$ is zero for all $j$ and so

$$\sum_{j=1}^{m} \lambda_j g_j(x^0) = 0. \quad (13)$$

This proves the existence of the vector $\lambda$ specified in theorem XI.
**Particular case.** The domain $Y$ is frequently defined by conditions of the form

$$
\begin{align*}
\begin{cases}
g_j(x) & \geq 0 \quad j = 1, \ldots, m, \\
x_i & \geq 0 \quad i = 1, 2, \ldots, n.
\end{cases}
\end{align*}
$$

When we apply theorem XI, we know that, if $x^0$ is a maximum, there exists in $\mathbb{R}^{m+n}$ a vector \( \begin{bmatrix} \lambda \\ \mu \end{bmatrix} \) with no negative component and such that

$$
\text{grad } f(x^0) + \sum_{j=1}^{m} \lambda_j \text{grad } g_j(x^0) + \mu = 0, \tag{14}
$$

where

$$
\sum_{j=1}^{m} \lambda_j g_j(x^0) + \mu x^0 = 0. \tag{15}
$$

$\mu$ is then the vector of the dual variables of the constraints $x_i \geq 0$.

Let us introduce the Lagrange function

$$
l(x, \lambda) = f(x) + \sum_{j=1}^{m} \lambda_j g_j(x) \n$$

Remembering that $\mu$ has no negative component, we can write (14) and (15) in the form

(i) $x^0 \geq 0; \frac{\partial l(x^0, \lambda)}{\partial x_i} \leq 0$ for all $i = 1, \ldots, n$; in addition, if $\frac{\partial l}{\partial x_i} < 0$ for a particular index $i$, then $x_i^0 = 0$ for this index.

(ii) $\lambda \geq 0; \frac{\partial l(x^0, \lambda)}{\partial \lambda_j} = g_j(x^0) \geq 0$, for all $j = 1, \ldots, m$; in addition, if $\lambda_j > 0$ for a particular $j$, then $g_j(x^0) = 0$ for this $j$.

Taking the inverses, we note that the implications of (i) and (ii) are equivalent to

$$
x_i^0 > 0 \Rightarrow \frac{\partial l}{\partial x_i} = 0 \quad \text{and} \quad g_j(x^0) > 0 \Rightarrow \lambda_j = 0.
$$

**A case where the Kuhn-Tucker conditions are sufficient**

**Theorem XII.** If $f(x)$ and the $g_j(x)$ are concave, then the Kuhn-Tucker conditions imply that $x^0$ is a maximum.

Suppose that $x^0$ satisfies the conditions

$g_j(x^0) \geq 0 \quad j = 1, \ldots, m$

and that there exist $\lambda_j \geq 0$ such that

$$
\text{grad } f(x^0) + \sum_{j=1}^{m} \lambda_j \text{grad } g_j(x^0) = 0,
$$

\[\dagger\] Note that here, as opposed to the case in Section 3, $l$ is interpreted as a function of $x$ and of $\lambda$. 

Extremum subject to constraints of the form \( g_j(x) \geq 0, j = 1, \ldots, m \)

with

\[
\sum_{j=1}^{m} \lambda_j g_j(x^0) = 0.
\]

Let us apply theorem 1 to the concave functions \( f \) and \( g_j \):

\[
f(x) - f(x^0) \leq (x - x^0)' \text{grad} f(x^0),
\]

\[
g_j(x) - g_j(x^0) \leq (x - x^0)' \text{grad} g_j(x^0).
\]

For all \( x \) such that \( g_j(x) \geq 0 \), we can therefore establish directly the sequence of inequalities:

\[
f(x) - f(x^0) \leq (x - x^0)' \left[ - \sum_{j=1}^{m} \lambda_j \text{grad} g_j(x^0) \right]
\]

\[
\leq \sum_{j=1}^{m} \lambda_j [g_j(x^0) - g_j(x)]
\]

\[
\leq - \sum_{j=1}^{m} \lambda_j g_j(x) \leq 0,
\]

which completes the proof of theorem XII.
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